#### Fundamentals

Key Characteristics CC: On-demand, Ubiquitous network access, Resource pooling, Elasticity, Measured Service

Concerns: Maturity, Standards, security, interoperability, control Grid computing: solve single problem, cloud comp: solve independent tasks

Elasticity/Scalability: adapt resources, based on user's requirements

Provisioning: provide resources to user, self-service allows customer to request what they need

Virtualization: used to decouple software from hardware, partitioning(multiple apps on one machine), isolation(vm have no information about each other), encapsulation(state of vm is hwindependent)

Containers(docker) don't bundle a full OS but only libraries for an

application, Hypervisor enables vm's

Multitenancy: user's share resources

Billing via metering(number of users, capacity, services)

Service Models: IaaS: computing i. as a service(Amazon ec2)

PaaS: offer platform where to run applications (facebook, google appengine)

SaaS: offer application(dropbox)

Serverless Computing: User write's code and server administration is problem of cloud provider Cloud Deployment: Public, Private, Community, Hybrid, (virtual

private cloud)
Security risks: provider has crucial part->out of control, difficult to

monitor, Vm's are vulnerable

## Overview Hadoop

BD Chall: Disk failures, data dependencies

 ${\it Hadoop: reliable shared storage (HDFS)}$  and analysis (MapReduce) system.

Map (k1,v1)->list(k2,v2) || Reduce (k2,list(v2)) -> list(k3,v3) "Group by" operation that creates input for reduce is called "Shuffle and sort"

2 Types of Nodes, master(coordination), worker/slaves(run tasks/report)
Split size of input data: HDFS block size(def 128MB)

Data locality optimization: run task on a node where the data resides (only works for map tasks)

Fault tolerance: rerun task if it fails, op of map local, op of reduce HDFS

Partition: how to partition map outp

Combiner: intermediate step between map and reduce

HDFS prop: very large files, batch processing(data doesn't change)

low-cost hw(expect failures), move computation rather than data HDFS has master/slave architecture, namenode(coordination).

slave(storage, read/write)

HDFS arranges data in large (128MB) blocks(less disk seeks)

Namespace is handled at namenode

Blocks are replicated among multiple slaves for fault tolerance, Namenode is responsible for ensuring replication

Rack-aware placement: two replicas in different nodes in the local rack and another one in a different rack

Read request to closest rack from reader Communication via TCP

If Namenode fails we need manual intervention

HDFS Read: 1.client opens file through fs obj 2.fs obj calls namenode to determine location of data 3.client gets information and calls read function through input stream 4.client gets data of block, recalls read for next block 5. close in stream when finished reading

HDFS Write: Start is same, then client writes to out stream. The

outstream makes packets, keeps them in a data queue and streams them to the first datanode. The datanode forwards it to the next closest datanode (recursively), once it reaches the last datanode ack, the packet. Outputstream keeps track of acked packets. After that client closes and contacts namenode to inform about datachange
YARN(Yet another recourse negotiator): decouple programming

model and resource management

Client requests resource manager for application master-

>application master requests more resources if necessary

# MapReduce Programming

Anatomy of Mapreduce Job: 1.run Job 2. client ask YARN resource manager for jobID 3. client copies resources to fs 4. client tells RM to start job 5.RM allocate containter to run application(MapReduce master) in NodeManager 6.MR-Master keeps track of job progress and retrieves input splits form fs 7. Appl. master requests more container(YARNChild) for MR-tasks.

If master fails, resource manager creates new master (same with node manager), if RM fails we fucked Shuffle and sort happens on Map(make groups) and Reduce side(copy, sort)

Streaming: special kind of MR for communication with I/O streams

## MapReduce Algorithm Design

In-mapper combining -> reduce mapper outputs Pairs/stripes -> store more information in key/values Order inversion -> define order of keys to use this information (for relative frequencies f.i.)

Secondary sorting -> Use pairs as key to sort for value (value-to-key)

# MapReduce applications

Web search problem: Crawling(gather content), Indexing(search struct), Retrieval(rank documents)

Inverted index: data struct, that provides access to list of documents that contain the key. Entry(Posting) for each key consists of a list of (doc id, payload). Can be created with MR. Use value-to-key to let mapreduce do the sorting(partitioner is used to send all original keys to same reducer

Retrieval: use distributed retrieval (distribute based on term or document) instead of  ${\rm MR}$ 

Shortest path with MR: parallel bfs. Needs multiple MR its.

