Personalised Models of Argument Convincingness

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Abstract

1 Introduction

We hypothesise that different people find different types of argument more convincing than others and therefore, textual features have varying levels of importance in determining convincingness, depending on the audience. We investigate whether certain combinations of textual features are indicative of an argument's convincingness to a particular person. We hypothesise that predictions of convincingness will be more accurate if we adapt the model to the individual reader based on their previously observed preferences. However, preference data for a single individual for any given task can be very sparse, so it will be necessary to consider the similarities between different users' preferences. Furthermore, the computational cost of learning independent models for each person and each task may be impractically high, suggesting a need for more efficient approaches that combine information from multiple users.

Our approach is therefore to identify correlations between different people's preferences so that we can learn shared models of convincingness that can then be adapted to individuals to improve predictions of argument convincingness. We aim to establish whether such a model can be learned by observing pairwise convincingness preferences,

The experiments evaluate a number of techniques for modelling worker preferences, different types of language features, and the correlations between workers and features. We investigate whether workers with similar preferences according to each model give similar justifications for their decisions, thereby lending additional support for models based on correlations between prefer-

ences.

We provide a new preference learning model to handle large numbers of potentially very sparse features and large numbers of people. Our Bayesian approach enables us to perform automatic feature selection, learn in semi-supervised or unsupervised modes, and fully account for model and parameter uncertainty, while scaling to large numbers of input features.

2 Related Work

The Gaussian process (GP) preference learning approach of [10] resolves such inconsistencies and provides a way to predict rankings or preferences for items for which we have not observed any pairwise comparisons based on the item's features. An extension to multiple users was proposed by [10], but this method suffered from poor scalability.

Matrix factorisation techniques are commonly used in recommender systems to discover latent user and item features but can fail if the data is very sparse unless suitably regularised or given a Bayesian treatment. Matrix factorisation techniques are also unsuitable for pairwise comparisons as they must be learned using explicit numerical ratings. A more scalable approach that incorporates probabilistic matrix factorisation (specifically, probabilistic PCA) was proposed by [10]. Their method is applicable to both pairwise comparisons and ratings data and as such could be used to learn the model from implicit feedback such as clicks on an item. However, it may be more suitable to use a model for such feedback that explicitly considers the different bias and noise of each type or source of feedback. For such a purpose, the model of [10] may be appropriate but has to date been used for classifier combination and categorical labelling tasks in crowdsourcing and has not been applied to preference learning from different types of feedback. Bayesian approaches are suited to handling these problems of data sparsity, noise and bias, particularly as the modular nature of inference algorithms such as Gibb's sampling and variational approximation is suited to extending the model to handle different types of feedback that give indications of some underlying preferences.

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The GP methods require $\mathcal{O}(P_n)$ steps, where P_n is the number of pairs for user n. The method proposed by [10] reduces this scaling issue by using a random sample of pairs at each iteration of their EM algorithm. We use SVI to address scalability in a variational Bayesian framework. The modular nature of VB allows us to take advantage of models for feedback of different types where the input values for each type of feedback do not directly correspond (e.g. explicit user ratings and number of clicks may have different values). By using SVI, we provide a formal way to deal with scalability that comes with guarantees [10]. We also estimate the output scale of the GPs, the latent factors, and item bias as part of the variational approximation.

We compare our work on Sushi-A dataset or against the method of [10] to see if our modifications are actually useful.

Factor analysis differs from PPCA in allowing only diagonal noise covariance matrices, making the observed variables conditionally independent given the latent variables. It also provides a probabilistic treatment for inferring the latent features.

We also investigate whether argumentation preferences can be reduced to a simpler clustering structure, which may be easier to learn with very sparse user data.

In most scenarios where we wish to make predictions about arguments, there is a very large number of input variables potentially associated with each argument in the dataset, but very sparse observations of these variables. To illustrate this, consider a simple bag-of-words representation of the argument text, and a set of click-data recording which actions each user took when presented with a choice between different pieces of text. Given a large vocabulary, the words present in an argument will be a very small subset of possible words. Users will likely see a subset of texts and the recorded choices will be a much smaller subset of the possible combinations of texts. To make predictions about unobserved preferences when pre-

sented with a new text with sparse data, we require an abstraction from the raw input data, and thus seek a way to embed the texts into a space where texts with similar properties are placed close together. In the case of arguments, one property that may determine whether texts should be close together is that they have similar levels of convincingness to similar types of people, in similar contexts. Our proposal therefore produces a form of argument embedding, driven by convincingness. A similar approach to learning latent features, VB-MDS, is proposed by [?] for learning embeddings using approximate Bayesian techniques, but does not use the embeddings for preference learning to find separate person and item embeddings and does not apply this to NLP problems. Their proposal does, however, show how to combine points with and without side information - our input features – to make predictions about low-dimensional embeddings for unseen data. The kernelized probabilistic matrix factorization (KPMF) [?] proposes a similar approach to VBMDS using GP priors over latent dimensions, but with a simpler MAP inference scheme, and different likelihood and distance functions.

