University of Ottawa

Assignment 2 - FIR causal Wiener solution

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ELG5377 - Adaptive Signal Processing

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Setup A

Question 1

X(z) = U(z)T(z)

 $\mathrm{D}\left(z\right)=\;\mathrm{X}\left(z\right)\mathrm{H}\left(z\right)\;+\;\mathrm{V}\left(z\right),$

Y(z) = W(z)X(z)

E(z) = D(z) - Y(z)

In ideal case, the system can predict what's can be predicted, and whatever is left, is unpredictable of x.(i.e v(n) is a part of d(n) which can't be predicted.)

E(z) = D(z) - Y(z) = V(z)

$$W_{\text{opt}}(z) = H(z) = \frac{1}{1 - 0.95 z^{-1}}$$

However, H(z) is an IIR filter, while W(z) has to be FIR filter. So, the best we can do is to approximate H(z) using very long FIR filter. I.e.

$$w_{opt}[n] \ = \ h[n] \, (u[n] - u[n-N]) \ = \ 0.95^n \, (u[n] - u[n-N])$$

Question 2

 ϕ_{XX}

$$\phi_{xx}[l] = \phi_{uu}[l] * t[l] * t[-l]$$

But

$$\mathsf{t}[l] * \mathsf{t}[-l] = \sum_{k=-\infty}^{\infty} \mathsf{t}[l-k] \times \mathsf{t}[-k]$$

$$= \sum_{k=-\infty}^{\infty} 0.98^{l-k} \, \mathbf{u}[l-k] \, 0.98^{-k} \, \mathbf{u}[-k]$$

■ Interval 1: *l* < 0

$$\begin{split} \mathbf{t}[l] * \mathbf{t}[-l] &= \sum_{k=-\infty}^{l} 0.98^{l-k} \times 0.98^{-k} \\ &= 0.98^{l} \times \sum_{k=-\infty}^{l} 0.98^{-2 \, k} \qquad ; \ \mathrm{let} \, v = -k + l \\ &= 0.98^{l} \times \sum_{v=0}^{\infty} 0.98^{-2 \, (l-v)} \\ &= 0.98^{l} \times 0.98^{-2 \, l} \times \sum_{v=0}^{\infty} 0.98^{2 \, v} \\ &= 0.98^{-l} \left(\frac{1}{1 - 0.98^{2}} \right) = 25.25 \times 0.98^{-l} \, \mathbf{u}[-l-1] \\ &= 24.75 \times 0.98^{-l-1} \, \mathbf{u}[-l-1] \end{split}$$

Interval 1: l ≥0

$$t[l] * t[-l] = \sum_{k=-\infty}^{0} 0.98^{l-k} \times 0.98^{-k}$$

$$= 0.98^{l} \times \sum_{k=-\infty}^{0} 0.98^{-2k} \qquad ; let v = -k$$

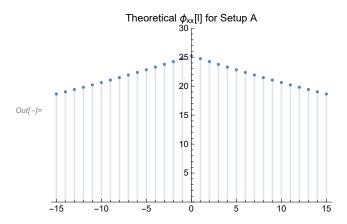
$$= 0.98^{l} \times \sum_{v=0}^{\infty} 0.98^{-2(-v)}$$

$$= 0.98^{l} \times \sum_{v=0}^{\infty} 0.98^{2v}$$

$$= 0.98^{l} \left(\frac{1}{1 - 0.98^{2}}\right) = 25.25 \times 0.98^{l} \text{ u}[l]$$

Substitute

$$\begin{split} \phi_{xx}[l] &= \phi_{uu}[l] * \left(25.25 \times 0.98^l \, u[l] + 25.25 \times 0.98^{-l} \, u[-l-1] \right) \\ &= \sigma_{u}^2 \, \delta[l] * \left(25.25 \times 0.98^l \, u[l] + 25.25 \times 0.98^{-l} \, u[-l-1] \right) \quad ; \ \sigma_{u}^2 = 1 \\ &= 25.25 \left(0.98^l \, u[l] + 0.98^{-l} \, u[-l-1] \right) \end{split}$$



