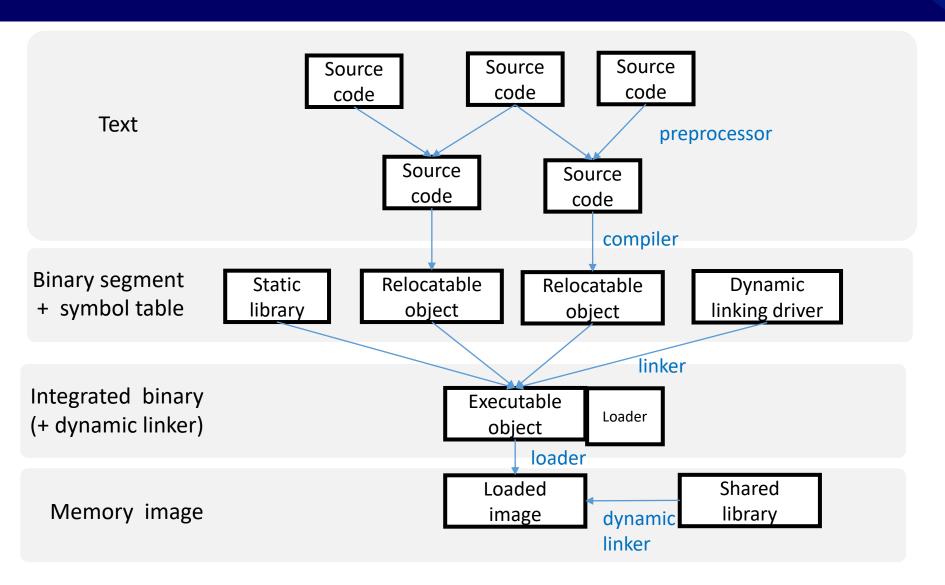
ECE20019 Open Source Software, Spring 2018

Build: Preprocessing, Compiling & Linking

Overview

- A build is a process of translating a high-level program into a machine-readable and executable form
 - operation into instructions
 - symbols into memory addresses
 - variables, functions
- Modern computer systems have different mechanisms for binding symbols with memory addresses
 - statically (code) vs. dynamically (execution)
 - trade-off between runtime performance and portability

Building Flow



Binding Time

```
    Coding

    printf("Hello, Application");

    Preprocessing

     #ifdef ARCH x86
        printf("Hello, x86");
    #endif
  Linking
    extern char * libversion;
    printf("Hello, library of version %s", libversion);

    Runtime (execution time)

    scanf("%s", name);
    printf("Hello, user %s", name);
```

C preprocessing overview

- A text processor employed by a compiler framework to manipulate source code text before compilation
 - inclusion of header files
 - macro expansion
 - conditional compilation
 - removal of unnecessary text
 - encoding conversion
- Preprocessing directives command most preprocessing tasks for source code files
 - in a form of '#name'
 - some directives receive arguments
 - a directive cannot cover more than one line except the one continued with backslash-newlines

Marco expansion (basic)

- A macro is a code fragment which has been given a name. Whenever the name is used, it is replaced by the content of the macro.
- #define x y
 - the preprocessor replaces all x token instances to y
 - x must not begin with '_'
- #define x
 - to notify a certain control message to the preprocessor (i.e., controlling macro or guard macro)
- A preprocessor can be invoked with macro definitions
 - e.g. gcc -D name=value ... starts a preprocessing with name being value
- #undef x
 - Cancel the x macro definition
 - Macro definitions are interpreted in the order that they appear in a text

Header file inclusion

- A header file is a file containing C declarations, structure definitions and macro definitions to be shared between several source files
 - h files
- #include copies the whole texts of the given file name to the current source file
 - A header file shall not include another header file in order to avoid the possibility of including the same file twice
- #include <name> (standard system directory first)
 #include "name" (current dir first)
- A computed include enables including one of many header files depending on a controlling condition

```
- E.g., #if SYSTEM_1
# include "system_1.h"
#elif SYSTEM_2
# include "system_2.h"
...
#endif
```

