

# Tutorial ELEC3506/9506 Communication Networks

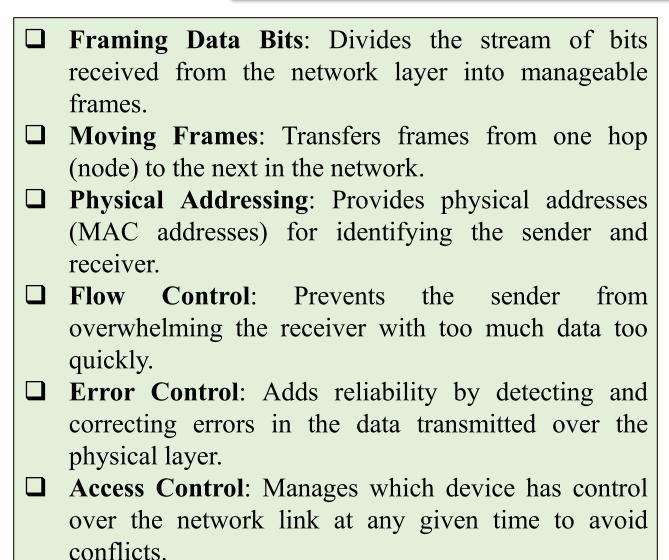
School of Electrical and Information Engineering
The University of Sydney

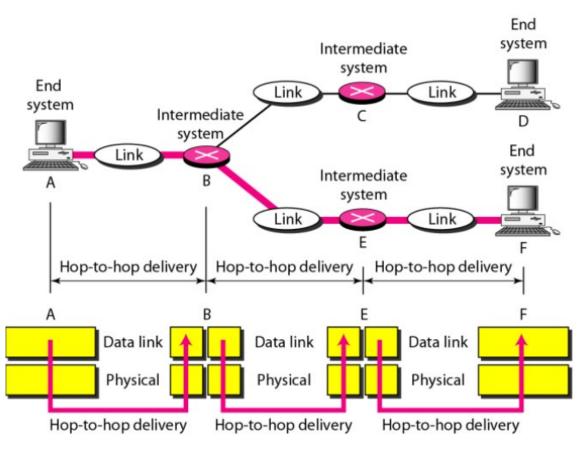
Tutorial 03 – Week 04





# SYDNEY Q1. Briefly describe the services provided by the data link layer.







# SYDNEY Q2. Define framing and the reason for its need.

# ☐ Framing

A process in data link layer to divide the stream of bits received from the network layer into frames.

# ☐ Reasons for framing:

- Framing adds the physical sender and destination addresses. The destination address specifies where the frame should go; the sender address is used to send an acknowledgement (ACK) back to the sender.
- Framing in data link layer divides the message into appropriate-sized frames such that the flow control and error control become efficient.
   Smaller-sized frames make flow control and error control more efficient.

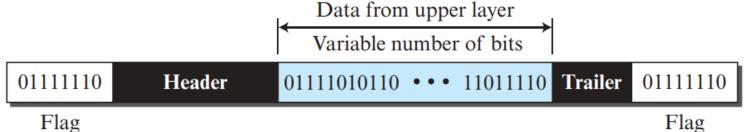
A frame has the following parts:				
☐ Frame header: Contains the source and				
destination address				
☐ Payload field: Contains the message to be				
delivered.				
☐ Trailer: Contains error detection &				
correction bits.				
☐ Flag: Marks the beginning and end of the				
frame.				

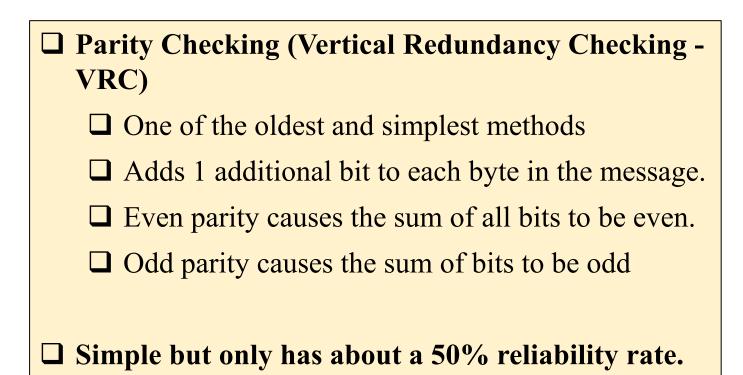
Flag	Header	Payload Field	Trailer	Flag	



Q3. Compare and contrast byte-oriented and bit-oriented protocols. Which category has been popular in the past? Which category is popular now?

