CS 225

Data Structures

March 24– Graphs

G Carl Evans

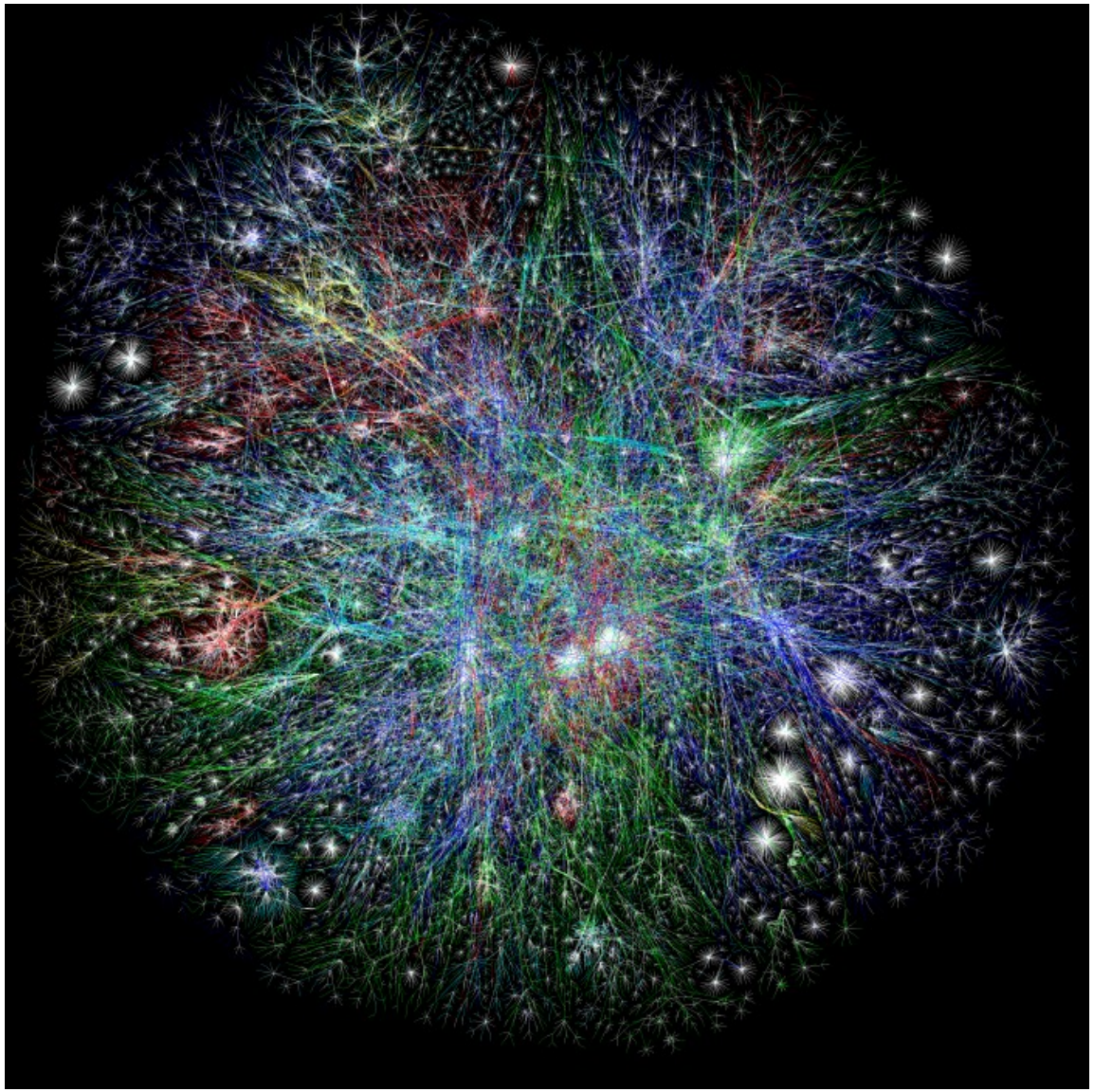
In Review: Data Structures

Array

- Sorted Array
- Unsorted Array
  - Stacks
  - Queues
  - Priority Queues
    - Heaps
  - Disjoint Sets
    - UpTrees

Linked

- Doubly Linked List
- Trees
  - BTree
  - Binary Tree
    - Huffman Encoding
    - kd-Tree
    - AVL Tree

