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# IS1204-Mathematical Methods

## 1. Vector Algebra

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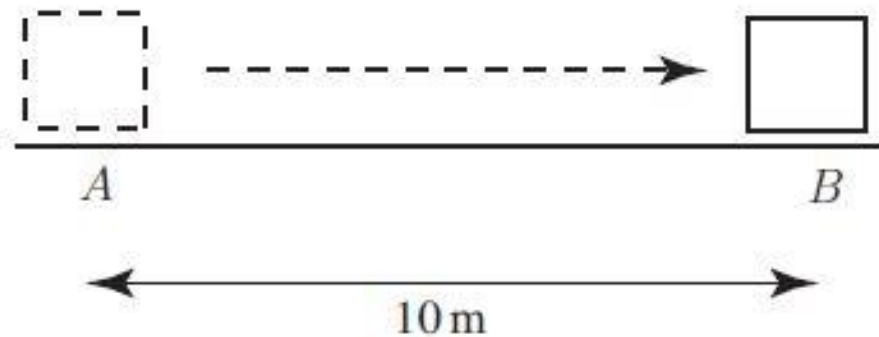
# Learning Outcomes

- Define scalars and vectors
- Define vector operations
- Define a vector in component form
- Find scalar product and vector product
- Discuss applications of scalar and vector products

# Outline

- Introduction: scalars and vectors
- Vector operations: addition, subtraction and multiplication
- Vectors in component form
- Scalar product and Vector product
- Applications of scalar and vector product

# What are Vectors ?



Referring to the figure,

- Distance ?
- Displacement ?

# Vectors and Scalars

Physical quantities can be divided into two main groups **scalar quantities** and **vector quantities**.

***Scalar:*** Quantity having magnitude but no direction.

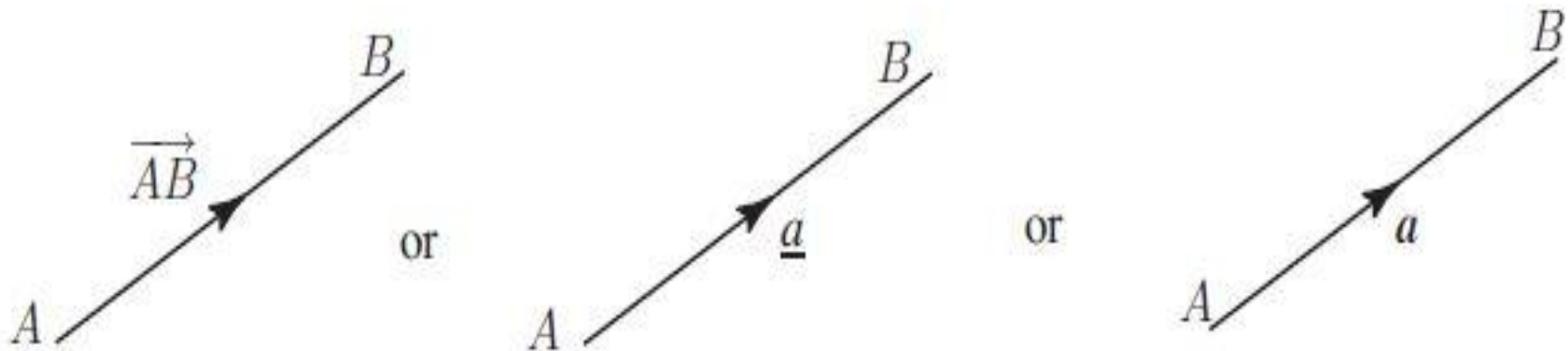
E.g. Length, Area, Volume, Mass etc...

***Vector:*** Quantity having both magnitude and direction.

E.g. Force, Velocity, Acceleration etc....

# Representation of Vectors

Vectors can be represented in different ways.



**Magnitude** of a vector:  $|\overrightarrow{AB}|$  or  $|\underline{a}|$ .

# Types of Vectors

- a. **Unit vector:** A vector which has a magnitude of 1 and is given by  $\hat{a} = \frac{\underline{a}}{|\underline{a}|}$ .
- b. **Equal vectors:** Two vectors are said to be equal vectors if they have the same magnitude and same direction.
- c. **Zero or Null vector:** A vector whose magnitude is zero.
- d. **Negative of a vector:** The vector which has the same magnitude as the vector  $\underline{a}$  but opposite in direction. It is represented by  $-\underline{a}$ .

