

5.1. **Stopped martingales are martingales.** Let $(M_n, n = 0, 1, 2, \dots)$ be a martingale in discrete time for the filtration $(\mathcal{F}_n, n \geq 0)$. Let τ be a stopping time for the same filtration. Use the martingale transform with the process

$$X_n(\omega) = \begin{cases} +1 & \text{if } n < \tau(\omega), \\ 0 & \text{if } n \geq \tau(\omega) \end{cases}$$

to show that the stopped martingale $(M_{\tau \wedge n}, n \geq 0)$ is a martingale.

For martingale $(M_n, n \geq 0)$ for filtration $(\mathcal{F}_n, n \geq 0)$ and $(X_n, n \geq 0)$ defined above, we can define the martingale transform I_t as

$$I_t = X_0(\omega) (M_1 - M_0) + X_1(\omega) (M_2 - M_1) + \dots + X_{t-1}(\omega) (M_t - M_{t-1})$$

$$\text{For } t < \tau(\omega), I_t = M_1 - M_0 + M_2 - M_1 + \dots + M_t - M_{t-1} = M_t - M_0 = M_t$$

$$\text{For } t \geq \tau(\omega), I_t = M_1 - M_0 + \dots + M_{\tau(\omega)} - M_{\tau(\omega)-1} = M_{\tau(\omega)} - M_0 = M_{\tau(\omega)}$$

Thus it corresponds to the stopped martingale $(M_{\tau \wedge n}, n \geq 0)$.

As martingale transforms are martingales, the stopped martingale $(M_{\tau \wedge n}, n \geq 0)$ is a martingale.

EX 5.2 we have $I_t = \begin{cases} 10B_t & t \in [0, \frac{1}{3}] \\ 10B_{1/3} + 5(B_t - B_{1/3}) & t \in (\frac{1}{3}, \frac{2}{3}] \\ 10B_{1/3} + 5(B_{2/3} - B_{1/3}) + 2(B_t - B_{2/3}) & t \in (\frac{2}{3}, 1] \end{cases}$

a) we have that $(I_{1/3}, I_{2/3}, I_1) = (10B_{1/3}, 10B_{1/3} + 5(B_{2/3} - B_{1/3}), 10B_{1/3} + 5(B_{2/3} - B_{1/3}) + 2(B_1 - B_{2/3}))$

By properties of Brownian motion, let $X = B_{1/3}$, $Y = B_{2/3} - B_{1/3}$, $Z = B_1 - B_{2/3}$

Then $X, Y, Z \sim N(0, 1/3)$ and they are independent.

Hence $(I_{1/3}, I_{2/3}, I_1) = (10X, 10X + 5Y, 10X + 5Y + 2Z)$

And hence for any $(w_1, w_2, w_3) \in \mathbb{R}^3$, $w_1 I_{1/3} + w_2 I_{2/3} + w_3 I_1$
 $= 10(w_1 + w_2 + w_3)X + 5(w_2 + w_3)Y + 2w_3 Z$

which is also normal (due to independence).

Hence by definition, $(I_{1/3}, I_{2/3}, I_1)$ is Gaussian.

b) For X, Y, Z defined above, the mean vector is $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ and covariance matrix

$\Sigma = \begin{pmatrix} \frac{1}{3} & 0 & 0 \\ 0 & \frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{3} \end{pmatrix}$. Now, $\begin{pmatrix} I_{1/3} \\ I_{2/3} \\ I_1 \end{pmatrix} = \begin{pmatrix} 10 & 0 & 0 \\ 10 & 5 & 0 \\ 10 & 5 & 2 \end{pmatrix} \begin{pmatrix} X \\ Y \\ Z \end{pmatrix}$, hence the covariance matrix

for $(I_{1/3}, I_{2/3}, I_1)$ is $\Sigma' = \begin{pmatrix} 10 & 0 & 0 \\ 10 & 5 & 0 \\ 10 & 5 & 2 \end{pmatrix} \begin{pmatrix} \frac{1}{3} & 0 & 0 \\ 0 & \frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{3} \end{pmatrix} \begin{pmatrix} 10 & 10 & 10 \\ 0 & 5 & 5 \\ 0 & 0 & 2 \end{pmatrix} = \begin{pmatrix} \frac{100}{3} & \frac{100}{3} & \frac{100}{3} \\ \frac{100}{3} & \frac{125}{3} & \frac{125}{3} \\ \frac{100}{3} & \frac{125}{3} & \frac{125}{3} \end{pmatrix}$
 $(\Sigma' = M \Sigma M^T)$

And the mean vector is $\mu' = M \mu = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$.

c) $E[B_1 I_1] = E[B_1 (10B_{1/3} + 5B_{2/3} - 5B_{1/3} + 2B_1 - 2B_{2/3})]$

$= 5E[B_1 B_{1/3}] + 3E[B_1 B_{2/3}] + 2E[B_1 B_1] \quad \triangleright \quad E[B_s B_t] = St.$

$= \frac{5}{3} + \frac{2}{3} \times 3 + 2 \times 1 = \frac{17}{3}$

Since $E B_1 = 0$, $E I_1 = 5E X + 3E Y + 2E Z = 0$, we have $\text{Cov}(B_1, I_1) = E[B_1 I_1] = \frac{17}{3}$

Hence B_1, I_1 are Gaussian with non-zero covariance $\rightarrow B_1$ and I_1 are not independent. □

EX 5.4

a) since $t_1 \leq t_2 \leq t_3 \leq t_4$, we have $\mathcal{F}_{t_1} \subseteq \mathcal{F}_{t_2} \subseteq \mathcal{F}_{t_3} \subseteq \mathcal{F}_{t_4}$.