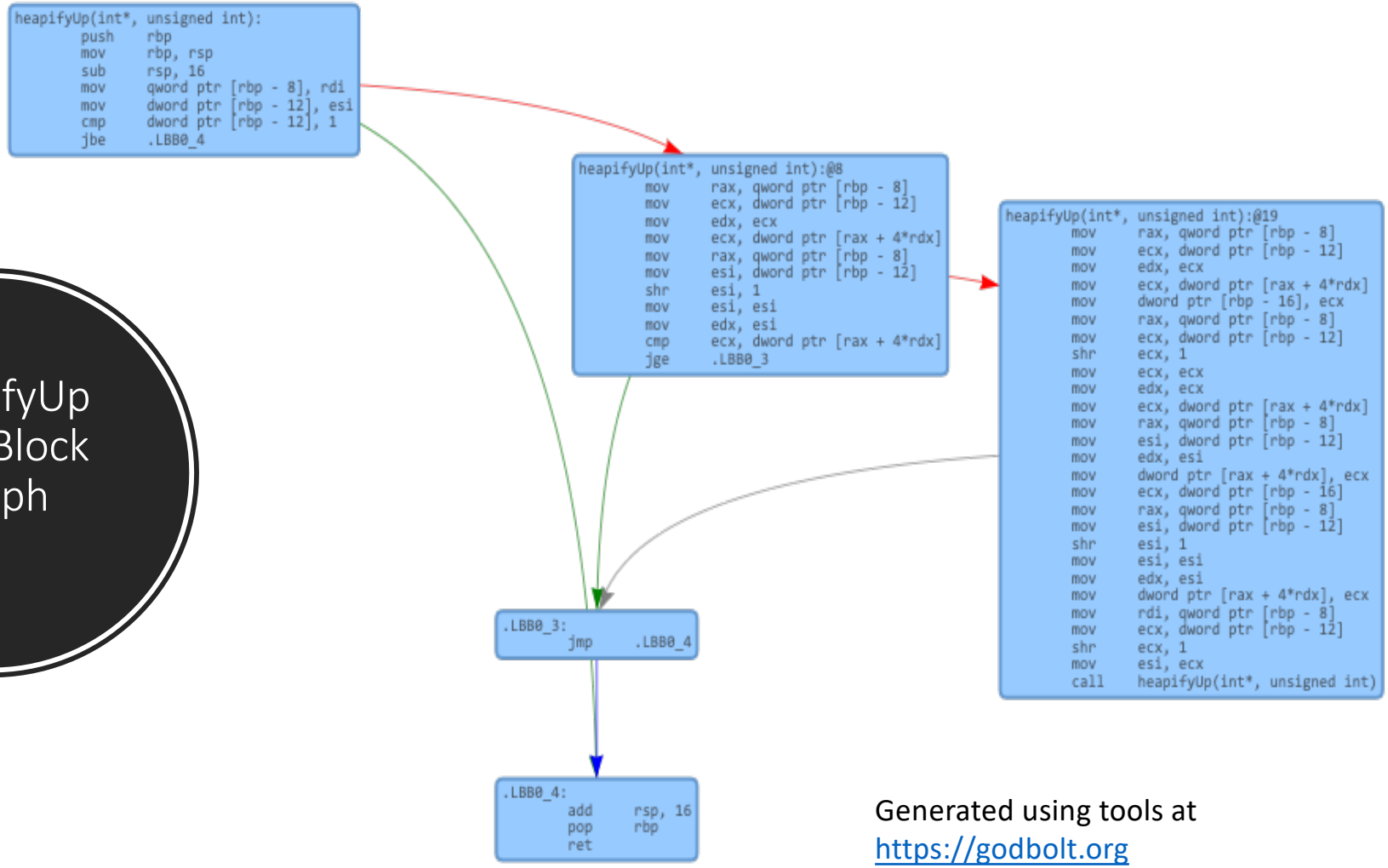


The Internet 2003

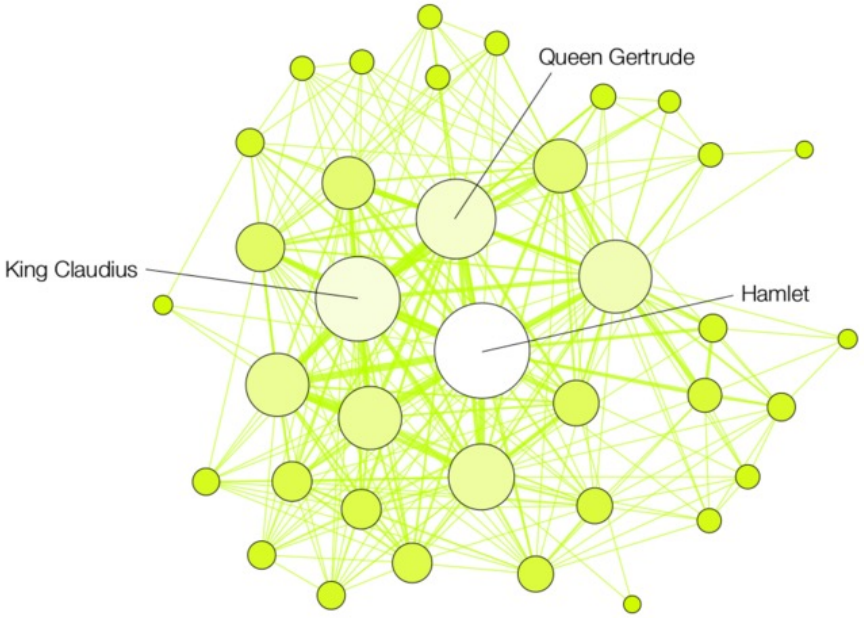
The OPTE Project (2003)

Map of the entire internet; nodes are routers; edges are connections.

