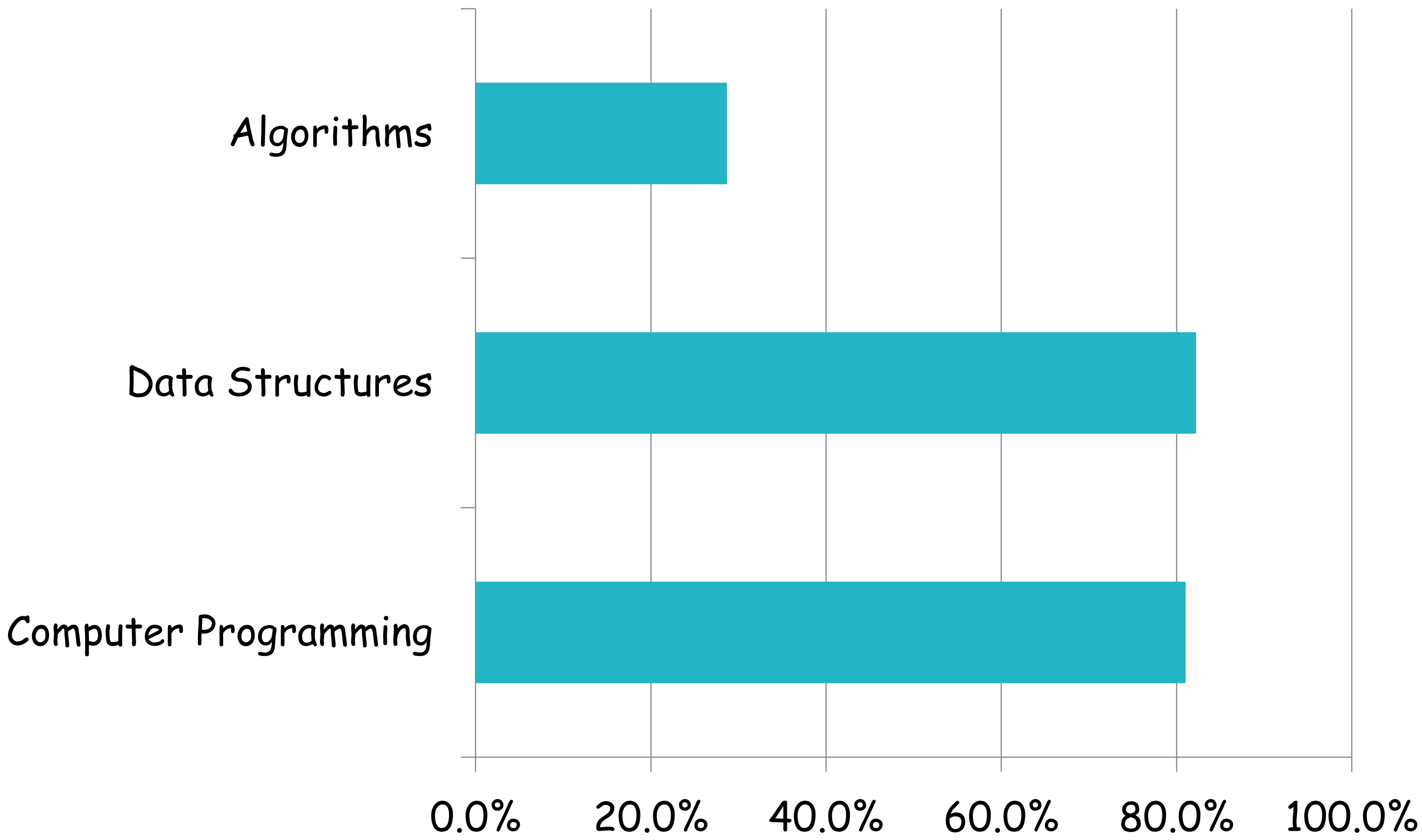
Announcement

Forum

- Piazza
- Blackboard Forum

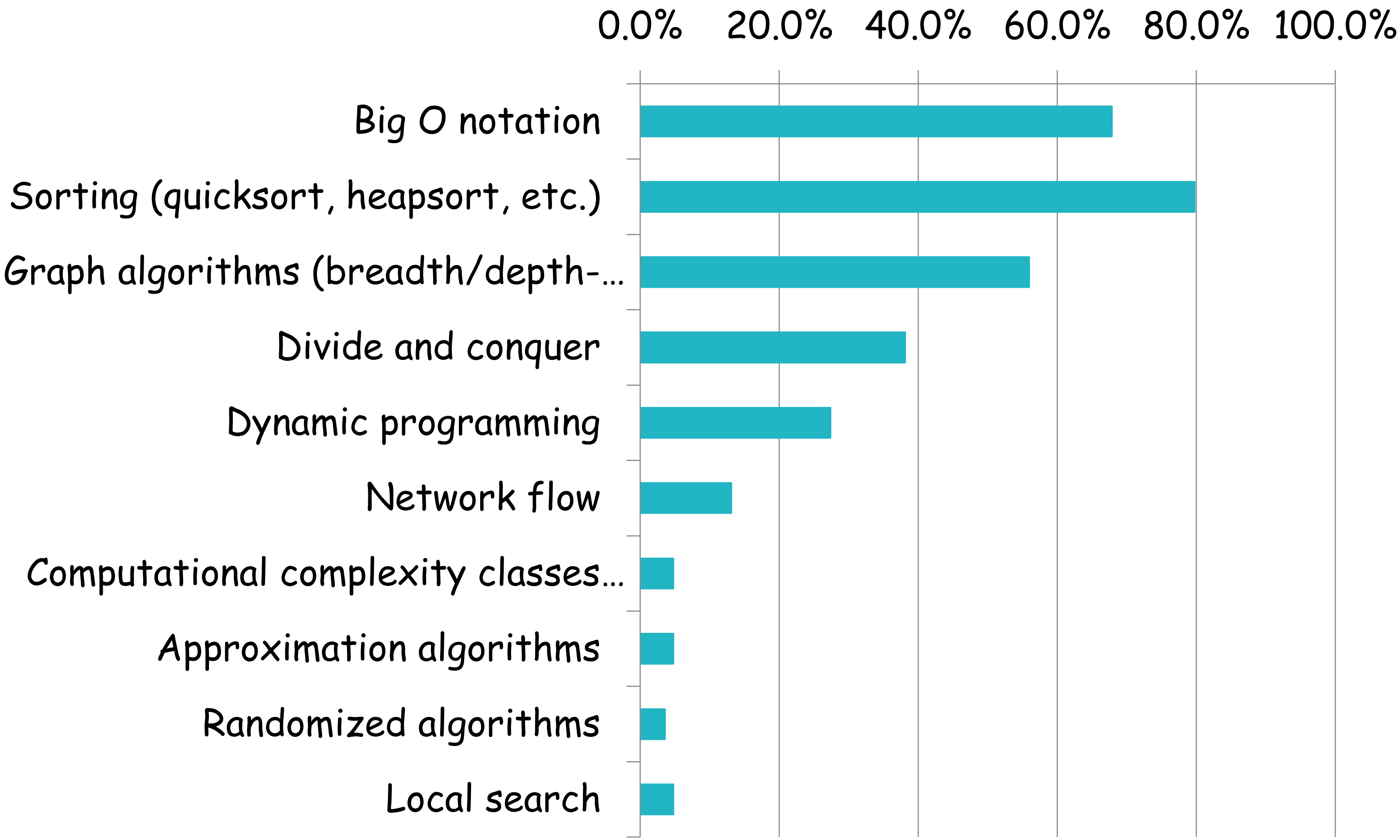
Survey Results

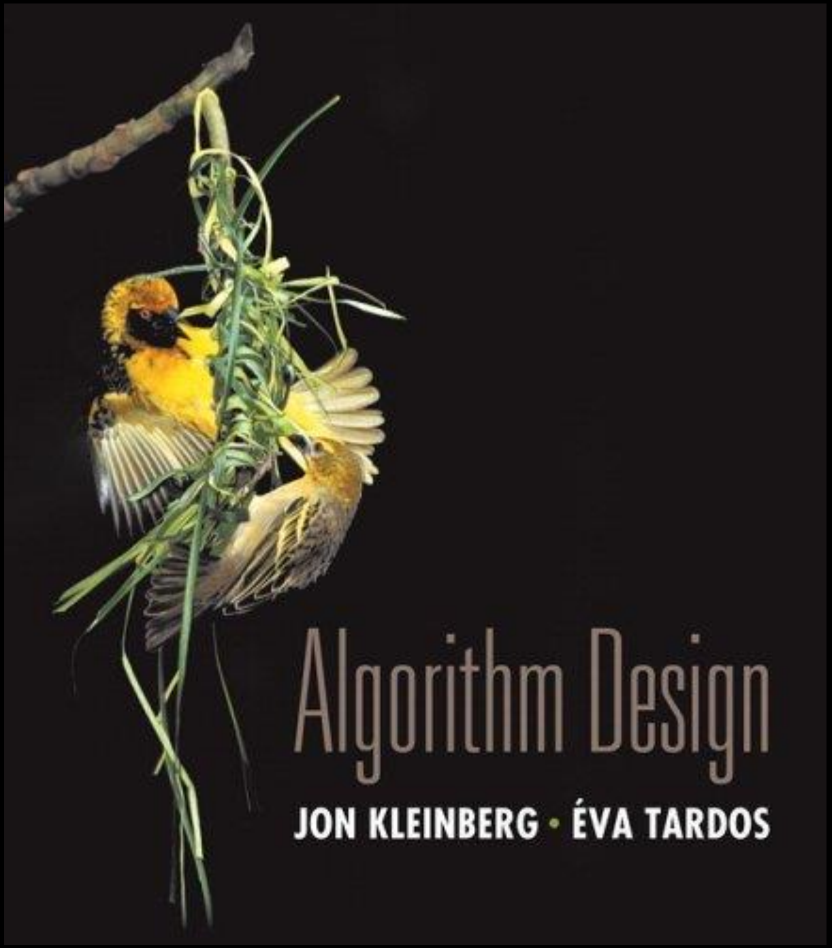
Select the subjects that you have learned in your undergraduate studies.



Survey Results

Select the concepts in algorithm design that you have a good understanding of.





Chapter 3

Graphs

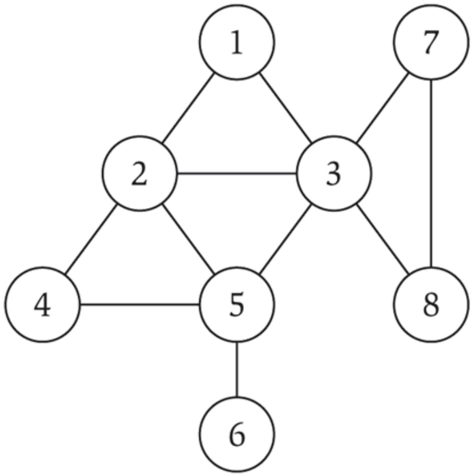
Slides by Kevin Wayne.

3.1 Basic Definitions and Applications

Undirected Graphs

Undirected graph. $G = (V, E)$

- V = nodes.
- E = edges between pairs of nodes.
- Captures pairwise relationship between objects.
- Graph size parameters: $n = |V|$, $m = |E|$.



$V = \{ 1, 2, 3, 4, 5, 6, 7, 8 \}$

$E = \{ 1\text{-}2, 1\text{-}3, 2\text{-}3, 2\text{-}4, 2\text{-}5, 3\text{-}5, 3\text{-}7, 3\text{-}8, 4\text{-}5, 5\text{-}6 \}$

$n = 8$

$m = 11$

9-11 Terrorist Network

Social network graph.

- Node: people.
- Edge: relationship between two people.

Reference: Valdis Krebs, http://www.firstmonday.org/issues/issue7_4/krebs

