

# Neural Networks: III. Regularization (Part 6)

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What to change to get better performance?

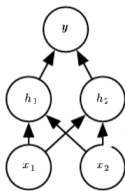
Accuracy & Loss

- improve generalization (and performance) by building several NN
- take the average of the outputs as our best guess
- problem: Machine intense
- ...but what if we already have several NN?

# Motivation

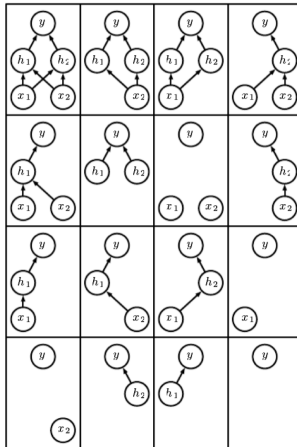
Consider our NN consists of  $M$  nodes. Then there exist  $2^M$  sampled networks.

Example:



**Figure:** Two Layer Network with Four Nodes (Deep Learning - Goodfellow, Bengio & Courville)

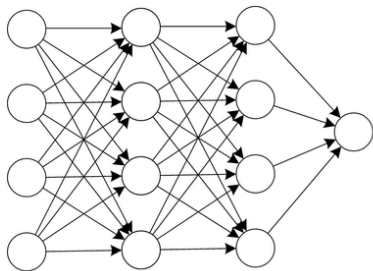
# Motivation



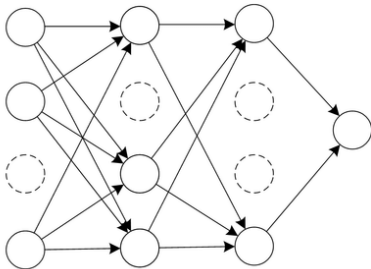
**Figure:** Possible Sampled Networks (Deep Learning - Goodfellow, Bengio & Courville)

- drop out units
  - temporarily removing it from the network
  - randomly choose which units to drop
- combining exponentially many different neural network architectures
- increases generalization i.e. prevents overfitting

# Dropout



(a) Standard Neural Network



(b) Network after Dropout

**Figure:** Before and after using Dropout (Dropout: A Simple Way to Prevent Neural Networks from Overfitting (2014))

How to?

- retain each unit with a probability  $p$  independent of other units
- drop each unit with a probability  $1 - p$  independent of other units
- you can choose the value of  $p$ 
  - to be 0.5 (which works quite well for most of the cases), while the probability for the input layer should be close to 1
  - according to your validation results (i.e. during training)
- increases generalization i.e. prevents overfitting



In practice:

- use dropout during training
- at test time, use the NN without dropout
- note: The weights of the NN without dropout are scaled-down versions of the trained weights:

$$E(\text{neuron}) = p \cdot y + (1 - p) \cdot 0 = p \cdot y$$

- Hence, we scale the NN without dropout by  $p$  to have the same weights:

$$p \cdot E(\text{neuron}) = p \cdot y$$