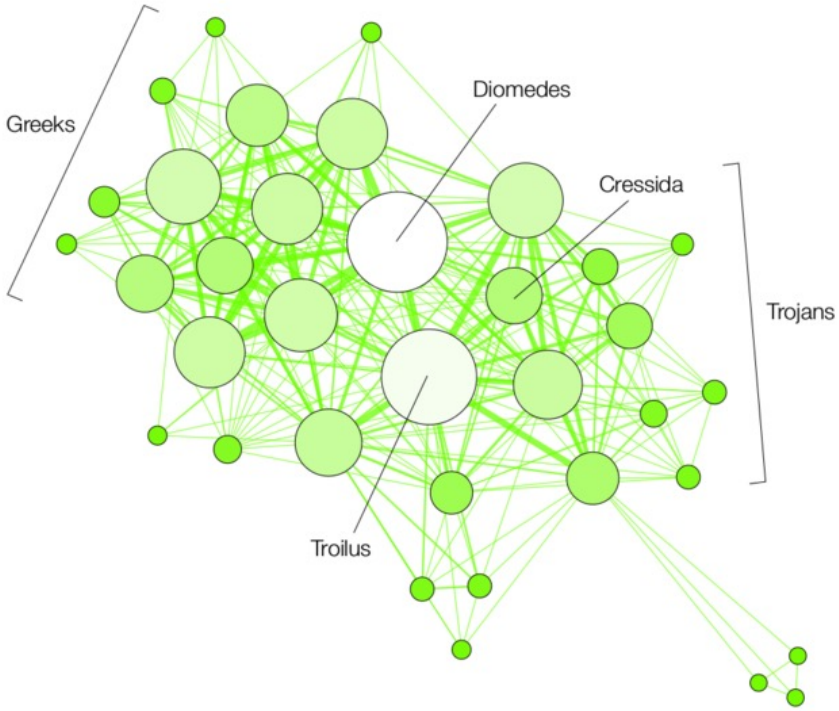
HeapifyUp BasicBlock Graph



Generated using tools at https://godbolt.org



HAMLET

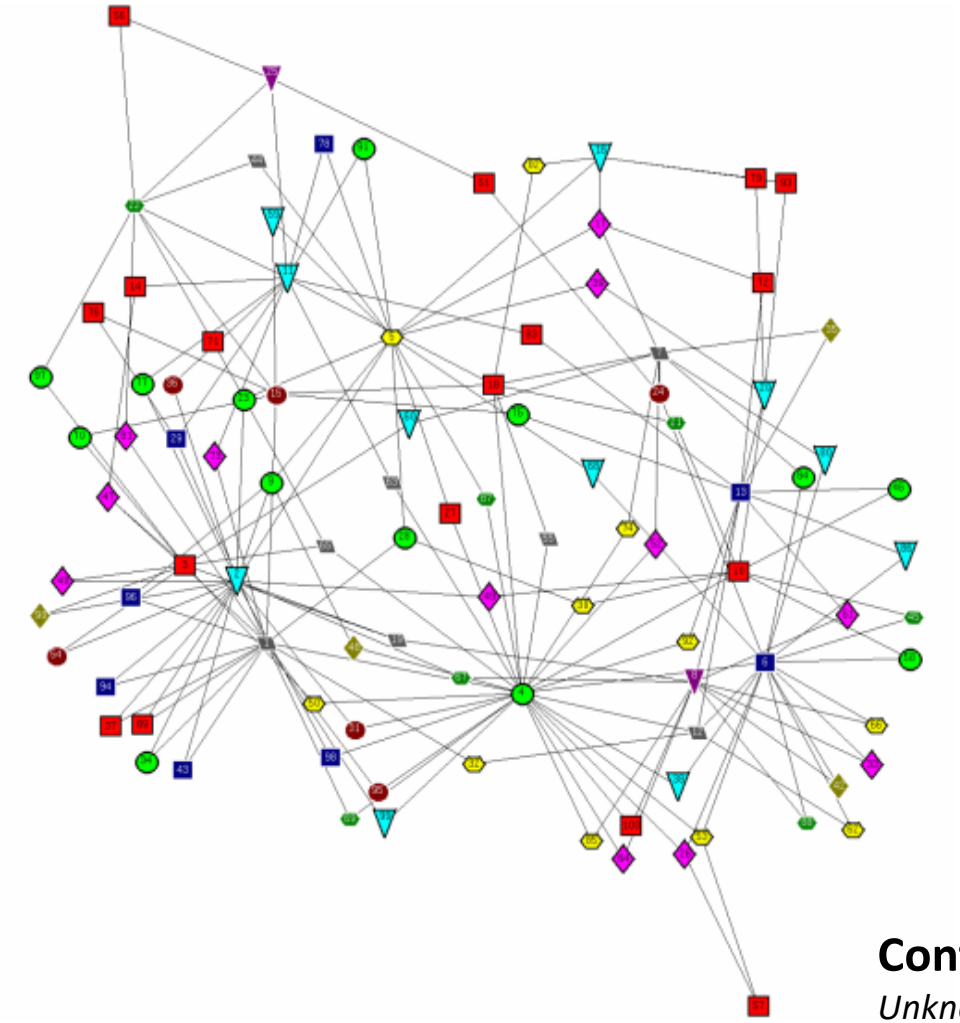


TROILUS AND CRESSIDA

Who's the real main character in Shakespearean tragedies?

Martin Grandjean (2016)

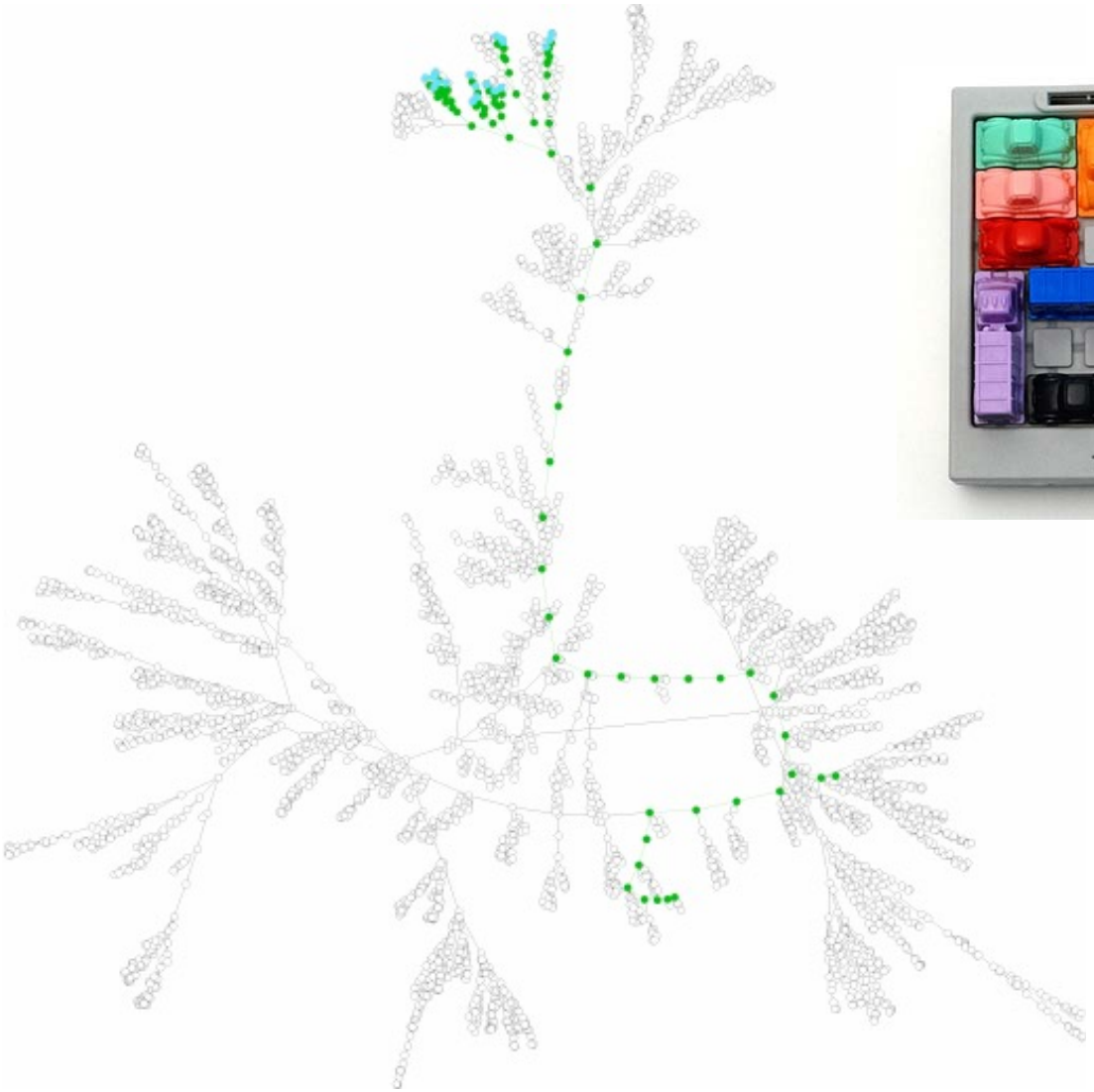
https://www.pbs.org/newshour/arts/whos-the-real-main-character-in-shakespearen-tragedies-heres-what-the-data-say