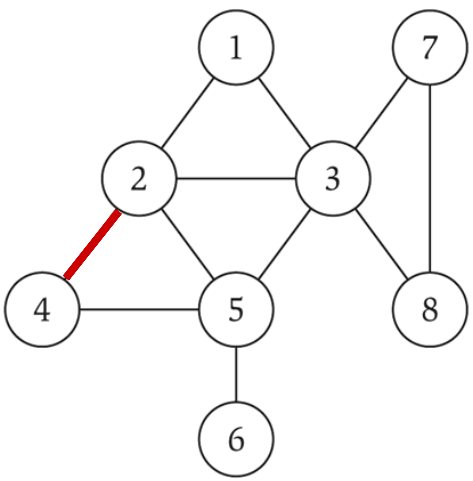
Some Graph Applications

Graph	*Nodes*	*Edges*
transportation	street intersections	highways
communication	computers	fiber optic cables
World Wide Web	web pages	hyperlinks
social	people	relationships
food web	species	predator-prey
software systems	functions	function calls
scheduling	tasks	precedence constraints
circuits	gates	wires

Graph Representation: Adjacency Matrix

Adjacency matrix. n-by-n matrix with $A_{uv} = 1$ if (u, v) is an edge.

- Two representations of each edge.
- Space proportional to n^2.
- Checking if (u, v) is an edge takes $\Theta(1)$ time.
- Identifying all edges takes $\Theta(n^2)$ time.



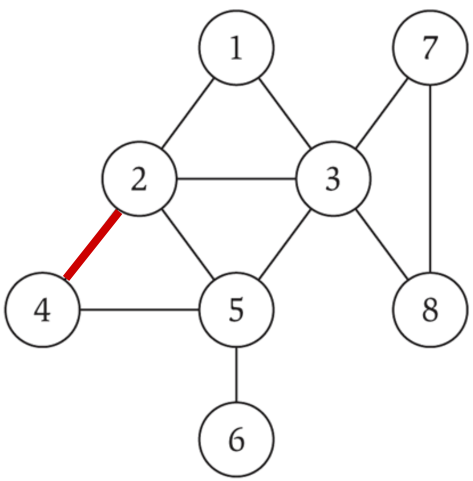
	1	2	3	4	5	6	7	8
1	0	1	1	0	0	0	0	0
2	1	0	1	1	1	0	0	0
3	1	1	0	0	1	0	1	1
4	0	1	0	1	1	0	0	0
5	0	1	1	1	0	1	0	0
6	0	0	0	0	1	0	0	0
7	0	0	1	0	0	0	0	1
8	0	0	1	0	0	0	1	0

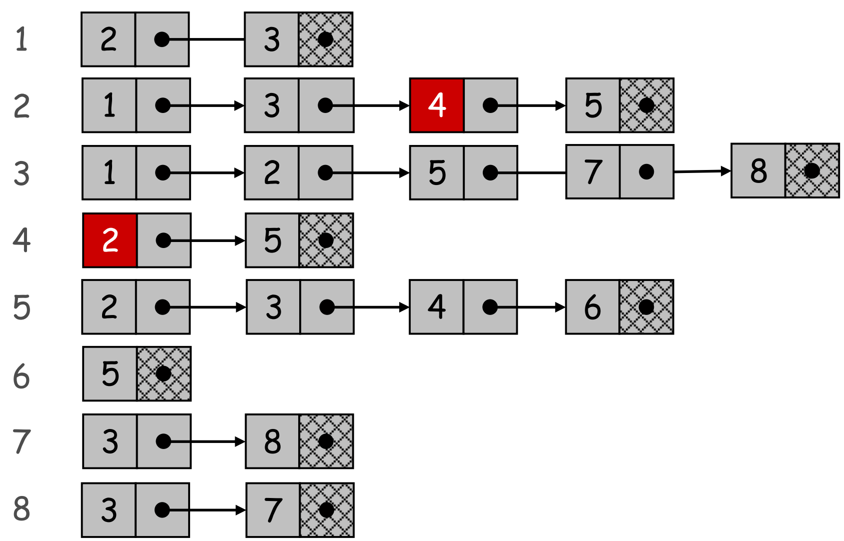
Graph Representation: Adjacency List

Adjacency list. Node indexed array of lists.

