# K8090D.DLL

Technical Guide

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### Introduction

### General

The K8090D DLL provides a wrapper for the functionality offered by the K8090. This wrapper is introduced in the form of a **Dynamic Link Library (DLL)**. An application can use this DLL to communicate with the K8090 in a simplified manner. In this manual we will describe each of these functions provided by the DLL in detail.

Readers should have an understanding of the basic data types as well as basic knowledge of the Microsoft Windows operating system.

# Calling convention

A calling convention is a scheme for how functions receive parameters from their caller and how they return a result. Different programming languages use different calling conventions, so it is important to know which calling convention is used by your programming language and which calling convention is used by the K8090 DLL.

The most common calling convention is the **stdcall** calling convention, and this is also the one we have used for our DLL.

If you are using .NET (VB.NET or C#) you do not need to worry about this since the calling convention in .NET is also stdcall. However if you are using C to import the functions provided by the DLL, you will need to pay special attention to this.

# **Function List**

# OpenDevice

Attempts to establish a connection to the K8090 using the specified serial communications port.

#### Syntax:

```
HANDLE WINAPI OpenDevice(
___in LPCSTR szPort
);
```

#### Parameters:

szPort [in]	Null-terminated string containing the port name
~ = - · · · [ · · · · ]	- · · · · -    - · · · · · · · · · · ·

#### Return value:

If the function succeeds, the return value is a handle to the K8090 device. If the function fails the return value is INVALID\_HANDLE\_VALUE. To get extended information, call **GetLastError**.

#### **Example**:

```
int main()
{
    HANDLE hDevice;

    hDevice = OpenDevice("COM1");
    if (hDevice == NULL) {
        printf("Connection failed");
        return 1;
    }

    CloseDevice(hDevice);
}
```

# CloseDevice

Closes a handle opened by a call to OpenDevice. This closes the connection and frees any used resources.

### Syntax:

```
VOID WINAPI CloseDevice(
__in HANDLE hDevice
);
```

#### **Parameters**:

ce [in] Device handle returned by a call to OpenDevic	e
---	---

### SendCommand

Sends an asynchronous command packet to the K8090 device.

#### Syntax:

```
BOOL WINAPI SendCommand(
___in HANDLE hDevice,
__in BYTE cmd,
__in BYTE mask,
__in BYTE hparam,
__in BYTE lparam
);
```

#### **Parameters**:

hDevice [in]	Device handle returned by a call to OpenDevice
cmd [in]	Command byte.
mask [in]	Mask byte.
hparam [in]	First command parameter.
lparam [in]	Second command parameter.

View the K8090 Protocol Manual for more information about each parameter and their possible values.

#### Return value:

If the function succeeds, the return value is TRUE. If the function fails the return value is FALSE. To get extended information, call **GetLastError**.

#### **Example**:

# RegisterListener

Register an event window to receive event messages sent by the K8090 board. Only one window can be registered at a time.

### Syntax:

```
VOID WINAPI RegisterListener(
__in HANDLE hDevice,
__in HWND hWnd
);
```

#### **Parameters**:

hDevice [in]	Device handle returned by a call to OpenDevice
	Window that is to receive K8090 event messages. These messages will have a message ID of WM_USER+1.

#### Example:

```
#define COMMAND SWITCH RELAY ON 0x11
LRESULT CALLBACK WndProc(
     HWND hWnd,
UINT message,
     WPARAM wParam,
     LPARAM lParam
) {
     BYTE cmd;
      switch (message)
      {
            case WM USER+1:
                  \overline{\text{cmd}} = (\text{wParam} >> 8);
                   switch(cmd)
                          case COMMAND SWITCH RELAY ON:
                               // do something
                               break;
                   break;
             default:
                   return DefWindowProc(hWnd, message, wParam, lParam);
      }
```

# UnregisterListener

Unregisters the event window registered by a call to RegisterListener.

### Syntax:

```
VOID WINAPI UnregisterListener(
__in HANDLE hDevice
);
```

### Parameters:

hDevice [in] Device handle	
----------------------------	--

# **Command List**

This is an overview of all available commands.

```
#define CMD SWITCH RELAY ON
                                             0x11
#define CMD SWITCH RELAY OFF
                                             0x12
#define CMD TOGGLE RELAY
                                             0x14
#define CMD QUERY RELAY STATUS
                                             0x18
#define CMD_SET_MANUAL_OPERATION_MODE 0x21
#define CMD_QUERY_MANUAL_OPERATION_MODE 0x22
#define CMD SET MANUAL OPERATION MODE
#define CMD START RELAY TIMER
                                            0x41
#define CMD SET RELAY TIMER DELAY
                                            0x42
#define CMD QUERY TIMER DELAY
                                            0x44
#define CMD BUTTON STATUS
                                            0x50
#define CMD RELAY STATUS
                                             0x51
#define CMD RESET FACTORY DEFAULTS
                                            0x66
#define CMD GET JUMPER STATUS
                                             0x70
#define CMD FIRMWARE VERSION
                                              0x71
```