Operating System Concepts

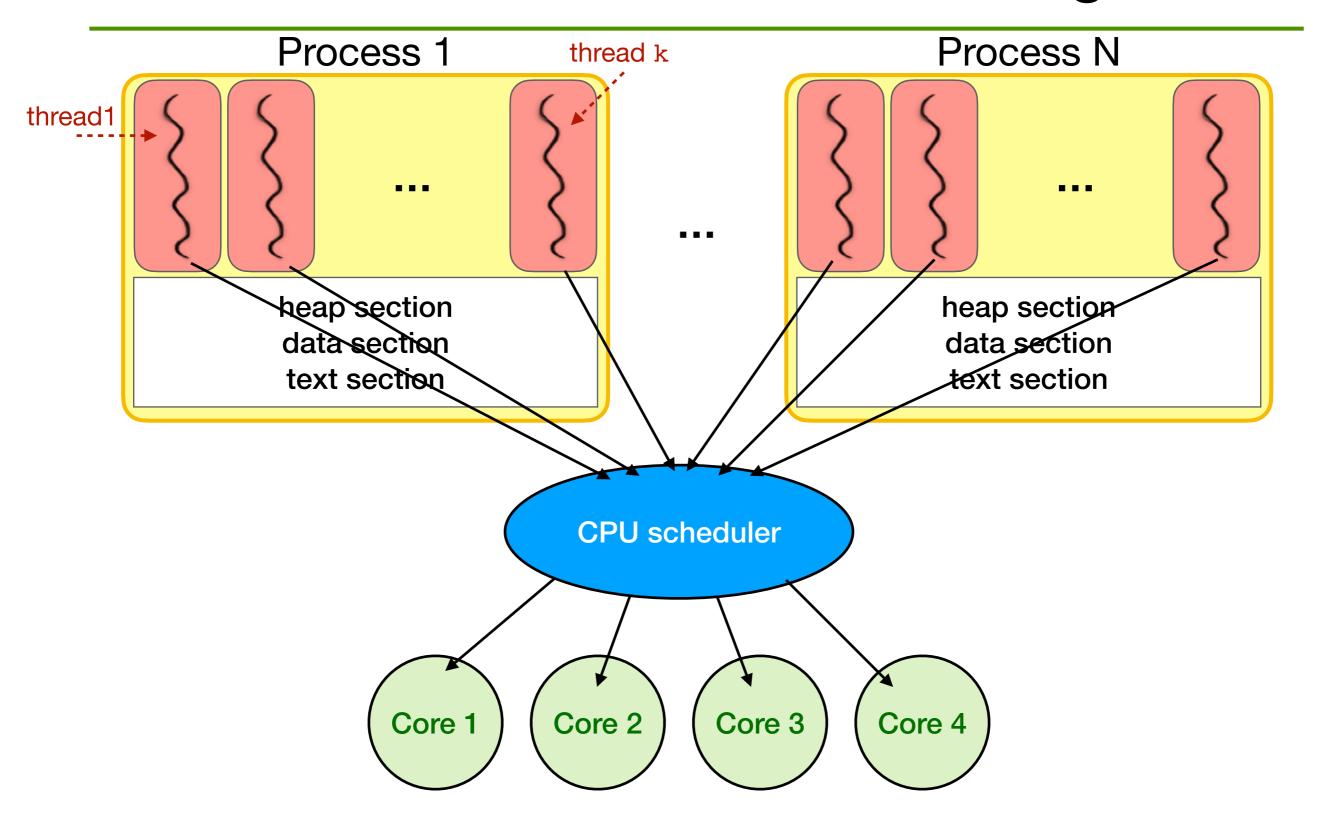
Lecture 12: CPU Scheduling - Part 2

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Recap

- Turnaround time: time elapsed from task submission until task completion
- Response time: time elapsed from task submission until the first response is produced
- Waiting time: total time spent by a task waiting in the ready queue
- Throughput: rate of task completion
- CPU utilization: percentage of time CPU is busy (i.e. the ready queue is not empty)

Process versus thread scheduling



Assumptions

- We make a couple of simplifying assumptions today
 - one process per user
 - one thread per process
 - independent processes
 - just one processing core
- Scheduling algorithms were developed in the 70's when these assumptions were realistic