# ☐ Byte-oriented (Character-oriented) protocol ☐ Data to be carried are 8-bit characters from a coding system, e.g., ASCII code ☐ Character-oriented protocols were popular when only text was exchanged by the data link layers Data from upper layer Variable number of characters **Trailer** Flag Flag Header ☐ Bit-oriented protocol: ☐ Data is transmitted as a stream of bits. ☐ More popular today, because we need to send text, graphic, audio, and video, which can be better represented by a bit pattern rather than by using a sequence of characters.



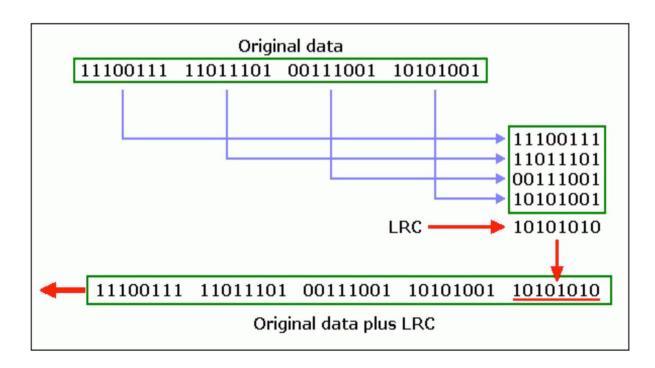


	Message	Codeword
Example: Even Parity	000	0000
	001	0011
	010	0101
	011	0110
	100	1001
	101	1010
	110	1100
	111	1111



### ☐ Longitudinal Redundancy Checking (LRC)

☐ A block of bits is divided into rows and redundant row of bits is added to the whole block.



- ☐ At the receiver side, this redundant row is used to detect the error.
- The receiver calculates the LRC and compares it to the LRC appended to the transmitted data. If two LRCs match, no error is detected.
- ☐ Compared to VRC, LRC increases the likelihood of detecting burst errors.

#### ☐ Cyclic Redundancy Check Codes (CRC)

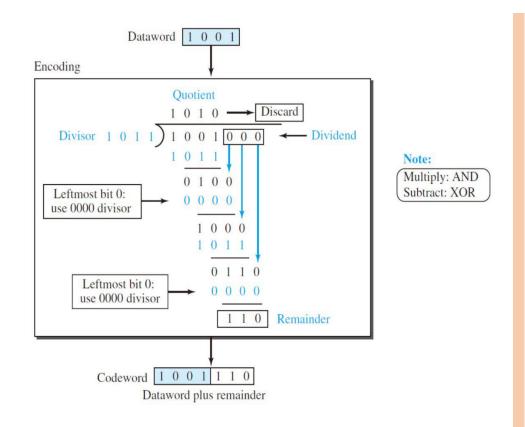
- ☐ Message length k, codeword length n
- **□** Encode
  - $\square$  Multiply u(x) with  $x^{n-k}$
  - $\square$  Divided  $u(x)x^{n-k}$  by g(x) and obtain the remainder b(x)
  - ☐ Forming the codeword

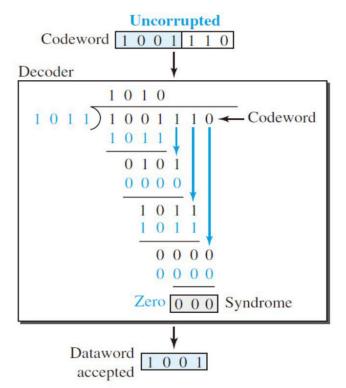
$$v(x) = b(x) + u(x)x^{n-k}$$

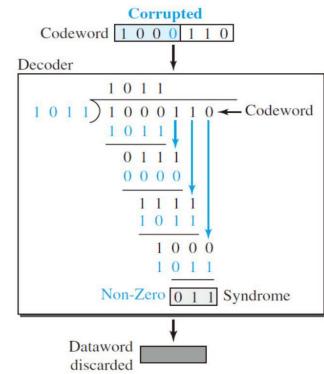
☐ Decode
$\square$ Divide $v(x)$ by $g(x)$
☐ If the remainder is zero, no error
☐ Otherwise, error
☐ CRC can detect more types of error
than VRC and LRC.