- Two representations of each edge.
- Space proportional to m + n.
- Checking if (u, v) is an edge takes O(deg(u)) time.
- Identifying all edges takes Θ(m + n) time.

degree = number of neighbors of u



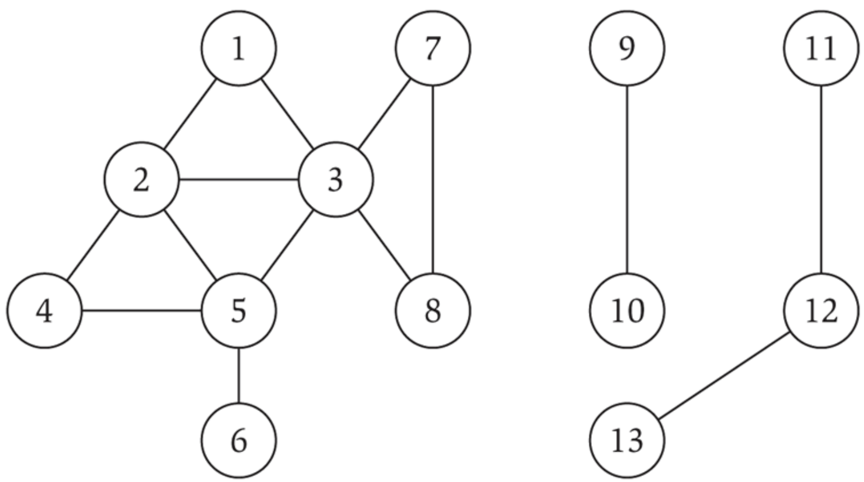


Paths and Connectivity

Def. A path in an undirected graph $G = (V, E)$ is a sequence P of nodes $v_1, v_2, \ldots, v_{k-1}, v_k$ with the property that each consecutive pair v_i, v_{i+1} is joined by an edge in E.

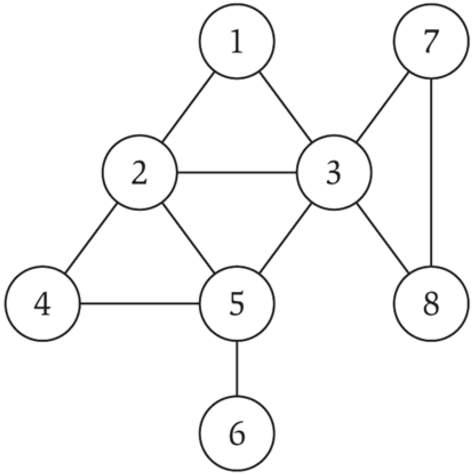
Def. A path is simple if all nodes are distinct.

Def. An undirected graph is connected if for every pair of nodes u and v, there is a path between u and v.



Cycles

Def. A cycle is a path $v_1, v_2, \ldots, v_{k-1}, v_k$ in which $v_1 = v_k$, $k > 2$, and the first $k-1$ nodes are all distinct.



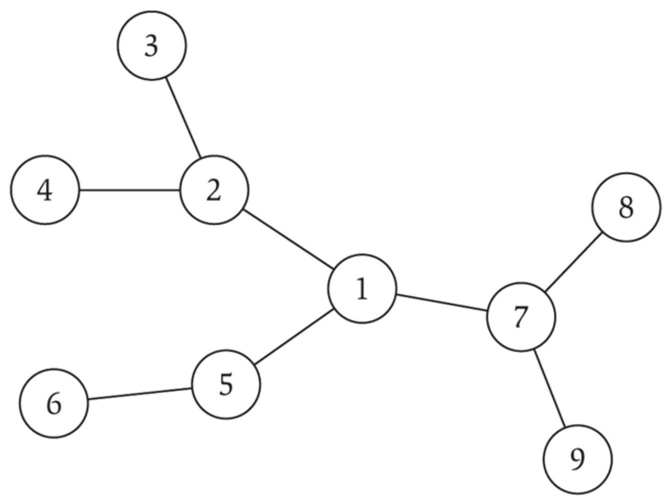
cycle C = 1-2-4-5-3-1

Trees

Def. An undirected graph is a tree if it is connected and does not contain a cycle.

Theorem. Let G be an undirected graph on n nodes. Any two of the following statements imply the third.

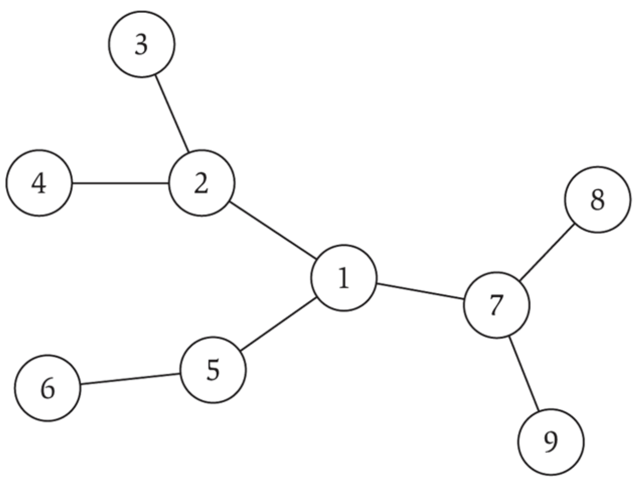
- G is connected.
- G does not contain a cycle.
- G has n-1 edges.



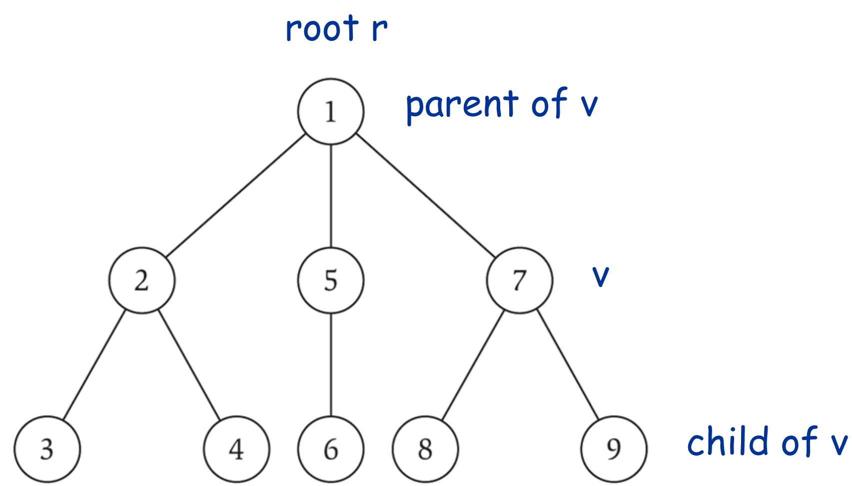
Rooted Trees

Rooted tree. Given a tree T, choose a root node r and orient each edge away from r.

Importance. Models hierarchical structure.



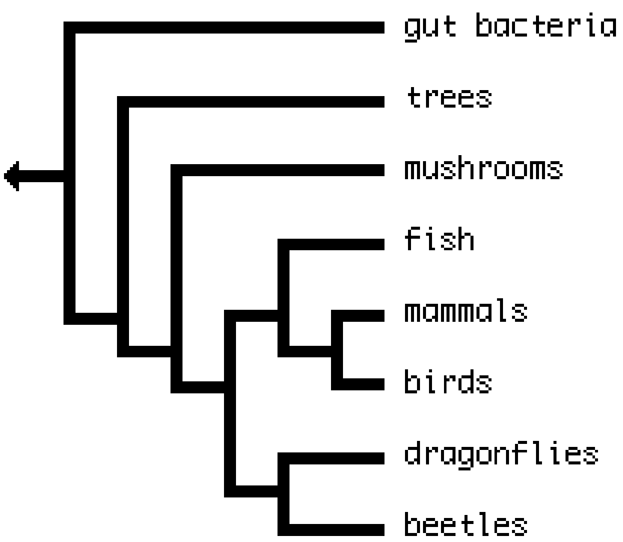
a tree



the same tree, rooted at 1

Phylogeny Trees

Phylogeny trees. Describe evolutionary history of species.



