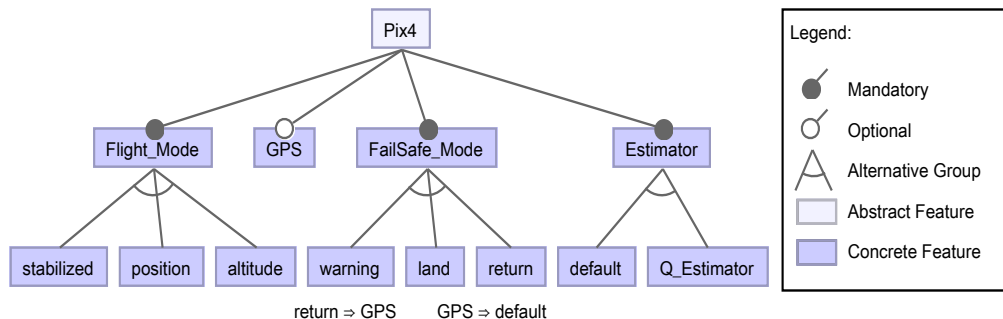


Flight Mode	GPS	Failsafe Mode	Estimator
stabilized	yes	warning	default
position	no	land	Q Estimator
altitude		return	

(a) Initial Model



(b) Feature Model

Flight Mode	GPS	Failsafe Mode	Estimator
altitude	no	warning	Q Estimator
stabilized	no	land	default
altitude	yes	return	default
position	no	return	default
position	no	warning	default
position	yes	land	Q Estimator
stabilized	no	return	Q Estimator
stabilized	yes	warning	default
altitude	no	land	default

(c) 2-way CIT Sample