

Multiply robust estimation of the causal effect of treatment in data subject to irregular observation times and confounding

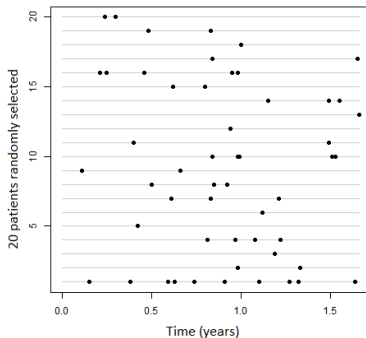
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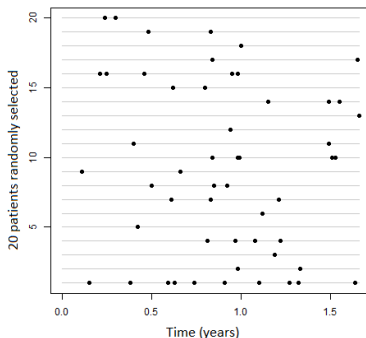
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Question: What is the average causal effect of air pollution (variable $A(t) \in \{0, 1\}$) on the FEV?

Setting (2)

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Under the following marginal structural model

$$E[Y^a(t)] = \beta_0 + \beta_1 a,$$

the average treatment effect (ATE) is given by

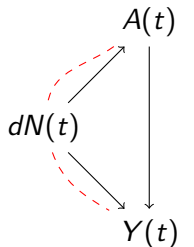
$$E[Y^1(t) - Y^0(t)] = \beta_1.$$

Why are irregular measurements problematic?

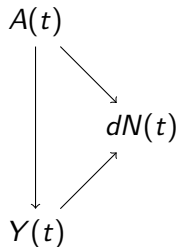
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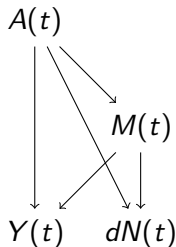
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Confounder



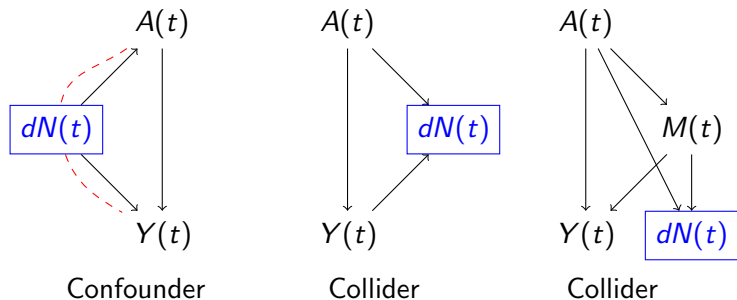
Collider



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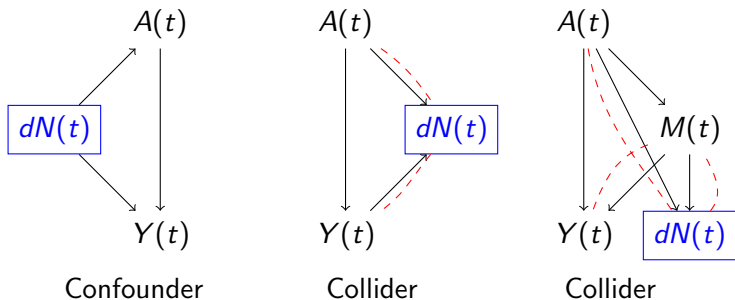
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Double missingness mechanism

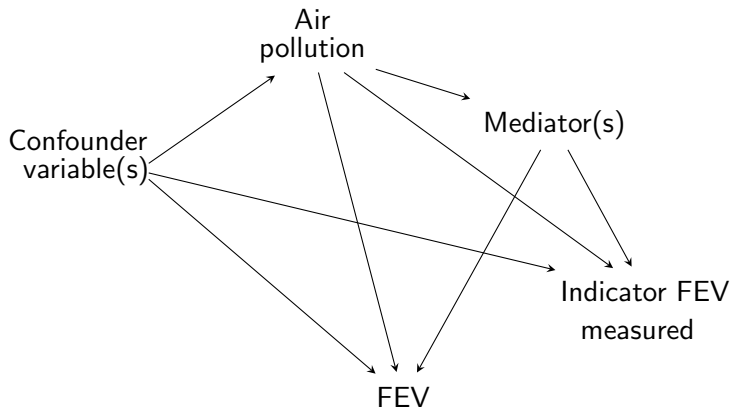
- We observe one of the two potential outcomes informatively, according to the **treatment** mechanism.
- We do not observe $Y^1(t)$ and $Y^0(t)$ at all times t but only at covariate-dependent **measurement** times.