#### **Cyclic Redundancy Check Codes (CRC)**

#### **Encoder**









# Compare and contrast flow control and error control. How does error control complement flow control?

□ Flow Control refers to a set of procedures used to restrict the amount of data that sender can send before waiting for acknowledgement.
☐ Any receiving device has a limited speed for processing data.
☐ The processing rate of the receiver is usually slower than the transmission rate.
☐ Each receiving device has a buffer for storing the incoming data before they are processed.
☐ When the buffer begins to fill up, the receiver must tell the sender to slow down the transmission.
☐ Error control refers to a set of procedures used to detect and correct errors.
Error control refers to a set of procedures used to detect and correct errors.
☐ Both flow control and error control help in proper delivering of data to the receiver.
☐ Flow control ensures that frames are not discarded due to buffer overflow. Error control complements flow control by ensuring that the frames received at the received side are error-free.



SYDNEY Q6. Standard Ethernet defines several Physical layer implementations. Discuss the most common implementation categories? implementation categories?

☐ Standard Ethernet has defined several physical layer implementations, out of which the following four are commonly used.						
Name	Media	Max Length	Line Encoding			
10Base5	Thick coaxial cable	500 m	Manchester			
10Base2	Thin coaxial cable	185 m	Manchester			
10Base-T	2 UTP	100 m	Manchester			
10Base-F	2 Fiber	2000 m	Manchester			



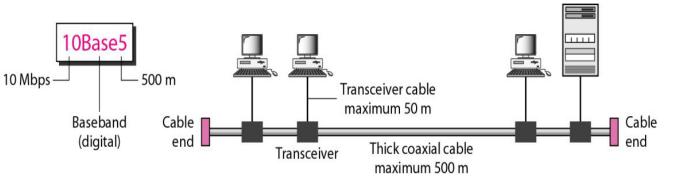
**Q6**. Standard Ethernet defines several Physical layer implementations. Discuss the most common implementation categories?

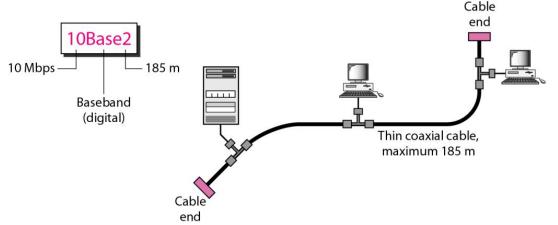
## 10Base5 (Thick Ethernet)

- □ 10Base5 is implemented in bus topology with an external transceiver connected to coaxial cable.
- ☐ The transceiver deals with transmitting, receiving and detecting collisions in the network.
- ☐ The 10Base5 Ethernet is also referred to by other names including thick **Ethernet** or **Thicknet**.
- $\Box$  The maximum length of the cable should not be more than 500 m.

#### 10Base2 (Thin Ethernet)

- □ 10Base2 is also implemented in the bus topology but with a thinner and flexible coaxial cable.
- ☐ The cable can be bent to pass very close to the stations.
- ☐ The transceiver is normally part of the NIC card, which is installed inside the station.
- ☐ The 10Base2 Ethernet is also referred to as **Thin Ethernet** or **Cheapernet**.
- $\square$  The maximum length of the cable should not be more than 185 m







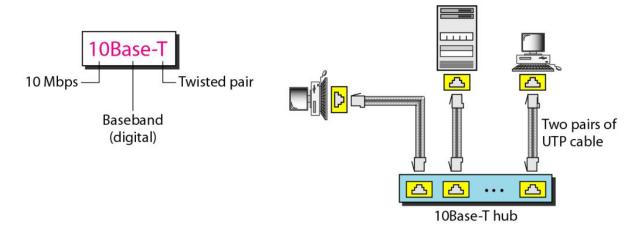
Q6. Standard Ethernet defines several Physical layer implementations. Discuss the most common implementation categories?