3.2 Graph Traversal

Connectivity

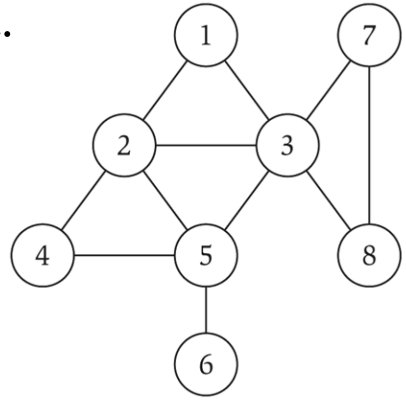
s-t connectivity problem. Given two node s and t, is there a path between s and t?

s-t shortest path problem. Given two node s and t, what is the length of the shortest path between s and t?

Def. The distance between two nodes s and t is the length of the shortest path between them.

Applications.

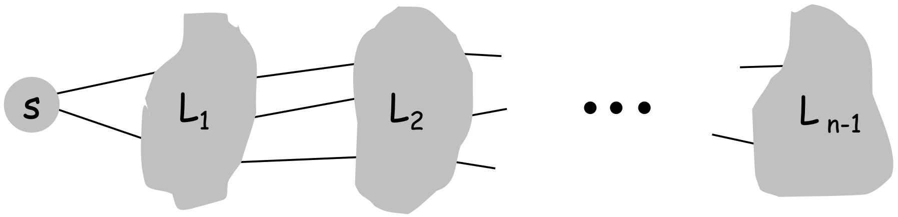
- Maze traversal.
- Fewest number of hops in a communication network.
- Driving direction in Google Maps



Breadth First Search

BFS intuition. Explore outward from s in all possible directions, adding nodes one "layer" at a time.

BFS algorithm.

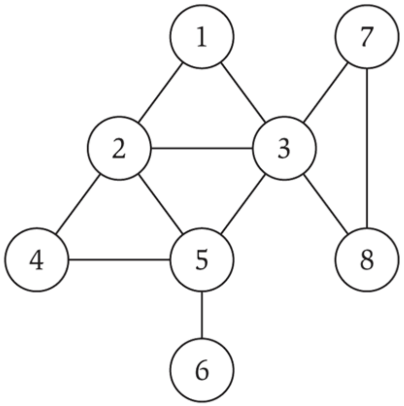


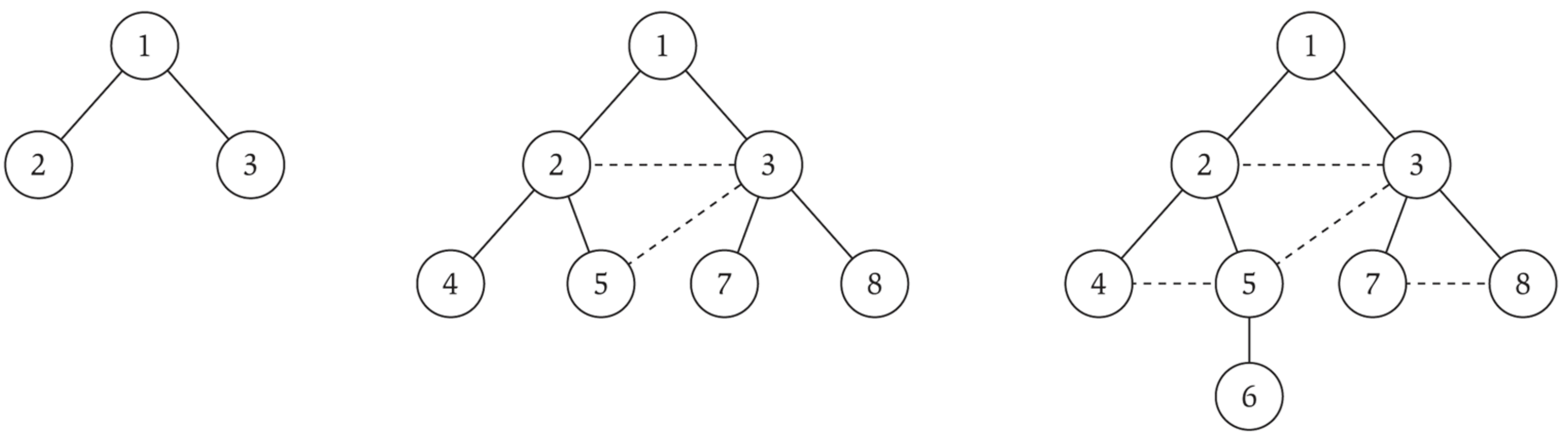
- $L_0 = \{ s \}$.
- L_1 = all neighbors of L_0.
- L_2 = all nodes that do not belong to L_0 or L_1, and that have an edge to a node in L_1.
- L_{i+1} = all nodes that do not belong to an earlier layer, and that have an edge to a node in L_i.

Theorem. For each i, L_i consists of all nodes at distance exactly i from s. There is a path from s to t iff t appears in some layer.

Property. Let (x, y) be an edge of G. Then the level of x and y differ by at most 1.

Breadth First Search





L_0

L_1

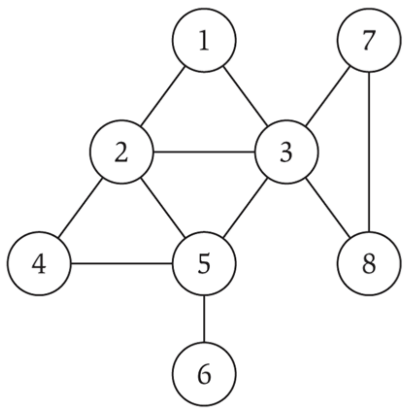
L_2

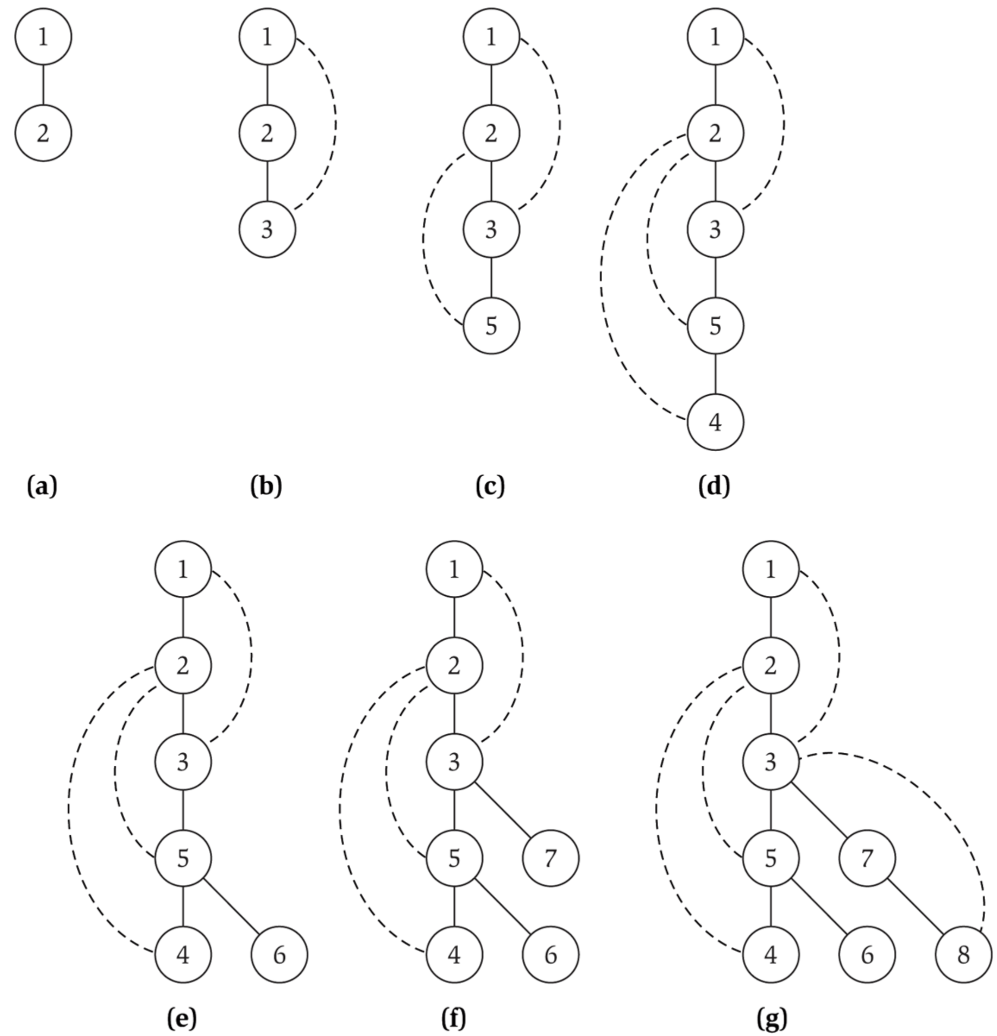
L_3

Depth First Search

DFS intuition. Starts at s and explores as far as possible along each branch before backtracking.

