Robot Programming #2

로봇제어기 - 아두이노 우노

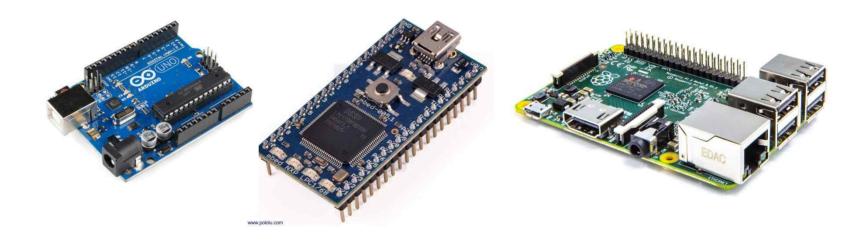
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How to control robots?

- We need a controller.
- The controller controls inputs and outputs according to program.
- There are numerous controllers available in the market.

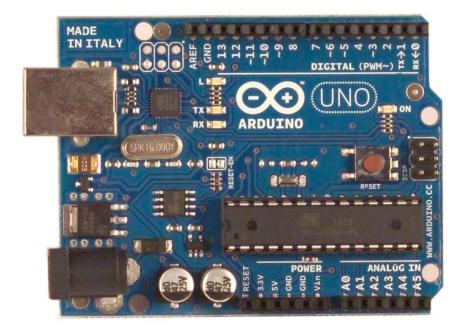


During experiment

- Don't bring food or beverage to the class.
- Turn off the power S/W before connecting or disconnecting cable!!!!
- When you bread-boarding, turn off power always!!!!
- Don't apply overload to the system.
- Electronic parts are volatile. Be careful when you handle them.
- Safety is first.

What is an Arduino?

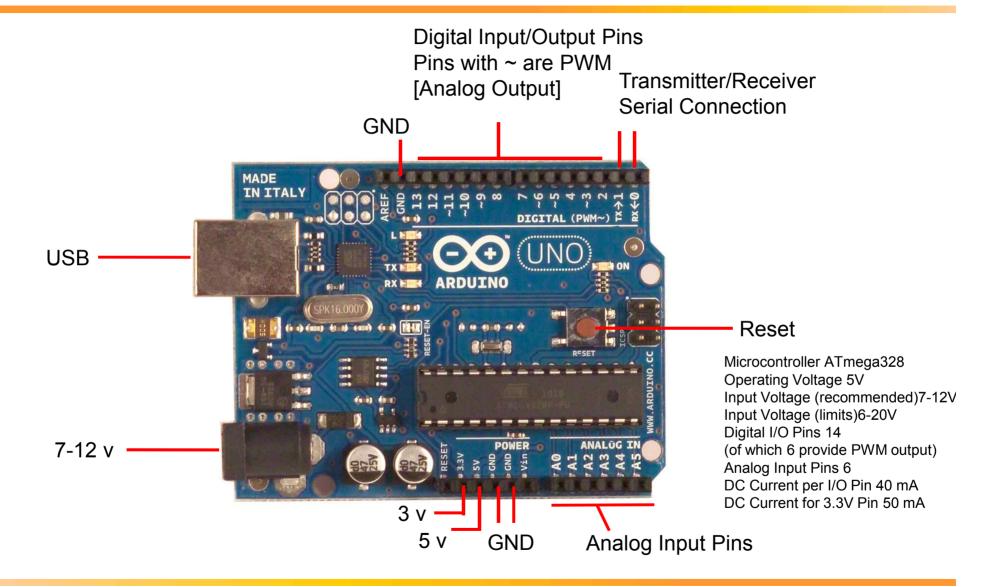
- Open source platform suitable to prototyping.
- Hardware connections and software are easy to use.



Getting Started with arduino controller

- To use Arduino controller, you need
- 1. PC and Internet connection
- 2. USB port
- Arduino is designed for beginners with little knowledge on electronics and microcontrollers.
- The advantage of the Arduino is that it doesn't require complex concepts such as flag and register.
- Basic commands such as digitalWrite are used to control ports.

Arduino Uno



Arduino Uno

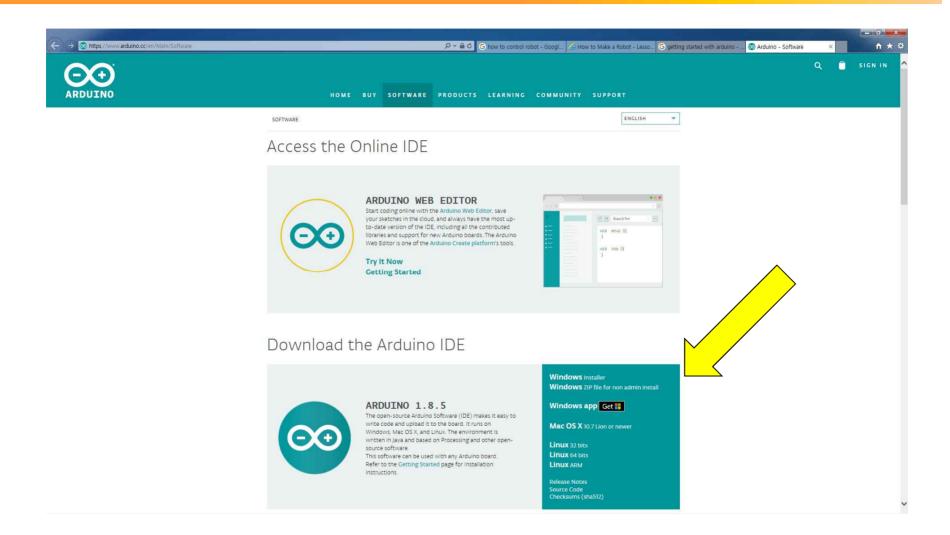
- Microcontroller: ATmega328
- Operating Voltage: 5V
- Input Voltage (recommended): 7-12V
- Input Voltage (limits): 6-20V
- 14 Digital I/O Pins (of which 6 provide PWM output)
- 6 Analog Input Pins
- DC Current per I/O Pin: 40 mA
- DC Current for 3.3V Pin: 50 mA