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An important aspect of convincingness is the context in which an argument is made, particularly as part of a dialogue. In our approach, this context can be represented as input variables that affect the item and person embeddings, where the variables encapsulate the previously seen arguments. While out-of-scope of the present investigation, future work may investigate the best way to determine novelty of an argument given a small number of variables representing previously seen arguments. Another related avenue of improvement is to consider the structure of arguments to select argument components – it may be important to consider not just novelty, but whether claims have sufficient support and premises are clearly linked to the claims they support or attack. Embedding this structure may require complex graph structures of claims and premises to be represented as short vectors, and may therefore be a topic of future study.

The latent features allow us to interpolate between items and people in a low-dimensional embedding space. A key question in this latent feature approach is how to model the deviation of individual preferences from that predicted by latent features common to multiple people (item deviations can be modelled through an item mean function). This deviation occurs when there is still entropy in a user's preferences given the latent features because the latent features only describe patterns that are common to multiple users. A simple approach is to allow additional noise with uniform variance at each data point, so that all preference patterns are represented by the latent feature vectors of items and people. However, any individual preference patterns particular to one user must then be represented by additional latent features that are not activated for any other users. An alternative is to use a personal model of preference deviation for each person. Given the input features of the items and any state variables relating to the person, this model can capture correlations in the deviation for different items for the same person. Both the latent person features and the individual noise model can also include any input features of the person that change over time, e.g. representing their state and the arguments they have previously seen. This individual noise model allows us to differentiate preference patterns that are specific to one user, when the input features may not otherwise be sufficient to distinguish these users.

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Whether an argument is persuasive or not is subjective [10], hence analysing which arguments a particular person or group of people finds convincing can tell us about their opinions and influences.

Identifying Common Patterns of Convincingness

Differences with/notes on Houlsby method:

- No common mean
- Houlsby uses: w as weights for each user on the D latent functions; w has a GP prior with the user features as the input space; in our • code, I think we call these weights y just to be confusing; they use a standard normal noise distribution for all users and all items
- It seems unnecessary to extend their model with a personal GP over noise because this could be captured the latent therefore it may GPs; better start with nfactors npeople, then see if the Bayesian shrinkage effect reduces the number of active latent functions due to prove the property of the Bayesian shrinkage effect reduces the number of active latent functions due to prove the property of the Bayesian shrinkage effect reduces the number of active latent functions due to prove the property of the property of the property of the Bayesian shrinkage effect reduces the number of active latent functions due to prove the property of the
- Common means for all workers could be unnecessary, since this too could be captured by a latent factor that is shared by most workers; how-

ever, if we want to determine the 'consensus' preference, we need to identify this common factor and it may be useful to view the workers as deviating from this underlying mean; this makes the view more similar to CBCC view, where latent factors correspond to community confusion matrices, and user weights correspond to worker community weights; the latent factor GPs model bias in a given community but unlike the CBCC model, they take into account the features of the items; the weights also account for user features when available, unlike CBCC; all modelling of noise, bias levels is then done at community level as in CBCC and individuals are described by weights alone.

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- novelty comes then in using this model for combining preferences from crowdsourcing to infer an underlying consensus or a ground truth (specified by training data in semi-supervised mode)
- experiments therefore need to look at not just predicting individuals' preference labels, but also at predicting a ground truth from noisy labels; we continue to use MACE with lots of labels to define ground truth, and see what happens when we use only one label per pair
- also need to examine differences between results produced by MACE and by collab. pref learning
- combining labels does not fit personalisation narrative? Personalised models help correct individual biases when inferring ground truth; helps transfer from one person's preferences to a target set of preferences
- Thompson sampling for active selection of labels from the crowd? like the crowdsample dataset but we get to choose which worker?
- Changing the current code: preference components needs to use a single GP with a diagonal covariance and pump the results correctly back into self.f

