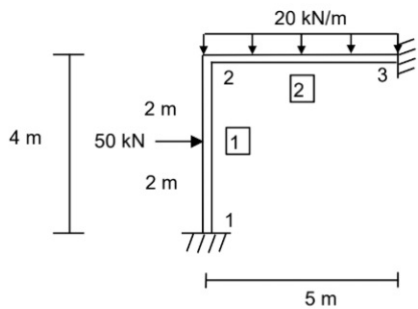


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Determine the reactions and member end forces for the frame shown by using the matrix stiffness method.



$$E = 200 \text{ GPa}$$

$$I = 400 \times 10^6 \text{ mm}^4$$

$$A = 7500 \text{ mm}^2$$

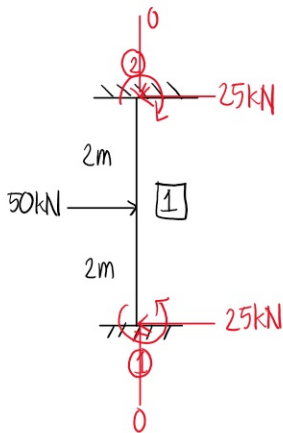
$$E = 200 \text{ GPa} (1000^2) = 200 \times 10^6 \text{ kPa}$$

$$I = 400 \times 10^6 \text{ mm}^4 \left( \frac{1}{1000^4} \right) = 0.0004 \text{ m}^4$$

$$A = 7500 \left( \frac{1}{1000^2} \right) = 0.0075 \text{ m}^2$$

$$L_1 = 4 \text{ m}$$

$$L_2 = 5 \text{ m}$$



$$Q_{f1} = -\frac{50}{2} = -25 = Q_{f4}$$

$$Q_{f2} = Q_{f5} = 0$$

$$Q_{f3} = Q_{f6} = \frac{50(2)(2)}{4^2} = 25 \text{ kN} \cdot \text{m}$$

$$F_{f1} = \begin{bmatrix} -25 \\ 0 \\ 25 \\ -25 \\ 0 \\ -25 \end{bmatrix} \begin{matrix} 0 \\ 0 \\ 0 \\ 1 \\ 2 \\ 3 \end{matrix}$$

$$\begin{matrix} 0 & 0 & 0 & 1 & 2 & 3 \end{matrix}$$

$$k_1 = \frac{EI}{L_1^3} \begin{bmatrix} \frac{AL^2}{I} & 0 & 0 & -\frac{AL^2}{I} & 0 & 0 \\ 0 & 12 & 6L & 0 & -12 & 6L \\ 0 & 6L & 4L^2 & 0 & -6L & 2L^2 \\ -\frac{AL^2}{I} & 0 & 0 & \frac{AL^2}{I} & 0 & 0 \\ 0 & -12 & -6L & 0 & 12 & -6L \\ 0 & 6L & 2L^2 & 0 & -6L & 4L^2 \end{bmatrix} = \begin{bmatrix} 37500 & 0 & 0 & -375000 & 0 & 0 \\ 0 & 15000 & 30000 & 0 & -15000 & 30000 \\ 0 & 30000 & 80000 & 0 & -30000 & 40000 \\ -37500 & 0 & 0 & 375000 & 0 & 0 \\ 0 & -15000 & -30000 & 0 & 15000 & -30000 \\ 0 & 30000 & 40000 & 0 & -30000 & 80000 \end{bmatrix} \begin{matrix} 0 \\ 0 \\ 0 \\ 1 \\ 2 \\ 3 \end{matrix}$$

$$\cos \theta = 0$$

$$\sin \theta = 1 \text{ (vertical member)}$$

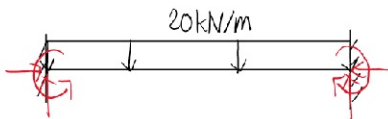
$$T = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T^T = \begin{bmatrix} 0 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