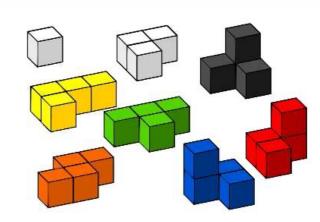
Today's class

Scheduling algorithms

- FCFS: First-Come, First-Served

- RR: Round Robin

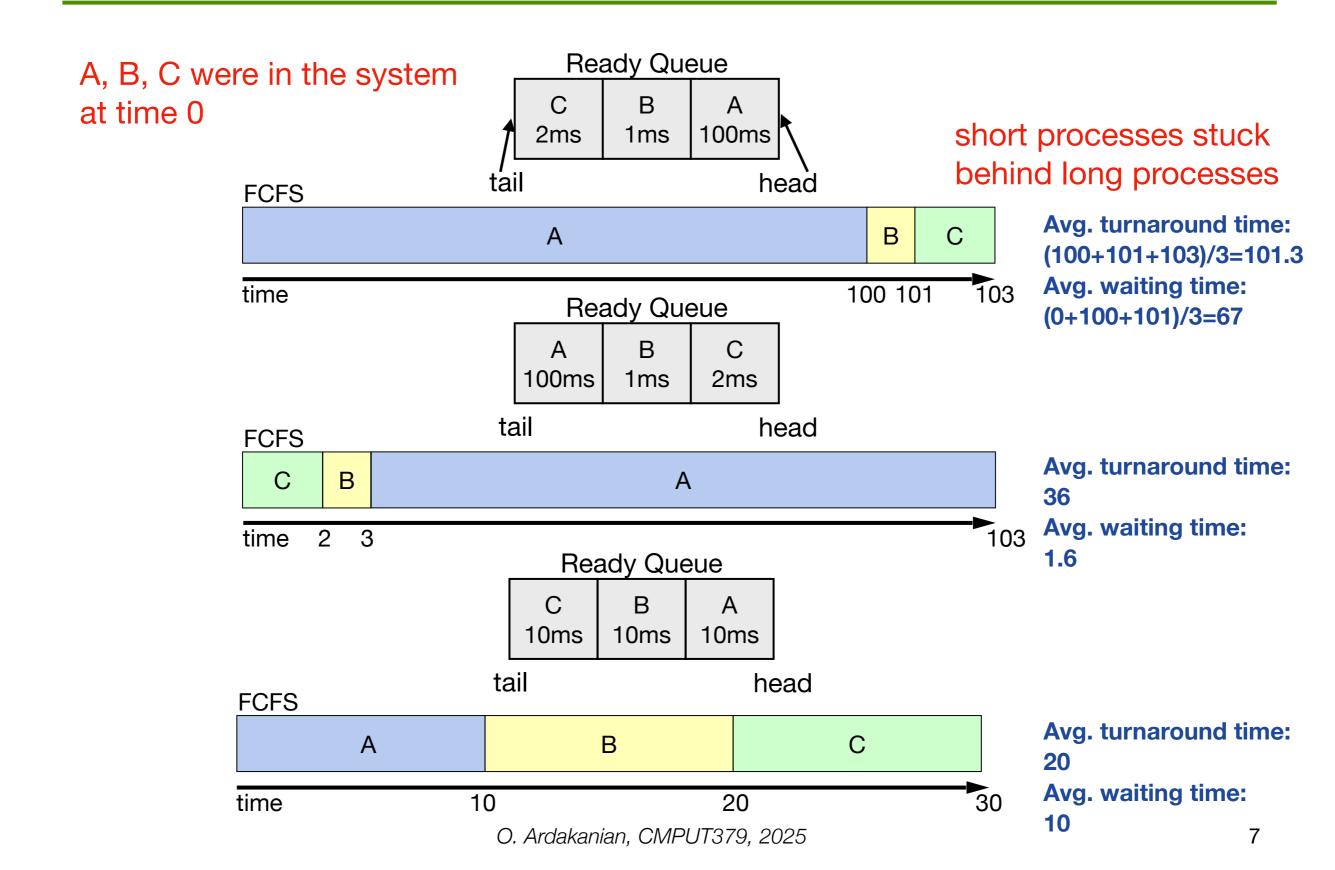
- SJF: Shortest Job First



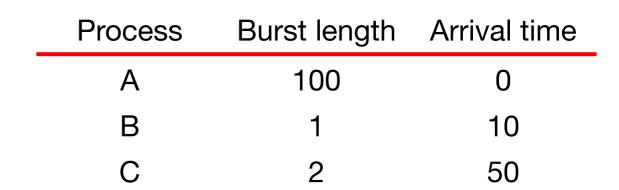
FCFS scheduling

- FCFS: First-Come-First-Served (or FIFO)
 - the scheduler executes jobs to completion in the order they arrive
 - in early FCFS schedulers, the job did not relinquish the CPU even when it was doing I/O
 - we will assume a FCFS scheduler that runs when processes are blocked waiting for I/O, but that is non-preemptive, i.e., the job keeps the CPU until it blocks (say on an I/O device)

FCFS example



FCFS example



FCFS



Avg. turnaround time: [100+(101-10)+(103-50)]/3 = 81.3

Avg. waiting time: [0+(100-10)+(101-50)]/3= 47

Pros and cons of FCFS scheduling

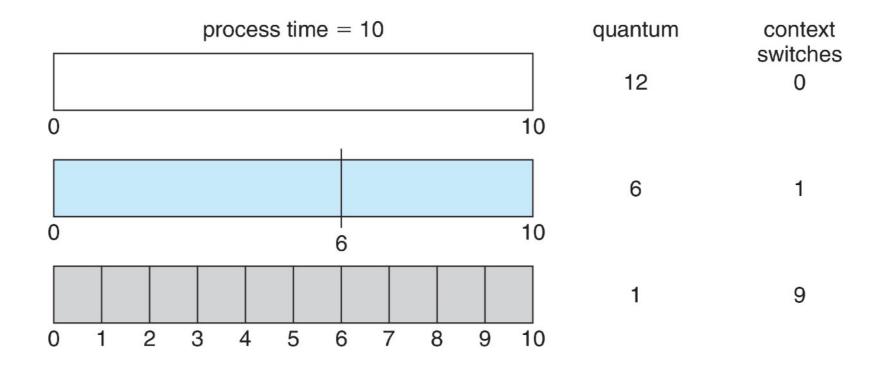
- Advantage: simplicity and low overhead
- Disadvantage:
 - average wait time is highly variable as short jobs may wait behind long jobs
 - if tasks are variable in size, FCFS can cause poor response time on average
 - If tasks are equal in size, FCFS is optimal in terms of average response time
 - not fair
 - may lead to poor overlap of I/O and CPU since CPU bound processes will force I/O bound processes to wait for the CPU, leaving the I/O devices idle

Round Robin scheduling

- Each task gets resources for a fixed period of time (time quantum)
 - if it does not finish its execution, it goes back in line (inserted at the end of the ready queue)
 - how to implement? add a timer and use a **preemptive** policy
- With quantum length Q ms, process waits at most (N-1)*Q ms to run again if there is a total of N processes

