

A simulation on intersection based on Vissim

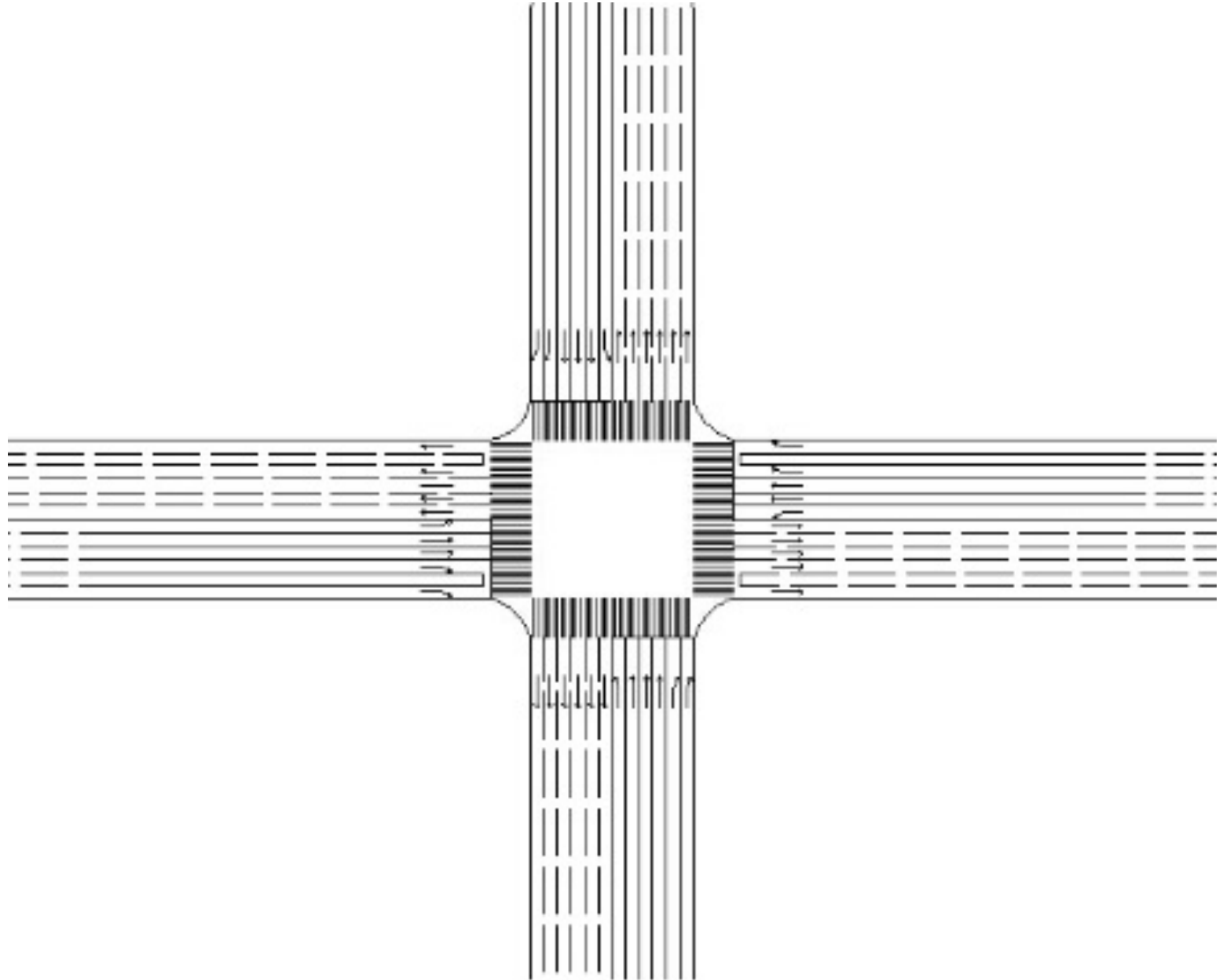
Ranran Cao

Introduction

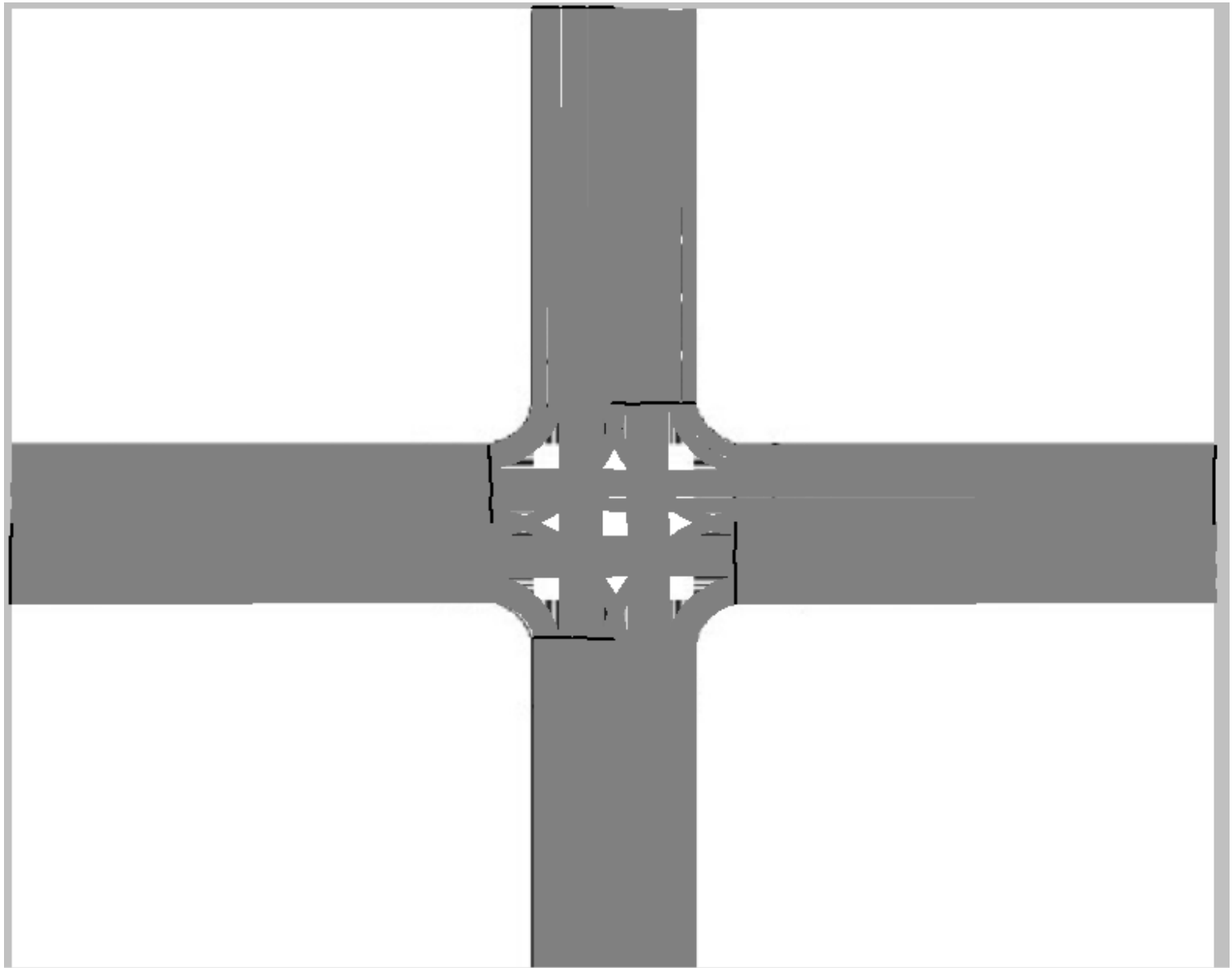
- **Topic--Intersection simulation**
- **Aim1: Trying to simulate a 12-line bothway intersection**
- **Aim2: Also trying to find a good signal cycle assignment to avoid any potential traffic delay or traffic collision on intersection and get a larger throughput.**