Depth First Search





BFS/DFS: Analysis

Theorem. BFS/DFS runs in $O(m + n)$ time if the graph is given by its adjacency list representation.

Pf.

Initialization of all the nodes takes $O(n)$ time.

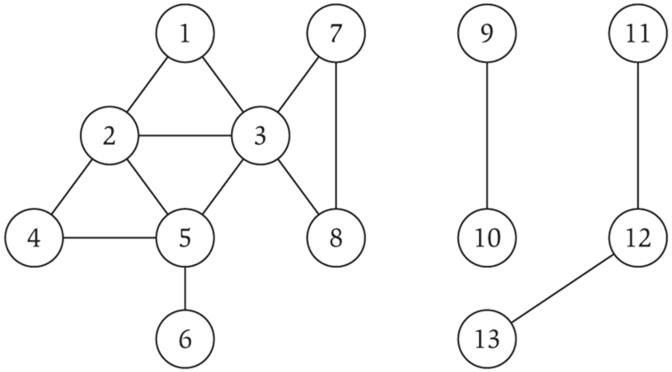
When visiting each node, we check all the edges connected to it

- when we consider node u, there are deg(u) edges
- total time processing edges is $\Sigma_{u \in V} \deg(u) = 2m$

each edge (u, v) is counted exactly twice in sum: once in deg(u) and once in deg(v)

Connected Component

Connected component. Find all nodes reachable from s.



Connected component containing node 1 = { 1, 2, 3, 4, 5, 6, 7, 8 }.

Approach: BFS/DFS from s

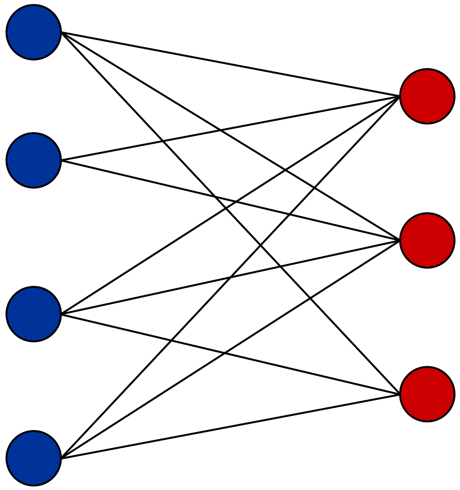
3.4 Testing Bipartiteness

Bipartite Graphs

Def. An undirected graph G = (V, E) is bipartite if the nodes can be colored red or blue such that every edge has one red and one blue end.

Applications.

- Stable marriage: men = red, women = blue.
- Scheduling: machines = red, jobs = blue.

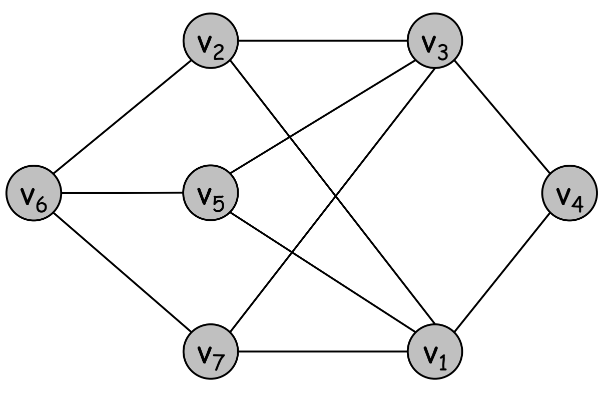


a bipartite graph

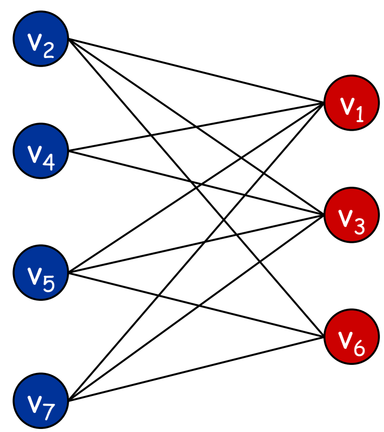
Testing Bipartiteness

Testing bipartiteness. Given a graph G, is it bipartite?

- Many graph problems become:
  - easier if the underlying graph is bipartite (matching)
  - tractable if the underlying graph is bipartite (independent set)
- Before attempting to design an algorithm, we need to understand structure of bipartite graphs.



a bipartite graph G

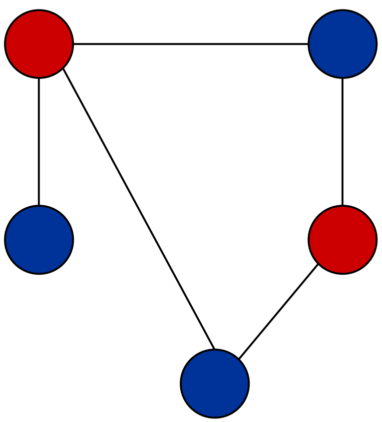


another drawing of G

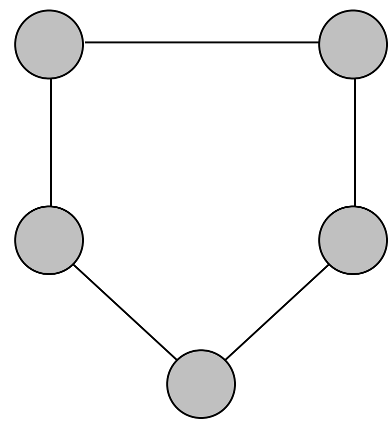
An Obstruction to Bipartiteness

Lemma. If a graph G is bipartite, it cannot contain an odd length cycle.

Pf. Not possible to 2-color the odd cycle, let alone G.



bipartite
(2-colorable)



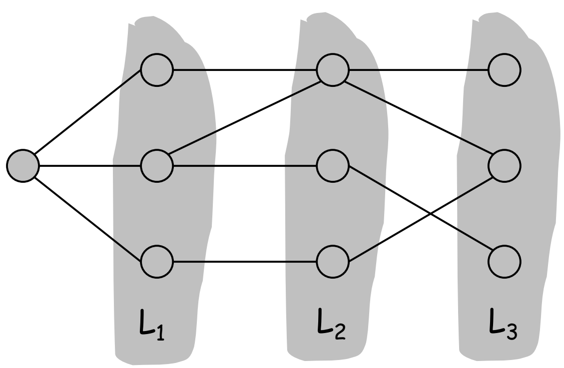
not bipartite
(not 2-colorable)

Bipartite Graphs

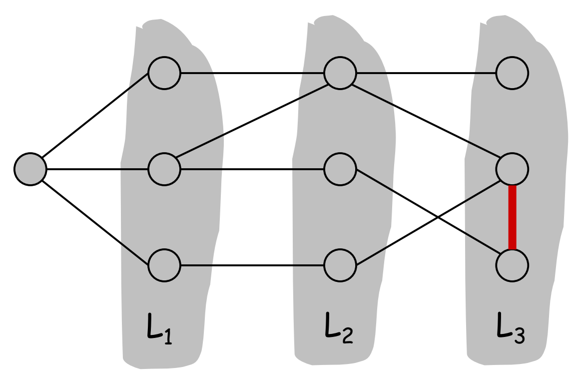
Lemma. Let G be a connected graph, and let $L_0, \ldots, L_k$ be the layers produced by BFS starting at node s. Exactly one of the following holds.

