

Neural networks

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History

- Neural networks originally appeared as an attempt to model human brain



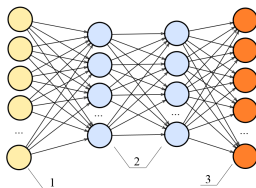
- Human brain consists of multiple interconnected neuron cells
 - cerebral cortex (the largest part) is estimated to contain 15–33 billion neurons
 - communication is performed by sending electrical and electro-chemical signals
 - signals are transmitted through axons - long thin parts of neurons.

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Definition

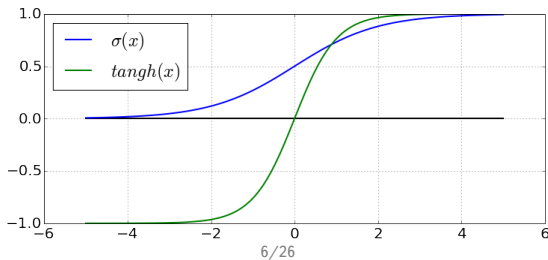
- linear / logistic regression - simplest case
- acyclic directed graph
- verticals called neurons
- edges correspond to certain weights



- Structure of neural network:
 - 1-input layer
 - 2-hidden layers
 - 3-output layer

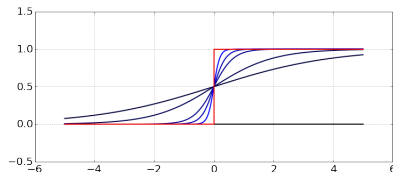
Definition

- Each neuron j is associated a non-linear transformation φ .
- For multilayer perceptron class neural networks φ belongs to a class of activation functions.
- Most common activation functions:
 - sigmoidal: $\sigma(x) = \frac{1}{1+e^{-x}}$
 - 1-layer neural network with sigmoidal activation is equivalent to logistic regression
 - hyperbolic tangent: $\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$

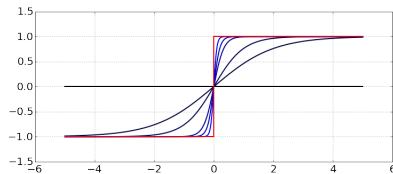


Activation functions

Activation functions are smooth approximations of step functions:



$\sigma(ax)$ limits to 0/1-step function as $a \rightarrow \infty$



$\tanh(ax)$ limits to -1/1-step function as $a \rightarrow \infty$

Definition details

- Label each neuron with integer i .
- Denote: I_i - input to neuron i , O_i - output of neuron i
- Output of neuron i : $O_i = A(I_i)$, where A is activation function.
- Input to neuron i : $I_i = \sum_{k \in inc(i)} w_{ki} O_k + w_{k0}$,
 - w_{k0} is the bias term
 - $inc(i)$ is a set of neurons with outgoing edges to neuron i .
 - further we will assume that at each layer there is a vertex with constant output $O_{const} \equiv 1$, so we can simplify notation

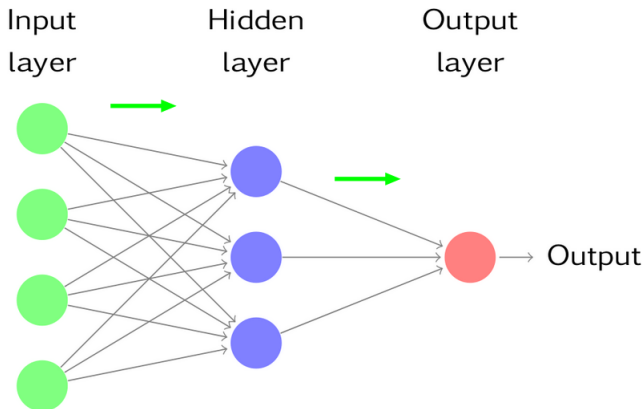
$$I_i = \sum_{k \in inc(i)} w_{ki} O_k$$

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Output generation

- Forward propagation is a process of successive calculations of neuron outputs for given features.