# Vector Operations

## I. Addition of vectors

A vector whose effect is the same as a set of two vectors is called the sum or resultant of the given vectors.

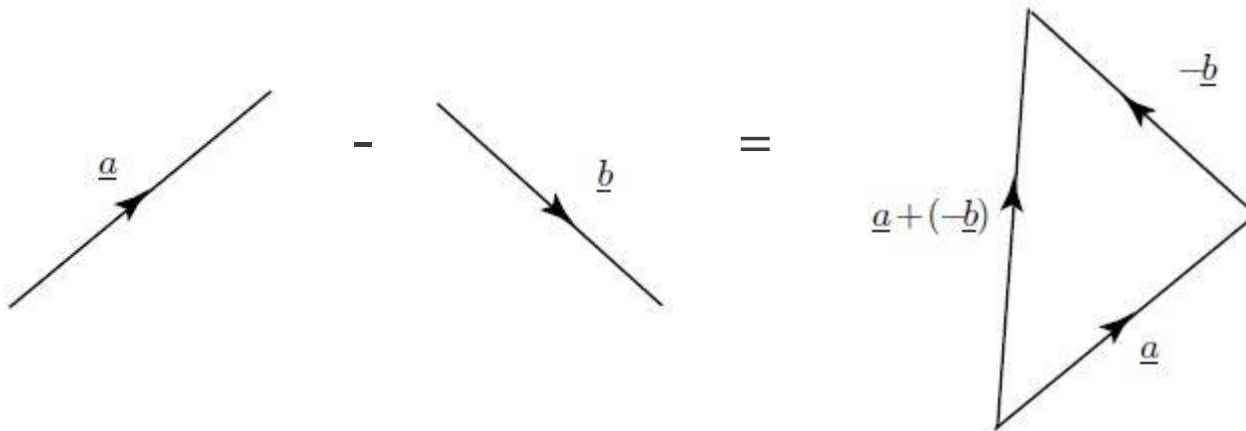




# Vector Operations contd..

## II. Subtraction of vectors

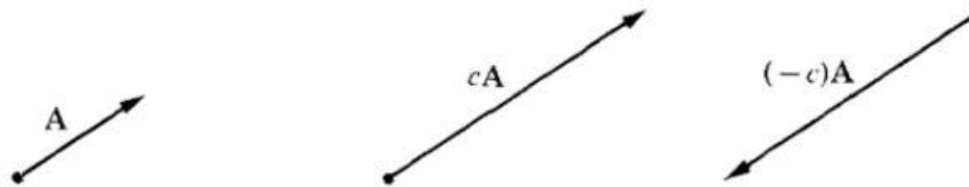
Subtraction of one vector from another is performed by adding the corresponding negative vector.



# Vector Operations contd..

## III. Scalar multiplication

Let  $\underline{\mathbf{A}}$  be a given vector and  $c$  be a scalar. Then, the product of the vector  $\underline{\mathbf{A}}$  by the scalar  $c$  is  $c\underline{\mathbf{A}}$ .