The convolution can also be calculated using the formulas given in the assignment (using z-transform)

$$t[l] * t[-l] = 0.98^{l} u[l] * 0.98^{-l} u[-l]$$

= A 0.98^l u[l] - B 0.98^{-l} u[-l -1]

where

$$A = -B = \frac{1}{1 - 0.98^2} = 25.25$$

■ So

$$t[l] * t[-l] = 25.25 (0.98^{l} u[l] + 0.98^{-l} u[-l-1])$$

ϕ_{dx}

$$\begin{split} \phi_{\rm dx}[l] &= \phi_{\rm xx}[l] * h[l] \\ &= 25.25 \left(0.98^l \, u[l] + 0.98^{-l} \, u[-l-1] \right) * 0.95^l \, u[l] \\ &= 25.25 \left(0.98^l \, u[l] * 0.95^l \, u[l] \right) + 25.25 \left(0.98^{-l} \, u[-l-1] * 0.95^l \, u[l] \right) \end{split}$$

where

$$0.98^{l} u[l] * 0.95^{l} u[l] = IZT \left[\frac{1}{1 - 0.98 z^{-1}} \frac{1}{1 - 0.95 z^{-1}} \right]$$
$$= IZT \left[\frac{A}{1 - 0.98 z^{-1}} + \frac{B}{1 - 0.95 z^{-1}} \right]$$

where

$$A = \left(\frac{1}{1 - 0.95 z^{-1}}\right)_{z=0.98} = 32.6667$$

$$B = \left(\frac{1}{1 - 0.98 z^{-1}}\right)_{z=0.95} = -31.6667$$

substitute

$$0.98^l\,\mathrm{u}[l] \, * \, 0.95^l\,\mathrm{u}[l] = \, 32.6667 \left(0.98^l\,\mathrm{u}[l]\right) - 31.6667 \left(0.95^l\,\mathrm{u}[l]\right)$$

and

$$\begin{split} 0.98^{-l} \ u[-l-1] \ * \ 0.95^l \ u[l] &= \left(0.98^{-l}\right)^{-l} \ u[-l-1] \ * \ 0.95^l \ u[l] \\ &= IZT \Big[\frac{-1}{1-0.98^{-l} \ z^{-1}} \ \frac{1}{1-0.95 \ z^{-1}} \Big] \\ &= IZT \Big[\frac{B}{1-0.98^{-l} \ z^{-1}} + \frac{A}{1-0.95 \ z^{-1}} \ \Big] \end{split}$$

where

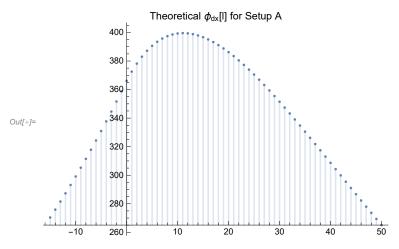
$$A = \left(\frac{1}{1 - 0.98^{-1} z^{-1}}\right)_{z=0.95} = 13.5$$

$$B = \left(\frac{-1}{1 - 0.95 z^{-1}}\right)_{z=0.98^{-1}} = -14.5$$

substitute

$$0.98^{-l} \text{ u}[-l-1] * 0.95^{l} \text{ u}[l] = 14.5 (0.98^{-l} \text{ u}[-l-1]) + 13.5 (0.95^{l} \text{ u}[l])$$

Substitute



 $\phi_{\rm dd}$

$$\begin{split} \phi_{\mathrm{dd}}[l] &= \phi_{\mathrm{xx}}[l] * h[l] * h[-l] + \phi_{\mathrm{vv}}[l] \\ &= \phi_{\mathrm{uu}}[l] * \left(\mathsf{t}[l] * \mathsf{t}[-l] * h[l] * h[-l] \right) + \phi_{\mathrm{vv}}[l] \\ &= \sigma_{\mathrm{u}}^{2} \, \delta[l] * \left(0.98^{l} \, \mathsf{u}[l] * 0.98^{-l} \, \mathsf{u}[-l] * 0.95^{l} \, \mathsf{u}[l] * 0.95^{-l} \, \mathsf{u}[-l] \right) + \sigma_{\mathrm{v}}^{2} \, \delta[l] \\ &= \mathrm{IZT} \Big[\frac{\mathrm{A}}{1 - 0.98 \, \mathrm{z}^{-1}} \, \frac{\mathrm{B}}{1 - 0.98^{-1} \, \mathrm{z}^{-1}} \, \frac{\mathrm{C}}{1 - 0.95 \, \mathrm{z}^{-1}} \, \frac{\mathrm{D}}{1 - 0.95^{-1} \, \mathrm{z}^{-1}} \Big] \, + \, \delta[l] \end{split}$$