Output generation

- Output layer transformations

- regression: $\varphi(I) = I$
- classification:
 - 2 classes: sigmoid, indicating target class probability

$$\varphi(I) = \frac{1}{1 + e^{-I}}$$

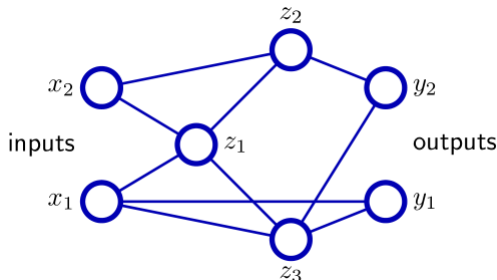
- multiple classes: softmax, indicating probabilities of each class:

$$\varphi(I_i) = \frac{e^{O_i}}{\sum_{k \in OL} e^{O_k}}, i \in OL$$

where OL denotes neuron indices at output layer.

Generalizations

- each neuron j may have custom non-linear transformation φ_j
- weights may be constrained:
 - non-negative
 - equal weights
 - etc.
- layer skips are possible



- recurrent networks.

Number of layers selection

- Number of layers usually denotes all layers except input layer (hidden layers+output layer)
- We will consider only continuous activation functions.
- Classification:
 - single layer network selects arbitrary half-spaces
 - 2-layer network selects arbitrary convex polyhedron (by intersection of 1-layer outputs)
 - therefore it can approximate arbitrary convex sets
 - 3-layer network selects (by union of 2-layer outputs) arbitrary finite sets of polyhedra
 - therefore it can approximate almost all sets with well defined volume (Borel measurable)

Number of layers selection

- Regression
 - single layer can approximate arbitrary linear function
 - 2-layer network can model indicator function of arbitrary polyhedron
 - 3-layer network can uniformly approximate arbitrary continuous function (as sum of indicators of various polyhedra)

Sufficient amount of layers

Any continuous function on a compact space can be uniformly approximated by 2-layer neural network with linear output and wide range of activation functions (excluding polynomial).

- In practice often it is more convenient to use more layers with fewer amount of neurons
 - model becomes more interpretable and tunable

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Network optimization: regression

- Single output:

$$\frac{1}{N} \sum_{n=1}^N (\hat{y}_n(x_n) - y_n)^2 \rightarrow \min_w$$

Network optimization: regression

- Single output:

$$\frac{1}{N} \sum_{n=1}^N (\hat{y}_n(x_n) - y_n)^2 \rightarrow \min_w$$

- K outputs

$$\frac{1}{NK} \sum_{n=1}^N \sum_{k=1}^K (\hat{y}_{nk}(x_n) - y_{nk})^2 \rightarrow \min_w$$

Network optimization: classification

- Two classes ($y \in \{0, 1\}$, $p = P(y = 1)$):

$$\prod_{n=1}^N p(y_n = 1|x_n)^{y_n} [1 - p(y_n = 1|x_n)]^{1-y_n} \rightarrow \max_w$$

Network optimization: classification

- Two classes ($y \in \{0, 1\}$, $p = P(y = 1)$):

$$\prod_{n=1}^N p(y_n = 1|x_n)^{y_n} [1 - p(y_n = 1|x_n)]^{1-y_n} \rightarrow \max_w$$

- C classes ($y_{nc} = \mathbb{I}\{y_n = c\}$):

$$\prod_{n=1}^N \prod_{c=1}^C p(y_n = c|x_n)^{y_{nc}} \rightarrow \max_w$$

Network optimization: classification

- Two classes ($y \in \{0, 1\}$, $p = P(y = 1)$):

$$\prod_{n=1}^N p(y_n = 1|x_n)^{y_n} [1 - p(y_n = 1|x_n)]^{1-y_n} \rightarrow \max_w$$

- C classes ($y_{nc} = \mathbb{I}\{y_n = c\}$):

$$\prod_{n=1}^N \prod_{c=1}^C p(y_n = c|x_n)^{y_{nc}} \rightarrow \max_w$$

- In practice log-likelihood is maximized.