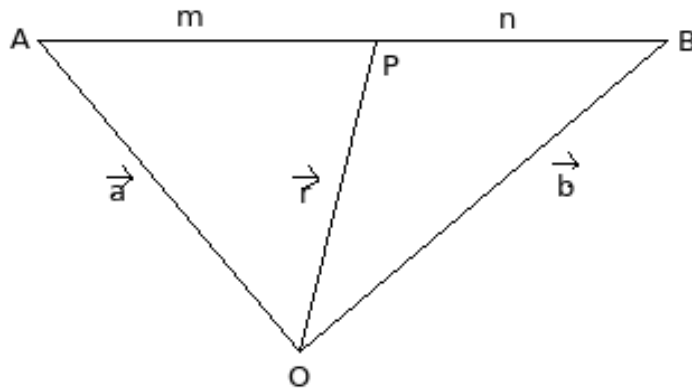


### Properties of vector operations:

1.  $\underline{\mathbf{a}} + \underline{\mathbf{b}} = \underline{\mathbf{b}} + \underline{\mathbf{a}}$  (Commutative)
2.  $(\underline{\mathbf{a}} + \underline{\mathbf{b}}) + \underline{\mathbf{c}} = \underline{\mathbf{a}} + (\underline{\mathbf{b}} + \underline{\mathbf{c}})$  (Associative)
3.  $(m + n)\underline{\mathbf{a}} = m\underline{\mathbf{a}} + n\underline{\mathbf{a}}$
4.  $m(\underline{\mathbf{a}} + \underline{\mathbf{b}}) = m\underline{\mathbf{a}} + m\underline{\mathbf{b}}$

# Ratio Formula

Let A and B be two points with position vectors  $\vec{a}$  and  $\vec{b}$ , C divides AB in the ratio of  $m:n$ .



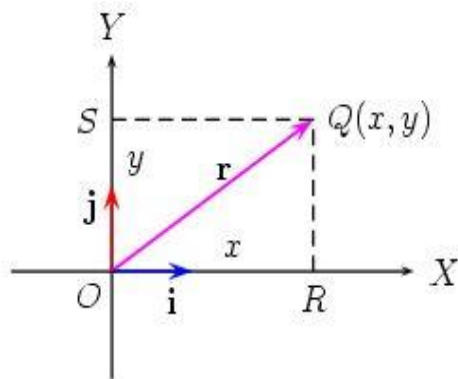
$$\overrightarrow{OP} = \frac{n\vec{a} + m\vec{b}}{n + m}$$

## ***Example 4.1:***

Prove that line joining the mid-point of two sides of a triangle is parallel to the third and half of its magnitude.

# Vectors in Component Form

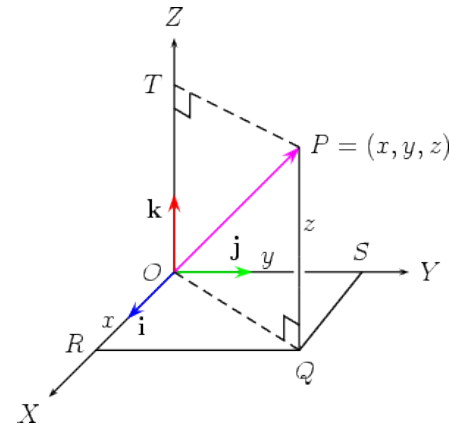
## Two-Dimensional Representation



$$\overrightarrow{OQ} = \underline{r} = x\underline{i} + y\underline{j}$$

$$|\overrightarrow{OQ}| = |\underline{r}| = \sqrt{x^2 + y^2}$$

## Three-Dimensional Representation



$$\overrightarrow{OP} = \underline{r} = x\underline{i} + y\underline{j} + z\underline{k}$$

$$|\overrightarrow{OP}| = |\underline{r}| = \sqrt{x^2 + y^2 + z^2}$$

### Example 4.2:

If the coordinates of the point P be (3,4,12) then find  $\overrightarrow{OP}$ , its magnitude and direction cosines.

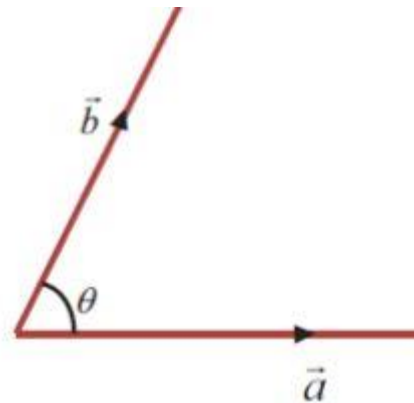
# Vector Multiplication

## I. Scalar product (Dot product)

Let  $\underline{\mathbf{a}}$  and  $\underline{\mathbf{b}}$  be two non-zero vectors and  $\theta$  be the angle between them with  $0 < \theta < \pi$ .

