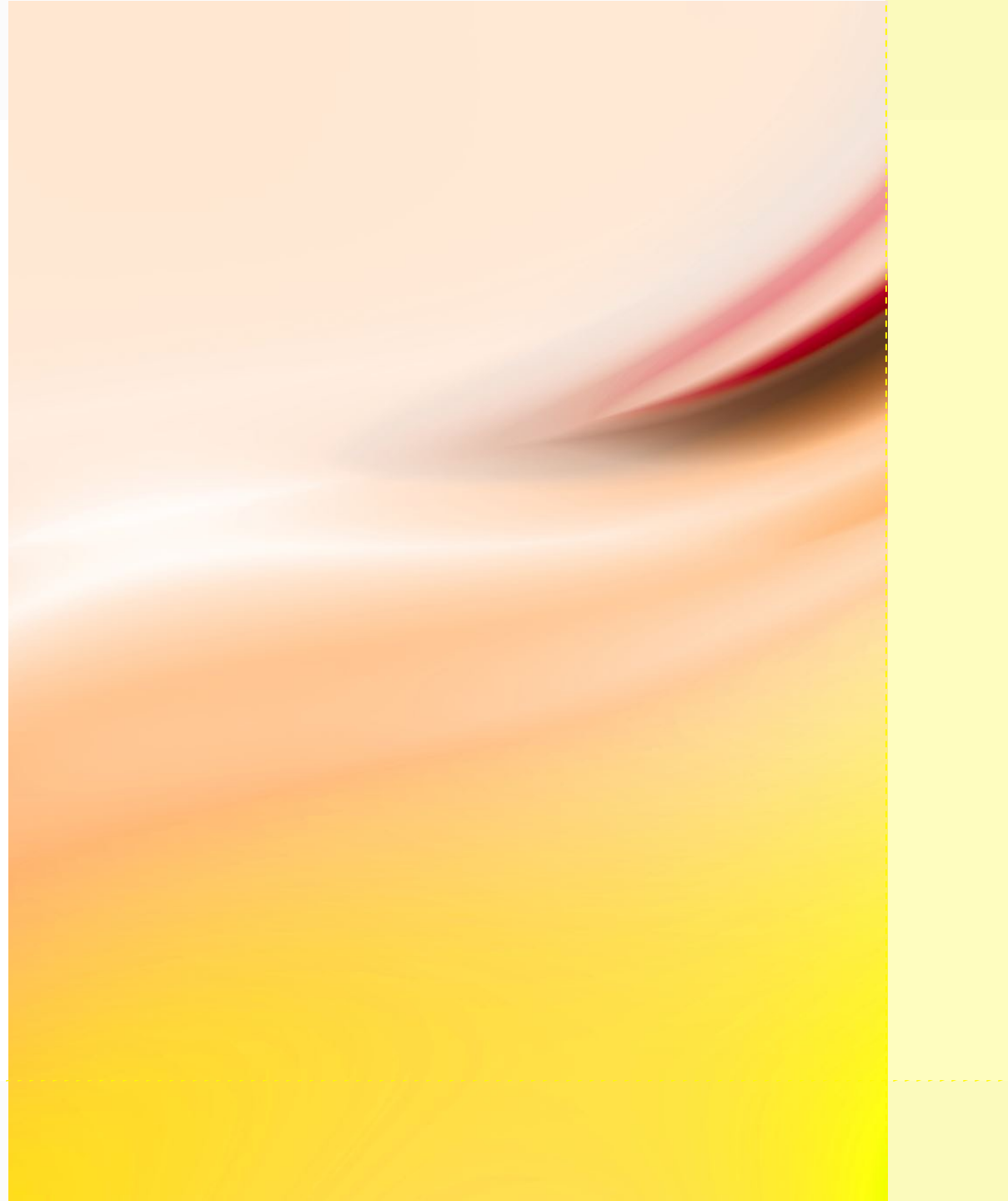
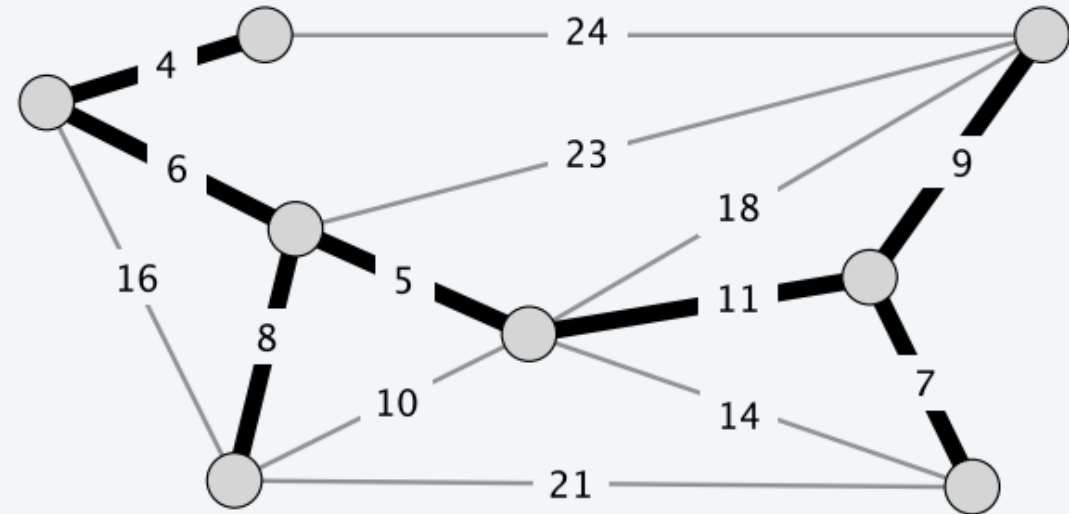


