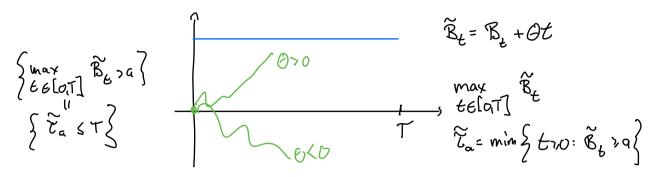
## Another application of Cameron-Mortin-Girsanor



**Proposition 9.7** (Bachelier formula for Brownian motion with constant drift). Let  $\widetilde{B}_t = B_t + \theta t$  be a Brownian motion with drift  $\theta$ . Let  $\widetilde{\tau}_a = \min\{t \geq 0 : \widetilde{B}_t > a\}$ . Then we have

$$\mathbf{P}\left(\max_{t\in[0,T]}\widetilde{B}_t > a\right) = \mathbf{P}(\widetilde{\tau}_a \le T) = \int_0^T \frac{a}{s^{3/2}} \frac{e^{-\frac{(a-\theta s)^2}{2s}}}{\sqrt{2\pi}} \, \mathrm{d}s. \qquad \mathbf{Q} > 0$$

In particular, the PDF of  $\tilde{\tau}_a$  is

(9.11) 
$$f_{\tilde{\tau}_a}(t) = \frac{a}{t^{3/2}} \frac{e^{-\frac{(a-\theta t)^2}{2t}}}{\sqrt{2\pi}}.$$

$$\begin{array}{ll} \operatorname{Prof} & \operatorname{Beautiful} \end{array} \qquad \mathcal{E}_{a} = \left\{ \begin{array}{l} \operatorname{max} \, \widetilde{\mathcal{B}}_{t} > \alpha \, \end{array} \right\} = \left\{ \begin{array}{l} \widehat{\mathcal{Z}}_{a} \leqslant T \right\} \end{array}$$

$$\operatorname{P}\left( \begin{array}{l} \operatorname{max} \, \widetilde{\mathcal{B}}_{t} > \alpha \, \end{array} \right) = \operatorname{E}\left[ \begin{array}{l} 1\left(\mathcal{E}_{a}\right) \right] \\ \left( \frac{\partial \widetilde{\mathcal{D}}}{\partial P} \right)^{1} \, 1\left(\mathcal{E}_{a}\right) \right] \\ = \operatorname{E}\left[ \left( \frac{\partial \widetilde{\mathcal{B}}}{\partial P} \right)^{1} \, 1\left(\mathcal{E}_{a}\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} e^{-\partial \widetilde{\mathcal{B}}_{T} + \frac{1}{2}\theta^{2}T} \\ = \operatorname{E}\left[ \begin{array}{l} e^{-\partial \widetilde{\mathcal{B}}_{T} - \frac{1}{2}\theta^{2}T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \end{array} \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \begin{array}{l} \operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \left( \operatorname{M}_{T} \, 1\right) \left(\operatorname{M}_{T} \, 1\left(\widetilde{\mathcal{T}}_{a} \leqslant T\right) \right] \\ = \operatorname{E}\left[ \left( \operatorname{M}_{T} \, 1\right) \left(\operatorname{M}_{T} \, 1\right) \left(\operatorname{M}_{T} \, 1\right) \right] \\ = \operatorname{E}\left[ \operatorname{M}_{T} \, 1\left(\operatorname{M}_{T} \, 1\right) \left(\operatorname{M}_{T} \, 1\right) \left(\operatorname{M}_{T} \, 1\right) \right]$$

$$= \widetilde{E} \left[ e^{\alpha \theta - \frac{1}{3} \theta^3 \widetilde{\zeta}_{\alpha}} \Lambda(\widetilde{\zeta}_{\alpha} \leq T) \right]$$

We know the distribution of En for std BM!

$$= \int_{0}^{\infty} \frac{(\alpha - \theta s)^{2}}{\sqrt{2\pi 1}} \frac{1}{\sqrt{2}} ds$$

### 6. Multivariate Ito Calculus

We generalize Itô calculus to several variables.