Conflict-Free Final Exam Scheduling Graph

Unknown Source

Presented by Cinda Heeren, 2016



“Rush Hour” Solution

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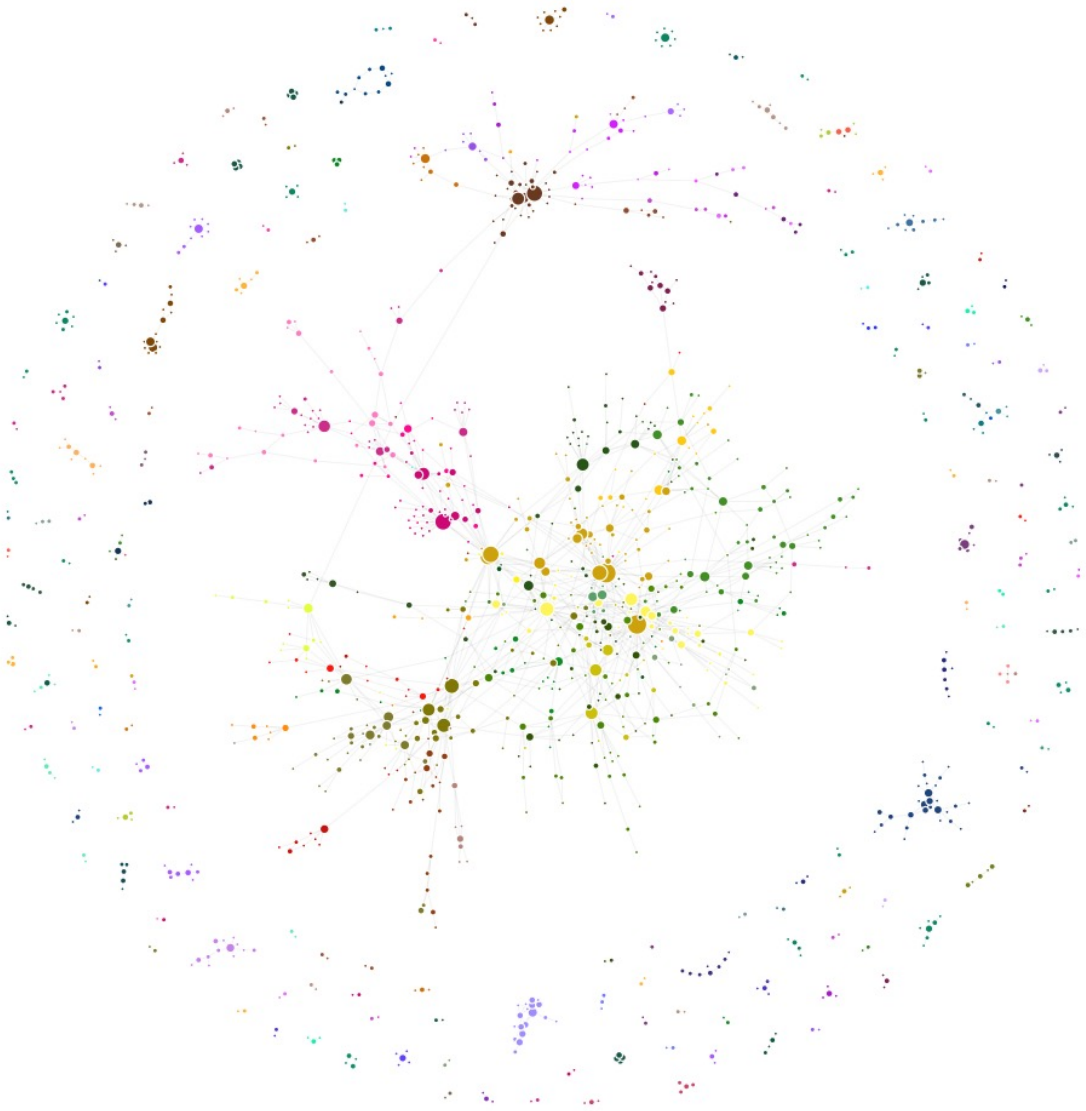
Presented by Cinda Heeren, 2016

