

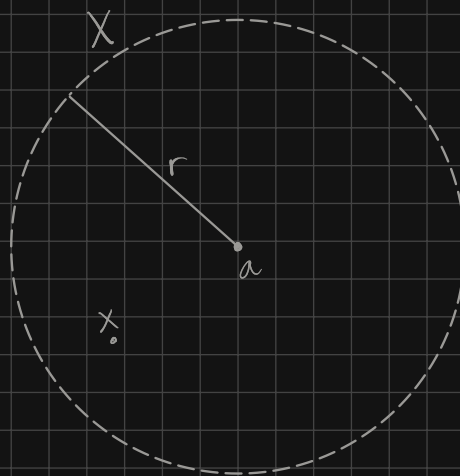
Observe how we used definitions from 3.1.1. As the theory develops, we'll have more and more tools to work with.

We can also phrase the notion of convergence in geometric terms:

If a is an element of a metric space X , and $r > 0$, then the (open) ball centered at a with radius r is the set:

$$B_r(a) = \{x \in X; d(x, a) < r\}$$

So saying $x \in B_r(a)$ is equivalent to saying $d(x, a) < r$.



The def. of convergence can now be rephrased by saying that $\{x_n\}$ converges to a if the elements in the sequence eventually end up inside ANY ball $B_\varepsilon(a)$ centered at a :

$$\forall \varepsilon > 0, \exists N \in \mathbb{N}, \forall n \geq N : x_n \in B_\varepsilon(a) \Leftrightarrow d(x_n, a) < \varepsilon \Leftrightarrow \lim_{n \rightarrow \infty} d(x_n, a) = 0 \Leftrightarrow \lim_{n \rightarrow \infty} x_n = a$$

Next we define the continuity of functions from one metric space to another, by following the same principles as for \mathbb{R}^m (section 2.1).