- **For each direction, there will be one left turn line and three straight lines and two right lines.**

map



1, Print links and define routes



 Traffic Composition

No.: Name:

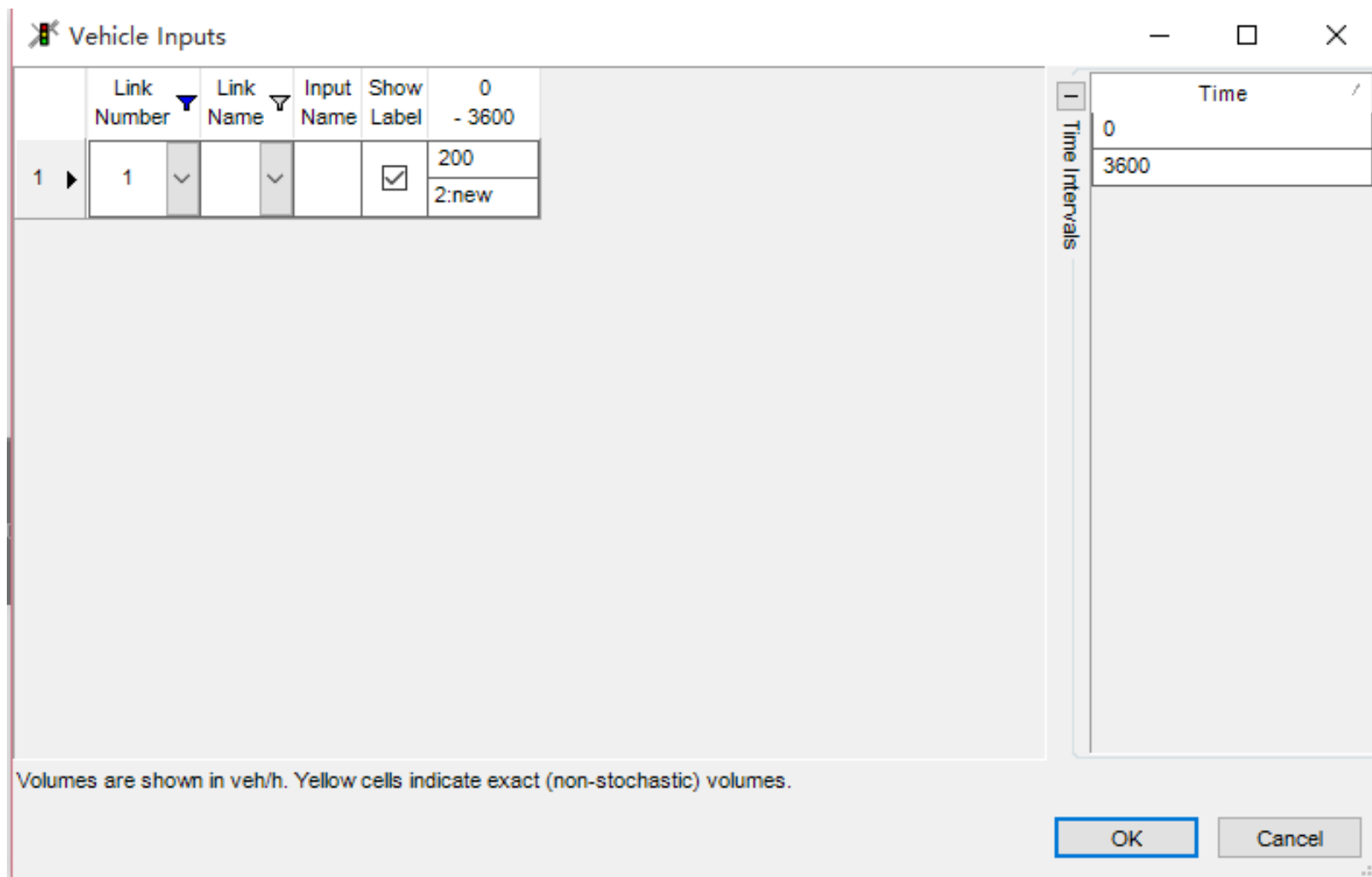
Vehicle Type	Rel. Flow	Des. Speed
100, Car	0.800	100 (88.0, 130.0)
200, HGV	0.100	90 (85.0, 120.0)
300, Bus	0.100	60 (58.0, 68.0)

