

# Spacetime smoothing rates

Elias Teixeira Krainski<sup>1</sup>

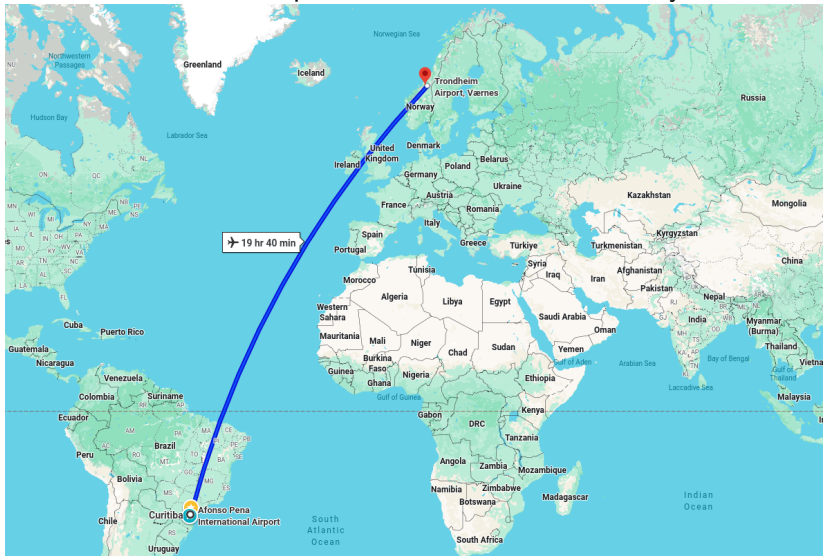
October 2025

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# Where

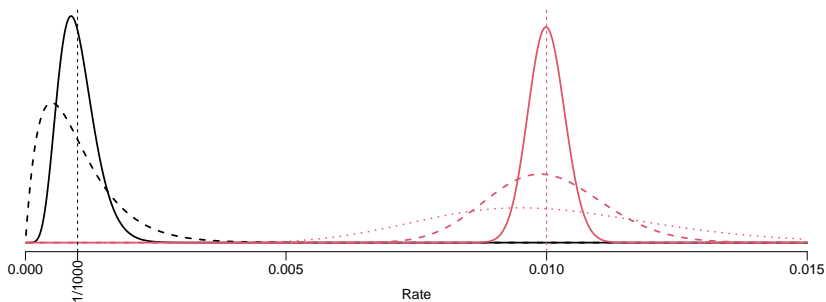
I am from Brazil, meet professor Håvard Rue in Norway



## **Data and parameters**

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Rate and uncertainty



## **Data example: Infant mortality**

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- ▶ Number of children born

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<b>Araucária</b>	2207	2262	2188

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► Infant deaths

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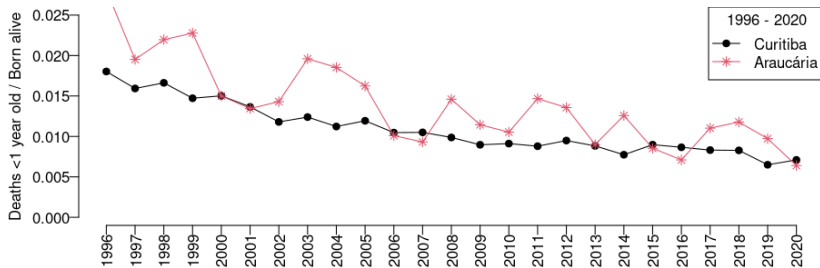
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- ▶ Infant mortality rate (per thousand) (por mil)

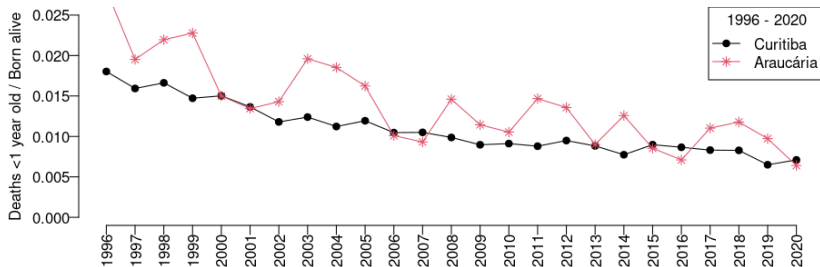
	2018	2019	2020
<b>Curitiba</b>	8.276	6.497	7.097



# Visualize the observed rates



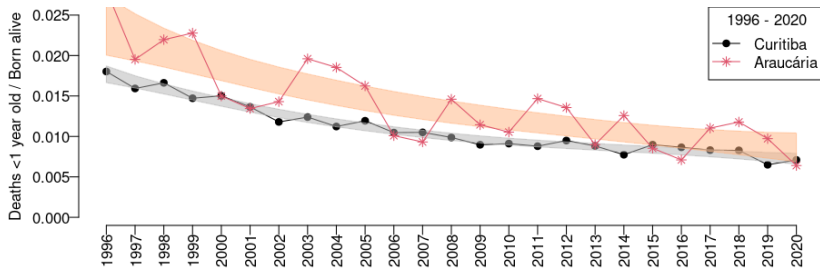
# Visualize the observed rates



- Rates vary more in “small areas” (less population)