Scalar or dot product of  $\underline{\mathbf{a}}$  and  $\underline{\mathbf{b}}$  is defined as:

$$\underline{\mathbf{a}} \cdot \underline{\mathbf{b}} = |\underline{\mathbf{a}}| |\underline{\mathbf{b}}| \cos \theta$$



Algebraically, the dot product is defined as follows:

If  $(a_1\underline{i} + a_2\underline{j} + a_3\underline{k})$  and  $(b_1\underline{i} + b_2\underline{j} + b_3\underline{k})$ , then

$$\begin{aligned}\underline{a} \cdot \underline{b} &= (a_1\underline{i} + a_2\underline{j} + a_3\underline{k}) \cdot (b_1\underline{i} + b_2\underline{j} + b_3\underline{k}) \\ &= a_1b_1 + a_2b_2 + a_3b_3\end{aligned}$$

***Example 4.3:***

Find the projection of the vector  $\underline{i} - 2\underline{j} + \underline{k}$  on  $4\underline{i} - 4\underline{j} + 7\underline{k}$

## Properties of Scalar Product

$$1. \underline{a} \cdot \underline{b} = \underline{b} \cdot \underline{a}$$

$$2. \underline{a} \cdot (\underline{b} + \underline{c}) = \underline{a} \cdot \underline{b} + \underline{a} \cdot \underline{c}$$

$$3. \text{ If } k \text{ is a scalar, then } k(\underline{a} \cdot \underline{b}) = (k\underline{a}) \cdot \underline{b} = \underline{a} \cdot (k\underline{b})$$

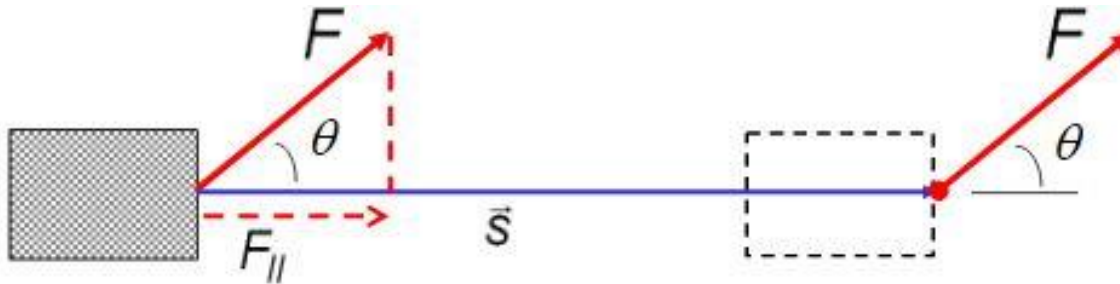
$$4. \underline{i} \cdot \underline{i} = \underline{j} \cdot \underline{j} = \underline{k} \cdot \underline{k} = 1 \text{ and } \underline{i} \cdot \underline{j} = \underline{i} \cdot \underline{k} = \underline{j} \cdot \underline{k} = 0$$

$$5. \text{ If } \underline{a} \text{ and } \underline{b} \text{ are orthogonal, then } \underline{a} \cdot \underline{b} = 0$$

# Application of Scalar Product

## I. Work Done

Let a constant force  $\mathbf{F}$  acting on an object during a displacement  $\mathbf{s}$ .



$$\begin{aligned} W &= (\text{Force}).(\text{Displacement}) \\ &= \underline{\underline{F.s}} \end{aligned}$$

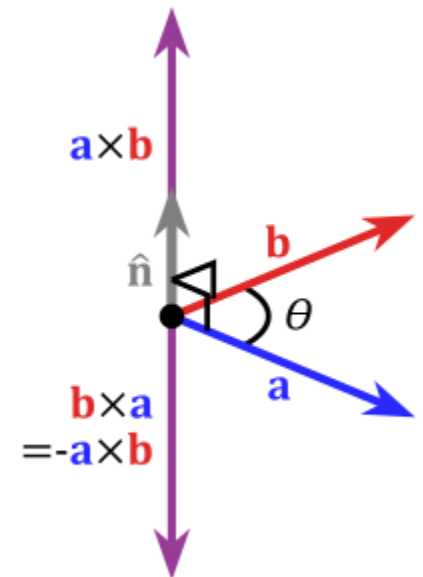


## II. Vector product (Cross product)

Let  $\underline{\mathbf{a}}$  and  $\underline{\mathbf{b}}$  be two non-zero vectors and  $\theta$  be the angle between them with  $0 < \theta < \pi$ .