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$$K_1 = T^T k \cdot T = \begin{bmatrix} 0 & -1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 37500 & 0 & 0 & -375000 & 0 & 0 \\ 0 & 15000 & 30000 & 0 & -15000 & 30000 \\ 0 & 30000 & 80000 & 0 & -30000 & 40000 \\ -37500 & 0 & 0 & 375000 & 0 & 0 \\ 0 & -15000 & -30000 & 0 & 15000 & -30000 \\ 0 & 30000 & 40000 & 0 & -30000 & 80000 \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 15000 & 0 & -30000 & -15000 & 0 & -30000 \\ 0 & 375000 & 0 & 0 & -375000 & 0 \\ -30000 & 0 & 80000 & 30000 & 0 & 40000 \\ -15000 & 0 & 30000 & 15000 & 0 & 30000 \\ 0 & -375000 & 0 & 0 & 375000 & 0 \\ -30000 & 0 & 40000 & 30000 & 0 & 80000 \end{bmatrix} \begin{matrix} 0 \\ 0 \\ 0 \\ 1 \\ 2 \\ 3 \end{matrix}$$



$$Qf_1 = 0$$

$$Qf_2 = \frac{20(5)}{2} = 50$$

$$Qf_3 = \frac{20(5)^2}{12} = 41.67$$

$$Qf_4 = 0$$

$$Qf_5 = 50$$

$$Qf_6 = -Qf_3 = -41.67$$

$$Ff_2 = \begin{bmatrix} 0 \\ 50 \\ 41.67 \\ 0 \\ 50 \\ -41.67 \end{bmatrix} \begin{matrix} 1 \\ 2 \\ 3 \\ 0 \\ 0 \\ 0 \end{matrix}$$

$$k_2 = \frac{EI}{L^3} \begin{bmatrix} \frac{AL^2}{I} & 0 & 0 & -\frac{AL^2}{I} & 0 & 0 \\ 0 & 12 & 6L & 0 & -12 & 6L \\ 0 & 6L & 4L^2 & 0 & -6L & 2L^2 \\ -\frac{AL^2}{I} & 0 & 0 & \frac{AL^2}{I} & 0 & 0 \\ 0 & -12 & -6L & 0 & 12 & -6L \\ 0 & 6L & 2L^2 & 0 & -6L & 4L^2 \end{bmatrix} = \begin{bmatrix} 300000 & 0 & 0 & -300000 & 0 & 0 \\ 0 & 7680 & 19200 & 0 & -7680 & 19200 \\ 0 & 19200 & 64000 & 0 & -19200 & 32000 \\ -300000 & 0 & 0 & 300000 & 0 & 0 \\ 0 & -7680 & -19200 & 0 & 7680 & -19200 \\ 0 & 19200 & 32000 & 0 & -19200 & 64000 \end{bmatrix} \begin{matrix} 1 \\ 2 \\ 3 \\ 0 \\ 0 \\ 0 \end{matrix}$$

$$Ff_1 = 0$$

Joint Load Vector:

$$P_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \begin{matrix} 1 \\ 2 \\ 3 \end{matrix}$$

Fixed-Joint Force Vector:

$$P_f = Ff_1 + Ff_2$$

$$P_f = \begin{bmatrix} -25 + 0 \\ 0 + 50 \\ -25 + 41.67 \end{bmatrix} = \begin{bmatrix} -25 \\ 50 \\ 16.67 \end{bmatrix}$$

$$S = \begin{bmatrix} 15000 + 300000 & 0 + 0 & 30000 + 0 \\ 0 + 0 & 375000 + 7680 & 0 + 19200 \\ 30000 + 0 & 0 + 19200 & 80000 + 64000 \end{bmatrix} = \begin{bmatrix} 315000 & 0 & 30000 \\ 0 & 382680 & 19200 \\ 30000 & 19200 & 144000 \end{bmatrix} \begin{matrix} 1 \\ 2 \\ 3 \end{matrix}$$

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$$P - P_f = Sd$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} -25 \\ 50 \\ 16.67 \end{bmatrix} = \begin{bmatrix} 115000 & 0 & 30000 \\ 0 & 382680 & 19200 \\ 30000 & 19200 & 141000 \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix}$$

$$\begin{aligned} d_1 &= 0.0000906 \text{ mm} \\ d_2 &= -0.000125 \text{ mm} \\ d_3 &= -0.000118 \text{ rad} \end{aligned} //$$

$$U_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0.0000906 \\ -0.000125 \\ -0.000118 \end{bmatrix}$$