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- We observe one of the two potential outcomes informatively, according to the **treatment** mechanism.
- We do not observe $Y^1(t)$ and $Y^0(t)$ at all times t but only at covariate-dependent **measurement** times.
- Informative sampling and inverse weighting methods were discussed in the survey sampling (e.g., Horvitz and Thompson 1952) and causal inference (e.g., Robins, Rotnitzky, and Zhao 1994) literatures.
- In Coulombe et al. (2021), we proposed a doubly-weighted (DW) estimator for that setting.

Causal diagram in Coulombe et al. (2021)

We (again) assume the following causal diagram at time t :



We further suppose that air pollution $A(t)$, confounders of the pollution-FEV relationship, $\mathbf{K}(t)$, and predictors of the measurement of FEV, $\mathbf{V}(t)$ are updated and available daily.

Causal assumptions

- Outcome consistency: $Y(t) = A(t)Y^1(t) + \{1 - A(t)\} Y^0(t)$
- Positivity of treatment: $0 < P\{A(t) \mid \mathbf{K}(t)\} < 1$
- Positivity of observation: $0 < E[dN(t) \mid \mathbf{V}(t)] < 1$
- No unmeasured confounder (NUC): $\{Y^0(t), Y^1(t)\} \perp A(t) \mid \mathbf{K}(t)$
- Conditional exchangeability:
$$\text{NUC} + \{A(t), Y^0(t), Y^1(t)\} \perp dN(t) \mid \mathbf{V}(t)$$

For consistency of the novel estimator only, we also require $\mathbf{K}(t) \subset \mathbf{V}(t)$.

Previous estimator

The DW estimator solved the following equations for β_0 and β_1 (the ATE):

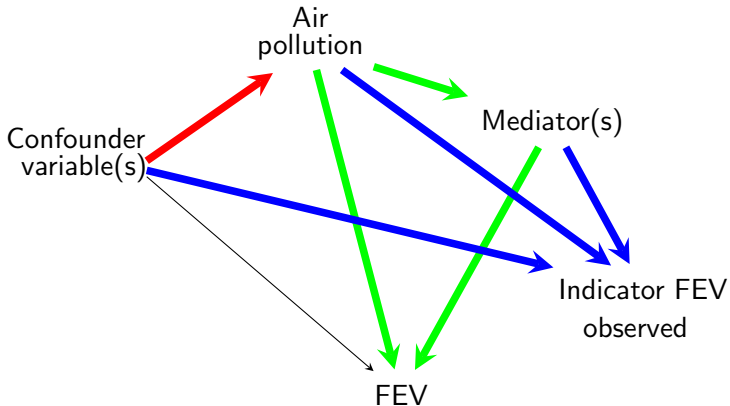
$$E \left[\int_0^\tau \frac{\frac{\mathbf{1}\{A(t)=a\}}{P\{A(t)=a|\mathbf{K}(t);\hat{\psi}\}} Y(t) - \beta_0 - \beta_1 a}{E[dN(t) | \mathbf{V}(t);\hat{\gamma}]} dN(t) \right] = 0,$$

where $\frac{\mathbf{1}\{A(t)=a\}}{P\{A(t)=a|\mathbf{K}(t);\hat{\psi}\}}$ are inverse probability of treatment (IPT)¹ weights and $\frac{dN(t)}{E[dN(t)|\mathbf{V}(t);\hat{\gamma}]}$ are inverse intensity of visit (IIV)² weights.

¹ Horvitz and Thompson, 1952; Rosenbaum and Rubin, 1983; Robins et al., 2000

² Lin, Scharfstein and Rosenheck, 2004

The DW tackled two nuisance models: the **treatment** and the **outcome measurement** models:



Blocking these associations leads to consistent estimation of the **average treatment effect (ATE)**.

Two weaknesses of the DW

- Consistency relies on the **correct specification** of IPT and IIV weights
- Relatively **variable** estimator

Semiparametric efficiency

For a general estimand $E[AY]$ estimated with outcome data selected at random given A and \mathbf{K} , and π the conditional selection probability, the class of estimators

$$N\hat{T}_{diff}(\mu) = \sum A\mu(A, \mathbf{K}) + \sum_{\mathbf{1}\{A=a\}} A\{Y - \mu(A, \mathbf{K})\} / \pi$$

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The function $\mu_{eff}(a, \mathbf{k}) = E[Y \mid A = a, \mathbf{K} = \mathbf{k}]$ leads to the smallest possible variance (Robins et al., 1994, 1998).

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In parallel, similar results were found in the survey sampling literature (see e.g., the discussion in Robins et Rotnitzky (1998) on the paper of Firth and Benneth (1998). Firth and Benneth were interested in *model-based estimators* that are *design consistent*).

Example: The AIPW

The AIPW (see e.g., Robins et al. (1995), Scharfstein et al. (1999), Bang and Robins (2005)) is the most efficient estimator from its class for $E[Y^a]$.