This is useful when considering market models with:

- i) several risky assets
- a) random interest rates

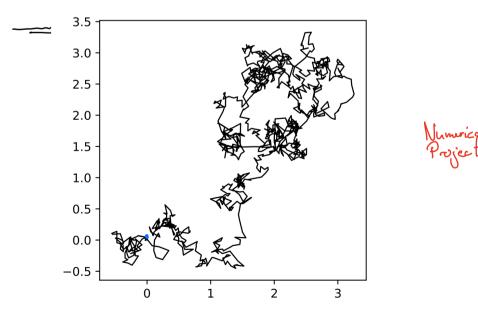
#### 6.1 Multidimensional Brownian motion

Definition

A d-dimensional standard Bravnian motion is a process in Rd of the form

$$t \longmapsto (\mathcal{B}_{t}^{\alpha_{1}}, ..., \mathcal{B}_{t}^{\alpha_{l}}) = \widehat{\mathcal{B}_{t}^{\alpha_{l}}}$$

where  $(B_t^{(j)}, \xi_{70})$ , jed, are IID standard BM's.



**Figure 6.1.** A simulation of a path of two-dimensional Brownian motion starting at (0,0) from time 0 to time 5 for a time discretization of 0.005. See Numerical Project 6.1.

BM's as follows:

$$\begin{pmatrix} W_{t}^{(i)} \\ W_{t}^{(i)} \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} B_{t}^{(i)} \\ B_{t}^{(i)} \end{pmatrix} \qquad \chi = A2$$

More generally  $\overrightarrow{W_t} = \overrightarrow{OB_t}$  where  $\overrightarrow{O}$  is an orthogonal matrix.

Exercise 6.1 and 6.2

### 62 Itô's formula

For a smooth function  $f: \mathbb{R}^d \to \mathbb{R}$ , we can define a process  $t \mapsto f(\mathcal{B}_t^{(i)}, \dots, \mathcal{B}_t^{(d)})$ .

- 1) Can we write this process in differential form?
- 2) Can we find conditions on f for f(Bz) to be a matingale?

Same questions as for 10!

**Theorem 6.6** (Itô's formula). Let  $(B_t, t \ge 0)$  be a d-dimensional Brownian motion. Consider  $f \in \mathcal{C}^2(\mathbb{R}^d)$ . Then we have with probability one that for all  $t \ge 0$ ,  $f : \mathbb{R}^d \to \mathbb{R}$ 

$$(6.6) f(B_t) - f(B_0) = \sum_{i=1}^d \int_0^t \partial_i f(B_s) dB_s^{(i)} + \frac{1}{2} \int_0^t \sum_{i=1}^d \partial_i^2 f(B_s) ds.$$

$$\int_0^t \nabla f(B_s) \cdot dB_s = \sum_{i=1}^d \partial_i^2 f(B_s) ds.$$

**Corollary 6.8** (Brownian martingales). Let  $(B_t, t \ge 0)$  be a Brownian motion in  $\mathbb{R}^d$ . Consider  $f \in \mathcal{C}^2(\mathbb{R}^d)$  such that the processes  $(\partial_i f(B_t), t \le T) \in \mathcal{L}^2_c(T)$  for every  $i \le d$ . Then the process

$$f(B_t) - \int_0^t \frac{1}{2} \Delta f(B_s) \, \mathrm{d}s, \quad t \le T,$$

is a martingale for the Brownian filtration.

# Remark: If $\Delta f = 0$ , then $f(B_{\ell})$ is a mortingale Harmonic of $d^2 f = 0 \Rightarrow f = q \times d b$

Why does the farmula make sense? Taylor + Quadratic Variation

$$f(B_{e}) - f(B_{o}) = \sum_{j=0}^{n-1} f(B_{t_{j+1}}) - f(B_{t_{j}})$$

$$\frac{d}{dt} \left( \sum_{j=0}^{n-1} \partial_{k} f(B_{t_{j}}) \left( B_{t_{j+1}}^{(n)} - B_{t_{j}}^{(n)} \right) + \sum_{j=0}^{n-1} \partial_{k} \partial_{t} f(B_{t_{j}}) \left( B_{t_{j+1}}^{(n)} - B_{t_{j}}^{(n)} \right) + \sum_{j=0}^{n-1} \partial_{k} \partial_{t} f(B_{t_{j}}) \left( B_{t_{j+1}}^{(n)} - B_{t_{j}}^{(n)} \right) + \sum_{j=0}^{n-1} \partial_{t_{j}} \partial_{t_{j$$

6.5. **Cross-variation of**  $B_t^{(1)}$  **and**  $B_t^{(2)}$ . Let  $(t_j, j \le n)$  be a sequence of partitions of [0, t] such that  $\max_j |t_{j+1} - t_j| \to 0$  as  $n \to \infty$ . Prove that

Problem Set

$$\lim_{n \to \infty} \sum_{j=0}^{n} (B_{t_{j+1}}^{(1)} - B_{t_{j}}^{(1)})(B_{t_{j+1}}^{(2)} - B_{t_{j}}^{(2)}) = 0 \quad \text{in } L^{2}.$$

This justifies the rule  $dB_t^{(1)} \cdot dB_t^{(2)} = 0$ . *Hint: Just compute the second moment of the sum.* 

Worning: cross variation is not always 0.