This slide is taken from a class material of 15-213 Intro. to Computer System conducted in CMU at Fall 2015

http://www.cs.cmu.edu/afs/cs/academic/class/15213-f15/www/schedule.html

Linking

15-213: Introduction to Computer Systems 13th Lecture, Oct. 13, 2015

Instructors:

Randal E. Bryant and David R. O'Hallaron

Example C Program

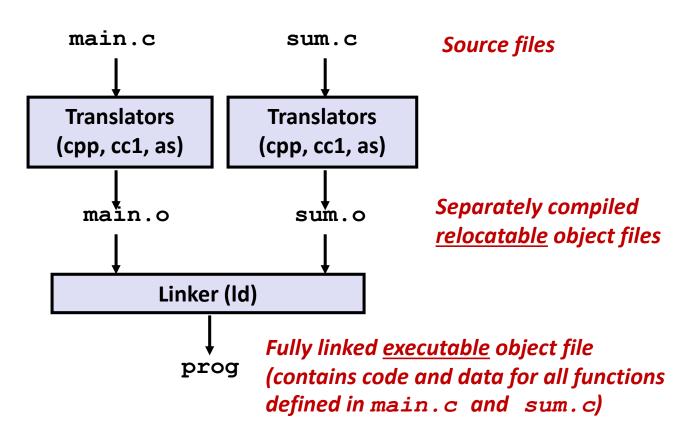
```
int sum(int *a, int n);
int array[2] = {1, 2};
int main()
{
   int val = sum(array, 2);
   return val;
}
```

```
int sum(int *a, int n)
{
   int i, s = 0;

   for (i = 0; i < n; i++) {
        s += a[i];
    }
   return s;
}</pre>
```

Static Linking

- Programs are translated and linked using a compiler driver:
 - linux> gcc -Og -o prog main.c sum.c
 - linux> ./prog



Why Linkers?

- Reason 1: Modularity
 - Program can be written as a collection of smaller source files, rather than one monolithic mass.
 - Can build libraries of common functions (more on this later)
 - e.g., Math library, standard C library

Why Linkers? (cont)

- Reason 2: Efficiency
 - Time: Separate compilation
 - Change one source file, compile, and then relink.
 - No need to recompile other source files.
 - Space: Libraries
 - Common functions can be aggregated into a single file...
 - Yet executable files and running memory images contain only code for the functions they actually use.

What Do Linkers Do?

Step 1: Symbol resolution

Programs define and reference symbols (global variables and functions):

```
void swap() {...} /* define symbol swap */
swap(); /* reference symbol swap */
int *xp = &x; /* define symbol xp, reference x */
```

- Symbol definitions are stored in object file (by assembler) in symbol table.
 - Symbol table is an array of structs
 - Each entry includes name, size, and location of symbol.
- During symbol resolution step, the linker associates each symbol reference with exactly one symbol definition.

What Do Linkers Do? (cont)

- Step 2: Relocation
 - Merges separate code and data sections into single sections
 - Relocates symbols from their relative locations in the .o files to their final absolute memory locations in the executable.
 - Updates all references to these symbols to reflect their new positions.

Let's look at these two steps in more detail....

Three Kinds of Object Files (Modules)

Relocatable object file (. o file)

- Contains code and data in a form that can be combined with other relocatable object files to form executable object file.
 - Each .o file is produced from exactly one source (.c) file

Static library (.a file)

Collection of relocatable objects of a certain module

Executable object file (a . out file)

 Contains code and data in a form that can be copied directly into memory and then executed.

Shared object file (.so file)

- Special type of relocatable object file that can be loaded into memory and linked dynamically, at either load time or run-time.
- Called Dynamic Link Libraries (DLLs) by Windows

Executable and Linkable Format (ELF)

- Standard binary format for object files
- One unified format for
 - Relocatable object files (.o)
 - Static library (.a)
 - Executable object files (a.out)
 - Shared object files (.so)
- Generic name: ELF binaries

ELF Object File Format

Elf header

Word size, byte ordering, file type (.o, exec, .so), machine type, etc.

Segment header table

 Page size, virtual addresses memory segments (sections), segment sizes.