Minimum Spanning Tree



MST (chapter 23)

- Two classic algorithms
 - Kruskal's
 - Requires Data Structure for Disjoint Sets
 - Prim's
 - Requires Priority Queue (Heap)



MST cost = 50 = 4 + 6 + 8 + 5 + 11 + 9 + 7

Applications of MST

- ♦ Design of networks, including computer networks, telecommunications networks, transportation networks, water supply networks, and electrical grids
- ♦ Approximating the traveling salesman problem
- ♦ Approximating the multi-terminal minimum cut problem
- ♦ Approximating the minimum-cost weighted perfect matching
- ♦ Taxonomy
- ♦ Cluster analysis
- ♦ Etc.

Data Structure for Disjoint Sets

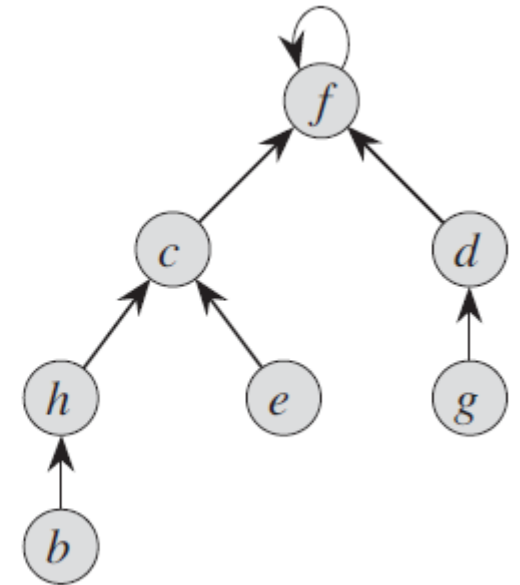
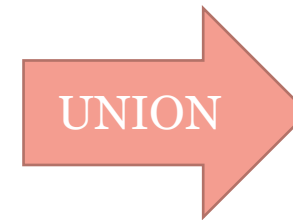
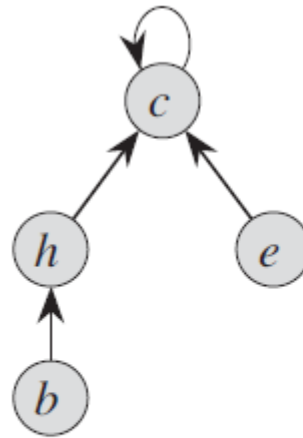
A set is identified by the
representative (a member)

Operations

- **MAKE-SET(x)** creates a new set whose only member.
 - Thus, representative is x .
 - x is not already be in some other set.
- **UNION(x, y)** unites the dynamic sets that contain x and y , say S_x and S_y , into a new set. The representative of the resulting set is any member.
- **FIND-SET(x)** returns the representative of the (unique) set containing x .

