#### Overview of Automatic Differentiation

James Yang

27th January 2022



Introduction

Forward-Mode Automatic Differentiation

Reverse-Mode Automatic Differentiation

Tips

**Applications** 

**Benchmarks** 



#### Introduction

Forward-Mode Automatic Differentiation

Reverse-Mode Automatic Differentiation

Tips

Applications

Benchmarks



- Addresses the question: How do we write a framework (e.g. Tensorflow, PyTorch) where users can differentiate a wide class of functions automatically?
- Users should not manually write derivatives.
- Solves issues with other forms of differentiation methods.
- Seppo Linnainmaa (1970) master thesis.



# Why should we care about computing derivatives?

- Many optimization/statistical methods require the use of gradients.
- Optimizers: gradient descent and all its variants.
- Neural network + back propagation: differentiate loss w.r.t. all parameters.
- Bayesian Hamiltonian Monte Carlo Samplers (HMC, Langevin, NUTS, etc.): differentiate joint-log-pdf of hierarchical model.
- ightharpoonup ODE/PDE solvers: differentiate a known function H, which is used to specify the dynamics of another variable.
- MLE computation: gradient descent on the (negative) log-likelihood.



# Why should we care about computing derivatives?

- Many optimization/statistical methods require the use of gradients.
- Optimizers: gradient descent and all its variants.
- Neural network + back propagation: differentiate loss w.r.t. all parameters.
- Bayesian Hamiltonian Monte Carlo Samplers (HMC, Langevin, NUTS, etc.): differentiate joint-log-pdf of hierarchical model.
- ➤ ODE/PDE solvers: differentiate a known function H, which is used to specify the dynamics of another variable.
- MLE computation: gradient descent on the (negative) log-likelihood.
- ➤ Your homework: I know you used Wolfram at some point in your life O\_O!



# Finite Difference (FD)

 $\triangleright$  Given f and x, compute

$$\frac{f(x+h) - f(x)}{h}$$

for small h and declare it to be f'(x).

# Finite Difference (FD)

- Pros:
  - Very easy to implement.
  - Works for any programmable functions.
- Cons:
  - Suffers from numerical precision issues (dividing two small numbers leads to wild results) (example code: fd\_prec).
  - Cannot take advantage of analytical forms even if they exist.
  - Must run p times if there are p input variables.



# Symbolic Differentiation (SD)

- E.g. Wolfram, Mathematica.
- Given a formula or mathematical expression of the function of interest f, generate a new expression for the derivative.

# Symbolic Differentiation (SD)

- Pros:
  - if f is composed of elementary functions, SD produces the analytical form for f' (no approximations).
  - Convenient output for mathematicians who need the functional form.
- ► Cons:
  - Difficult to represent programmatic expressions.
    - ▶ How do we differentiate an if-else statement?
    - How do we differentiate a for-loop?



# Automatic Differentiation (AD)

- Combines (most of) the Pros and solves the Cons of SD and FD.
- Computes analytical derivatives for any (including programmatic) expressions.
- Does not suffer from numerical precision issues as in FD.
- Does not output an expression like SD, but rather the derivative at a given x like FD.
  - Allows for optimization in implementation if it doesn't need to return the full expression for gradient.

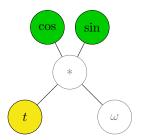


#### Forward-Mode Automatic Differentiation



$$(x(t), y(t)) = (\cos(\omega t), \sin(\omega t))$$

$$(x(t), y(t)) = (\cos(\omega t), \sin(\omega t))$$



00000000 000000

- Extend elementary functions to dual numbers.
- $\blacktriangleright$  Unary f:

$$f((w, \frac{dw}{dx})) := \left(f(w), \frac{df}{dw}\frac{dw}{dx}\right)$$

▶ Binarv f:

$$f\left((w_1, \frac{dw_1}{dx}), (w_2, \frac{dw_2}{dx})\right) := \left(f(w_1, w_2), \frac{df}{dw_1} \frac{dw_1}{dx} + \frac{df}{dw_2} \frac{dw_1}{dx}\right)$$