Cat. converter temp. dist.:

Cooling water temp. dist.:

2, Traffic composition. give 80% cars and 10% HGVs and 10% buses (Similar to the real world)

uts for one left line (ie.200)



The image shows a software dialog box titled "Vehicle Inputs". It contains a table for defining input data and a sidebar for time intervals.

	Link Number	Link Name	Input Name	Show Label	
1 ▶	1			<input checked="" type="checkbox"/>	0 - 3600 200 2:new

Time Intervals

Time

0
3600

Volumes are shown in veh/h. Yellow cells indicate exact (non-stochastic) volumes.

OK Cancel

Three straight lines vehicle inputs size inputs ie.1000)

Vehicle Inputs

	Link Number	Link Name	Input Name	Show Label	0 - 3600
1	2			<input checked="" type="checkbox"/>	1000 2:new

Time Intervals


Time

0
3600

Volumes are shown in veh/h. Yellow cells indicate exact (non-stochastic) volumes.

OK Cancel

Two right lines vehicle inputs(ie.300)

 Vehicle Inputs

	Link Number	Link Name	Input Name	Show Label	0 - 3600
1	5			<input checked="" type="checkbox"/>	300 2:new

Volumes are shown in veh/h. Yellow cells indicate exact (non-stochastic) volumes.

Time Intervals

Time
0
3600

OK Cancel

4, Signal cycle assignment

General rules: we assign one complete signal cycle to 80s including green cycle, amber cycle and red cycle.

Specific rules:

4.1 Two right turn lines doesn't need signal;

4.2 Only left turn line and straight lines need signal;

Give each straight line 27s green cycle and 3s amber cycle

Give left turn line 7s green cycle and 3s amber cycle

4.3 The opposite direction share the same rules. Opposite straight lines and left line could work at the same time respectively.

Thus we could first let W-E straight lines consume 30s and then W-E left line consume 10s and then N-S straight lines 30s and then N-S left line 10s.

4.3 we assigned signal number by anticlockwise from number 1-16



Signal Control



No.	Name	Cycl	# Signals	Type
1		80	16	Fixed time

Number: Name: Cycle Time: ☒ s

Type: Fixed time

☐ variableOffset: s

Signal Groups

SigTimTbl Config

No.	Name	Red/ Amber	Amber	Red End	Green End	Red End 2	Green End 2	Type
▶ 1		0	3	30	37			Cycle
2		0	3	0.1	27			Cycle
3		0	3	0.1	27			Cycle
4		0	3	0.1	27			Cycle
5		0	3	70	77			Cycle
6		0	3	40	67			Cycle
7		0	3	40	67			Cycle
8		0	3	40	67			Cycle
9		0	3	30	37			Cycle
10		0	3	0.1	27			Cycle

OK

Cancel

Signal Control



No.	Name	Cycl	# Signals	Type
1		80	16	Fixed time

Number:

Name:

Cycle Time: ☒ s

Type: Fixed time

☐ variable

Offset: s

Signal Groups

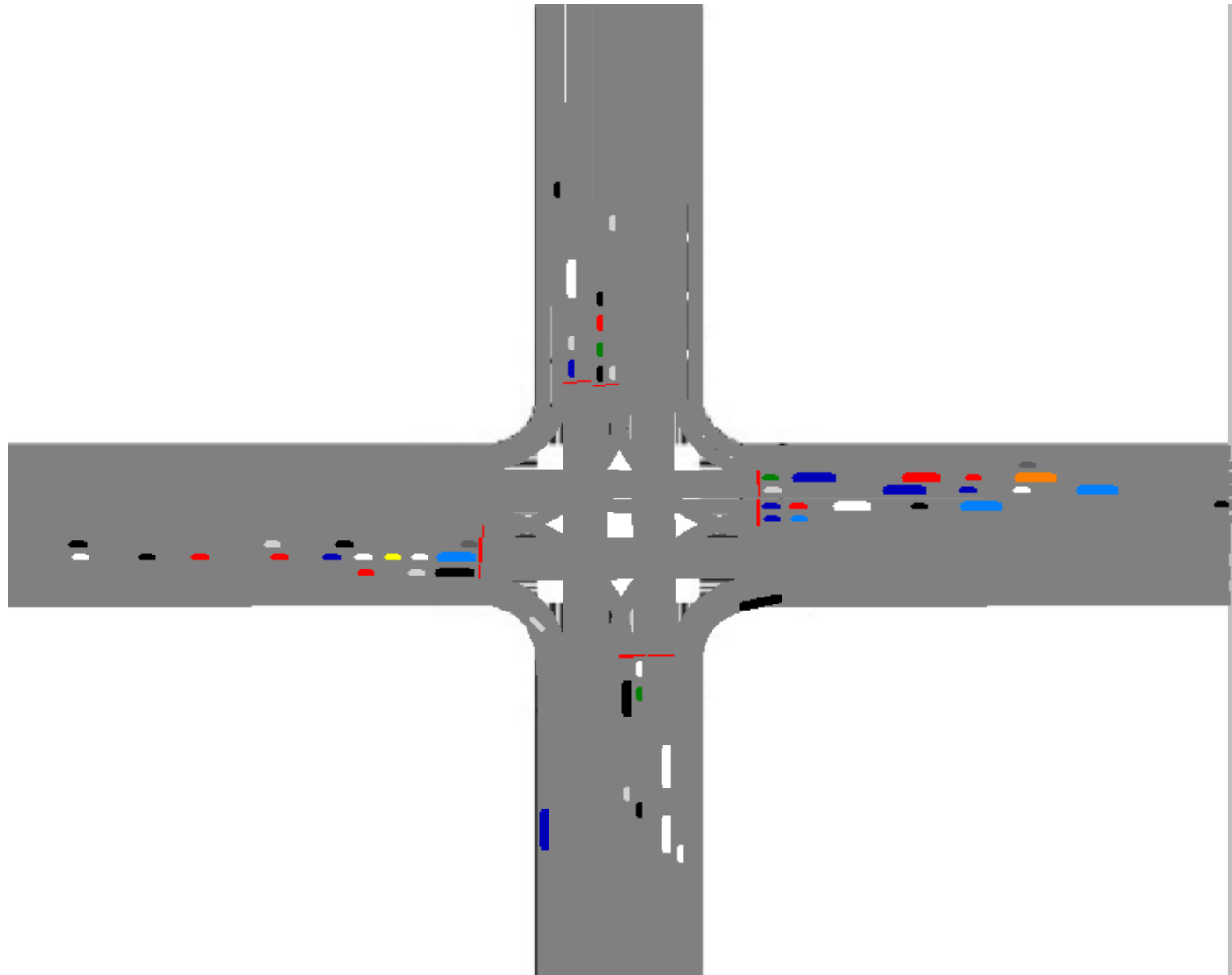
SigTimTbl Config

No.	/	Name	Red/ Amber	Amber	Red End	Green End	Red End 2	Green End 2	Type
	10		0	3	0.1	27			Cycle
	11		0	3	0.1	27			Cycle
	12		0	3	0.1	27			Cycle
	13		0	3	70	77			Cycle
	14		0	3	40	67			Cycle
	15		0	3	40	67			Cycle
	16		0	3	40	67			Cycle