Vector or cross product of  $\underline{\mathbf{a}}$  and  $\underline{\mathbf{b}}$  is defined as:

$$\underline{\mathbf{a}} \times \underline{\mathbf{b}} = |\underline{\mathbf{a}}||\underline{\mathbf{b}}| \sin \theta \hat{\mathbf{n}}$$



Algebraically, the cross product is defined as follows:

If  $(a_1 \underline{i} + a_2 \underline{j} + a_3 \underline{k})$  and  $(b_1 \underline{i} + b_2 \underline{j} + b_3 \underline{k})$ , then

$$\underline{a} \times \underline{b} = (a_1 \underline{i} + a_2 \underline{j} + a_3 \underline{k}) \times (b_1 \underline{i} + b_2 \underline{j} + b_3 \underline{k})$$

$$= \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

## Properties of vector cross product

$$1. \underline{a} \times \underline{b} = -(\underline{b} \times \underline{a})$$

$$2. (k\underline{a}) \times \underline{b} = k(\underline{a} \times \underline{b}) = \underline{a} \times (k\underline{b})$$

$$3. \underline{a} \times (\underline{b} + \underline{c}) = \underline{a} \times \underline{b} + \underline{a} \times \underline{c}$$

$$4. (\underline{a} + \underline{b}) \times \underline{c} = \underline{a} \times \underline{c} + \underline{b} \times \underline{c}$$

$$5. \underline{i} \times \underline{i} = \underline{j} \times \underline{j} = \underline{k} \times \underline{k} = 0 \text{ and } \underline{i} \times \underline{j} = \underline{k}, \underline{j} \times \underline{k} = \underline{i}, \underline{k} \times \underline{i} = \underline{j}$$

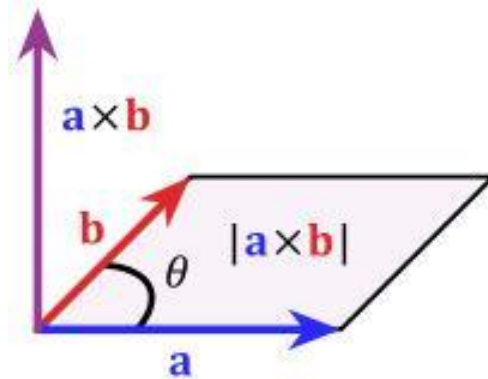
$$6. \text{ If } \underline{a} \text{ and } \underline{b} \text{ are parallel, then } \underline{a} \times \underline{b} = 0$$

# Applications of Vector Product

## I. Area of a parallelogram

The magnitude of the cross product can be interpreted as the positive area of the parallelogram having **a** and **b** as sides.

$$\text{Area} = |\underline{a} \times \underline{b}|$$

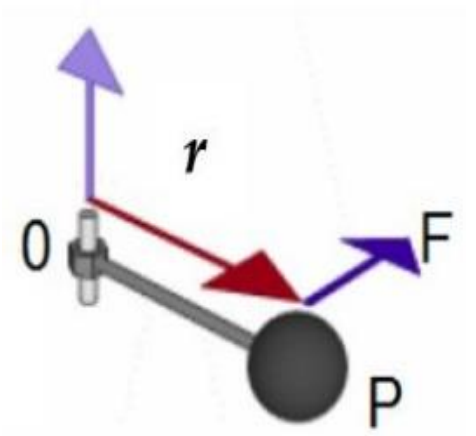


## II. Moment of a force about a point

If a force  $\mathbf{F}$  acting through a point P with position vector  $\mathbf{r}$  with respect to O, then  $\mathbf{F}$  and  $\mathbf{r}$  lie in a plane through O.