Neural network optimization

- Let W denote the total dimensionality of weights space
- Let $E(\hat{y}, y)$ denote the loss function of output
- We may optimize neural network using gradient descent:

```
while (stop criteria not met):  
     $w^{k+1} = w^k - \eta \nabla E(w^k)$ 
```

- Standardization of features makes gradient descend converge faster
- Other optimization methods are more efficient (conjugate gradients)

Neural network optimization

- Direct $\nabla E(w)$ calculation, using

$$\frac{\partial E}{\partial w_i} = \frac{E(w + \varepsilon_i) - E(w)}{\varepsilon} + O(\varepsilon)$$

or better

$$\frac{\partial E}{\partial w_i} = \frac{E(w + \varepsilon_i) - E(w - \varepsilon_i)}{2\varepsilon} + O(\varepsilon^2)$$

has complexity $O(W^2)$ [W forward propagations to evaluate W derivatives]

Backpropagation algorithm needs only $O(W)$ to evaluate all derivatives.

Multiple local optima problem

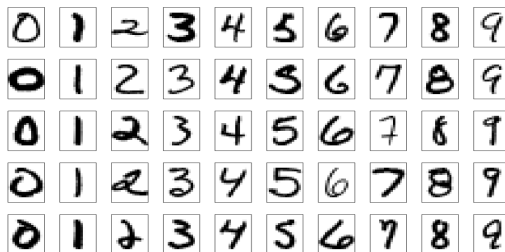
- Instability with respect to:
 - different starting parameter values
 - different subsamples
 - different feature selections
- Solutions
 - select best optimum from local optima
 - average predictions for different local optima

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Case study (due to Hastie et al. The Elements of Statistical Learning)

ZIP code recognition task



Neural network structures

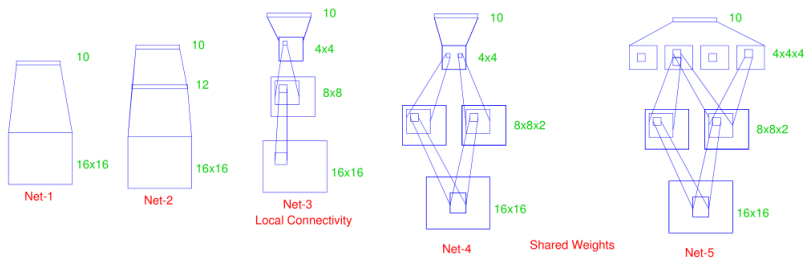
Net1: no hidden layer

Net2: 1 hidden layer, 12 hidden units fully connected

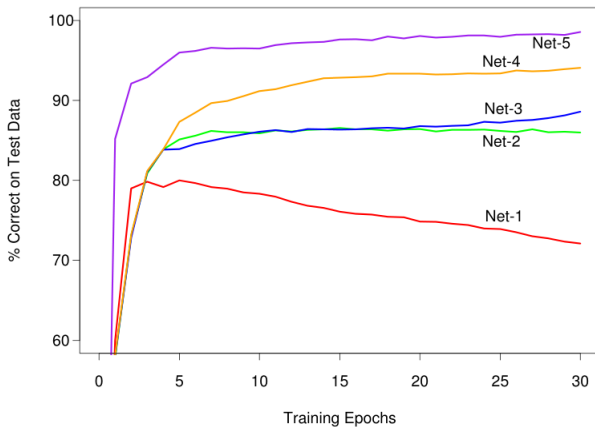
Net3: 2 hidden layers, locally connected

Net4: 2 hidden layers, locally connected with weight sharing

Net5: 2 hidden layers, locally connected, 2 levels of weight sharing



Results



Addition

- Deep learning
- Neural networks may model not only real value outputs, but densities
 - each output - frequency of histogram bin
 - each output - parameter of a distribution

Conclusion

- Advantages of neural networks:
 - can model accurately complex non-linear relationships
 - easily parallelizable
- Disadvantages of neural networks:
 - hardly interpretable (“black-box” algorithm)
 - optimization requires skill
 - too many parameters
 - may converge slowly
 - may converge to inefficient local minimum far from global one