where

$$A = \frac{0.98}{(1 - 0.98^2)(0.98 - 0.95)(1 - 0.98 \times 0.95)} = 11955.3$$

$$B = \frac{-0.98}{(1 - 0.98^2)(0.98 - 0.95)(1 - 0.98 \times 0.95)} = -11955.3$$

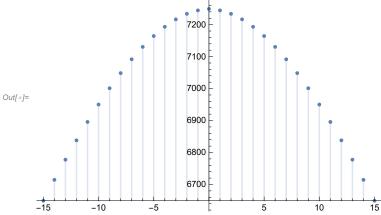
$$C = \frac{-0.95}{(1 - 0.95^2)(0.98 - 0.95)(1 - 0.98 \times 0.95)} = -4707.05$$

$$D = \frac{0.95}{(1 - 0.95^2)(0.98 - 0.95)(1 - 0.98 \times 0.95)} = 4707.05$$

substitute

$$\begin{split} \phi_{\rm dd}[l] &= \phi_{\rm xx}[l] * h[l] * h[-l] + \phi_{\rm vv}[l] \\ &= 11\,955.3\,\big(0.98^l\,{\rm u}[l] + \,0.98^{-l}\,{\rm u}[-l-1]\big) - \\ &\quad 4707.05\,\big(0.95^l\,{\rm u}[l] + \,0.95^{-l}\,{\rm u}[-l-1]\big) + \delta[l] \end{split}$$

Theoretical $\phi_{\text{dd}}[l]$ for Setup A

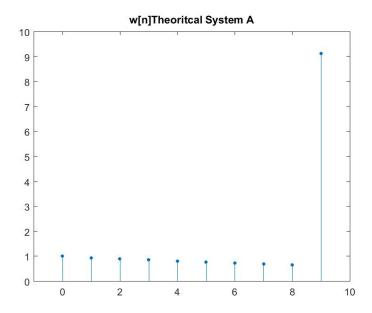


Note

$$\sigma_{\rm d}^2 = \phi_{\rm dd}[0] = 7249.25$$

Theoretical Wopt

 $W_{opt} \, = R^{-1} \, P \,$; the plot is shown below

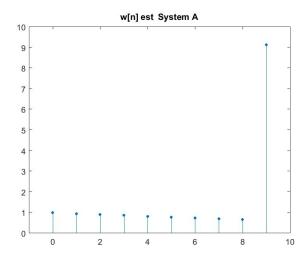


Normalized MMSE =
$$\frac{\sigma_d^2 - P^H R^{-1} P}{\sigma_d^2} = 0.1062$$

- x[n] is colored noise (i.e. is band limited unlike the white noise). h[n] is an IIR filter and $W_{\text{opt}}[n]$ is FIR filter(*i.e.* it has a shorter impuse response).
- Since h[n] is a decaying function, it is possible to approximate the IIR filter using FIR Wiener solution. However, this requires length N to be large enough.
- Using N = 10 samples, as shown above, resulted in poor prediction of h[n] because
 - the number of samples is not enough.
 - W_{opt} is not only trying to model h[n] but also predict the sensor white noise (v[n]).
- This can be observed by looking at the last sample of $w_{out}[n]$. The explanation for this behaviour is as follows:
 - since v[n] is a white noise that should not be included, it's desired that to have a narrow bandwidth FIR Wiener solution. This can be achieved by increasing the filter length (in the time domain).
 - In the case with N = 10 sample, the filter is very short leading to a wideband frequency response. This allows many frequencies from the v[n] to be included (resulting in corrupting w_{opt}).

Question 3

■ The Estimated w_{opt} for Setup A (using MATLAB)



■ The Estimated normalized MMSE for Setup A = 0.1067

Note

• It's noticeable that the Estimate w_{opt} , MMSE agree with the theoretical ones.