3.1 Baseline methods

- Random: select a label at random
- Most common (MC): select the most common preference label from across the dataset

differences between workers. Labels are estimated by taking the average of other people's labels for the same preference pair. When

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there are no previous pairs available, select the most common preference label

 Gaussian process preference learning with no differentiation (GP-ND): learn a latent ranking function for the objects from pairwise preferences, ignoring differences between workers and features of the arguments. This provides a probabilistic variant of ND

3.2 Modelling Correlations Between Individuals

Two main types of approach:

- Factor analysis map the set of pairwise preferences to a low-dimensional embedding
- Clustering assumes that people fall into distinct preference clusters, or can be modelled as a mixture of several archetypes

Specific methods to test can be split into several types. First, we can run different clustering methods on the training data, then predict a worker's label by taking the mean of the other cluster members. When the no members of the cluster have labelled the pair, we predict using the most common label. This method is applied to several clustering algorithms:

- Affinity propagation (AP-mean)
- Gaussian mixture model, using most probable cluster assignment (GMM-mean)
- Gaussian mixture model, using cluster assignments weighted by probability (GMM-WM)

A similar approach can be taken with dimensionality reduction techniques, where we can use K-nearest neightbours (in this case, few workers label each pair, so we choose k=1 and use MC when no workers have labelled the current instance?):

 Factor analysis with K-nearest neighbours (FA-KNN)

Alternatively, we can take a weighted average of the other labels for a pair, where the weights are based on inverse distance from the worker in question in the embedded space:

 Factor analysis with an inverse distanceweighted mean (FA-weighted)

The distance function can be optimised, which leads to proposing more sophisticated methods...

4 Bayesian Preference Learning Model

The model introduced in [10] combines preference learning with matrix factorisation to identify latent features of items and users that affect their preferences. This allows for a collaborative filtering effect, whereby users with similar preferences on a set of observed items are assumed to have similar preferences for other items with similar features. This allows us to make better predictions about the unobserved preferences of a given user when we have seen preferences of a similar user.

The method presented in [10] uses a combination of expectation propagation (EP) and variational Bayes (VB). Since the inference steps require inverting a covariance matrix, this method scales with $\mathcal{O}(N^3)$ and is therefore impractical for large datasets. For our modified version of this method, we improve scalability by using stochastic variational inference to infer the complete model. The variational approximation to the posterior is given by...

The variational inference algorithm maximises a lower bound on the log marginal likelihood:

$$\mathcal{L} = \sum_{i=1}^{N} \mathbb{E}[\log p(t_{i}|x_{i,1}, x_{i,2}, \mathbf{f})] +$$

$$\sum_{u=1}^{U} \mathbb{E}\left[\log \frac{p(\mathbf{f}_{u}|\mathbf{w}\mathbf{y}_{u}, \mathbf{K}_{f,u}/s_{f,u})}{q(\mathbf{f}_{u})}\right] +$$

$$\sum_{c=1}^{C} \mathbb{E}\left[\log \frac{p(\mathbf{w}_{c}|\mathbf{0}, \mathbf{K}_{w}/s_{w,c})}{q(\mathbf{w}_{c})}\right] +$$

$$\sum_{c=1}^{C} \mathbb{E}\left[\log \frac{p(\mathbf{y}_{c}|\mathbf{0}, \mathbf{K}_{y}/s_{y,c})}{q(\mathbf{y}_{c})}\right] +$$

$$\mathbb{E}\left[\log \frac{p(\mathbf{t}|\boldsymbol{\mu}, \mathbf{K}_{t}/s_{t})}{q(\mathbf{t})}\right] +$$

$$\sum_{u=1}^{U} \mathbb{E}\left[\log \frac{p(s_{f,u}|a_{f,u}, b_{f,u})}{q(s_{f,u})}\right] +$$

$$\sum_{d=1}^{D} \mathbb{E}\left[\log \frac{p(s_{w,d}|a_{w,d}, b_{w,d})}{q(s_{w,d})}\right] +$$

$$\sum_{d=1}^{D} \mathbb{E}\left[\log \frac{p(s_{y,d}|a_{y,d}, b_{y,d})}{q(s_{w,d})}\right]$$

$$(1)$$

where t_i is the preference label for the *i*th pair,

To perform feature selection with large numbers of features, we introduce an automatic relevance determination (ARD) approach that uses the gradient of the lower bound on the log marginal likelihood to optimise the kernel length-scales using