## As usual we have the extension to f(t, B,)

**Theorem 6.11** (Itô's formula). Let  $(B_t, t \leq T)$  be a d-dimensional Brownian motion. Consider a function  $f \in \mathcal{C}^{1,2}([0,T] \times \mathbb{R}^d)$ . Then we have with probability one for all  $t \leq T$ ,

$$f(t,B_t) - f(0,B_0) = \sum_{i=1}^d \int_0^t \partial_i f(s,B_s) dB_s^{(i)} + \int_0^t \left( \partial_0 f(s,B_s) + \frac{1}{2} \Delta f(s,B_s) \right) ds,$$
 where  $\Delta = \sum_{i=1}^d \partial_{x_i}^2$ .

Martingale condition: 
$$\frac{1}{2}\Delta f = -\partial_{\xi} f$$

Example Write the following process in differential form:

$$(1) \quad X_{\xi} = \left(\mathcal{B}_{\xi}^{(1)}\right)^{2} + \left(\mathcal{B}_{\xi}^{(2)}\right)^{2}$$

$$dX_{t} = X_{t} = \int_{0}^{t} B_{t}^{(n)} dB_{t}^{(n)} + \int_{0}^{t} 2B_{t}^{(n)} dB_{t}^{(n)} + 2t$$

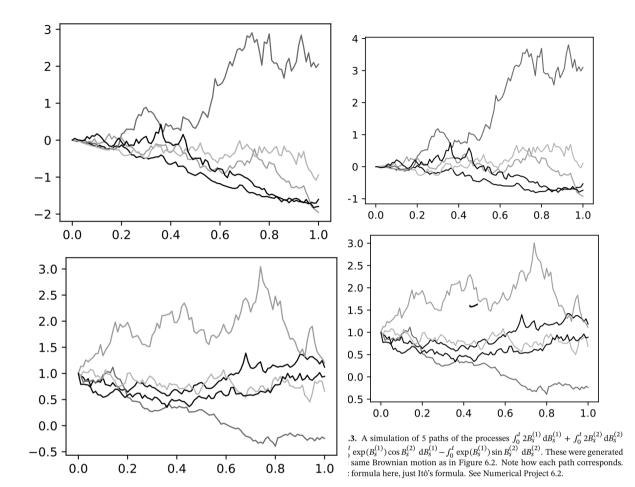
$$X_{t} = 2t \text{ is a modified}$$

(2) 
$$f(x,y) = e^{x} \cos y \quad \begin{cases} e^{x} + \int_{0}^{x} e^{x} \cos R_{s} dR_{s}^{(1)} \\ \frac{\partial}{\partial s} f = e^{x} \cos y \quad \frac{\partial}{\partial s} f = e^{x} \cos y \quad f^{\dagger} e^{R_{s}^{(1)}} \sin R_{s}^{(2)} dR_{s}^{(3)}, \\ \frac{\partial}{\partial s} f = -e^{x} \sin y \quad \frac{\partial}{\partial s} f = -e^{x} \cos y \quad \frac{\partial}{\partial s} f = e^{x} \cos y \quad \frac{\partial}{\partial s} f = e^{x$$

Xt-ot

Y

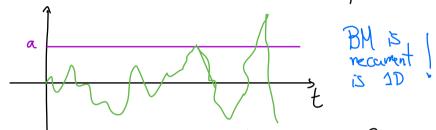
**Figure 6.2.** A simulation of 5 paths of the processes  $(X_t-2t,t\in[0,1])$  and  $(Y_t,t\in[0,1])$  defined in equation (6.5).



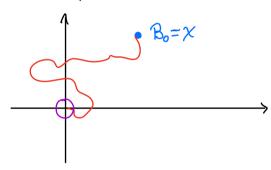
### 6.3 Recurrence vs Transience of BM

In 1D, we know that a BM path reaches any height a.

In particular, it will came back to a infinitely often.



Is there an equivalent statement in higher of?