(i) No edge of G joins two nodes of the same layer, and G is bipartite.

(ii) An edge of G joins two nodes of the same layer, and G contains an odd-length cycle (and hence is not bipartite).



Case (i)



Case (ii)

Bipartite Graphs

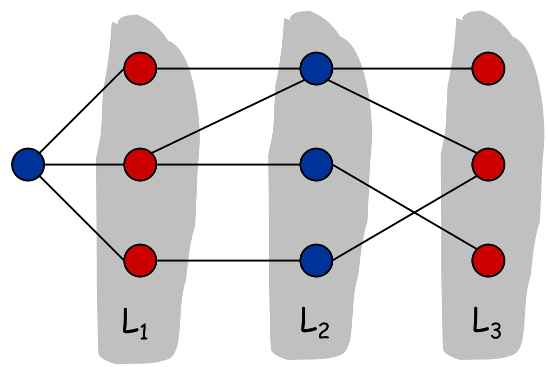
Lemma. Let G be a connected graph, and let L_0, …, L_k be the layers produced by BFS starting at node s. Exactly one of the following holds.

(i) No edge of G joins two nodes of the same layer, and G is bipartite.

(ii) An edge of G joins two nodes of the same layer, and G contains an odd-length cycle (and hence is not bipartite).

Pf. (i)

- Suppose no edge joins two nodes in the same layer.
- Bipartition: red = nodes on odd levels, blue = nodes on even levels.



Case (i)

Bipartite Graphs

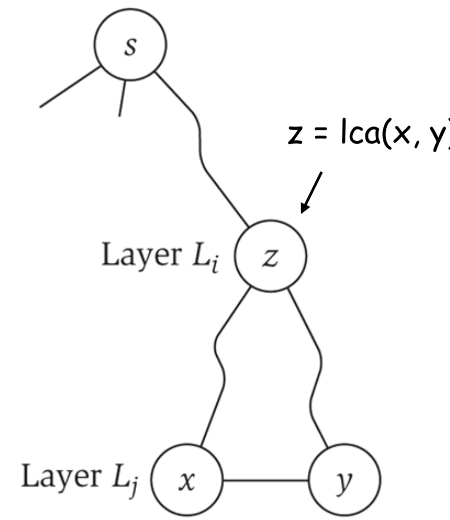
Lemma. Let G be a connected graph, and let $L_0, \ldots, L_k$ be the layers produced by BFS starting at node s. Exactly one of the following holds.

(i) No edge of G joins two nodes of the same layer, and G is bipartite.

(ii) An edge of G joins two nodes of the same layer, and G contains an odd-length cycle (and hence is not bipartite).

Pf. (ii)

- Suppose (x, y) is an edge with x, y in same level L_j.
- Let z be lowest common ancestor of x, y in BFS tree.
- Let L_i be level containing z.
- Consider cycle that takes edge from x to y, then path from y to z, then path from z to x.
- Its length is $\underbrace{1}_{(x,\, y)} + \underbrace{(j-i)}_{\text{path from } y \text{ to } z} + \underbrace{(j-i)}_{\text{path from } z \text{ to } x}$, which is odd. ▪

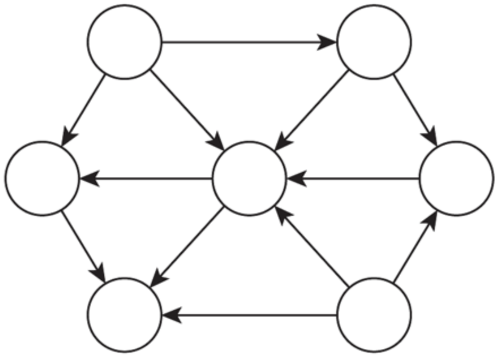


3.5 Connectivity in Directed Graphs

Directed Graphs

Directed graph. $G = (V, E)$

- Edge (u, v) goes from node u to node v.



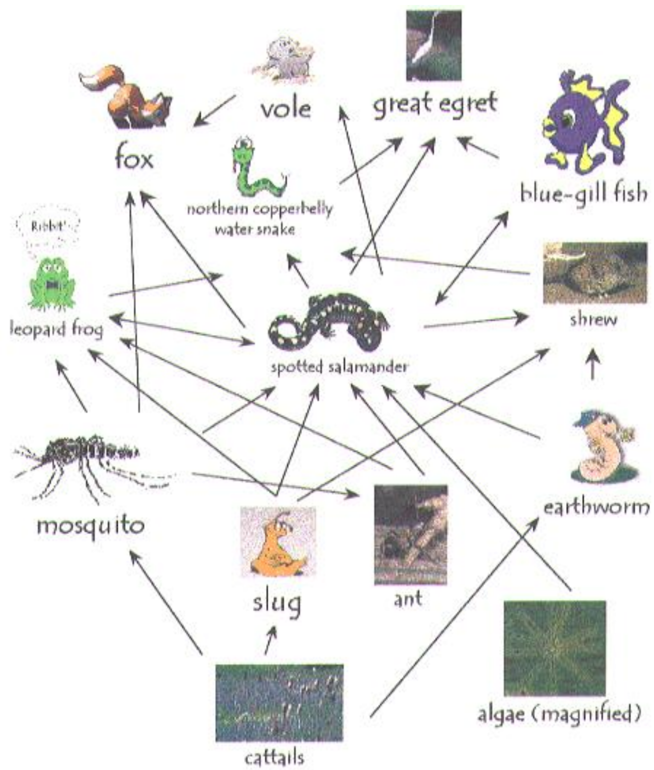
Ex. Web graph - hyperlink points from one web page to another.

- Directedness of graph is crucial.
- Modern web search engines exploit hyperlink structure to rank web pages by importance.

Ecological Food Web

Food web graph.

- Node = species.
- Edge = from prey to predator.



Reference: http://www.twingroves.district96.k12.il.us/Wetlands/Salamander/SalGraphics/salfoodweb.giff

Graph Search

Directed reachability. Given a node s, find all nodes reachable from s.

Directed s-t shortest path problem. Given two node s and t, what is the length of the shortest path between s and t?

Graph search. BFS/DFS extends naturally to directed graphs.

Web crawler. Start from web page s. Find all web pages linked from s, either directly or indirectly.

Strong Connectivity

Def. Node u and v are mutually reachable if there is a path from u to v and also a path from v to u.

Def. A graph is strongly connected if every pair of nodes is mutually reachable.

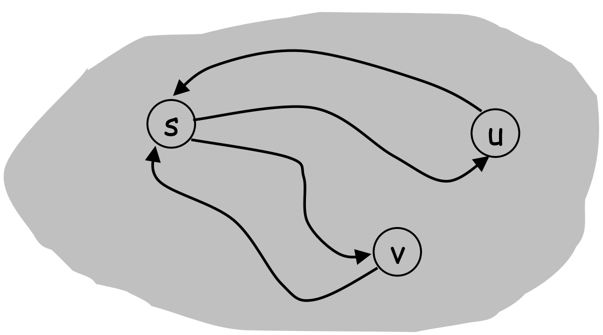
Lemma. Let s be any node. G is strongly connected iff every node is reachable from s, and s is reachable from every node.

Pf. $\Rightarrow$ Follows from definition.

Pf. $\Leftarrow$ Path from u to v: concatenate u-s path with s-v path.

Path from v to u: concatenate v-s path with s-u path. ▪

ok if paths overlap



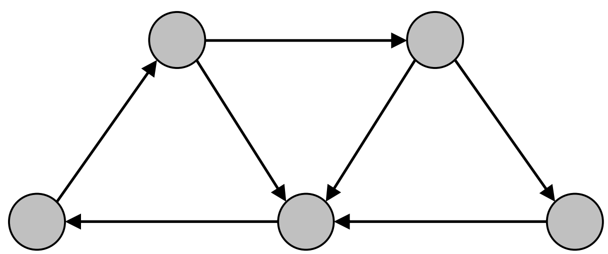
Strong Connectivity: Algorithm

Theorem. Can determine if G is strongly connected in $O(m + n)$ time.