# Fitted rates

## ► Considering temporal “neighborhood”

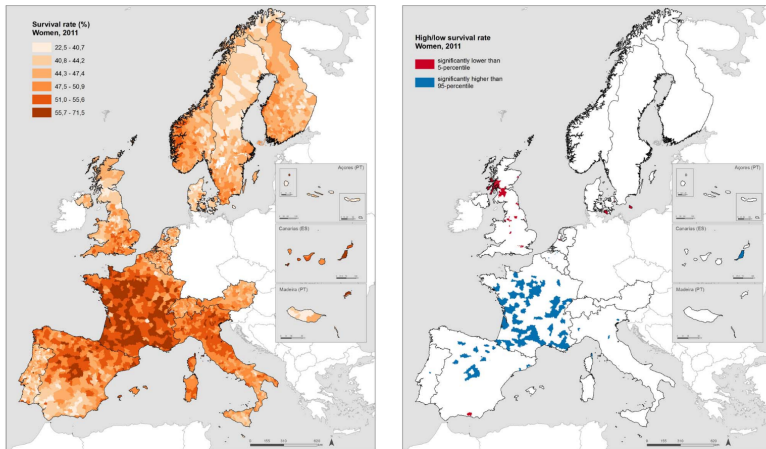


# Spatial neighborhood



# Old survival in Europe, Ribeiro et al. (2016)

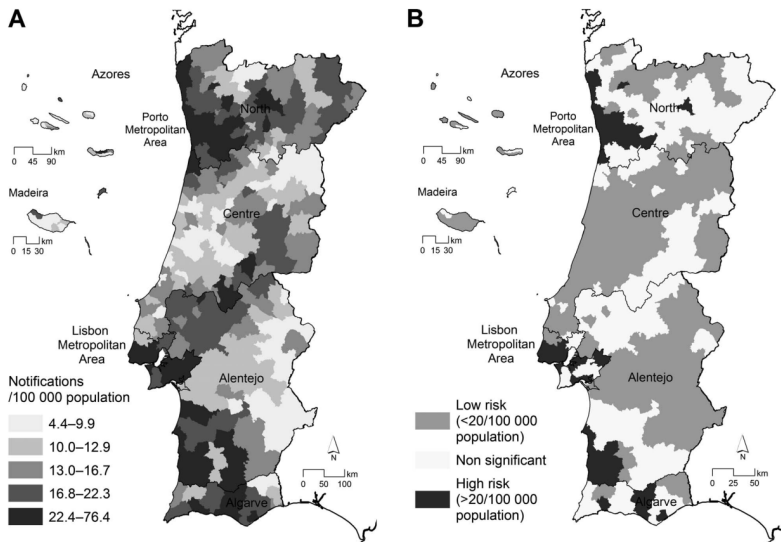
Probability (75-84 years old in 2001 survive until 2011)



**Figure 2** Spatial distribution of the 10-year survival rates across small areas of Europe in 2001 and 2011 (women). (A) Survival rates; (B) areas of high (above 95th centile) and low (below 5th centile) survival.

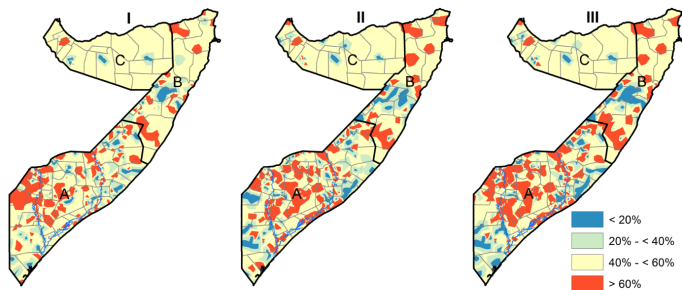
# Tuberculosis in Portugal, Apolinário et al. (2017)

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**Figure** Spatial distribution of **A)** tuberculosis-standardised notification rates and **B)** location of municipalities with higher/lower notification rates, Portugal, 2010–2014