Disjoint-Set Forests (sec 21.3, page 568)

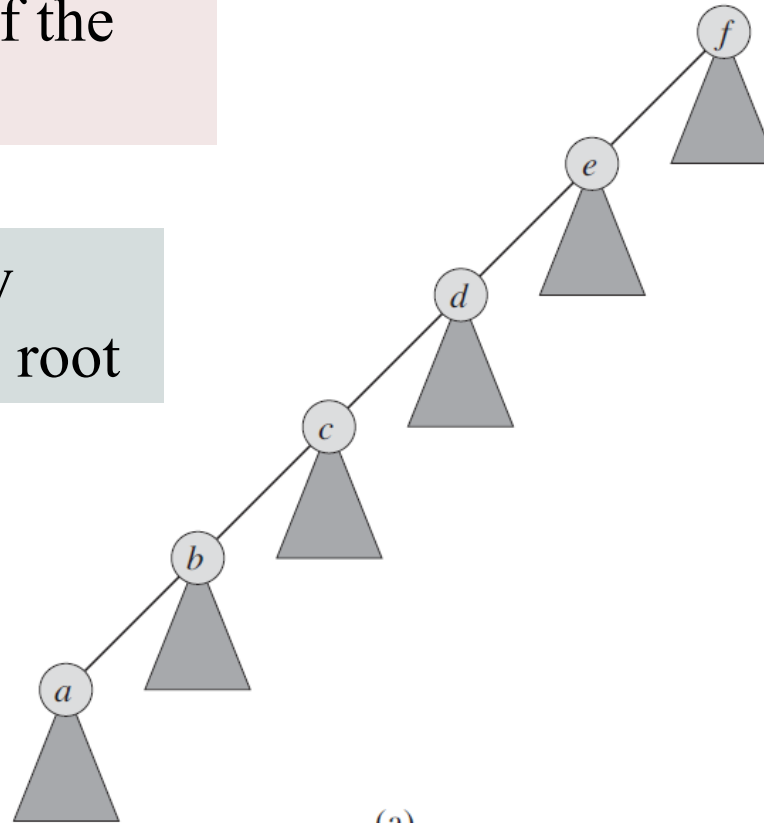
- ♦ $\text{FIND-SET}(b)$ is c
- ♦ $\text{FIND-SET}(g)$ is f
- ♦ “rank” maintains the approximation of subtree height
 - ♦ is not updated by path compression



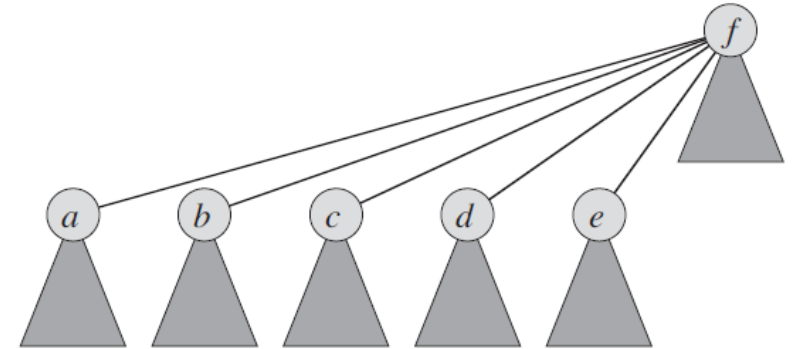
Union by Rank and Path Compression

When Union, make the root with smaller rank become child of the root with larger rank

When Find-set, update every parent on the find-path to be root



(a)



(b)