### Key-Value stores

tor sends Vote-request, participant responds with V-commit(do comp)/V-abort 2. Coordinator sends Global-commit, if all partic. committed, else G-abort, participants handle accordingly

NoSOL: simple flexible but not ACID. Multiple types: Key-value.

Distributed RelatioanlDBMS via 2 phase commit: 1. Coordina-

NoSQL: simple, flexible but not ACID. Multiple types: Key-value, column, document, Graph Key-Value: stores pairs, key often simple, value complex. Supports

Get and Put BigTable: not fully relational, data index via row & cols, client controlls locality

BT consists of GFS(storage), Chubby(lock manager, fault-tolerance) and SSTable(file format)

SSTable: Persistent, ordered, immutable map from key to value. Consists of sequence of blocks + index for lookup

Tablet: Dynamically partitioned range of rows, consists of multiple

sstables. Tablets can share sstables

Table: multiple tablets make table

BT has single master and multiple tablet servers. Coordination

BT has single master and multiple tablet servers. Coordination via master, tablet server manages set of tablets, splits them if they grow too large

grow too large
Write: update log, store info in memtable first and flush it to
sstable when it gets older

Read: check memtable and sstables

Compaction: minor->convert memtable to sstable, merge->merge sstables, major->left with 1 sstable

HBase: OS clone of BT, HFile SSTable, columns are grouped into families, tables partitioned into regions, uses Zookeeper for locking HBase is distributed, col-oriented, scalable

RDBMS fixed-schema, row-oriented, strong consistency, complex queries

CAP: Consistency, Availability, Partition tolerance (only 2 out of 3 possible). CPDDB, APDNS, CASingle-nodeDB Amazon Dynamo: highly available key-value storage, tries to be always writable, decentralized, distr. hash table, enforces eventual

consistency(weaker)

Dynamo solves Partitioning(consistent hashing) and temporary
failures(sloppy quorum)

Consistent hashing, map obj to nodes(storage) via hash function, replicate to following nodes, new node takes data from successor (update routing of it)

Eventual consistency via W replicas that need to acknowledge the update(not all!), eventually all N replicas update. Read contacts R servers and checks for consistency

Common (N,R,W) (3,2,2)

Sloppy quorum: read/write on the first N healthy nodes (not always the first N in the hash ring). Hinted handoff: "backup" nodes send replica to orderly node once they recovered -> eventually the first N contain the replica

#### Deduplication

Cloud storage pricing based on: space, requests, transfers (Tiers) Dropbox uses deduplication for storage

Deduplication: eliminate redundant data, coarse-grained compression in chunks

Compression: transform data in another representation to safe space, fine-grained

Indicate chunks via fingerprint

Chunking: fixed/variable-sized, anchor points via Rabin-Karp algo  $p_0 = (\sum_{i=1}^m t_i * 10^{m-i})\%q$ 

$$p_s = (10 * (p_{s-1} - 10^{m-1} * t_s) + t_{s+m})\%q$$

Duplicates can be checked directly or out-of-order

Store Index struct: RAM(too small), disk(slow), or via bloom filter

Bloom Filter  $P[FP] = (1 - (1 - \frac{1}{m})^{kn})^k$ 

Bloom filter is in memory and full index on disk

Sparse indexing introduces new level of granularity(segments. multiple chunks) & tries to make use of spatial locality of chunks Extreme binning: exploits file similarity

Fragmentation happens when we get a lot of updates in the data (destroys locality)

Containers: group of chunks, basic unit of I/O

Capping: limits number of containers a segment can refer to, limit's I/O for a file

Convergent encryption(security sol): encrypt on per-chunk basis, use hash value as crypt. key, vulnerable to offline brute-force dictionary attack

Can use server-aid for encryption

Side-channel attacks: upload file and see if deduplication occurs -> gives information about copy of file

3 problems for DropB: Hash value manipulation, stolen host id, direct up/download

### Facebook photo storage

Design goals: Throughput, fault tolerant, cost effective, simple Use content delivery networks for large-scale cache, effective because old content is rarely revisited

Haystack: offload CDN with haystack cache

Haystack directory provides mapping from logical to physical, does load balancing, checks if we go to cdn or haystack, manages rw