the L-BFGS-B method [?]. The gradient is given

$$\nabla \mathcal{L} = \left[\frac{\partial \mathcal{L}}{\partial l_{w,1}}, ..., \frac{\partial \mathcal{L}}{\partial l_{w,D_w}}, \frac{\partial \mathcal{L}}{\partial l_{y,1}}, ..., \frac{\partial \mathcal{L}}{\partial l_{y,D_y}}\right], \quad (2\text{features}.$$

$$\frac{\partial \mathcal{L}}{\partial l_{w,d}} = \frac{\partial}{\partial l_{w,d}} \sum_{u=1}^{U} \mathbb{E} \left[\log \frac{p(f_u|wy_u, K_{f,u}/s_{f,u})}{q(f_u)}\right] \text{ This is all useful because we can use the approach to determine which features are worth obtaining, make predictions when data is sparse, and obtain
$$\sum_{c=1}^{C} \mathbb{E} \left[\log \frac{p(w_c|0, K_w/s_{w,c})}{q(w_c)}\right] - \text{The steps to show this are:}$$

$$1. \text{ Show a table comparing the baselines, alternative collaborative filtering methods, results from [10], and unsupervised method}$$

$$= 0.5(\hat{f}_u - wy_u)^T K_{f,u}^{-1} \frac{\partial K}{\partial \log l_{w,d}} \hat{s}_{f,u} K_{f,u}^{-1} (\hat{f}_u - wy_u) 2. \text{ Add in results when using the input information with out method}$$

$$-0.5 \text{tr} \left((K_{f,u}^{-1} - \frac{C^{-1}}{\hat{s}_{f,u}}) \frac{\partial K_{f,u}}{\partial \log l_{w,d}}\right) 3. \text{ Show a table comparing the baselines, alternative collaboration of the baselines, alternative collaboration of the baselines, alternative collaboration.}$$$$

where $l_{w,d}$ is a length-scale used for all the GPs over item features. The implicit terms are zero when the VB algorithm has converged.

Experiments

In the first set of experiments we evaluate the baselines and the different methods for modelling correlations between workers' preferences. In the second set of experiments, we assess the value of different language features. Finally, the third experiment evaluates approaches that integrate both argument features and models of preference correlations.

Prior work on convincingness:

- [10] shows how to predict convincingness of arguments by training a NN from crowdsourced annotations.
- [10] shows that persuasion is correlated with personality traits.

We build on this to show...

- How we can predict convincingness for a specific user given only previous preferences and preferences of others (collaborative filtering)
- How a combination of text and personality features improves predictions of convincingness

• That we can extract human-interpretable latent features in people and items, which improve performance over just using the input This is all useful because we can use the approach

- - - tion with out method
- native collaborative filtering methods, results $\frac{\partial \mathcal{L}}{\partial l_{u,d}}$ = (3) native collaborative filtering methods
 - 4.⁽⁴⁾Add in results using item information, person information and both
 - 5. Visualise latent features?
 - 6. Table showing importance of input features
 - 7. Add results with lower confidence items excluded to the tables in 1-4. We can also plot the effect of confidence threshold on our results and on the rival methods.
 - 8. Add in Bier/cross entropy may need to rerun the original code from the previous papers?
 - 9. Run [10] and my complete method with reduced data - check accuracy as it increases. Use confidence cut-off from previous results.
 - 10. Simple active learning approach selecting the most uncertain data point (this will be due to uncertainty about a person, an item with too little data, or disagreement/stochasticity in the likelihood). The plot can be added to the previous results and should be run with rival methods.

Future Work

The collaborative preference model can be adapted so that it can be trained using classification data, scores/ratings (a regression task), or a mixture of different observation types by applying a different likelihood. The core of the method is the abstraction of a latent function over items and people, dependent on latent features of items and people, with the ability to include side information and observed features. Future work will therefore investigate the ability to learn from multiple types of labelled data, (rather than only using preference pairs).

A further direction for future work is to apply this model to transfer learning: instead of modelling different latent functions per person, we model latent functions per task. Tasks for which the target function follows a similar pattern would then share information in a collaborative manner, so that training data for one task can inform similar tasks. This may be useful when data is limited, e.g. when performing domain adaptation. In the latter case, there would need to be sufficient similarity between the features of the texts that are being classified for the collaborative effect to take place. For example, in argument mining, we may have several training datasets from different topics, which can be used to learn a model of argument convincingness. Applying a collaborative model would identify topics with common latent features, which would inform predictions on the target domain in parts of the feature space with no training data.

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