The **torque** or **moment** of  $\mathbf{F}$  about an axis through O perpendicular to this plane is given by

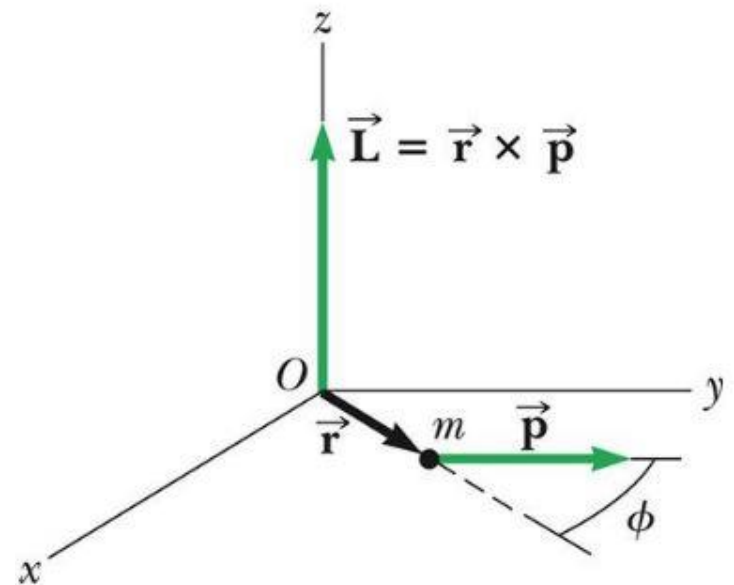
$$\mathbf{T} = \mathbf{r} \times \mathbf{F} = |\mathbf{r}| |\mathbf{F}| \sin \theta \boldsymbol{\eta}$$



### III. Angular momentum

Let a particle of mass  $m$  located at the vector position  $\mathbf{r}$  and moving with linear momentum  $\mathbf{p}$ . The **angular momentum** of the particle is defined as;

$$\mathbf{L} = \mathbf{r} \times \mathbf{p}$$



# Summary

- A vector is a quantity which has magnitude as well as direction while scalar is a quantity which has only magnitude. Vector is denoted by  $\overrightarrow{OP}$
- Unit coordinator vectors  $\underline{i}, \underline{j}, \underline{k}$  are taken as unit vectors along axis  $\overrightarrow{OP} = \underline{r} = x\underline{i} + y\underline{j} + z\underline{k}$
- Magnitude of a vector:  $|\overrightarrow{OP}| = |\underline{r}| = \sqrt{x^2 + y^2 + z^2}$
- Unit vector of  $\underline{a}$  (non-zero vector), then  $\hat{a} = \frac{\underline{a}}{|\underline{a}|}$ .

# Summary contd..


- Scalar product of **a** and **b**:  $\underline{a} \cdot \underline{b} = |\underline{a}| |\underline{b}| \cos \theta$ 
  1.  $\underline{i} \cdot \underline{i} = \underline{j} \cdot \underline{j} = \underline{k} \cdot \underline{k} = 1$  while  $\underline{i} \cdot \underline{j} = \underline{i} \cdot \underline{k} = \underline{j} \cdot \underline{k} = 0$
  2. If a and b are perpendicular, then  $\underline{a} \cdot \underline{b} = 0$
  3.  $\underline{a} \cdot \underline{b} = (a_1 \underline{i} + a_2 \underline{j} + a_3 \underline{k}) \cdot (b_1 \underline{i} + b_2 \underline{j} + b_3 \underline{k}) = a_1 b_1 + a_2 b_2 + a_3 b_3$
- Vector product of **a** and **b**:  $\underline{a} \times \underline{b} = |\underline{a}| |\underline{b}| \sin \theta \hat{n}$ 
  1. If a and b are parallel, then  $\underline{a} \times \underline{b} = 0$
  2.  $\underline{i} \times \underline{i} = \underline{j} \times \underline{j} = \underline{k} \times \underline{k} = 0$  and  $\underline{i} \times \underline{j} = \underline{k}, \underline{j} \times \underline{k} = \underline{i}, \underline{k} \times \underline{i} = \underline{j}$
  3.  $\underline{a} \times \underline{b} = (a_1 \underline{i} + a_2 \underline{j} + a_3 \underline{k}) \times (b_1 \underline{i} + b_2 \underline{j} + b_3 \underline{k}) = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$



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# Thank You..!!

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