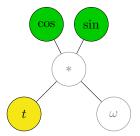


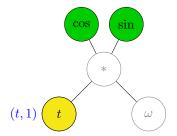
# Forward AD

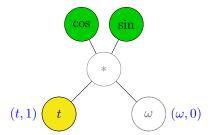
00000000 000000

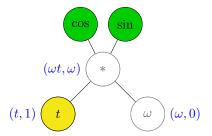
Example:

$$\sin((w, \frac{dw}{dx})) = (\sin(w), \cos(w) \frac{dw}{dx})$$
$$(w_1, \frac{dw_1}{dx}) \cdot (w_2, \frac{dw_2}{dx}) = (w_1 w_2, \frac{dw_1}{dx} w_2 + w_1 \frac{dw_2}{dx})$$









$$(\cos(\omega t), -\omega \sin(\omega t))$$
  $\cos$   $\sin$   $(\omega t, \omega)$  \*  $(t, 1)$   $t$   $\omega$   $(\omega, 0)$ 

$$(\cos(\omega t), -\omega \sin(\omega t)) \cos \sin \sin \sin(\omega t), \omega \cos(\omega t))$$

$$(\omega t, \omega) *$$

$$(t, 1) \cot \omega \cos(\omega t)$$

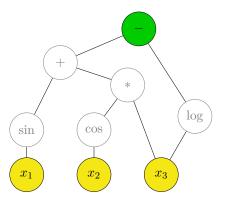
- Easy to implement.
- ▶ Fast for  $f: \mathbb{R}^n \to \mathbb{R}^m$  where  $m \gg n$  (O(n) sweeps of computation graph).
- Useful in physics applications when differentiating w.r.t. time.
- Example code (fwd\_ad).

Reverse-Mode Automatic Differentiation



$$f(x_1, x_2, x_3) = \sin(x_1) + \cos(x_2) \cdot x_3 - \log(x_3)$$

$$f(x_1, x_2, x_3) = \sin(x_1) + \cos(x_2) \cdot x_3 - \log(x_3)$$





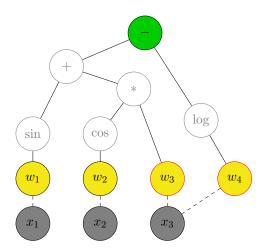
- x<sub>i</sub> can be referenced by multiple nodes.
  - ightharpoonup e.g.  $x_3$  is referenced by the \* and log nodes.
- Convert expression graph into an expression tree.
  - Replace all nodes with multiple parents as separate nodes that reference back to the actual variables.
- Mathematically,

$$f(x_1, x_2, x_3) = \tilde{f}(g(x_1, x_2, x_3))$$

$$\tilde{f}(w_1, w_2, w_3, w_4) = \sin(w_1) + \cos(w_2) \cdot w_3 - \log(w_4)$$

$$g(x_1, x_2, x_3) = (x_1, x_2, x_3, x_3)$$
(1)







# Expression Tree Conversion

- Why do we need this conversion?
  - All nodes except x<sub>i</sub> have exactly one parent.
  - Leads to cleaner implementation.
  - $\triangleright$  Better to treat  $x_i$  as containers for initial values and their **adjoints**,  $\frac{\partial f}{\partial x}$ , instead of nodes of the graph.