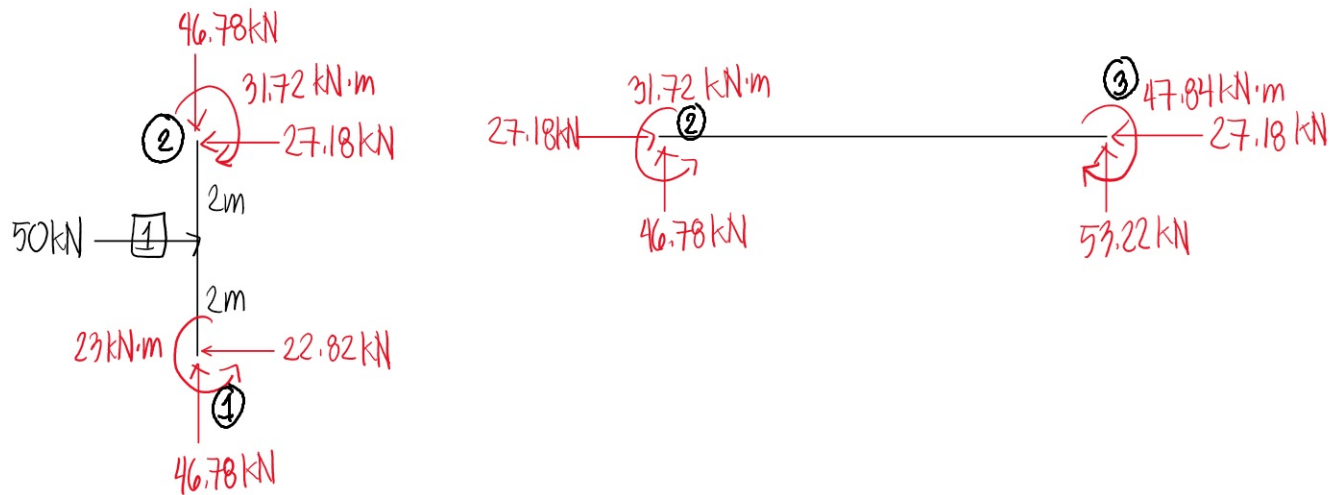
$$U_2 = \begin{bmatrix} 0.0000906 \\ -0.000125 \\ -0.000118 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$Q = K_u + Q_f$$

$$Q_1 = \begin{bmatrix} 15000 & 0 & -30000 & -15000 & 0 & -30000 \\ 0 & 775000 & 0 & 0 & -775000 & 0 \\ -30000 & 0 & 80000 & 30000 & 0 & 40000 \\ -15000 & 0 & 30000 & 15000 & 0 & 30000 \\ 0 & -775000 & 0 & 0 & 775000 & 0 \\ -30000 & 0 & 40000 & 30000 & 0 & 80000 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0.0000906 \\ -0.000125 \\ -0.000118 \end{bmatrix} + \begin{bmatrix} -25 \\ 0 \\ 25 \\ -25 \\ 0 \\ -25 \end{bmatrix} = \begin{bmatrix} -22.82 \\ 46.78 \\ 23 \\ -27.18 \\ -46.78 \\ -31.72 \end{bmatrix}$$

$$Q_2 = \begin{bmatrix} 300000 & 0 & 0 & -300000 & 0 & 0 \\ 0 & 7680 & 19200 & 0 & -7680 & 19200 \\ 0 & 19200 & 64000 & 0 & -19200 & 32000 \\ -300000 & 0 & 0 & 300000 & 0 & 0 \\ 0 & -7680 & -19200 & 0 & 7680 & -19200 \\ 0 & 19200 & 32000 & 0 & -19200 & 64000 \end{bmatrix} \begin{bmatrix} 0.0000906 \\ -0.000125 \\ -0.000118 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 50 \\ 41.67 \\ 0 \\ 50 \\ -41.67 \end{bmatrix} = \begin{bmatrix} 27.18 \\ 46.78 \\ 31.72 \\ -27.18 \\ 53.22 \\ -47.84 \end{bmatrix}$$

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Original Beam