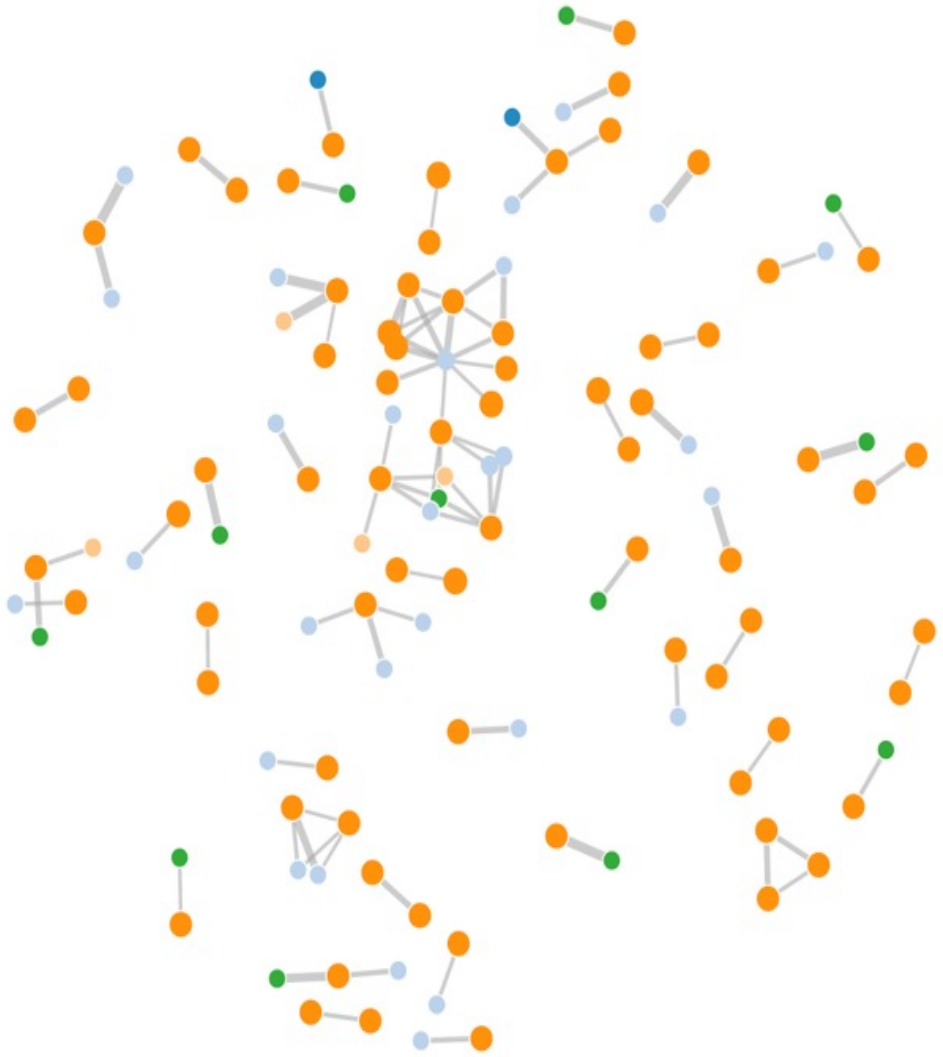


Class Hierarchy At University of Illinois Urbana-Champaign

A. Mori, W. Fagen-Ulmschneider, C. Heeren

Graph of every course at UIUC; nodes are courses, edges are prerequisites

http://waf.cs.illinois.edu/discovery/class_hierarchy_at_illinois/



MP Collaborations in CS 225

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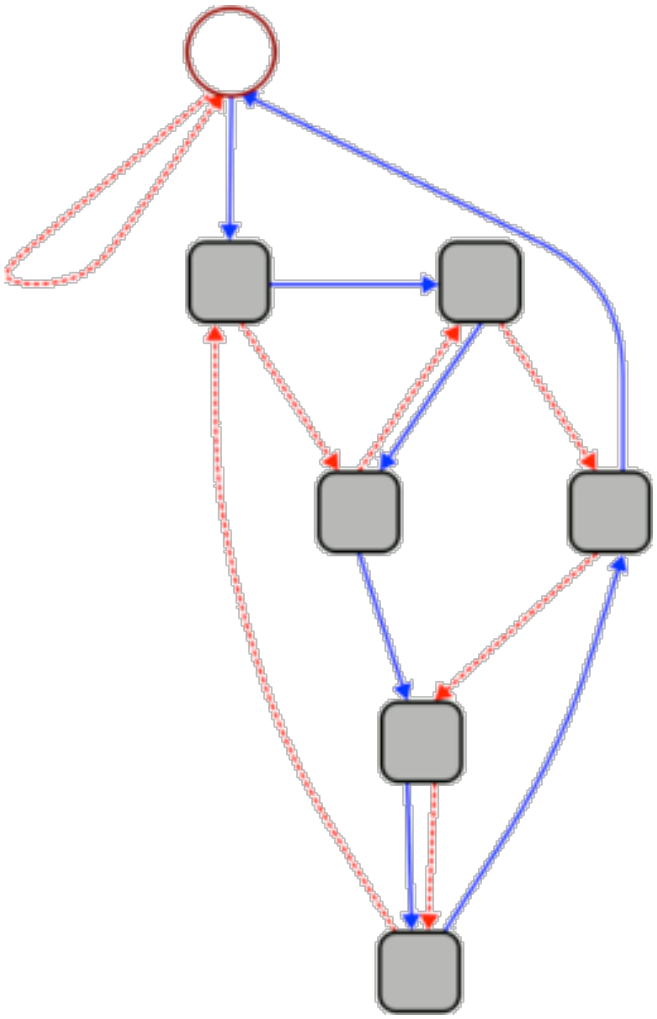

This graph can be used to quickly calculate whether a given number is divisible by 7.

1. Start at the circle node at the top.
2. For each digit **d** in the given number, follow **d** blue (solid) edges in succession. As you move from one digit to the next, follow **1** red (dashed) edge.
3. If you end up back at the circle node, your number is divisible by 7.

3703

"Rule of 7"

