## **Code:**

```
import copy
from typing import Union
inf = float('inf')
class TSP_AI:
  """Traveling Salesman Problem
     Traveling Salesman Problem using Nearest Neighbour AI algorithm
  def __init__(
     self,
     matrix: list[list[Union[int, float, str]]] = None,
     source: int = 0
  ) -> None:
     """TSP
       Parameters
       1. matrix (Default 4x4 Matrix of Zeros): User can provide the matrix
beforehand
       2. source (Default 0): The index of the city which should be considered
as source
     ** ** **
     self.matrix = [[0]*4]*4 if matrix is None else matrix
     self.n: int = len(self.matrix)
     self.source: int = source
```

```
def Input(self):
  self.n = int(input('Enter city count : '))
  # Get the distances between cities
  for i in range(self.n):
     self.matrix.append([
        \inf if i == i else int(
          input(f'Cost to travel from city \{i+1\} to \{j+1\}: '))
        for j in range(self.n)
     ])
  # Get the source city
  self.source = int(input('Source: ')) % self.n
def solve(self):
  # Initially minCost is infinity
  minCost: float = inf
  for i in range(self.n):
     print("Path", end=")
     # Calling solver for each as source city
     cost = self._solve(copy.deepcopy(matrix), i, i)
     print(f'' -> \{i+1\} : Cost = \{cost\}'')
     if cost and cost < minCost:
                                    # If this cost is optimal, save it
        minCost = cost
```

return minCost

```
def_solve(
     self,
     matrix: list[list[Union[int, float, str]]],
     currCity: int = 0,
     source: int = 0
  ) -> int:
     if self.n < 2:
        return 0
     print(f" -> {currCity+1}", end=")
     for i in range(self.n):
       # Set all values in the currCity column as infinity (once visited, shouldn't
be visited anymore)
       matrix[i][currCity] = inf
     currMin, currMinPos = inf, 0
     for j in range(self.n):
       # Get the nearest city to the current city
       if currMin > matrix[currCity][j]:
          currMin, currMinPos = matrix[currCity][j], j
     if currMin == inf:
       # If currMin is infinity(i.e. all cities have been visited, return cost of
moving from this last city to start city to complete the path-loop)
       return self.matrix[currCity][source]
     # Set distance from currCity to next city and vice versa to infinity
```

```
matrix[currCity][currMinPos] = matrix[currMinPos][currCity] = inf
    # Calling the next recursion for selected city
    return currMin + self._solve(matrix, currMinPos, source)
# Driver code
if __name__ == '__main___':
  matrix = [
    [inf, 10, 15, 20, 299, 67, 24],
    [10, inf, 35, 25, 5, 88, 44],
    [15, 35, inf, 30, 52, 454, 13],
    [20, 25, 30, inf, 139, 23, 89],
    [299, 5, 52, 139, inf, 93, 10],
    [67, 88, 454, 23, 93, inf, 89],
    [24, 44, 13, 89, 10, 89, inf],
  ]
  source\_city = 0
  tsp = TSP_AI(matrix, source_city)
  print(f"Optimal Cost : {tsp.solve()}")
```

## **Output:**

```
Path -> 1 -> 2 -> 5 -> 7 -> 3 -> 4 -> 6 -> 1
                                                    Cost = 158
Path -> 2 -> 5 -> 7 -> 3 -> 1 -> 4 -> 6 -> 2
                                              :
                                                    Cost = 174
Path -> 3 -> 7 -> 5 -> 2 -> 1 -> 4 -> 6 -> 3
                                                    Cost = 535
Path -> 4 -> 1 -> 2 -> 5 -> 7 -> 3 -> 6 -> 4
                                                    Cost = 535
                                              :
Path -> 5 -> 2 -> 1 -> 3 -> 7 -> 4 -> 6 -> 5
                                                    Cost = 248
                                              :
Path -> 6 -> 4 -> 1 -> 2 -> 5 -> 7 -> 3 -> 6
                                                    Cost = 535
Path -> 7 -> 5 -> 2 -> 1 -> 3 -> 4 -> 6 -> 7 :
                                                    Cost = 182
Optimal Cost: 158
```