. text section

Code

.rodata section

Read only data: jump tables, ...

data section

Initialized global variables

.bss section

- Uninitialized global variables
- "Block Started by Symbol"
- "Better Save Space"
- Has section header but occupies no space

ELF header
Segment header table (required for executables)
. text section
.rodata section
. data section
.bss section
.symtab section
.rel.txt section
.rel.data section
. debug section
Section header table

ELF Object File Format (cont.)

. symtab section

- Symbol table
- Procedure and static variable names
- Section names and locations

.rel.text section

- Relocation info for . text section
- Addresses of instructions that will need to be modified in the executable
- Instructions for modifying.

.rel.data section

- Relocation info for .data section
- Addresses of pointer data that will need to be modified in the merged executable

debug section

■ Info for symbolic debugging (gcc -g)

Section header table

Offsets and sizes of each section

ELF header
Segment header table (required for executables)
. text section
.rodata section
. data section
.bss section
.symtab section
.rel.txt section
.rel.data section
. debug section
Section header table

Linker Symbols

Global symbols

- Symbols defined by module m that can be referenced by other modules.
- E.g.: non-static C functions and non-static global variables.

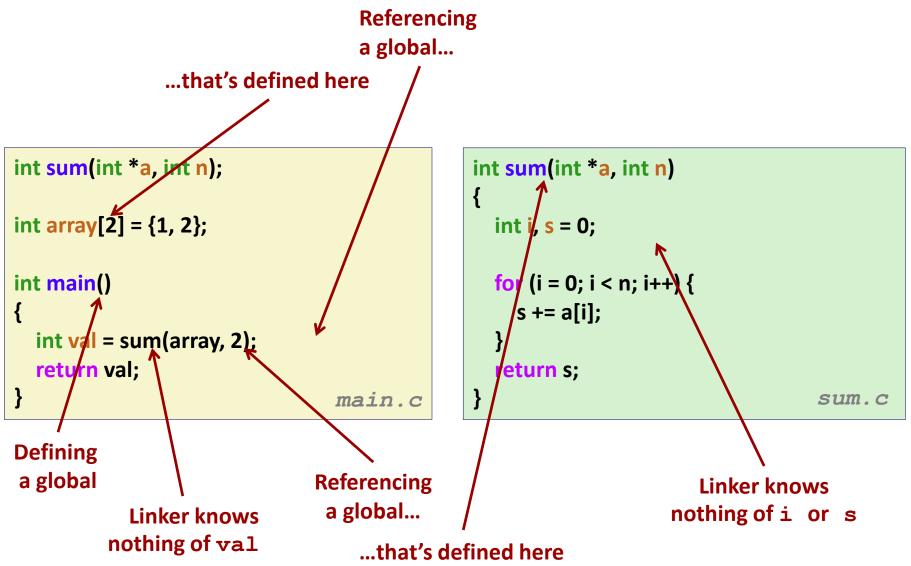
External symbols

 Global symbols that are referenced by module m but defined by some other module.

Local symbols

- Symbols that are defined and referenced exclusively by module m.
- E.g.: C functions and global variables defined with the static attribute.
- Local linker symbols are not local program variables

Step 1: Symbol Resolution



Local Symbols

- Local non-static C variables vs. local static C variables
 - local non-static C variables: stored on the stack
 - local static C variables: stored in either .bss, or .data

```
int f()
{
    static int x = 0;
    return x;
}

int g()
{
    static int x = 1;
    return x;
}
```

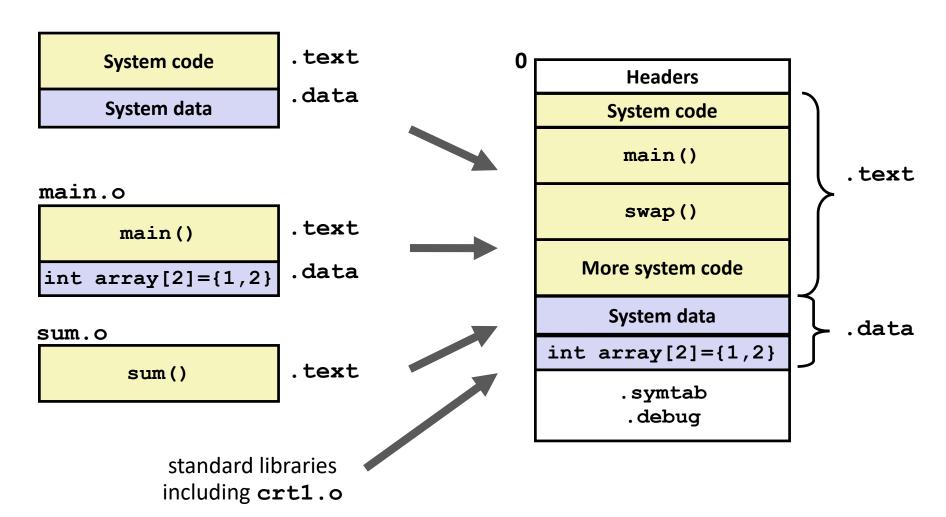
Compiler allocates space in .data for each definition of x