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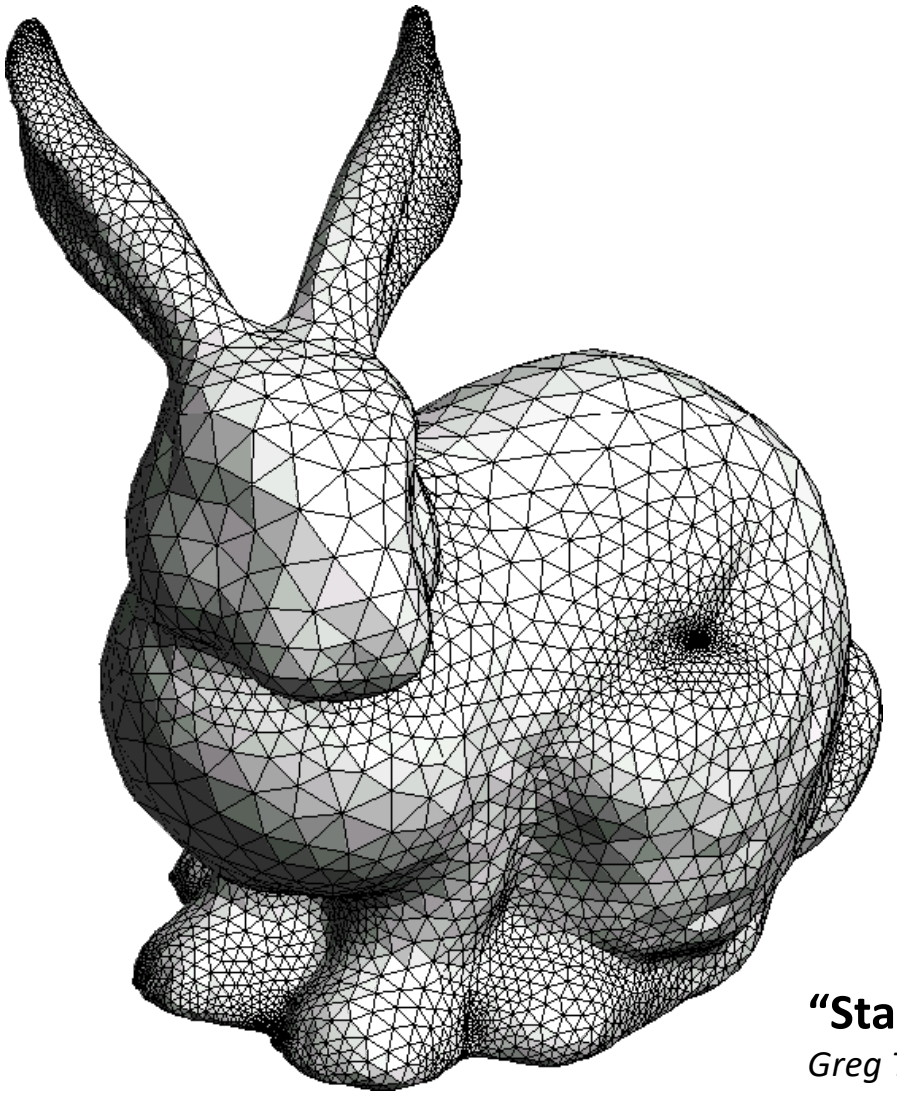
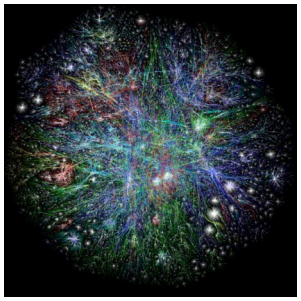
Presented by Cinda Heeren, 2016

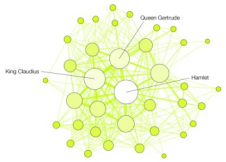


“Stanford Bunny”

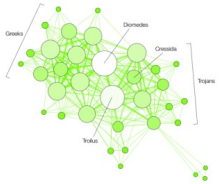
Greg Turk and Mark Levoy (1994)

Graphs

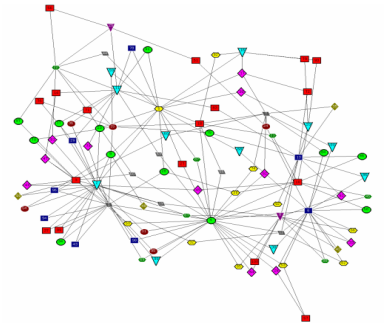




HAMLET

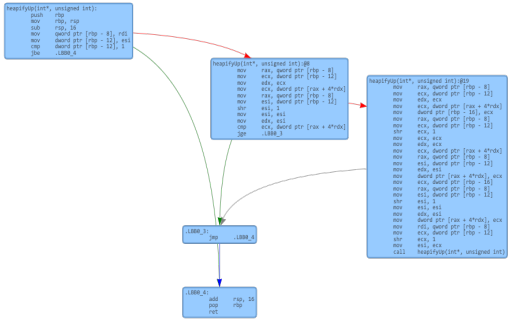


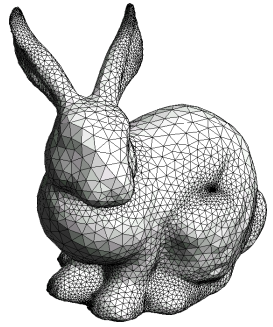
TROILUS AND CRESSIDA

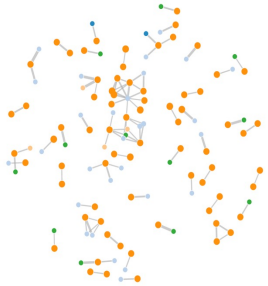


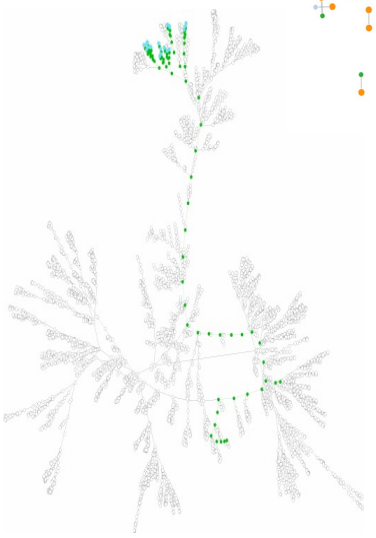
To study all of these structures:

1. A common vocabulary
2. Graph implementations
3. Graph traversals
4. Graph algorithms







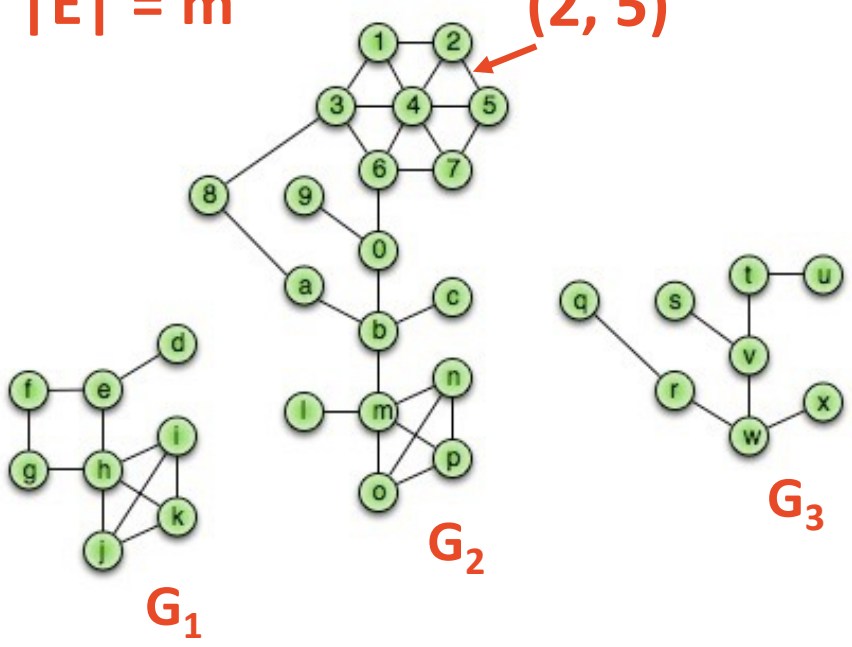


Graph Vocabulary

G = (V, E)

|V| = n

|E| = m



Incident Edges:
I(v) = { {x, v} in E }

Degree(v): |I|

Adjacent Vertices:
A(v) = { x : {x, v} in E }

Path or Walk: Sequence of vertices connected by edges

Path or Simple Path: Sequence of vertices connected by edges with no reuse

Cycle: A path with a common begin and end vertex with at least 3 vertices.

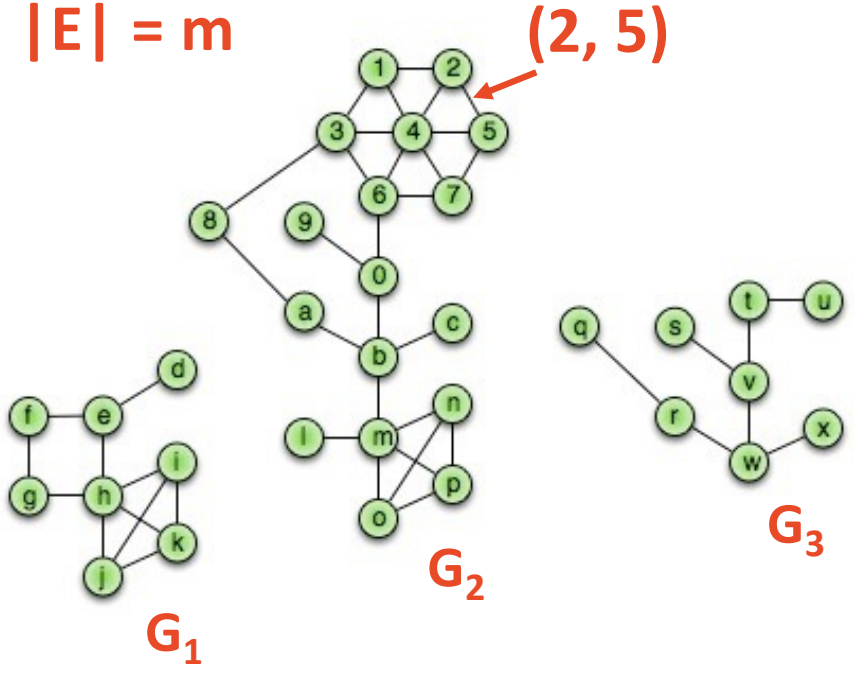
Simple Graph(G): A graph with no self loops or multi-edges.

Graph Vocabulary

G = (V, E)

|V| = n

|E| = m



Subgraph(G):

G' = (V', E'):

V' ∈ V, E' ∈ E, and

(u, v) ∈ E' → u ∈ V', v ∈ V'

Complete subgraph(G)

Connected subgraph(G)

Connected component(G)

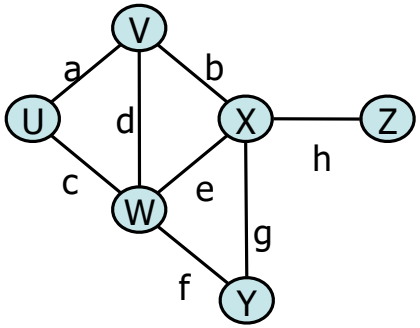
Acyclic subgraph(G)

Spanning tree(G)

Running times are often reported by **n**, the number of vertices, but often depend on **m**, the number of edges.

How many edges? **Minimum edges:**

Not Connected:



Connected*:

Maximum edges:

Simple:

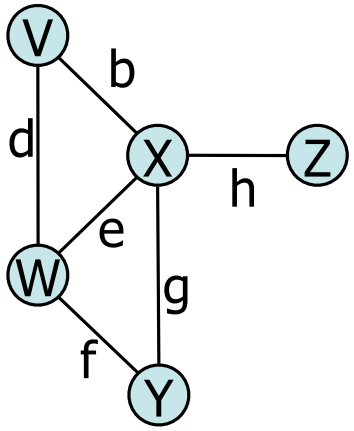
Not simple:

$$\sum_{v \in V} \deg(v) =$$

Graph ADT

Data:

- **Vertices**
- **Edges**
- **Some data structure maintaining the structure between vertices and edges.**



Functions:

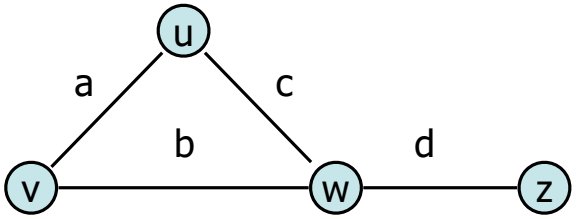
- **insertVertex(K key);**
- **insertEdge(Vertex v1, Vertex v2, K key);**

