The tipsae package: mapping indicators through space and time via small area estimation

Silvia De Nicolò Aldo Gardini

Department of Statistical Sciences, University of Bologna

email: silvia.denicolo@unibo.it

Small Area Estimation

We want to estimate a generic indicator on the unit-interval (e.g. poverty, health insurance coverage rates):

- in a specific sub-population (domains or areas) (e.g. districts, counties, sex-age-race groups)
- from survey data
- in domains not originally planned by the survey design
- resulting in small-sized sample

Survey estimation is unreliable due to the high variability.

Small Area Estimation

→ We have to resort Small Area Estimation (SAE) techniques.

Area-level model class:

- hierarchical Bayes models with survey estimators as responses
- exploit domain-specific quantities as auxiliary information
- borrow strength across areas, producing estimates with a decreased and acceptable level of uncertainty.

Space-time models in SAE

- When historical data are available, it is also possible to borrow strength from time.
- Often domains are geographical regions: spatial correlation may be observed.
- Recent Bayes spatio-temporal SAE models have been used to measure:
 - relative risk of disease (Choi et al. 2011);
 - gender-based violence (Vicente et al. 2020);
 - patterns of crime (Law et al. 2014).

SAE and R packages

Area-level SAE for unit interval-defined measures:

 Gaussian Model (Fay-Herriot) with suitable transformations;
(Esteban et al., 2012, 2020; Marhuenda et al., 2013, 2014)

Mixed Beta-based models.

R implementations: Gaussian model with arcsin transformation in emdi package without any spatio-temporal specification.

What we did

What we did 5/19

The tipsae goals

Providing a friendly framework to deal with unit interval indicators:

- Bayesian inferential framework.
- Focus on Beta, inflated Beta and other Beta mixtures models.
- Possible dependence structures in the data: spatial and/or temporal random effects.
- Estimation via Hamiltonian MC (Stan) and customized parallel computing imported from rstan.
- Ad-hoc functions for small-area model diagnostics with plots and maps tools.
- A friendly Shiny app.

What we did 6/19

Some notation

We consider a finite population with size *N* partitioned into *D* domains. For each domain *d*, we define:

- The quantities of interest θ_d , with $\theta_d \in (0, 1)$;
- The survey (or crude) estimator y_d of θ_d with large variance;
- An estimate of the sampling variance $\widehat{\mathbb{V}}[y_d]$;
- ightharpoonup A vector \mathbf{x}_d of auxiliary variables (recorded without error).

What we did 7/19

Standard Beta Small Area Model

When $y_d \in (0; 1)$, the sampling level is

$$y_d | \theta_d \sim \text{Beta} \left(\theta_d \phi_d, (1 - \theta_d) \phi_d \right) \quad \forall d,$$

where

- $\theta_d = \mathbb{E}[y_d|\theta_d],$
- $ightharpoonup \phi_d$ is a **dispersion parameter** usually assumed to be **known**.

The linking level models the target quantity

$$logit(\theta_d)|\boldsymbol{\beta}, e_d = \boldsymbol{x}_d^T \boldsymbol{\beta} + e_d.$$

 e_d is the random effects term which can incorporate several data dependency structures.

What we did 8/19

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What we did 8/19

Spatial structure

- **Spatial structure:** $e_d = s_d + v_d$
 - \mathbf{v}_d an unstructured area random effect;
 - ► s_d a spatial random effect;

where
$$\mathbf{s} = (s_1, \dots, s_D)$$
 has prior

$$\mathbf{s}|\sigma_{\mathsf{s}} \sim \mathit{ICAR}(\sigma_{\mathsf{s}}^2 \tilde{\mathbf{K}}^-), \quad \sigma_{\mathsf{s}} \sim \mathsf{half-}\mathcal{N}\left(0, 2.5\right).$$

- $\tilde{\mathbf{K}}^-$ is the inverse of a singular precision matrix $\tilde{\mathbf{K}}$
- ightharpoonup obtained from $\mathbf{K} = \mathbf{D} \mathbf{W}$ with
 - **D** a diagonal matrix with the number of connections,
 - ► **W** the adjacency matrix.

What we did 9/19

Spatial structure

K results from K after a:

scaling procedure (Sørbye and Rue 2014):

The structure of **K** affects prior variability irrespective of the hyperprior set up on dispersion parameter.