Creates local symbols in the symbol table with unique names, e.g., $x \cdot 1$ and $x \cdot 2$.

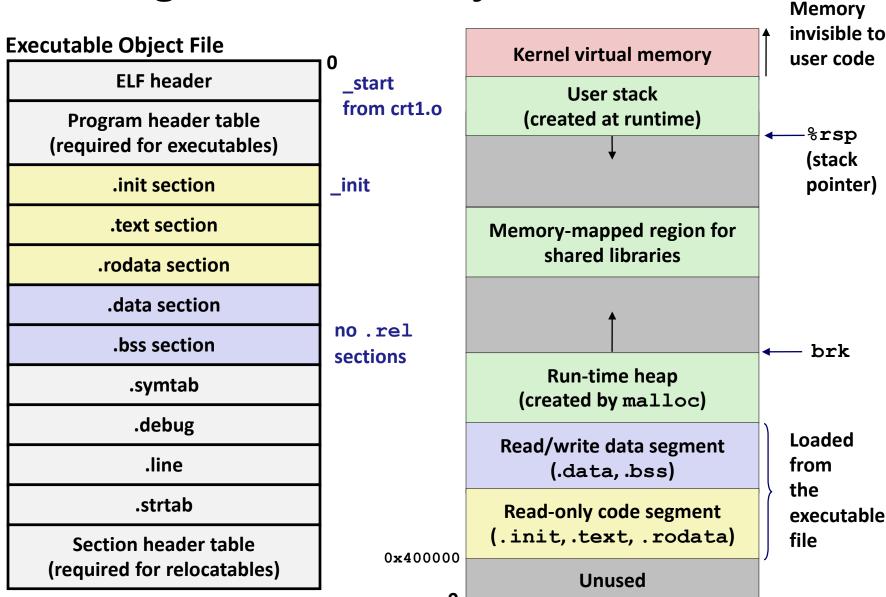
Step 2: Relocation

Relocatable Object Files

Executable Object File



Loading Executable Object Files



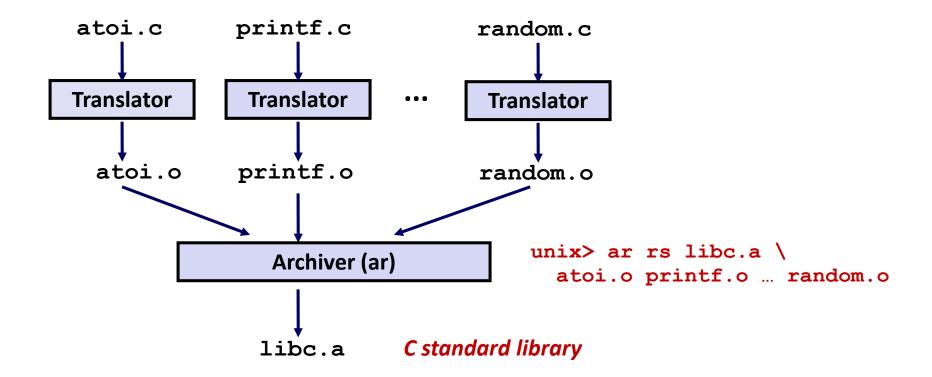
Packaging Commonly Used Functions

- How to package functions commonly used by programmers?
 - Math, I/O, memory management, string manipulation, etc.
- Awkward, given the linker framework so far:
 - Option 1: Put all functions into a single source file
 - Programmers link big object file into their programs
 - Space and time inefficient
 - Option 2: Put each function in a separate source file
 - Programmers explicitly link appropriate binaries into their programs
 - More efficient, but burdensome on the programmer

Old-fashioned Solution: Static Libraries

- Static libraries (.a archive files)
 - Concatenate related relocatable object files into a single file with an index (called an archive).
 - Enhance linker so that it tries to resolve unresolved external references by looking for the symbols in one or more archives.
 - If an archive member file resolves reference, link it into the executable.