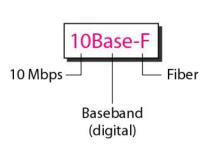
#### **10Base-T (Twisted-Pair Ethernet)**

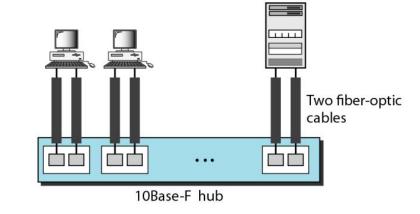
- ☐ The third implementation is called 10Base-T or twisted-pair Ethernet.
- □ 10Base-T uses two pairs of twisted cable and is implemented in star topology.
- All nodes are connected to the hub via two pairs of cable and thus, creating a separate path for sending and receiving the data.
- $\Box$  The maximum length of the cable should not be more than 100 m.

### 10Base-F (Fiber Ethernet)

- ☐ It is the most common 10-Mbps Ethernet that is implemented in star topology.
- ☐ It uses a pair of fiber optic cables to connect the nodes to the central hub.
- ☐ The transceiver is normally part of the NIC card, which is installed inside the station.
- ☐ The 10Base-F Ethernet is also referred to as Fiber Ethernet.
- $\Box$  The maximum length of the cable should not be more than 2000 m



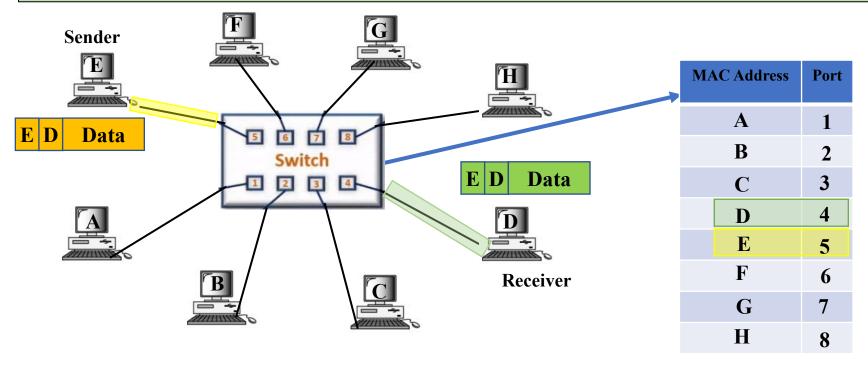






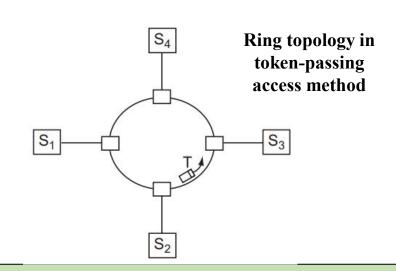
#### Q7. What is switched Ethernet?

- □ Switch Ethernet: It connects all the devices on same network, so that they can communicate with one another.
- ☐ When a port of the switch receives a frame, it checks the destination address in the frame and then sends the frame to the corresponding port for outgoing data.
- ☐ In switch Ethernet, MAC address Table (Forwarding Table) are used to forward the data.
- ☐ Bandwidth is shared only between the station and the switch.



### **Q8**. What are the advantages of token passing?

- □ **Token Passing**: A token is regularly passed from one node to another. And if a node has some information to pass on the network, the node releases the information.
- If the node does not have any data to release on the network, then it transfers the token to the next node.



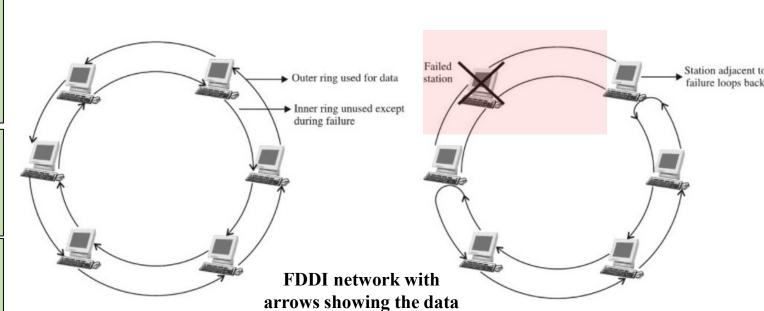
#### **Advantages of Token Passing**

- □ Reduced chances of data collision as each node release a data packet after receiving the token.
- ☐ Token passing makes ring topology perform better than bus topology under heavy traffic.
- ☐ No need of server to control connectivity among the nodes.
- ☐ The channel bandwidth can be fully utilized when demand is heavy