- 2. contemplating the presence of **disconnected graphs in the model** e.g., islands (Freni-Sterrantino et al. 2018; Morris et al. 2019).
 - Independent scaling for sub-blocks of K related to components with size > 1.
 - Every components has its own intercept.
 - Constant prior replaced with standard Gaussian for components of size 1 (singletons).

What we did 10/19

Temporal or spatio-temporal

- **Temporal effect:** $e_{dt} = u_{dt} + v_d$, each area d is repeatedly observed at times t = 1, ..., T.
 - ▶ v_d an unstructured area random effect;
 - u_{dt} a temporal random effect;

$$u_{dt}|u_{d,t-1}, \sigma_u \stackrel{\textit{ind}}{\sim} \mathcal{N}\left(u_{d,t-1}, \sigma_u\right), \quad \sigma_u \sim \mathsf{half-}\mathcal{N}\left(0, 2.5\right).$$

Spatio-Temporal effect: $e_{dt} = u_{dt} + s_{dt}$

Marginal spatial and temporal components are **non-identifiable**! SAE models have only predictive purposes.

What we did 11/19

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What we did

Alternative Likelihoods

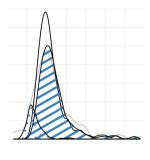
Let $f_B(y; \mu, \phi)$ be the Beta p.d.f., the following extensions are provided:

2-components Beta mixture: for $y_d \in (0,1)$ (De Nicolò et al. 2022).

$$y_d | \dots \stackrel{\text{ind}}{\sim} p \cdot f_B(y_d; \lambda_{1d}, \phi_d) + (1 - p) \cdot f_B(y_d; \lambda_{2d}, \phi_d).$$

Zero/one inflated Beta: for $y_d \in [0, 1]$

$$\begin{aligned} y_{d}|\dots &\stackrel{\textit{ind}}{\sim} p_{d}^{(0,1)} f_{B}(y_{d}; \mu_{d}, \phi_{d}) \mathbb{1}\{0 < Y_{d} < 1\} \\ &+ p_{d}^{z} \cdot \mathbb{1}\{Y_{d} = 0\} \\ &+ p_{d}^{o} \cdot \mathbb{1}\{Y_{d} = 1\}. \end{aligned}$$

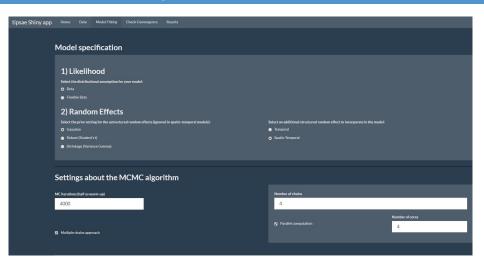


What we did 12/19

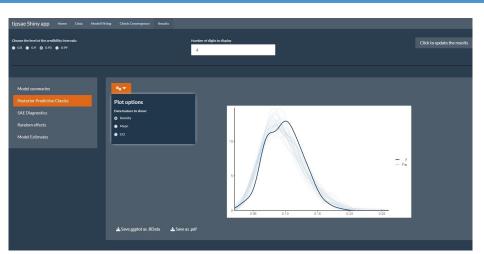
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- Poverty rates in 38 health districts within the Emilia-Romagna region.
- Starting from unreliable survey estimates of the Head-Count Ratio indicator,
- recorded annually from 2014 to 2018,
- and generated covariates.

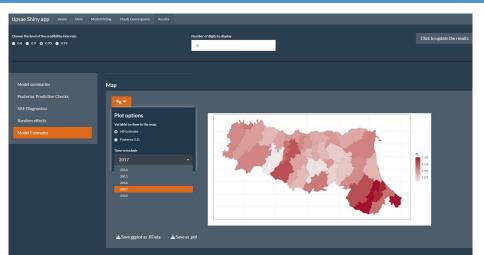
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Conclusions

- 🕨 R package available on CRAN
- fitting Beta-based small area models with spatio-temporal dependency structures.

Additional tools under developments:

- Regularizing prior for regression coefficients (HorseShoe).
- Alternative 0/1 inflated Beta models that incorporate survey information.

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