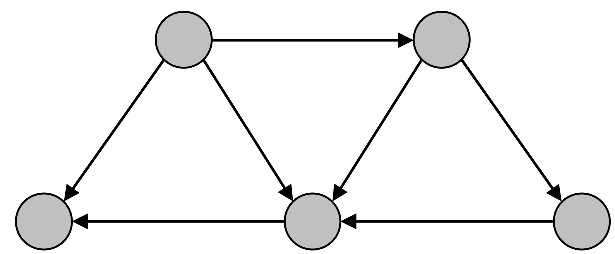
Pf.

- Pick any node s.
- Run BFS from s in G.
- Run BFS from s in G^{rev}.
- Return true iff all nodes reached in both BFS executions.
- Correctness follows immediately from previous lemma. ▪

reverse orientation of every edge in G



strongly connected



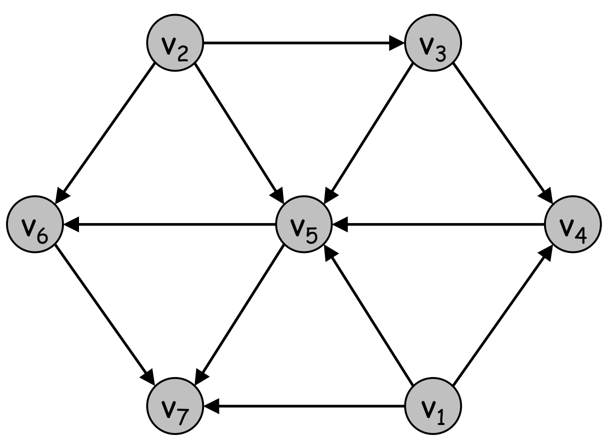
not strongly connected

3.6 DAGs and Topological Ordering

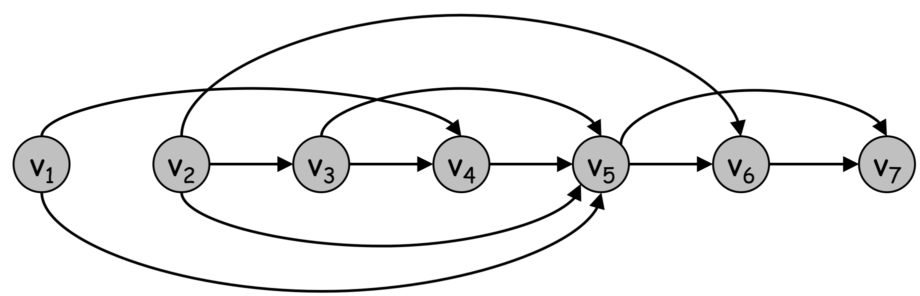
Directed Acyclic Graphs

Def. An DAG is a directed graph that contains no directed cycles.

Def. A topological order of a directed graph $G = (V, E)$ is an ordering of its nodes as $v_1, v_2, \ldots, v_n$ so that for every edge (v_i, v_j) we have $i < j$.



a DAG



a topological ordering

Precedence Constraints

Precedence constraints. Edge (v_i, v_j) means task v_i must occur before v_j.

Applications.

- Course prerequisite graph: course v_i must be taken before v_j.
- Compilation: module v_i must be compiled before v_j.
- Pipeline of computing jobs: output of job v_i needed to determine input of job v_j.

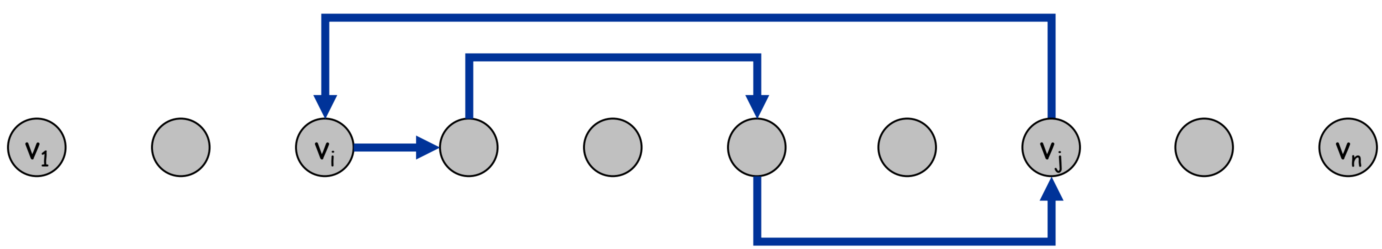
Directed Acyclic Graphs

Lemma. If G has a topological order, then G is a DAG.

Pf. (by contradiction)

- Suppose that G has a topological order $v_1, \ldots, v_n$ and that G also has a directed cycle C. Let's see what happens.
- Let v_i be the lowest-indexed node in C, and let v_j be the node just before v_i; thus (v_j, v_i) is an edge.
- By our choice of i, we have $i < j$.
- On the other hand, since (v_j, v_i) is an edge and $v_1, \ldots, v_n$ is a topological order, we must have $j < i$, a contradiction. ▪

the directed cycle C



the supposed topological order: $v_1, \ldots, v_n$

Directed Acyclic Graphs

Lemma. If G has a topological order, then G is a DAG.

Q. Does every DAG have a topological ordering?

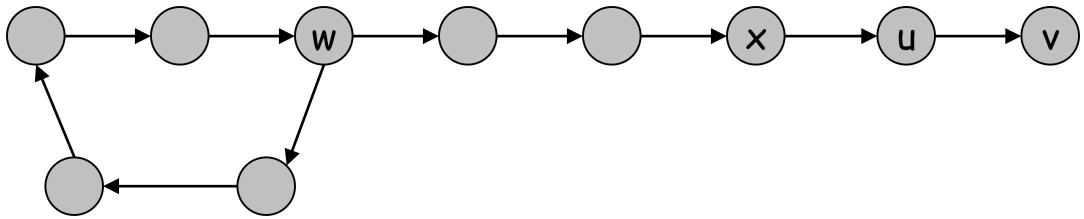
Q. If so, how do we compute one?

Directed Acyclic Graphs

Lemma. If G is a DAG, then G has a node with no incoming edges.

Pf. (by contradiction)

- Suppose that G is a DAG and every node has at least one incoming edge. Let's see what happens.
- Pick any node v, and begin following edges backward from v. Since v has at least one incoming edge (u, v) we can walk backward to u.
- Then, since u has at least one incoming edge (x, u), we can walk backward to x.
- Repeat until we visit a node, say w, twice.
- Let C denote the sequence of nodes encountered between successive visits to w. C is a cycle. ▪



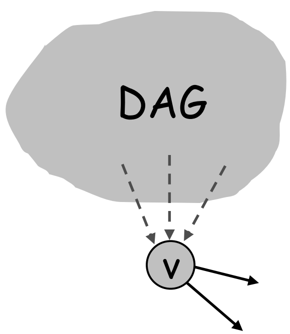
Directed Acyclic Graphs

Lemma. If G is a DAG, then G has a topological ordering.

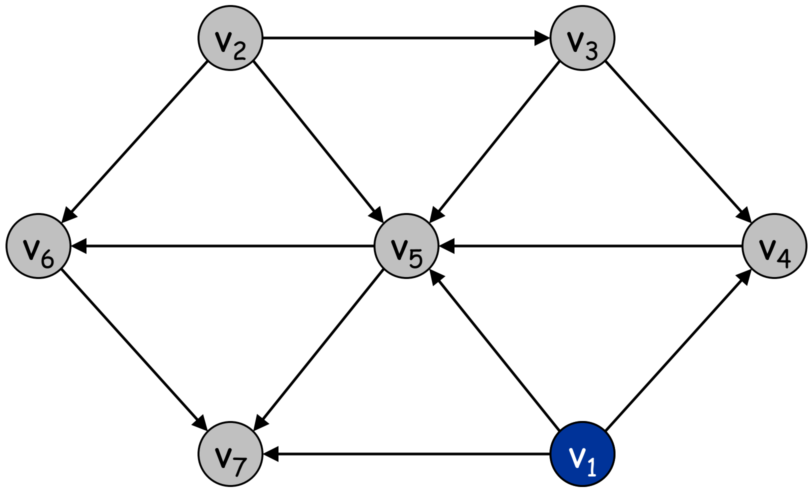
Pf. (by induction on n)