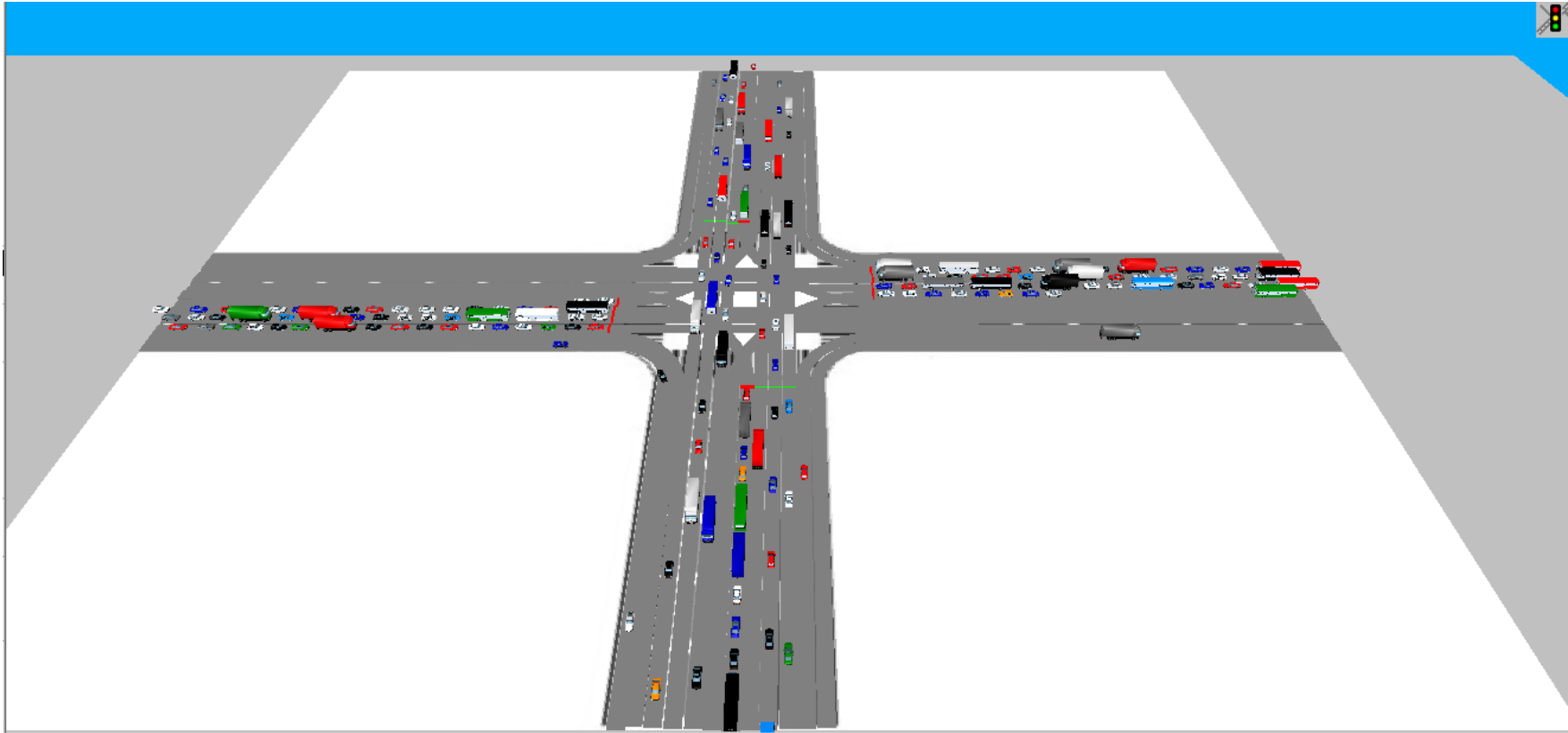
OK

Cancel

Run simulation:
2D results



Results: 3D

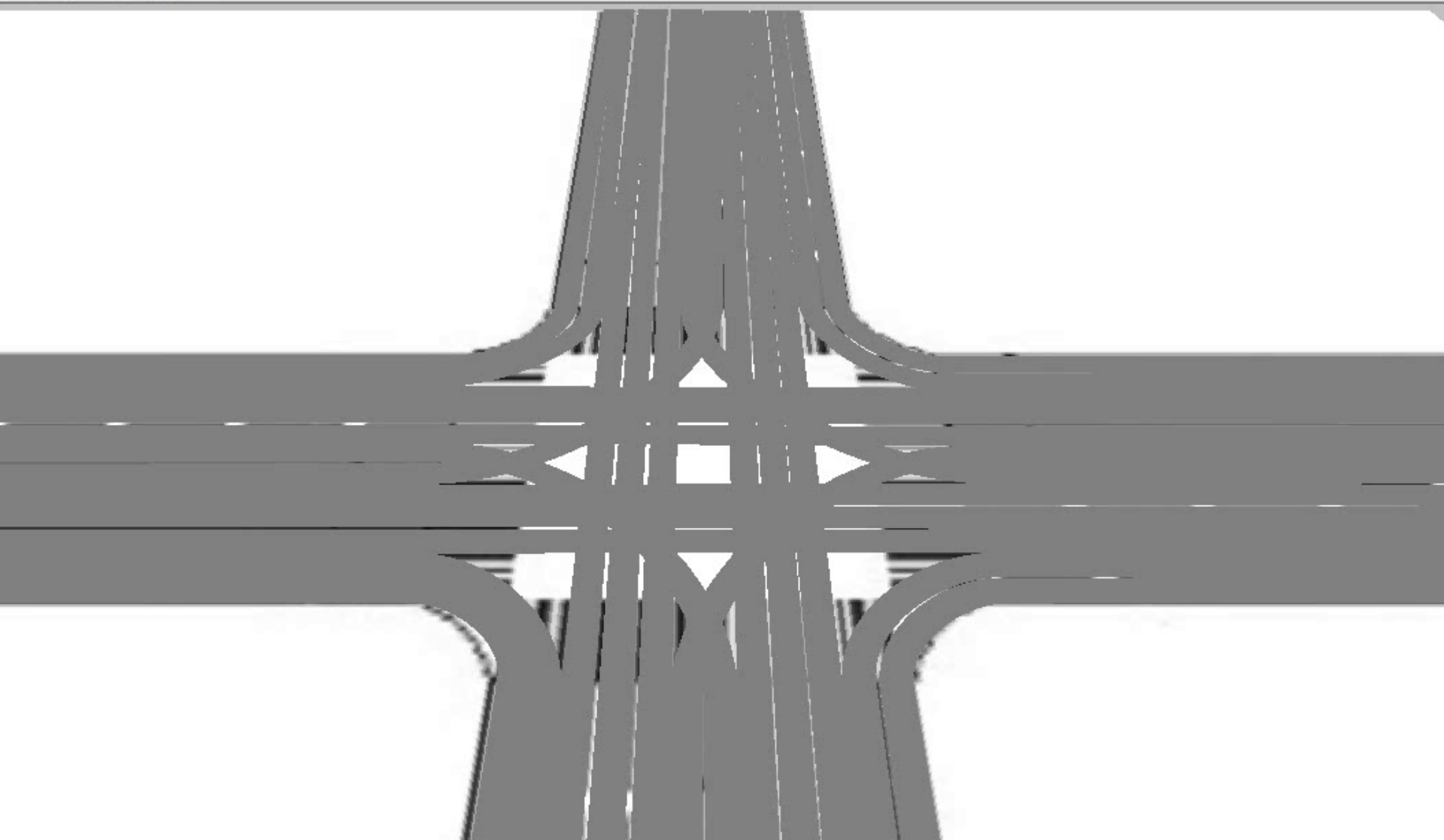


The results show that there is no traffic collision.

We dynamically modify vehicle inputs and signal cycle to avoid the traffic delay and traffic collision on intersection.

am files (x86)\ptv_vision\vissim430\example\9.1.inp

Traffic Signal Control Evaluation Simulation Presentation Test Scripts 2



Vehicle Input: select link

Conclusions and Future Work

- 1, use th real data in real world and solve real problem
- 2, adjust the signal cycle dynamically to achieve the best throughput
- 3, (perspective goal)maybe could design an adaptative algorithms(rules) to be applied to any map background.
- ie. according to the different line design and line inputs(dynamically maybe), to avoid any traffic delay or traffic collision and thus improve throughputs.