

# PRIM – Micro:bit

## 4-3 Kompass

# Azimut

- Co je to kompas, azimut
- Kalibrace

```
from microbit import *  
compass.calibrate()  
while True:  
    display.show(compass.heading())  
    sleep(1000)
```

# Světová strana

```
from microbit import *
compass.calibrate()
while True:
    uhel = compass.heading()
    if (uhel < 46):
        display.show("S")
    elif (uhel < 136):
        display.show("V")
    elif (uhel < 226):
        display.show("J")
    elif (uhel < 316):
        display.show("Z")
    else:
        display.show("S")
    sleep(1000)
```

# Práce s hodinovými ručičkami

```
from microbit import *  
for uhel in range(0, 12):  
  
    display.show(Image.ALL_CLOCKS[uhel])  
    sleep(1000)  
    display.clear()
```

# Směr sever

```
from microbit import *  
compass.calibrate()  
while True:  
    uhel = ((compass.heading()-15) // 30)  
    display.show(Image.ALL_CLOCKS[uhel])
```