# Wasting, Stunting and Underweight: shared risk, Kinyoki et al. (2016)



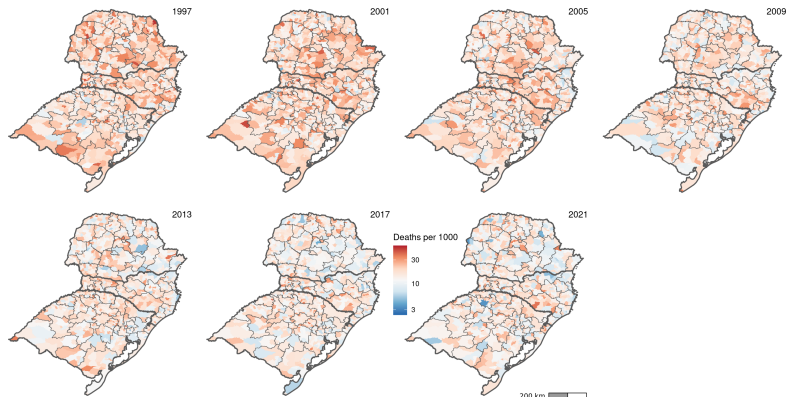
**Figure 4** Estimated shared components classified at 95% credible level among children aged 6–59 months using the marginal probabilities calculated using the quintile correction (QC) method.<sup>35</sup> I=Wasting and Stunting, II=Stunting and Underweight, III=Wasting and Underweight. South Central (A), North East (B) and North West (C).

# Spacetime



# The spacetime discrete domain case

$$\mathbf{u} = \{u_{11}, \dots, u_{n1}, u_{12}, \dots, u_{n2}, \dots, u_{1T}, \dots, u_{nT}\}$$



# Spatially structured trends

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- ▶ Interaction between fixed and random terms
  - ▶ linear trend for each area, Bernardinelli et al. (1995)
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- ▶ Interaction between spatial and temporal random effects, Clayton (1996)

## **Spacetime models**

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- ▶ **Q1** has dimension equals  $T$  (from a model over time)
- ▶ **Q2** has dimension equals  $n$  (from a model over space)
- ▶ The Kronecker product models follows the Clayton's rule
- ▶ Combine **Q1** (time) and **Q2** (space) available



# Some examples on spacetime interactions

- ▶  $\text{Precision}(\mathbf{u}) = \tau \mathbf{H} \otimes \mathbf{R}$ , Knorr-Held (2000)
  - ▶  $\mathbf{H}$ : precision structure matrix over the temporal domain
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- ▶ **care** when main effects are in the model
- ▶ **super care** when **Q1** and/or **Q2** have rank deficiency
  - ▶ e.g. `rw1`, `rw2` and `besag` models
  - ▶ if both **Q1** and **Q2** are intrinsic, Knorr-Held (2000):
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    - ▶ see `inla.knmodels()`
- ▶ Proper in time, Martínez-Beneito, López-Quilez, and Botella-Rocamora (2008)
  - ▶ example in INLA:  

```
f(spatial, model='besag', ...,  
  group=time, control.group=list(model='ar1'))
```
  - ▶ NOTE: Here the constraints are only set for the main model, and not for the group model!

# The Knorr-Held (2000) models

- ▶ Linear predictor is modeled as

$$\eta_{it} = \text{other effects} + v_t + s_i + d_{it}$$

- ▶  $v_t$  is a temporal effect common for all areas,
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  - ▶  $s_i$  is a spatial effect common for all times and
  - ▶  $d_{it}$  is the space-time effect.
- ▶ Decompose:  $v_t = \gamma_t + \alpha_t$  and  $s_i = \phi_i + \theta_i$ 
    - ▶ zero mean Gaussian distributions, with precision  $\tau_\gamma \mathbf{I}$ ,  $\tau_\alpha \mathbf{K}$ ,  $\tau_\phi \mathbf{I}$  and  $\tau_\theta \mathbf{R}$ , for  $\gamma$ ,  $\alpha$ ,  $\phi$  and  $\theta$ , respectively.
    - ▶  $\mathbf{I}$ : identity matrix with required dimension
    - ▶  $\mathbf{K}$  and  $\mathbf{R}$ : temporal and spatial precision structure matrices, from the neighborhood structure

# The Knorr-Held (2000) models (cont.)

- ▶ Let  $\mathbf{R} = \tilde{\mathbf{G}} - \mathbf{G}$ , where
  - ▶  $\mathbf{G}$  is the spatial neighborhood structure

$$\mathbf{G}_{i,j} = \begin{cases} 1 & \text{if } j \sim i \\ 0 & \text{otherwise,} \end{cases}$$

- ▶  $j \sim i$  means “ $j$  neighbor to  $i$ ”
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- ▶ Considering the type IV interaction:

$$\begin{aligned} \tau_d \mathbf{K} \otimes \mathbf{R} &= \tau_d (\tilde{\mathbf{H}} - \mathbf{H}) \otimes (\tilde{\mathbf{G}} - \mathbf{G}) \\ &= \tau_d (\tilde{\mathbf{H}} \otimes \tilde{\mathbf{G}} - \tilde{\mathbf{H}} \otimes \mathbf{G} - \mathbf{H} \otimes \tilde{\mathbf{G}} + \mathbf{H} \otimes \mathbf{G}) \end{aligned}$$

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