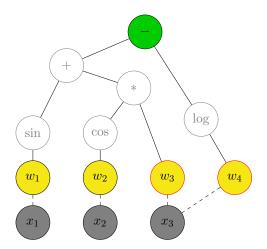


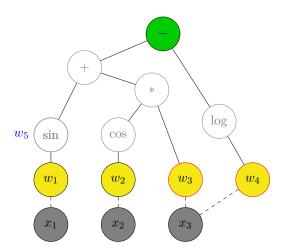
# Reverse-Mode AD Algorithm

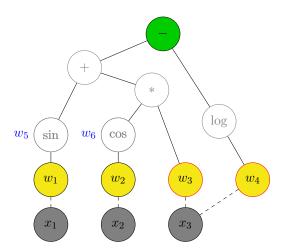
- Assume for the moment that  $f: \mathbb{R}^n \to \mathbb{R}$ .
- Reverse-mode algorithm consists of two passes of the expression tree:
  - forward-evaluation (not to be confused with forward-mode AD)
  - backward-evaluation

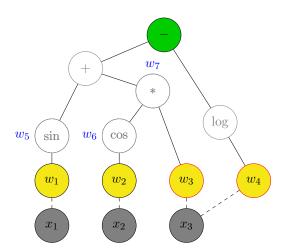


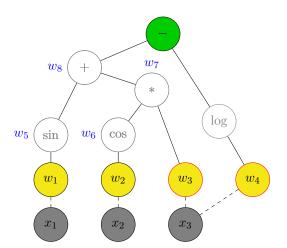
- Compute expression in the usual fashion.
  - Start at the root.
  - Recursively forward-evaluate left to right all its children.
  - Compute current node operation using children results.
    - e.g. for sin node,  $x_1 \to w_1 \to \sin(w_1)$



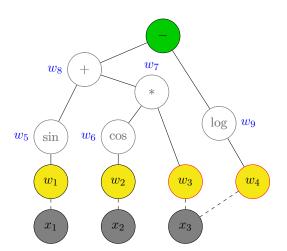


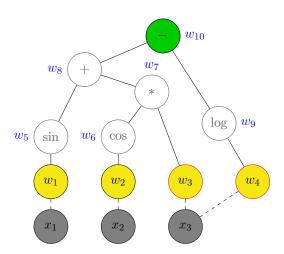






## Forward-Evaluation







- Current node receives its adjoint from its parent.
- This adjoint is also referred to as seed.
- ▶ Hence, root will receive seed = 1 from the caller.
- Current node computes seeds for all its children and recursively backward-evaluates from right-to-left.



- Next seed is computed by a simple chain-rule.
- Let the current node be  $w \in \mathbb{R}^{p \times q}$  and  $v \in \mathbb{R}^{m \times n}$  one of its children.
- ► The seed for v is given by

$$\frac{\partial f}{\partial v_{ij}} = \sum_{k=1}^{P} \sum_{l=1}^{q} \frac{\partial f}{\partial w_{kl}} \frac{\partial w_{kl}}{\partial v_{ij}}$$
 (2)

Since we are working with an expression tree, f only depends on v through w, hence this is the full adjoint.

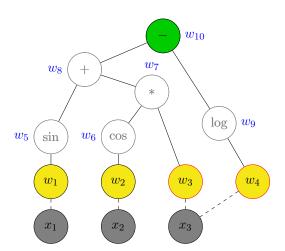


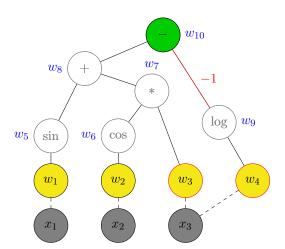
- Nodes with reference to containers must increment the adjoints in the containers with their seed.
  - ightharpoonup e.g.  $w_3$  and  $w_4$  increments the adjoint in  $x_3$  with their seeds.
- Why? Chain-rule, once again.
- Let  $w_1, \ldots, w_k$  denote all variables with a reference to x. For simplicity assume they are all scalars (easily generalizable). Then,

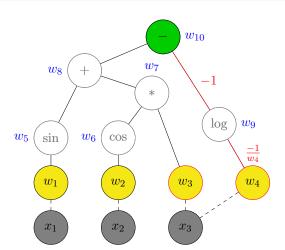
$$\frac{\partial f}{\partial x} = \sum_{i=1}^{k} \frac{\partial f}{\partial w_i} \frac{\partial w_i}{\partial x} = \sum_{i=1}^{k} \frac{\partial f}{\partial w_i}$$

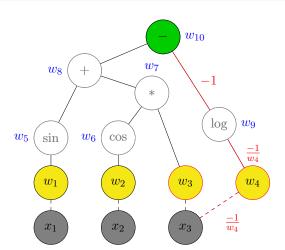
ightharpoonup Accumulated adjoints for  $x_1, x_2, x_3$  is the gradient of f.