Pic URL: http://<CDN>/<Cache>/<Machine id>/<Logical volume, Photo>

Haystack cache gets only updated, when the request comes from the browser directly & phto is fetched from a write-enabled store machine

Haystack cache consists of store file(all the "needles"/pictures) and index file(metadata of "needles")

Store manages multiple physical volumes, handles Read(1I/O), Write(2I/O) and Delete

Write does always add 4 images to the store file, need to update index as well

Summary HS: Reduced I/O, Simplified metadata, single photo serving and storage layer

f4 Fault Tolerance: try to achieve storage-efficient fault tolerance 4 Types of Failures: Drive, Host, Rack, Datacenter(bad)

Erasure Coding: divide file into k data blocks, encode datab to additional n-k parity blocks, distribute n data/parity blocks to n nodes, any k out of n blocks can recover file data

Most common version Reed-solomon. f4: (n,k)=(14,10)

Tolerate data center failures: Double replication(data in multiple centers) or Geo-distributed XOR(add an XOR parity to two parts) f4 is used for BLOB(big binary files), very useful for warm data

## ZooKeeper

Zookeeper: highly-available/-performance coordination service. Scalable, distributed..

Guarantees: never detect old data, get informed if data changes while watching it

Zab protocol: 1. Elect leader (one of the machines that store data)2.atomic broadcast(all write request to follower will be forwarded to leader, he broadcasts it to all followers)

Data model: znode organises hierarchy like directory(intermediate nodesgroups, leaf nodesmembers. Znode can store data

Groups are persistent, members get deleted if not accessed recently Watches notifies client when znode content changes (only once after you need to reassign)

when a client creates a znode he takes the lock. Other clients watch the node and race the lock once it get's freed

Create ordering for lock acquisition EPHEMERAL SEQUENTIAL(let clients watch only the node right before them)

Create distributed barrier by waiting until a certain number of children are created(watcher on all children, then check count, if count == barrier continue)

Similarly create a producer-consumer queue. Producer creates sequential children, consumer watches all children, processes them and deletes them if there are any

Always elect the leader with the smalles seg number

## MR App part 2

PageRank: measure of webpage quality.  $PR(x) = \alpha * (\frac{1}{n}) + (1 - \alpha \sum_{i=1}^{n} \frac{PR(t_i)}{C(t_i)})$  We need to add dangling mass equally to all nodes as well.

MR needs efficient primitives for data sharing and reuse. Distributed memory needs to be fault-tolerant and efficient -> Resilient Distributed DB(read-only, partition collection of records) Spark: driver/worker, transform(new rdd)/act(info abt rdd) on RDD, computes lazy, control of partition and persistence Fault-recovery of rdd's based on rdd before transformation

Tail Tolerance

Tail: prob that latency is high. If tail is big overall performance gets bottled strongly

Latency is very variable due to: Resource sharing, background jobs, queueing, energy management Reduce variability: differentiate service classes & queuing, reduce

head-of-line blocking, manage background activities and synchric disruption

Tactics for short-term adaptations: Hedged request: request data from multiple servers shortly after one another. Tied request: request data simultaneously from multiple ones

Long-term adaptations: Micro-partitions(finer-grained), selective replication(replicate hot data), latency-induced probations(reduce requests to slow server)

Special cases: Good enough(accept inclompete result), canary request(send request to a few servers and call more if successful) Tail latency is not uncommon in storage as well, independent of I/O

rate and size imbalance How to be tail-tolerant: Reactive(extra reads, if we don't get a result in time), proactive(extra reads from the start), adaptive(detect

patterns and use proactive policy)

## Containerization and Serverless Computing

Containers are more lightweight than VMs (micro-service compute model). Only focus on application and its images

Docker: Daemon(coordinator), client and registry. Image contains all necessary files and has multiple read-only layers(file subset) Daemon creates writable layer out of image. Graph driver provides mapping to storage

Kubernetes: Groups containers based on purpose(POD). Master coordinates, worker run's PODs

Serverless Computing: User writes code, server provisioning and administration is offered by cloud provider. FaaS+Baas. Offers high elasticity and fine-grained resource billing

The tricky point is how to share data between jobs efficiently: common data store, Pocket

Pocket: way to store intermediate data. Uses Apache Crail, ReFlex and Kubernetes