Note we only see Y^a in those for whom $\mathbf{1}\{A = a\}$, $a \in \{0, 1\}$, and that selection depends on confounders \mathbf{K} .

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The estimator for each potential outcome mean is given by

$$\begin{aligned} N\hat{T}_{diff}(\mu_a) = & \sum \frac{Y\mathbf{1}\{A = a\}}{P(A = a \mid \mathbf{K})} \\ & - \sum E[Y \mid A = a, \mathbf{K}] \left(\frac{\mathbf{1}\{A = a\} - P(A = a \mid \mathbf{K})}{P(A = a \mid \mathbf{K})} \right) \end{aligned}$$

for $\mu_a = E[Y \mid A = a, \mathbf{K}]$.

Construction of the novel estimator

Now suppose instead that we have a selection on both $\mathbf{1}\{A(t) = a\}$ and $\mathbf{1}\{dN(t) = 1\}$. We can start from the AIPW equations:

$$\eta(t) = \frac{\mathbf{1}\{A(t)=a\}}{P\{A(t)=a|\mathbf{K}(t);\hat{\psi}\}} Y(t) - \frac{\mathbf{1}\{A(t)=a\} - P\{A(t)=a|\mathbf{K}(t);\hat{\psi}\}}{P\{A(t)=a|\mathbf{K}(t);\hat{\psi}\}} \mu_a\{\mathbf{K}(t); \hat{\alpha}_K\} \\ - \beta_0 - \beta_1 A(t)$$

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and take the selection on $dN(t)$:

$$\begin{aligned} & E \left[\int_0^\tau \frac{\eta(t)}{E[dN(t) | \mathbf{V}(t); \hat{\gamma}]} dN(t) \right] \\ & - E \left[\int_0^\tau \left(\frac{dN(t) - E[dN(t) | \mathbf{V}(t); \hat{\gamma}]}{E[dN(t) | \mathbf{V}(t); \hat{\gamma}]} \right) E[\eta(t) | A(t) = a, dN(t) = 1, \mathbf{V}(t); \hat{\alpha}_V] \right] \\ & = 0 \end{aligned}$$

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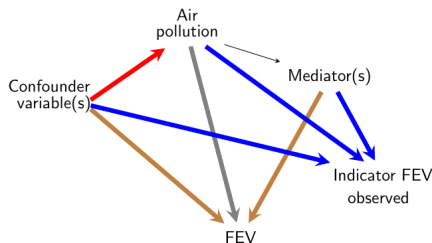
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which corresponds to projecting the influence function of the AIPW onto spaces orthogonal to residuals from IIV weights and to the projection of the outcome onto $\mathbf{V}(t)$. The novel estimator is called the AAIW.

Novel estimator

The AAIW is consistent when at least one of the “**treatment-related**” models and one of the “**measurement-related**” models are correctly specified, among:

- $P\{A(t) = a \mid \mathbf{K}(t); \psi\}$
- $\mu_a \{\mathbf{K}(t); \alpha_K\} = E[Y(t) \mid A(t) = a, \mathbf{K}(t); \alpha_K]$ (augmented term)
- $E[dN(t) \mid \mathbf{V}(t); \gamma]$
- $\mu_a \{\mathbf{V}(t); \alpha_V\} = E[Y(t) \mid A(t) = a, \mathbf{V}(t); \alpha_V]$ (augmented term)



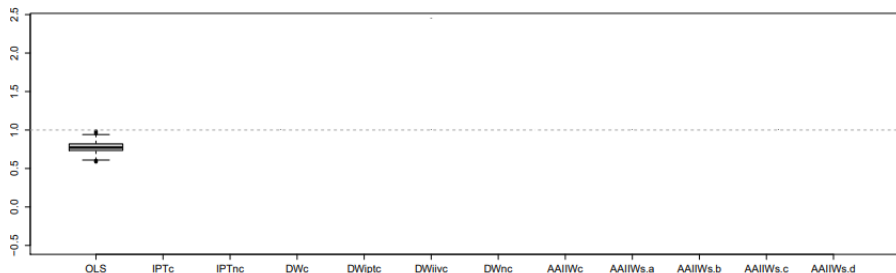
Under all nuisance models correctly specified, the AAIW attains the semiparametric efficiency bound, and we also find

$$\sigma_{AAIW}^2 - \sigma_{DW}^2 = (\beta_0 + \beta_1)^2 E \left[\frac{1 - e_1}{e_1} - \frac{2}{e_1} \right] + \beta_0^2 E \left[\frac{1 - e_0}{e_0} - \frac{2}{e_0} \right]$$

where $e_0 = P \left\{ A(t) = 0 \mid \mathbf{K}(t); \hat{\psi} \right\}$, $e_1 = P \left\{ A(t) = 1 \mid \mathbf{K}(t); \hat{\psi} \right\}$.