Round Robin scheduling

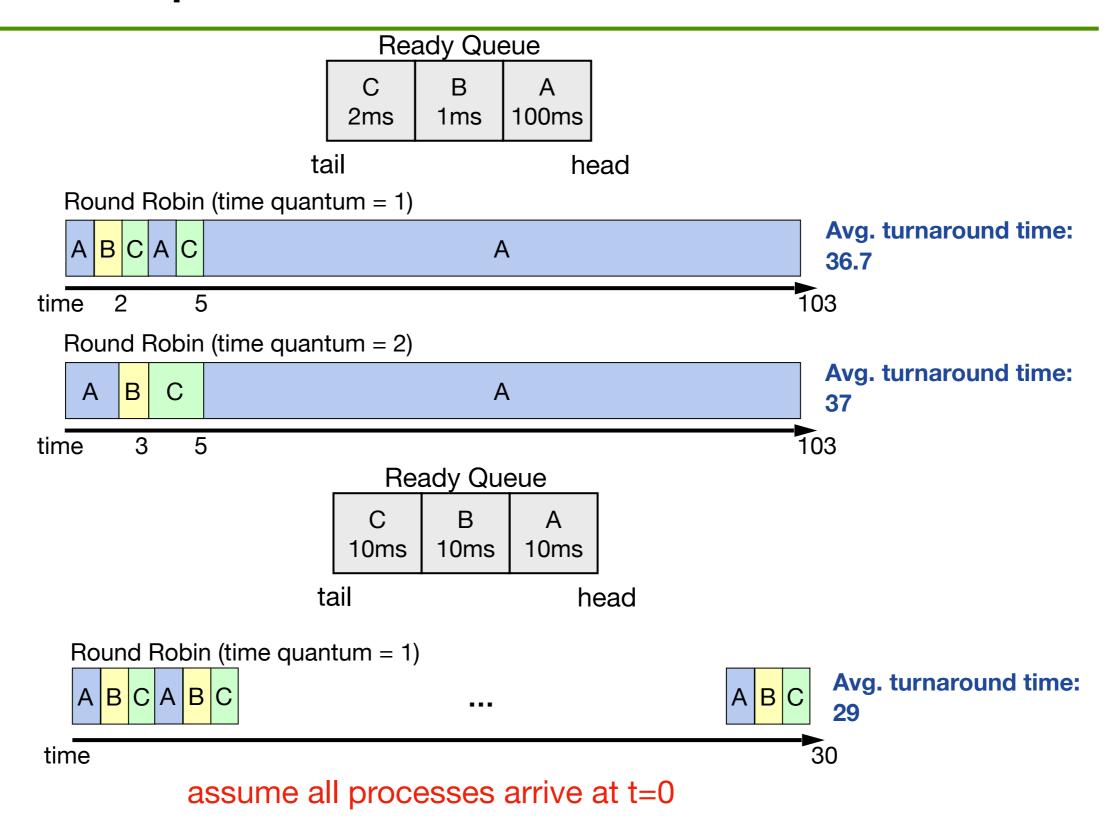
- Choosing the time quantum (Q) is key
 - if too long waiting time suffers, degenerates to FCFS if processes are never preempted
 - if too short throughput suffers because too much time is spent context switching (high overhead)
- It is possible to strike a balance between waiting time and throughput by selecting a time slice where context switching is roughly 1% of the time slice
 - today: typical time slice is 10-100ms, context switch time is 0.1-1ms



Pros and cons of Round Robin scheduling

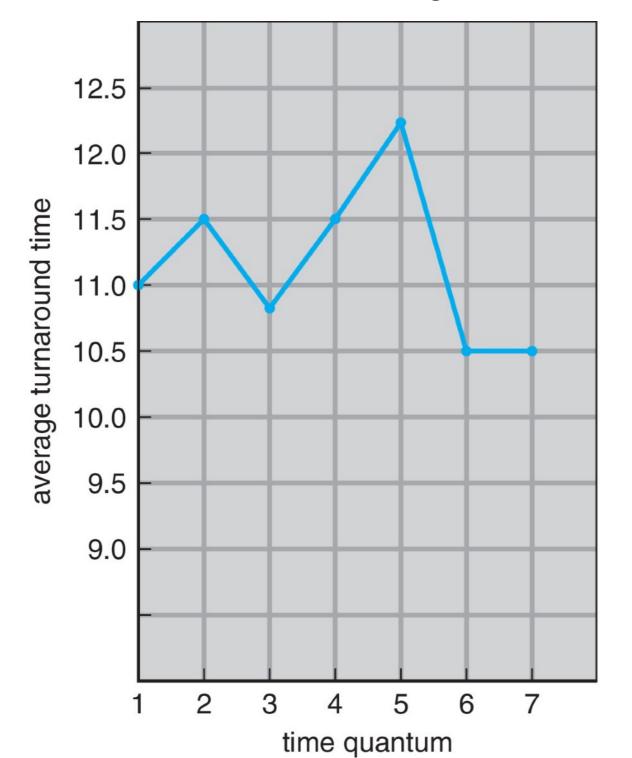
- Variants of the round robin scheduling are used in most time-sharing systems
- Advantage: round robin is fair; each job gets an equal shot at the CPU
- Disadvantage: average waiting time can be bad if tasks are equal in size