Download Arduino software

- Download Arduino Software from the website
 Arduino.cc and unzip the folder to your computer. A
 file within the folder called Arduino, allows you to
 launch the programming environment.
- You need to install a driver that comes with Arduino to be able to communicate with the board.



Download the Arduino IDE



Let us connect the Arduino to a PC as shown below.



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Run Arduino IDE and open Blink example.

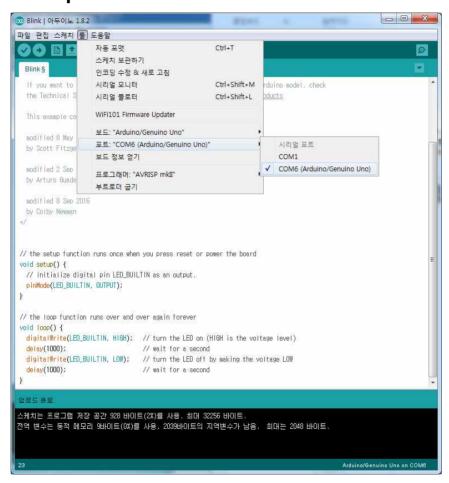


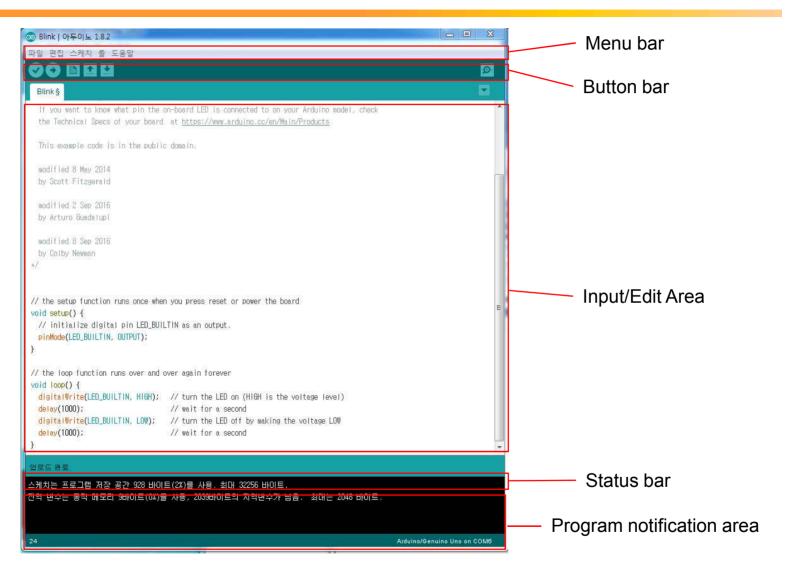
Blink example



```
- - X
○ Blink | 아두이노 1.8.2
파일 편집 스케치 둘 도움말
  Turns on an LED on for one second, then off for one second, repeatedly.
 // the setup function runs once when you press reset or power the board
 void setup() {
 // initialize digital pin LED_BUILTIN as an output.
 pinMode(LED_BUILTIN, OUTPUT):
 // the loop function runs over and over again forever
 void Toop() {
 digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the voltage level)
  delay(1000);
                                 // wait for a second
  digitalWrite(LED_BUILTIN, LOW); // turn the LED off by making the voltage LOW
                                 // wait for a second
  delay(1000);
언로드 완료
스케치는 프로그램 저장 공간 928 바이트(2%)를 사용. 최대 32256 바이트.
전역 변수는 동적 메모리 9바이트(0%)를 사용, 2039바이트의 지역변수가 남음. 최대는 2048 바이트.
                                                                 Arduino/Genuino Uno on COM6
```

Select serial port and board





- Press compile button to check for errors.
- Press upload button to program Arduino board with your sketch.
- What happens to the Arduino?

- View the default program source code.
- Can you tell me what is going on?

- Let's take a look at the Blink program.
- Bare minimum code consists of

```
void setup() {
// put your setup code here, to run once.
}

void loop() {
// put your main code here, to run repeatedly.
}
```

- setup: This is called only when the Arduino is powered on or reset. It is used to initialize variables and pin modes.
- loop: The loop function runs repeatedly until the device is powered off. The main logic of the code enters here. Similar to while(1) in other microcontroller programming.

- A pin on the Arduino board can be set as either input or output by using the pinMode function.
- pinMode(LED_BUILTIN,OUTPUT) implies that LED_BUILTIN pin is set as output pin.
- The LED_BUILTIN is a small LED on the board. By default its pin number is 13.

- We can set the digital value of the pin by using digitialWrite.
- digitalWrite(LED_BUILTIN,HIGH): it makes the output voltage of LED_BUILTIN(pin 13) 5V. It turns the LED on (HIGH is the voltage level).
- digitalWrite(LED_BUILTIN,LOW): it makes the output voltage of LED_BUILTIN(pin 13) 0V. It turns the LED off.
- delay(1000): Arduino will wait for a second(1000ms).