world Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 292.031 (-0.488 sec old) Buffer length: 4.940 sec base_link Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 291.538 (0.005 sec old) Buffer length: 4.940 sec $link_1$ Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 291.538 (0.005 sec old) Buffer length: 4.940 sec link_2 Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 291.538 (0.005 sec old) Buffer length: 4.940 sec link_3 Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 291.538 (0.005 sec old) Buffer length: 4.940 sec link_4 Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 291.538 (0.005 sec old) Buffer length: 4.940 sec link_5 Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 291.538 (0.005 sec old) Buffer length: 4.940 sec link_6 Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Most recent transform: 292.031 (-0.488 sec old) Buffer length: 4.940 sec end_effector Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.202 Hz Average rate: 50.202 Hz Most recent transform: 292.031 (-0.488 sec old) Most recent transform: 291.538 (0.005 sec old) Buffer length: 4.940 sec Buffer length: 4.940 sec end_frame camera_link

view_frames Result

Recorded at time: 291.543