- Base case: true if n = 1.
- Given DAG on n > 1 nodes, find a node v with no incoming edges.
- G - { v } is a DAG, since deleting v cannot create cycles.
- By inductive hypothesis, G - { v } has a topological ordering.
- Place v first in topological ordering; then append nodes of G - { v } in topological order. This is valid since v has no incoming edges. ▪

```
To compute a topological ordering of G:
Find a node v with no incoming edges and order it first
Delete v from G
Recursively compute a topological ordering of G−{v}
  and append this order after v
```

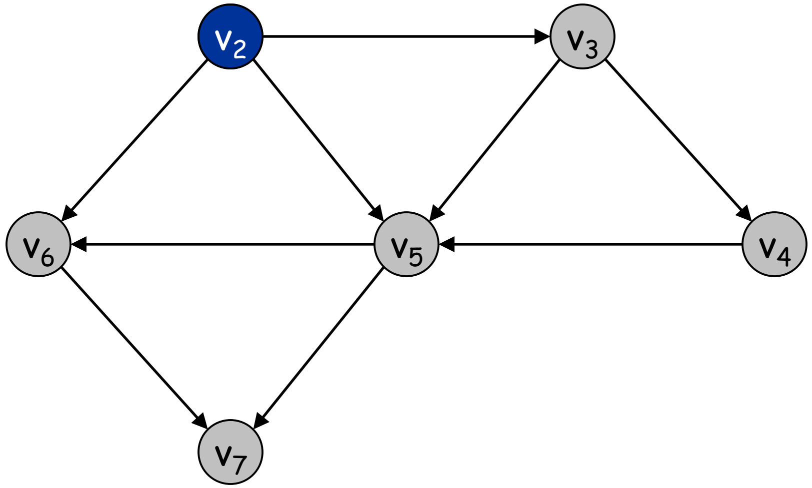


Topological Ordering Algorithm: Example



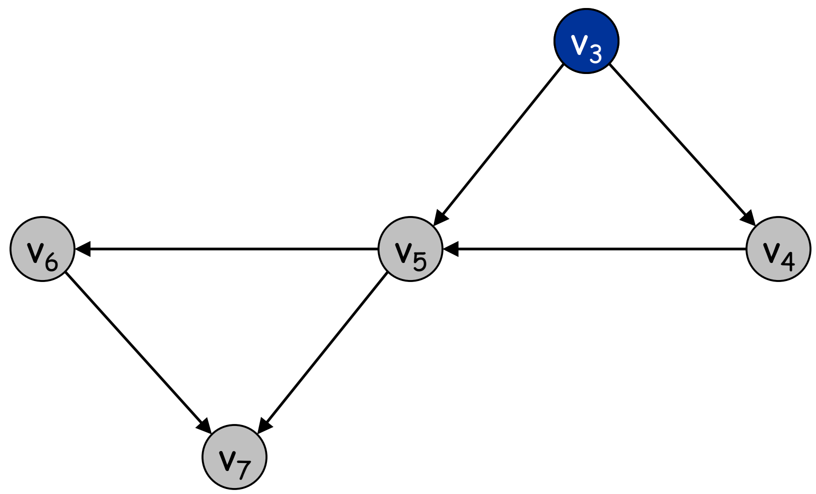
Topological order:

Topological Ordering Algorithm: Example



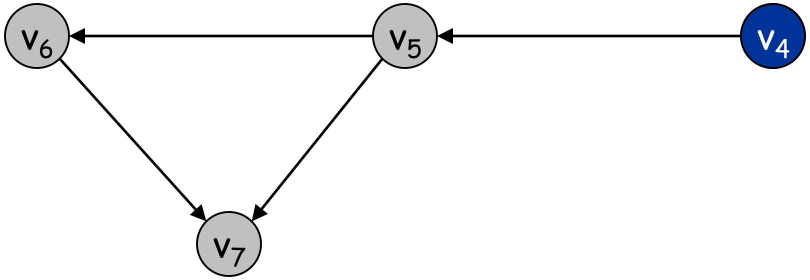
Topological order: v_1

Topological Ordering Algorithm: Example



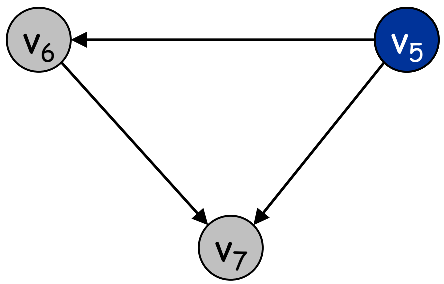
Topological order: v_1, v_2

Topological Ordering Algorithm: Example



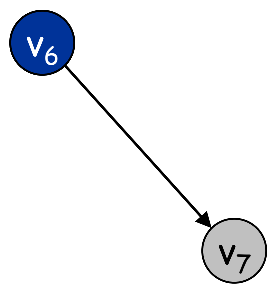
Topological order: v_1, v_2, v_3

Topological Ordering Algorithm: Example



Topological order: v_1, v_2, v_3, v_4

Topological Ordering Algorithm: Example

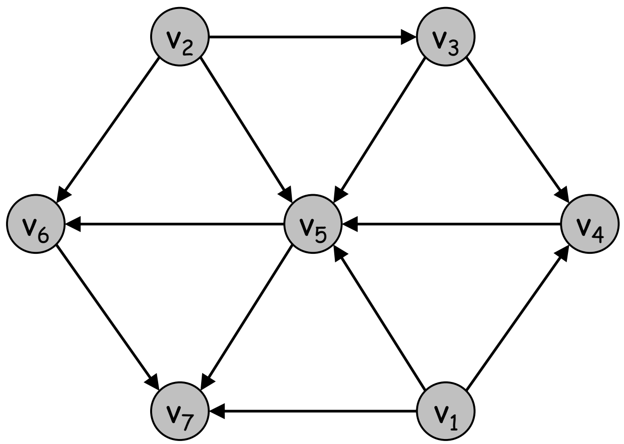


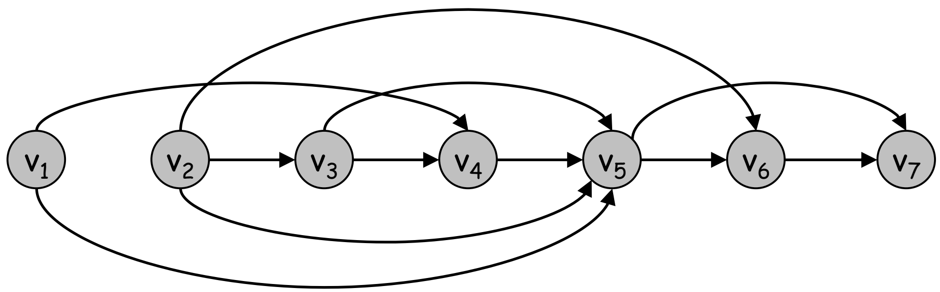
Topological order: v_1, v_2, v_3, v_4, v_5

Topological Ordering Algorithm: Example

Topological order: $v_1, v_2, v_3, v_4, v_5, v_6$

Topological Ordering Algorithm: Example





Topological order: $v_1, v_2, v_3, v_4, v_5, v_6, v_7$.

Topological Sorting Algorithm: Running Time

Theorem. Algorithm finds a topological order in $O(m + n)$ time.

Pf.

- Maintain the following information:
  - `count[w]` = remaining number of incoming edges
  - S = set of remaining nodes with no incoming edges
- Initialization: $O(m + n)$ via single scan through graph.
- Update: to delete v
  - remove v from S
  - decrement `count[w]` for all edges from v to w, and add w to S if c `count[w]` hits 0

Summary

Graph Algorithms

Graph Traversal

- Breadth First Search: Explore outward from s in all possible directions, adding nodes one "layer" at a time.
- Depth First Search: Starts at s and explores as far as possible along each branch before backtracking.

Testing Bipartiteness

- BFS and check if there is an edge between nodes of the same layer

Strong Connectivity in Directed Graphs

- BFS + reverse BFS

DAGs and Topological Ordering

- Recursively remove nodes with no incoming edge