Simulation studies, sample size 1000

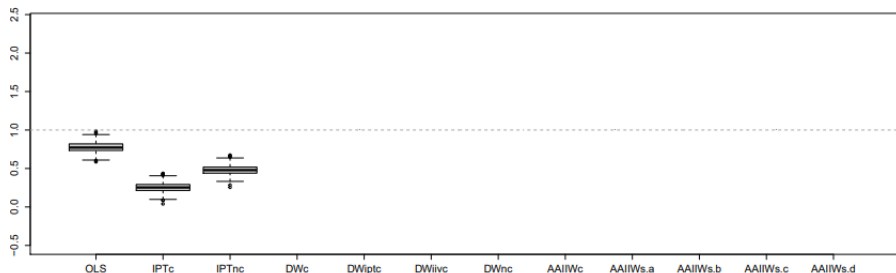
Distribution of 500 estimates:



OLS: Not adjusted for confounding nor irregular observation

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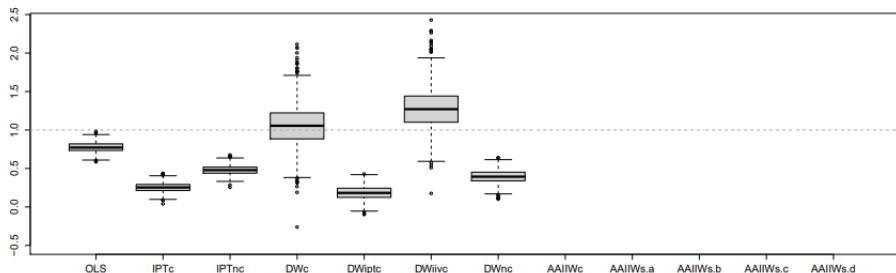


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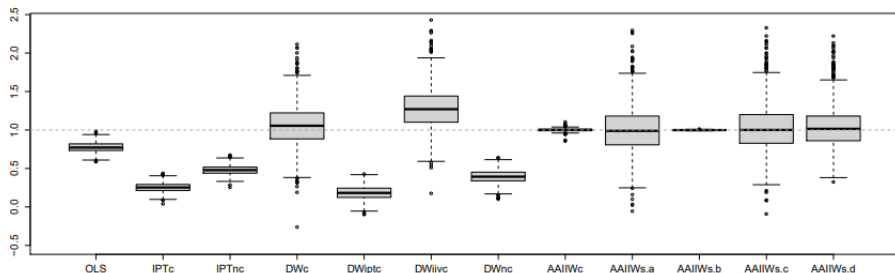
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AAIWc: All nuisance models correctly specified

AAIW.s.a: Two weight models are correctly specified

AAIW.s.b: Two outcome models are correctly specified

AAIW.s.c: IIV and outcome model conditional on confounders are correct

AAIW.s.d: IPT and outcome model conditional on measurement predictors are correct.

Application the Add Health study (Harris, 2009)

- American data on adolescents (4 waves: 1994-1995, 1996, 2001-2002, and 2008-2009)
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- Several confounders of the therapy-alcohol consumption relationship (included age, sex, socioeconomic status (SES), weight, smoking)
- Emulated missingness in the longitudinal outcome as a function of age, sex, counseling, depressive mood (mediator), SES
- Comparison of OLS, IPT, IIV, DW, and AAIW with[†] or without[‡] the correct measurement model

Results of the application

Table 1: Estimates (95% bootstrap percentiles confidence intervals) of the marginal effect of counselling on the average number of alcoholic beverages consumed, *Add Health* study, United States, 1996-2008

OLS	IPT	IIV [†]	IIV [‡]
0.62 (0.39, 0.75)	0.34 (0.15, 0.48)	0.64 (0.40, 0.77)	0.72 (0.49, 0.92)
DW [†]	DW [‡]	AAIIV [†]	AAIIV [‡]
0.35 (0.12, 0.50)	0.46 (0.24, 0.67)	0.35 (0.12, 0.51)	0.28 (0.04, 0.54)

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- Adjustments bring the estimates towards 0 in general
- Wrong IIV weights (Robustness of the AAIIV?):
 - DW[‡]: 0.46 (0.24, 0.67)
 - AAIIV[‡]: 0.28 (0.04, 0.54), i.e., not so far from AAIIV[†]

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- Important limitations: Causal and modeling assumptions, acute treatment effect, availability of other longitudinal processes than the outcome.
- Future avenues of work: Look at the cumulative effect of treatment or the effect of a series of treatments on the irregularly-measured outcome, and develop methods that can address irregularly observed $\mathbf{V}(t)$.

Where to find: The manuscript is under review and available on ArXiv (Coulombe et Yang, 2023).

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