System B

Question 1

Let's define B(z) to be the equivalent system of $1 - z^{-1}W(z)$. Then

$$B(z) = \frac{E(z)}{X(z)}$$

$$= \frac{D(z) - Y(z)}{X(z)} = \frac{X(z) - Y(z)}{X(z)}$$

$$= 1 - \frac{Y(z)}{X(z)}$$

$$= 1 - \frac{X(z)Z^{-1}W(z)}{X(z)}$$

$$= 1 - Z^{-1}W(z)$$

Since U (z), E (z) are white noise, then:

$$B(z) = T^{-1}(z)$$

$$1 - Z^{-1}W(z) = \frac{1}{T(z)} = 1 - 0.98 Z^{-1}$$

$$W(z) = 0.98$$

$$w(n) = 0.98 \delta(n)$$

In ideal case, Current signal can be predicted from past sample, and the error will be white noise.

Question 2



 ϕ_{xx} should be calculated at the input of Wiener filter w[n] (i.e. from x[n-1] not x[n]). However, since the delay system has an impulse response of $\delta[l-1]$.

Then $\delta[l-1] * \delta[-l-1] = \delta[l]$. i.e. calculating the correlation from x[n-1] is the same as correlation from x[n].

$$\begin{split} \phi_{\rm xx}[l] &= \phi_{\rm uu}[l] * {\rm t}[l] * {\rm t}^*[-l] \\ &= 25.25 \left(0.98^l \ {\rm u}[l] \ + \ 0.98^{-l} \ \ {\rm u}[-l-1] \right) \quad ; \ {\rm from \, Setup \, A} \end{split}$$

$\phi_{\rm dx}$

The relationship between d[n] and x[n-1] is shown below

$$\phi_{\rm dx}[l] = \phi_{\rm xx}[l] * \delta[l+1]$$

$$= \phi_{\rm xx}(l+1)$$

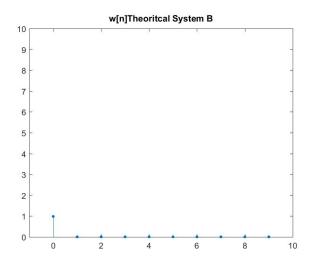
$$= 25.25 \left(0.98^{l+1} \ u[l+1] + 0.98^{-l-1} \ u[-l-2]\right)$$

$\phi_{\rm dd}$

$$\begin{split} \phi_{\rm dd}[l] &= \phi_{\rm xx}[l] \, * \, \delta[l] \, * \, \delta[-l] \\ &= \phi_{\rm xx}[l] \\ &= \, 25.25 \, \big(\, 0.98^l \, {\rm u}[l] \, + \, 0.98^{-l} \, \, {\rm u}[-l-1] \big) \quad ; \, {\rm from \, Setup \, A} \end{split}$$

Theoretical Wopt

 $W_{\text{opt}} = R^{-1} P$; the plot is shown below

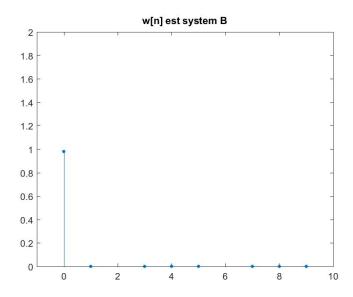


Normalized MMSE =
$$\frac{\sigma_d^2 - P^H R^{-1} P}{\sigma_d^2} = 0.0396$$

• As we can see, the Wiener solution agrees with the solution in Question 1. Only one sample is required to predict the next sample of x[n] from its previous value x[n-1] (i.e. $w_{opt}[n] = 0.98 \delta[n]$)

Question 3

■ The Estimated Wiener solution w_{opt} for Setup A (using MATLAB)



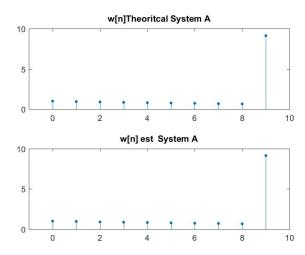
■ The Estimated normalized MMSE for Setup B = 0.0395

• It's noticeable that the Estimate w_{opt} , MMSE agree with the theoretical ones.

Appendix

Below is a side-by-side comparison of the theoretical and estimated solution for setup A and B.

Setup A



Setup B