Creating Static Libraries



- Archiver allows incremental updates
- Recompile function that changes and replace .o file in archive.

Commonly Used Libraries

libc.a (the C standard library)

- 4.6 MB archive of 1496 object files.
- I/O, memory allocation, signal handling, string handling, data and time, random numbers, integer math

libm. a (the C math library)

- 2 MB archive of 444 object files.
- floating point math (sin, cos, tan, log, exp, sqrt, ...)

```
% ar -t libc.a | sort
...
fork.o
...
fprintf.o
fpu_control.o
fputc.o
freopen.o
fscanf.o
fseek.o
fstab.o
...
```

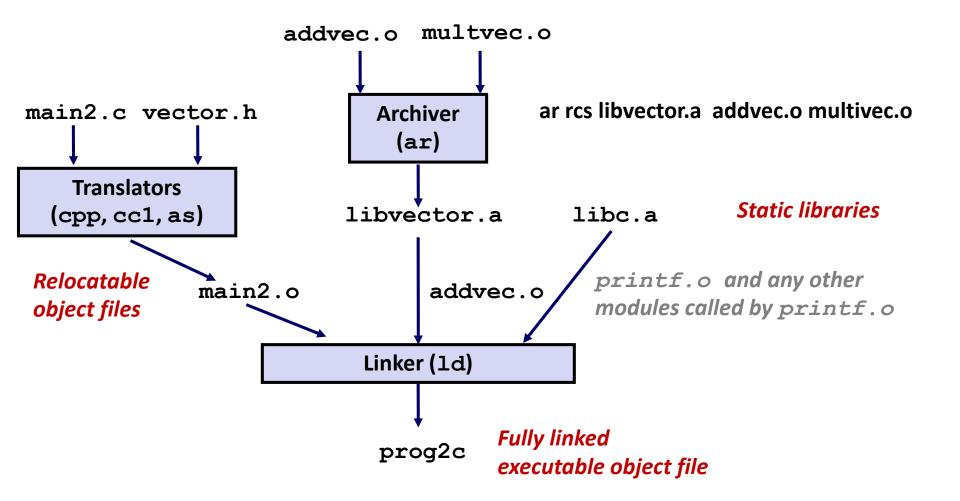
```
% ar -t libm.a | sort
...
e_acos.o
e_acosf.o
e_acosh.o
e_acoshf.o
e_acoshl.o
e_acosl.o
e_asin.o
e_asinf.o
e_asinf.o
e_asinf.o
...
```

Linking with Static Libraries

```
#include <stdio.h>
#include "vector.h"
int x[2] = \{1, 2\};
int y[2] = \{3, 4\};
int z[2];
int main()
  addvec(x, y, z, 2);
  printf("z = [%d %d]\n",
      z[0], z[1]);
  return 0;
                              main2.c
```


libvector.a

Linking with Static Libraries



"c" for "compile-time"

Using Static Libraries

Linker's algorithm for resolving external references:

- Scan .o files and .a files in the command line order.
- During the scan, keep a list of the current unresolved references.
- As each new .o or .a file, obj, is encountered, try to resolve each unresolved reference in the list against the symbols defined in obj.
- If any entries in the unresolved list at end of scan, then error.