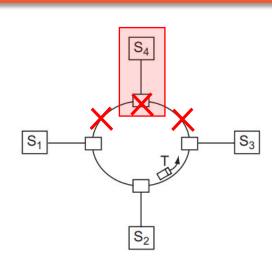


#### **Q9**. In the event of failure, how does the FDDI network automatically reconfigure?

- ☐ The problem with the **Token Ring** topology is that if one of the links-the medium between two adjacent stations fails, the whole system fails.
- ☐ To solve this problem, dual ring topology is used.
- ☐ One of the dual ring token topology is Fiber Distributed Data Interface (FDDI).
- ☐ FDDI networks called counter rotating as direction of data flows between two rings are opposite.
- ☐ The primary ring carries data, while the secondary ring is usually reserved as a backup in case a fault occurs on the primary ring.
- ☐ In the event of a failure on the primary ring, FDDI automatically reconfigures itself to use the secondary ring.
- ☐ This process of reconfiguring is called self-healing and FDDI is known as a self-healing network.



flowing directions





#### Q10. Compare and contrast between a hub (repeater) and a bridge.

#### Repeater

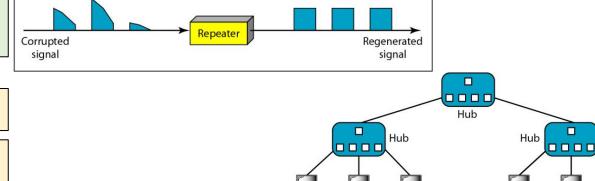
- ☐ Hub or Repeater operates at the physical layer of OSI model.
- Receives a signal and before it becomes too weak or corrupted, regenerates the original bit pattern.
- ☐ It is used to extend the physical length of a network.
- ☐ Repeater do not understand complete frame.
- ☐ Repeater cannot perform packet filtering.

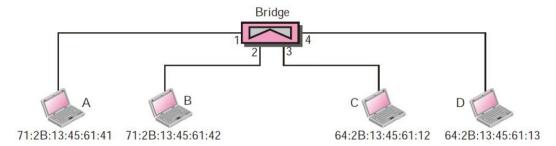
#### **Bridge**

- ☐ Bridge operates at the data link layer of OSI model.
- ☐ It can check the destination address of a frame and decide if the frame should be forwarded or discarded.
- ☐ It is mostly used in LANs.
- ☐ The complete frames is understood by bridge.
- ☐ Filtering of the packets in network is achieved by the bridge.

#### Hub

- ☐ A Hub is actually a multiport repeater.
- ☐ Broadcasts the message sent by one station to all other stations.
- ☐ It is most commonly used to connect multiple machines to the same LAN.







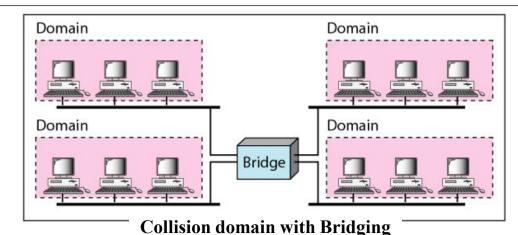
#### Q11. Compare and contrast between a bridge and a switch (Layer 2).

#### **Bridge**

- ☐ Bridge operated in the same LAN and performs relatively slow.
- ☐ Bridge has limited number of ports.
- ☐ Method of switching of a Bridge is store and forward.
- ☐ The collision domain becomes smaller

#### Collision domain without Bridging

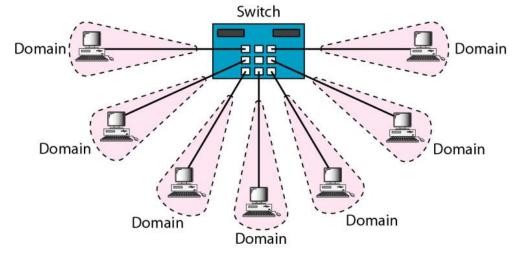




#### Switch (Layer 2)

- ☐ A layer 2 switch is an N-port bridge with additional sophistication that allows faster handling of the packets.
- ☐ Switch can have many ports.
- ☐ Method of switching of a Switch can be store and forward, cut-through, or fragment-free.
- ☐ The probability of collision is reduced tremendously