Thus, we have: $E[(M_{t_2} - M_{t_1})(M_{t_4} - M_{t_3})]$

$$= E[E[(M_{t_2} - M_{t_1})(M_{t_4} - M_{t_3}) | \mathcal{F}_{t_2}]]$$

$$= E[(M_{t_2} - M_{t_1}) E[(M_{t_4} - M_{t_3}) | \mathcal{F}_{t_2}]] \quad \text{since } M_{t_2} - M_{t_1} \text{ is } \mathcal{F}_{t_2}\text{-measurable}$$

$$= E[(M_{t_2} - M_{t_1}) E[M_{t_4} - M_{t_3}]] \quad \text{since } M_{t_4} - M_{t_3} \text{ independent from } \mathcal{F}_{t_2}$$

$$= E[(M_{t_2} - M_{t_1}) (E[M_{t_4}] - E[M_{t_3}])]$$

$$= 0, \text{ since } E[M_{t_4}] = E[M_{t_3}] = E[M_0] \text{ by the martingale property.}$$

b) Let $I_t = \int_0^t X_s dB_s$. By properties of $L^2_c(T)$ processes, $\int_0^t E[X_s^2] ds = E[(\int_0^t X_s dB_s)^2]$

under the notation, LHS becomes $E[I_t I_t] = E[I_t^2]$ (isometry)

$$\text{then, } E[I_t I_{t'} - I_t^2] = E[I_t (I_{t'} - I_t + I_t) - I_t^2] = E[I_t (I_{t'} - I_t)]$$

$$= E[(I_t - I_0)(I_{t'} - I_t)]$$

since $I_t, I_{t'}$ are martingales, then take $0 \leq t \leq t' \leq T$ and apply a), with $M_{t_1} = 0 = I_0$, $M_{t_2} = I_t$, $M_{t_3} = I_t$, $M_{t_4} = I_{t'}$. Thus we obtain:

$$E[(I_t - I_0)(I_{t'} - I_t)] = 0 \Rightarrow E[I_t I_{t'} - I_t^2] = 0$$

$$\Rightarrow E[I_t I_{t'}] = E[I_t^2]$$

$$\text{By Itô's isometry. } \Leftrightarrow E[\int_0^t X_s dB_s \cdot \int_0^{t'} X_s dB_s] = \int_0^t E[X_s^2] ds$$

□

EX 5.6 $M_t = \exp(\sigma B_t - \sigma^2 t/2)$

For any $T > 0$, we have

- ① Since B_t is adapted to \mathcal{F}_t for $t \leq T$ and M_t is a function of B_t , we have that M_t is \mathcal{F}_t -measurable. Hence M_t is adapted.
- ② Since B_t is continuous a.s. and M_t is a continuous function of B_t , we have that M_t is continuous almost surely on $[0, T]$ for any T .
- ③ $\int_0^T \mathbb{E}[M_t^2] dt = \int_0^T e^{-\sigma^2 t} \mathbb{E}[\exp(2\sigma B_t)] dt$.
 Since $B_t \sim N(0, t)$, then $\mathbb{E}[e^{2\sigma B_t}]$ is the MGF of $N(0, t)$ valued at σ : $\mathbb{E}[e^{2\sigma B_t}] = \exp(\frac{1}{2}t(2\sigma)^2) = \exp(2\sigma^2 t)$.
 Hence the integral becomes $\int_0^T e^{\sigma^2 t} dt = \frac{1}{\sigma^2} [e^{\sigma^2 t}]_0^T = \frac{1}{\sigma^2} [\exp(\sigma^2 T) - 1] < \infty$ for given $T > 0$.

thus, we conclude that $(M_t, t \leq T) \in \mathcal{L}_c^2(T) \quad \forall T > 0$. □

Ex 5.7 $M_t = \exp(B_t^2)$, $t \leq T$.

we check the case when $T > \frac{1}{4}$.

$$\begin{aligned} \int_0^T \mathbb{E}[M_t^2] dt &= \int_0^T \mathbb{E}[\exp(2B_t^2)] dt \\ &= \int_0^T \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi t}} e^{-\frac{x^2}{2t}} \cdot \exp(2x^2) dx dt \quad \text{since } B_t \sim N(0, t) \\ &= \int_0^T \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi t}} e^{(2-\frac{1}{2t})x^2} dx dt. \end{aligned}$$

if $2 - \frac{1}{2t} > 0$, then the inner integral diverges, leading to $\int_0^T \mathbb{E}[M_t^2] dt = \infty$.

since $t \in [0, T]$, then if $T \leq \frac{1}{4}$, we have $t \leq T \Rightarrow 2 - \frac{1}{2t} \leq 2 - \frac{1}{2 \cdot \frac{1}{4}} = 0$

Hence, the integral converges when $T \leq \frac{1}{4}$, and when $T > \frac{1}{4}$, for $t \in (\frac{1}{4}, T]$, we have

$$\text{that } 2 - \frac{1}{2t} > 0 \Rightarrow \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi t}} e^{(2-\frac{1}{2t})x^2} dx = \infty$$

$$\Rightarrow \int_0^T \mathbb{E}[M_t^2] dt = \infty \Rightarrow M_t \notin \mathcal{L}_c^2(T),$$

since M_t violates the condition that $\int_0^T \mathbb{E}[M_t^2] dt < \infty$.

thus, we conclude that $(e^{B_t^2}, t \leq T)$ is not in $\mathcal{L}_c^2(T)$ for $T > \frac{1}{4}$.