- **removeVertex(Vertex v);**
- **removeEdge(Vertex v1, Vertex v2);**

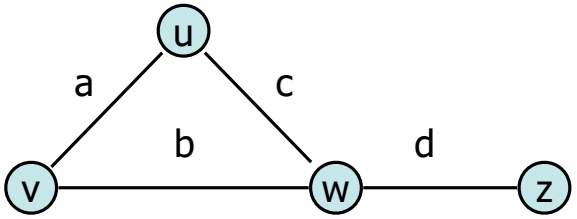
- **incidentEdges(Vertex v);**
- **areAdjacent(Vertex v1, Vertex v2);**

- **origin(Edge e);**
- **destination(Edge e);**

Graph Implementation Idea



Graph Implementation: Edge List



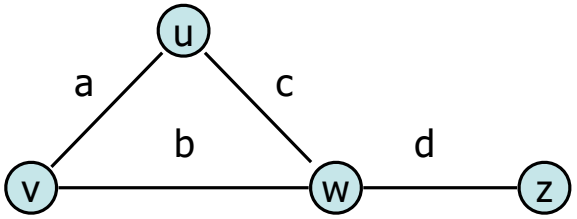
Vertex Collection:

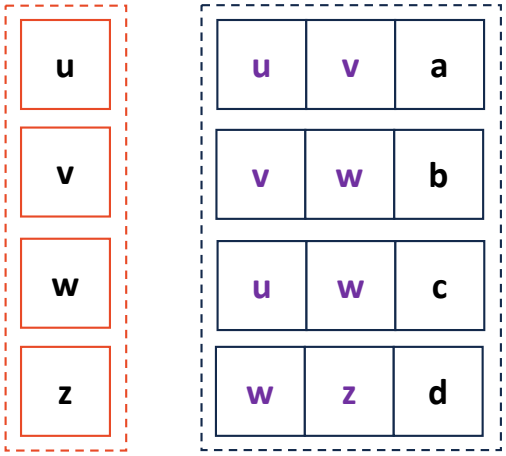
u
v
w
z

Edge Collection:

u	v	a
v	w	b
u	w	c
w	z	d

Graph Implementation: Edge List

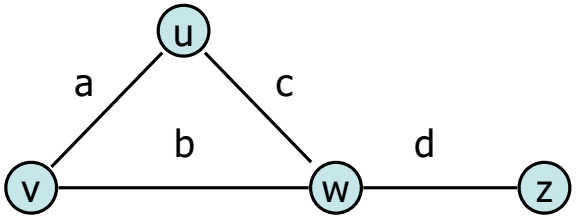


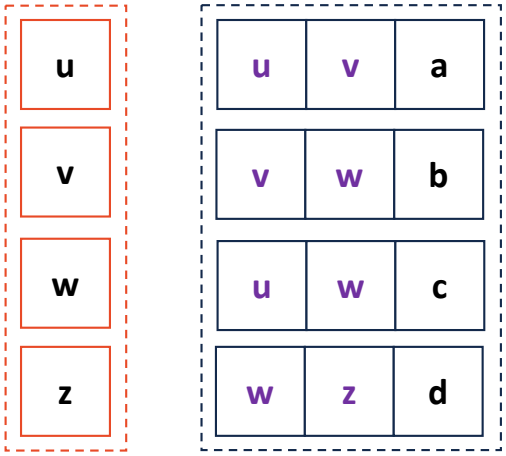


insertVertex(K key):

removeVertex(Vertex v):

Graph Implementation: Edge List



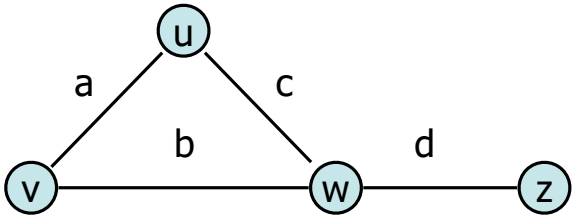


incidentEdges(Vertex v):

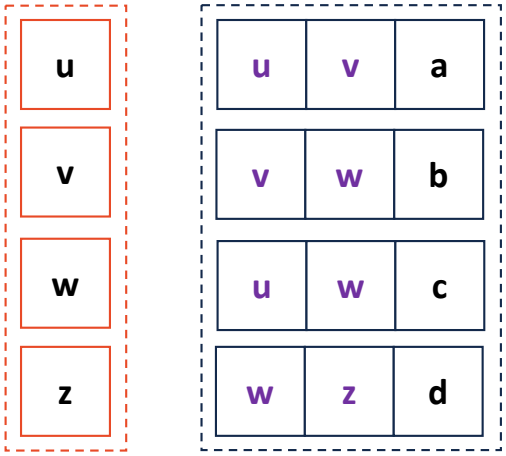
areAdjacent(Vertex v1, Vertex v2):

```
G.incidentEdges(v1).contains(v2)
```

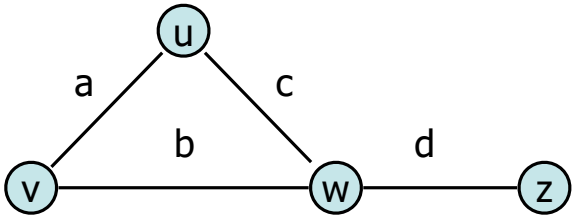
Graph Implementation: Edge List



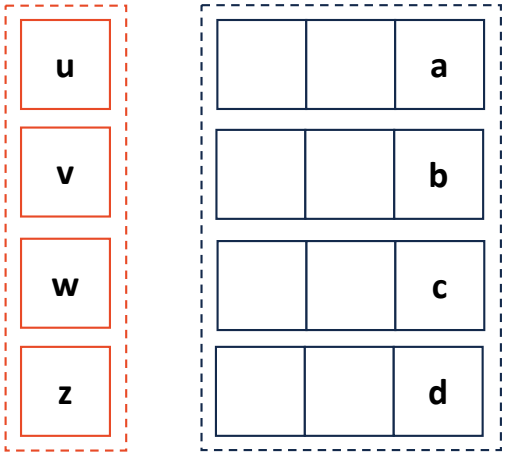
insertEdge(Vertex v1, Vertex v2, K key):



Graph Implementation: Adjacency Matrix



insertVertex(K key);
removeVertex(Vertex v);
areAdjacent(Vertex v1, Vertex v2);
incidentEdges(Vertex v);



	u	v	w	z
u				
v				
w				
z				