Kruskal's MST

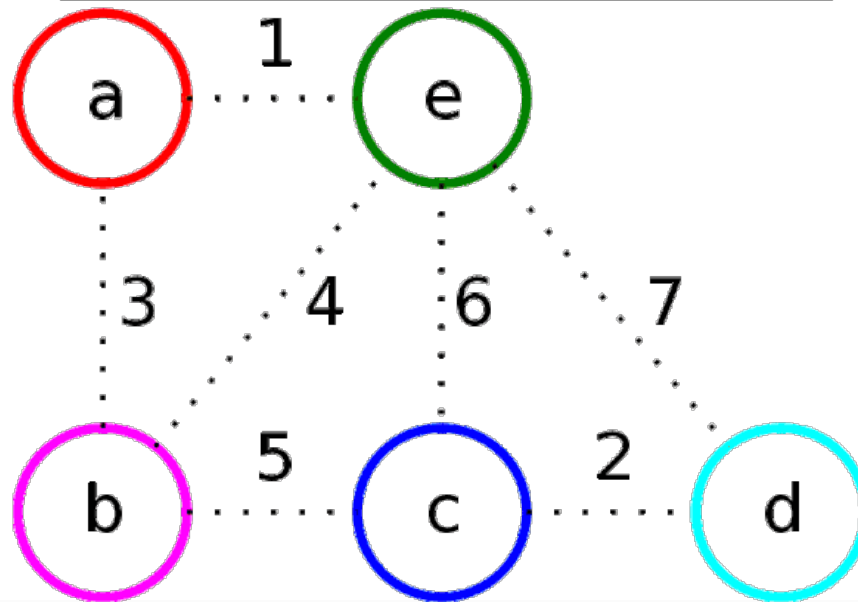
MST-KRUSKAL(G, w)

```
1   $A = \emptyset$ 
2  for each vertex  $v \in G.V$ 
3      MAKE-SET( $v$ )
4  sort the edges of  $G.E$  into nondecreasing order by weight  $w$ 
5  for each edge  $(u, v) \in G.E$ , taken in nondecreasing order by weight
6      if FIND-SET( $u$ )  $\neq$  FIND-SET( $v$ )
7           $A = A \cup \{(u, v)\}$ 
8          UNION( $u, v$ )
9  return  $A$ 
```

- A tree may not contain cycle.
- Disjoint sets are utilized for cycle detection

Kruskal's MST

Edge	ab	ae	bc	be	cd	ed	ec
Weight	3	1	5	4	2	7	6



Prim's MST

MST-PRIM(G, w, r)

```
1  for each  $u \in G.V$ 
2       $u.key = \infty$ 
3       $u.\pi = \text{NIL}$ 
4   $r.key = 0$ 
5   $Q = G.V$ 
6  while  $Q \neq \emptyset$ 
7       $u = \text{EXTRACT-MIN}(Q)$ 
8      for each  $v \in G.Adj[u]$ 
9          if  $v \in Q$  and  $w(u, v) < v.key$ 
10              $v.\pi = u$ 
11              $v.key = w(u, v)$ 
```

Priority Queue is utilized for vertex selection as the priority (value of key) of each vertex changes dynamically

Prim's MST with simple heap

- Simple heap does not support changing value of node's key.
- A vertex may be inserted multiple times with different values of key.
- Once a vertex is extracted, subsequent copy will be ignored.

```
MST-PRIM( $G, w, r$ )
1 for each  $u \in G.V$ 
2    $MST[u] = \text{False}$ 
3    $MinKey[u] = \infty$ 
4  $s.vertex = r$ 
5  $s.key = 0$ 
6  $s.\pi = \text{NIL}$ 
7  $\text{Insert}(PQ, s)$ 
8 while  $PQ \neq \emptyset$ 
9    $t = \text{Extract-Min}(PQ)$ 
10   $u = t.vertex$ 
11  if  $MST[u] = \text{False}$ 
12     $MST[u] = \text{True}$ 
13    for each  $v \in G.Adj[u]$ 
14      if  $MST[v] = \text{False}$  and  $w(u,v) < MinKey[v]$ 
15         $s.vertex = v$ 
16         $s.key = MinKey[v] = w(u,v)$ 
17         $s.\pi = u$ 
18         $\text{Insert}(PQ, s)$ 
```

Prim's MST

SET: { }