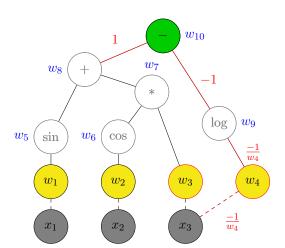


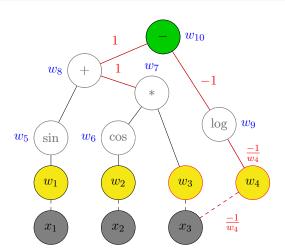


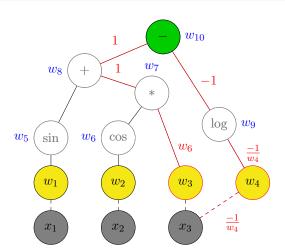


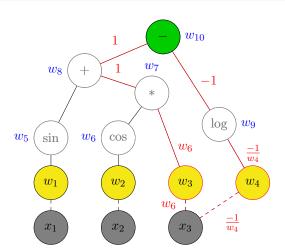


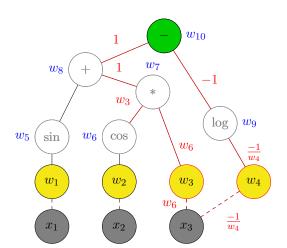


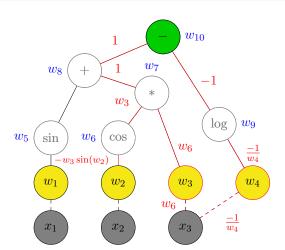


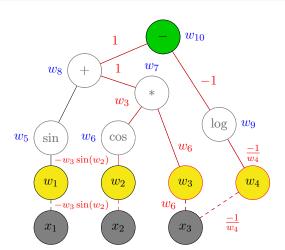


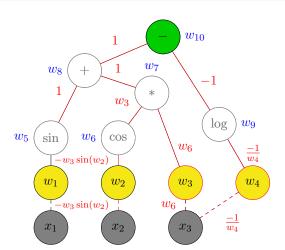


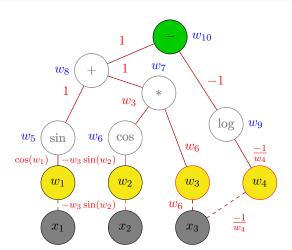




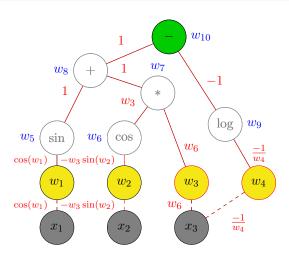














Sanity check:

$$f(x_1, x_2, x_3) = \sin(x_1) + \cos(x_2) \cdot x_3 - \log(x_3)$$
$$\nabla f = (\cos(x_1), -x_3 \sin(x_2), \cos(x_2) - x_3^{-1})$$

- Much harder to implement (memory management is tricky).
- ▶ Fast for  $f: \mathbb{R}^n \to \mathbb{R}^m$  where  $n \gg m$  (O(m) sweeps of computation graph).
- Useful when we need to compute gradient (of a scalar function).
- Example code:
  - rv ad
  - ▶ for each
  - if else



Tips



$$t = x + y$$
$$f(t) = \sin(t)\cos(t)$$

Use package-provided functions mostly to take advantage of vectorization, e.g.