RR example



Setting the time quantum

suppose there is no context switching overhead and all process arrive at t=0



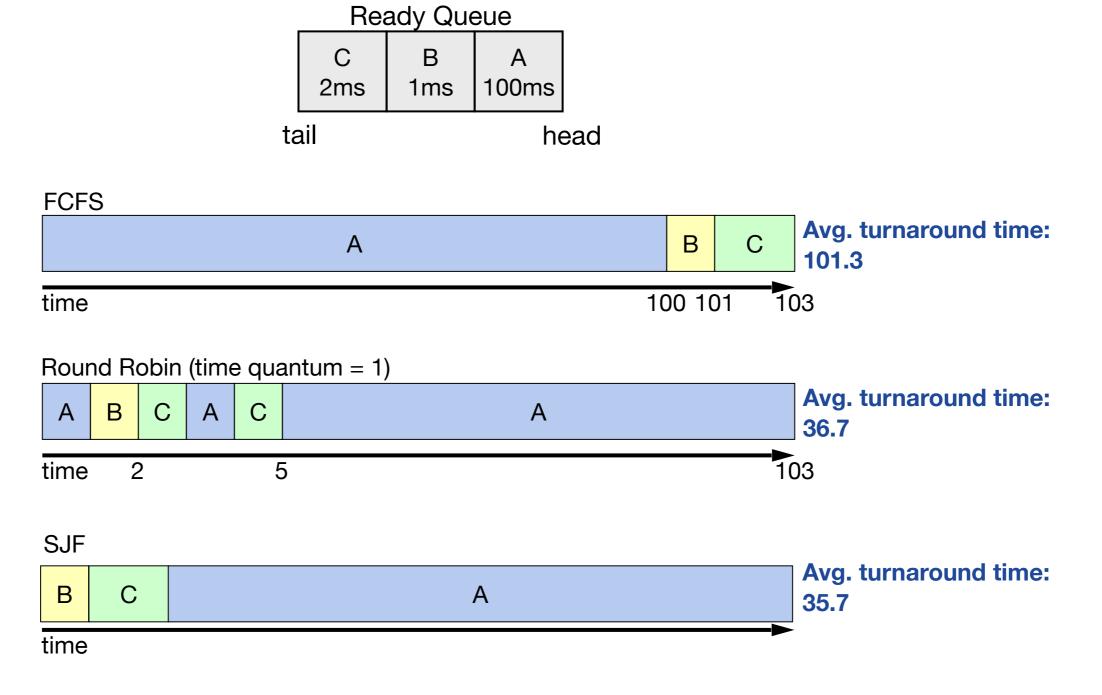
| process | time |
|---------|------|
| P_1 | 6 |
| P_2 | 3 |
| P_3 | 1 |
| P_4 | 7 |

increasing the time quantum can have different effects on the average turnaround time