Problem:

- Command line order matters!
- Moral: put libraries at the end of the command line.

```
unix> gcc -L. libtest.o -lmine
unix> gcc -L. -lmine libtest.o
libtest.o: In function `main':
libtest.o(.text+0x4): undefined reference to `libfun'
```

Modern Solution: Shared Libraries

Static libraries have the following disadvantages:

- Duplication in the stored executables (every function needs libc)
- Duplication in the running executables
- Minor bug fixes of system libraries require each application to explicitly relink

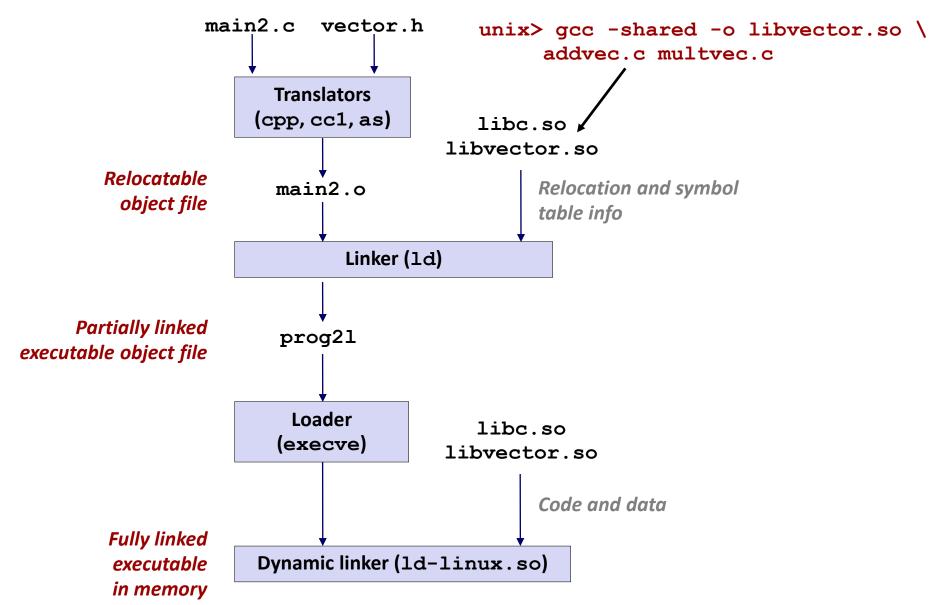
Modern solution: Shared Libraries

- Object files that contain code and data that are loaded and linked into an application dynamically, at either load-time or run-time
- Also called: dynamic link libraries, DLLs, .so files

Shared Libraries (cont.)

- Dynamic linking can occur when executable is first loaded and run (load-time linking).
 - Common case for Linux, handled automatically by the dynamic linker (ld-linux.so).
 - Standard C library (libc.so) usually dynamically linked.
- Dynamic linking can also occur after program has begun (run-time linking).
 - In Linux, this is done by calls to the dlopen() interface.
 - Distributing software.
 - High-performance web servers.
 - Runtime library interpositioning.
- Shared library routines can be shared by multiple processes.
 - More on this when we learn about virtual memory

Dynamic Linking at Load-time



Dynamic Linking at Run-time

```
#include <stdio.h>
#include <stdlib.h>
#include <dlfcn.h>
int x[2] = \{1, 2\};
int y[2] = \{3, 4\};
int z[2];
int main()
  void *handle;
  void (*addvec)(int *, int *, int *, int);
  char *error;
  /* Dynamically load the shared library that contains addvec() */
  handle = dlopen("./libvector.so", RTLD_LAZY);
  if (!handle) {
    fprintf(stderr, "%s\n", dlerror());
    exit(1);
                                                                                                dll.c
```

Dynamic Linking at Run-time

```
/* Get a pointer to the addvec() function we just loaded */
addvec = dlsym(handle, "addvec");
if ((error = dlerror()) != NULL) {
  fprintf(stderr, "%s\n", error);
  exit(1);
/* Now we can call addvec() just like any other function */
addvec(x, y, z, 2);
printf("z = [\%d \%d]\n", z[0], z[1]);
/* Unload the shared library */
if (dlclose(handle) < 0) {</pre>
  fprintf(stderr, "%s\n", dlerror());
  exit(1);
return 0;
                                                                                       d11.c
```

Linking Summary

- Linking is a technique that allows programs to be constructed from multiple object files.
- Linking can happen at different times in a program's lifetime:
 - Compile time (when a program is compiled)
 - Load time (when a program is loaded into memory)
 - Run time (while a program is executing)
- Understanding linking can help you avoid nasty errors and make you a better programmer.