Recurrent

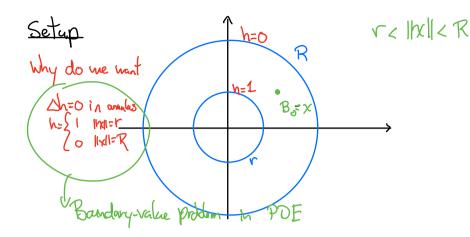
Yes d=2 (1) Does a BM path visit a neighborhood of 0 infinitely often? NO d>2 (2) Does it actually hit o? NO!

Transient

As usual, we need to find a martingale

Apply Dodo O.S.

A drunk man will eventually find his way home but a drunk bird may get lost forever.



$$T_{R}^{2} = \min \left\{ t_{7,0} : |B_{\ell}| > R \right\}$$
  $T_{R}^{2} < \infty \text{ wpods } 1$   
 $T_{r} = \min \left\{ t_{7,0} : |B_{\ell}| \le r \right\}$   $T_{r} < \infty \text{ w. prob } 1$ .

What is  $P(\tau_r < \tau_R^3)$ ?

· Let's find a good martingale:

We need 
$$\Delta f = 0$$
 in the annulus

$$f(x) = \begin{cases} \log ||x|| & d=0 \\ ||x||^{2-d} & d>3 \end{cases}$$
 Rotational symmetry

Of cause, he afth is also harmonic

$$\Delta h = a\Delta f + \Delta b = a\Delta f = 0$$

$$h(B_t)$$
 it is a martingale

$$T = \varepsilon_r N \varepsilon_R^2 / E[1(||B_E|| = r)]$$

$$P(\tau_r < \tau_R^2) = P(||B_E|| = r) = E[N(B_E)]$$

if 
$$h(x) = \begin{cases} 0 & ||x|| = R \\ 1 & ||x|| = r \end{cases}$$
 Bunday-value problem

$$P(Y, \langle T_{x}' \rangle = E_{x}[h(B_{z})] = h(x)$$

What is 
$$h(x)$$
?

af +b

$$h=\begin{cases} 0 & ||x||=|R| \\ 1 & ||x||=r \end{cases}$$

What is 
$$h(x)$$
? 
$$h(x) = \begin{cases} \frac{|\log ||x|| - \log R}{|\log x| - |\log R} & d=2 \\ \frac{|\log x| - |\log R}{|\log x| - |\log R} & d=2 \end{cases}$$

$$h = \begin{cases} 0 & ||x|| = |R| \\ 1 & ||x|| = |R| \end{cases}$$

$$= P(\tau_r < \tau_R^2)$$

$$P(\zeta_{r} < \infty) = \lim_{R \to \infty} \left\{ \frac{|\log ||x|| - \log R}{|\log x| - \log R} \right\} d= 1$$

$$\frac{||x||^{2-d} - R^{2-d}}{r^{2-d} - R^{2-d}} d= 1$$

$$= \left(\frac{r}{||x||}\right)^{d-2}$$

$$= \left(\frac{r}{||x||}\right)^{d-2}$$

$$E_{\chi}[h(B_{z})] = h(\chi)$$
  
Ly representation of a harmonic fell

An=0 in annulus

h= { in annulus

o outler

$$d=2$$
 BM paths visits a neighborhood of o of any vadius i.o.

In 
$$d=2$$
, does the path actually touches 0?  

$$\frac{|\log ||x|| - \log R}{|\log r - \log R} dc2$$

$$\frac{||x||^{2-d} - R^{2-d}}{r^{2-d} - R^{2-d}} d7.3 R-10 r-10 ()=0$$

T= min { 120: B, & 20}

## 6.4 Dynkin's formula

Consider a BM in a region (bounded)

Dirichlet prodem

Ah = 0 in 0

h = g on 20

Solution 
$$h(x) = E_x[h(B_z)] = E_x[g(B_z)]$$
  
 $h(x) = E_x[g(B_z)]$ 

For f, consider the morthgale  $M_{t} = f(B_{t}) - \frac{1}{3} \int_{0}^{t} \Delta f(B_{s}) dB_{s}$ 

The stopped martingale. Ment is bounded . 200

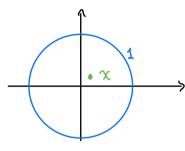
We have Doob O.S.

In particular if  $\Delta f = 0$  in O

$$f(x) = E^{x}[f(B^{s})]$$

f(x) is the average of f on  $\partial \Omega$ !

Example



=[~] - ?