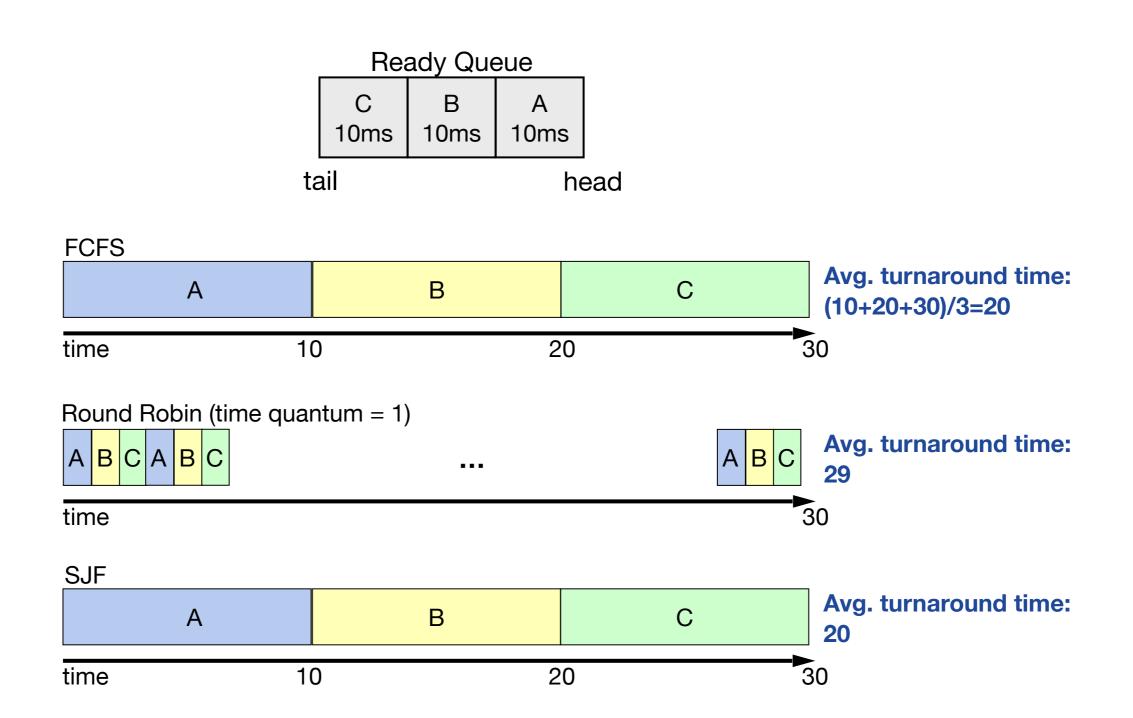
SJF scheduling

- Schedule the job that has the least (expected) amount of work (CPU time) to do until its next I/O request or termination
 - much less sensitive to the arrival order!
- If tasks are variable in size, Round Robin approximates SJF
- Advantages
 - provably optimal with respect to minimizing the average waiting time
 - works for preemptive and non-preemptive systems
 - preemptive SJF is called Shortest Remaining Time First (SRTF)
- Disadvantages
 - it is not possible to accurately predict the amount of CPU time that a job needs
 - with SRTF, long running CPU bound jobs can starve (if new short jobs keep arriving)

Scenario A

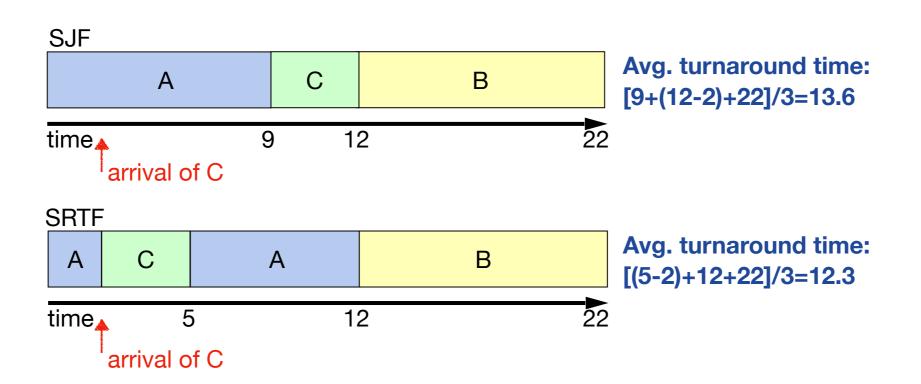


Scenario B



Comparing SRTF and SJF

| | Process | Burst length | Arrival time |
|---|---------|--------------|--------------|
| Ī | Α | 9 | 0 |
| | В | 10 | 0 |
| | С | 3 | 2 |



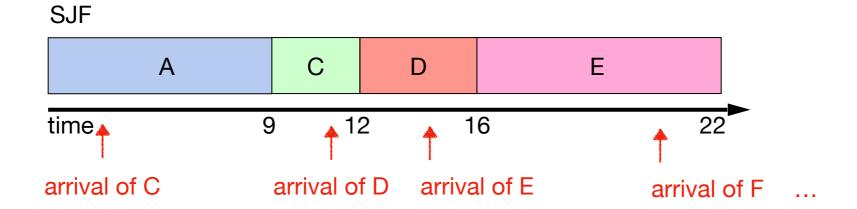
But how do we know the burst length of a process?

- Burst length can be estimated based on previous burst lengths
 - the exponential moving average estimator gives more importance to the recent past
 - $\hat{b}[1] = b[1]$
 - $\hat{b}[t] = \eta b[t] + (1 \eta)\hat{b}[t 1]$ for $\eta \in (0, 1]$
- Users can provide a burst length of their task
 - they can lie (declare a shorter burst length) to game the system
 - how to encourage truthfulness? terminate execution after the specified burst length has passed

SJF is starvation prone

Is SRJT starvation prone too?

| Process | Burst length | Arrival time |
|---------|--------------|--------------|
| А | 9 | 0 |
| В | 10 | 0 |
| С | 3 | 2 |
| D | 4 | 11 |
| E | 6 | 14 |



В

it may remain in the ready queue forever

Homework

- Suppose 1 long process (with burst size of 100 units) and n short processes (with burst size of 1 unit each) arrive in the system in a random order at time 0. Under the SJF policy
 - what is the probability that a short process gets stuck behind the large task?
 - how long is the long process expected to wait?