for-loop sum over 
$$x \not x$$
 
$$\operatorname{sum}(x) \not \checkmark$$



Minimize number of nodes in computation graph, e.g. if  $x \in \mathbb{R}^{10}$ .

$$x[1] + \ldots + x[10] \implies 9$$
 adjoints  $\textbf{X}$   $\operatorname{sum}(x) \implies 1$  adjoint  $\textbf{V}$ 

Minimize size of each node of computation graph, e.g. if  $x, y \in \mathbb{R}^n$ ,

$$\begin{aligned} \operatorname{sum}(x+y) & \Longrightarrow O(n) \operatorname{memory} \ \mathbf{X} \\ \operatorname{sum}(x) + \operatorname{sum}(y) & \Longrightarrow O(1) \operatorname{memory} \ \mathbf{V} \end{aligned}$$



Introduction

Forward-Mode Automatic Differentiation

Reverse-Mode Automatic Differentiation

Tips

#### **Applications**

Benchmarks



# Taste of using AD

- MLE: Gaussian model.
- MLE: Gaussian mixture model.
- MAP: Ridge.

- $X_i \stackrel{iid}{\sim} N(\mu, 1)$
- $\blacktriangleright \mu$  unknown.
- Negative log-pdf is given by

$$-\sum_{i=1}^{n} \log(p(x_i)) = \frac{1}{2} \sum_{i=1}^{n} (X_i - \mu)^2$$

Example code (mle).



#### MLE: Gaussian mixture model



## MLE: Gaussian mixture model

► This is for you Kevin Senpai.



- This is for you Kevin Senpai.
- $X_i \stackrel{iid}{\sim} \pi N(\mu_1, \sigma_1^2) + (1 \pi) N(\mu_2, \sigma_2^2)$
- $\blacktriangleright$   $(\pi, \mu_1, \mu_2, \sigma_1, \sigma_2)$  unknown.
- Negative log-pdf is given by

$$-\sum_{i=1}^{n} \log(p(x_i)) = -\sum_{i=1}^{n} \log(\pi p_{\mu_1,\sigma_1}(X_i) + (1-\pi)p_{\mu_2,\sigma_2}(X_i))$$

Example code (kevin\_senpai\_mle).



- ► MLE is really just MAP of likelihood + non-informative prior.
- In general, can apply any (differentiable) prior.
- Ridge regression (fixed X):

$$y|\beta \sim \mathcal{N}(X\beta, I)$$
  
 $\beta \sim \mathcal{N}(0, \lambda^{-1})$ 

MAP is posterior mean:

$$\mathbb{E}(\beta|y) = (X^{\top}X + \lambda I)^{-1}X^{\top}y$$

Example code (map).



Benchmarks



# Comparison with Finite Difference and Manual

**Example function:**  $x \in \mathbb{R}^p$ ,  $M \in \mathbb{R}^{n \times p}$ 

$$f(x) = \operatorname{sum}(Mx) - 2\log(\sum_{i=1}^{p} \exp(x_i))$$

Code (compare\_fd)

| Config       | FD     | AD      | Manual (df only) | Manual (f + df) |
|--------------|--------|---------|------------------|-----------------|
| n=1e2, p=1e2 | 1.4e-4 | 6.51e-6 | 1.41e-6          | 2.97e-6         |
| n=1e2, p=1e4 | 1.78   | 4.1e-4  | 1.35e-4          | 3.3e-4          |
| n=1e2, p=1e6 | NA     | 1.2e-1  | 3.3e-2           | 8.8e-2          |
| n=1e4, p=1e2 | 9.3e-3 | 2.1e-4  | 1.6e-4           | 2.5e-4          |
| n=1e4, p=1e4 | NA     | 4.37e-2 | 2.7e-2           | 4.9e-2          |
| n=1e4, p=1e5 | NA     | 4.3e-1  | 2.8e-1           | 4.9e-1          |