#### **Collision domain with Switch**





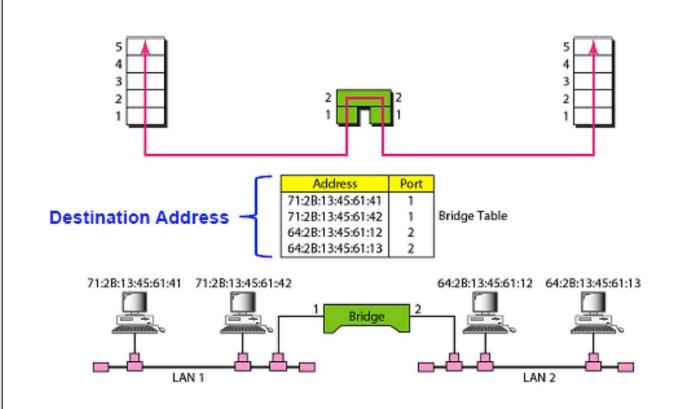
# Bridge & Switch (Layer 2)

- ☐ In general, a switch is a multi-port bridge.
- ☐ Both operate in physical and data link layers.
- ☐ Both make filtering decisions based on the physical address of the frame they receive.
- ☐ Both Bridge and Switch have forwarding table of MAC address and port number.

#### Q12. What do we mean when we say that a bridge can filter traffic? Why is filtering important?

Bridges have access to station physical addresses and can forward a packet to the appropriate segment of the network. In this way, they filter traffic.

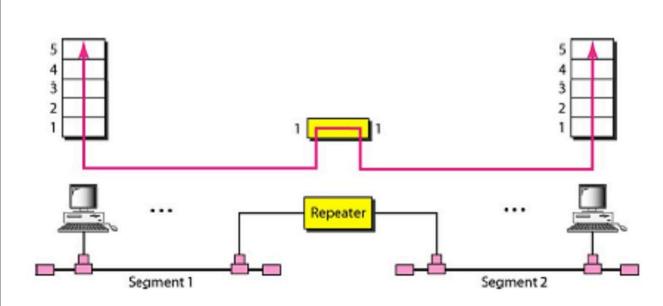
Filtering helps in controlling the congestion because it prevents a frame from reaching network segments where it is not needed. Filtering also improves security by restricting which ports receive traffic.





☐ Signals that carry information within a network can travel a fixed distance before attenuation endangers the integrity of the data

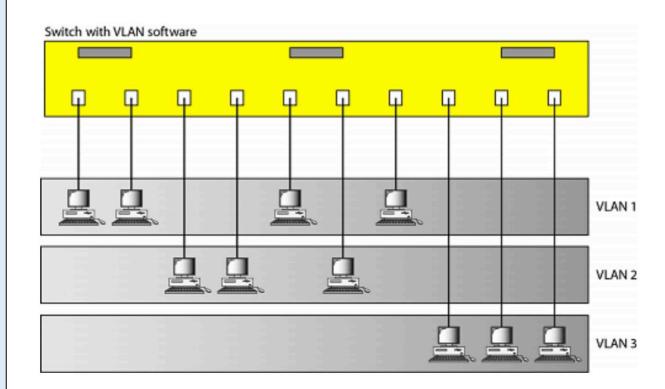
A repeater receives a signal and, before it becomes too weak or corrupted, regenerates the original bit pattern. The repeater then sends the refreshed signal. A repeater thus can extend the physical length of a LAN.





□ VLANs can form multiple broadcast domains (workgroups) by breaking up a large network into smaller independent segments.

□ Each workgroup member can send broadcast messages to others in the workgroup. This eliminates the need for broadcasting the message to all other stations and all the overhead messages associated with it. Thus, it reduces the traffic in the network.





**Q15.** For a CSMA/CD network with 1 Gbps bandwidth, if a frame size of 512 bits is used, what is the maximum possible distance between nodes? Assume zero processing delay and EM propagation delay is  $2 \times 10^8$  m/s.

☐ The maximum possible distance is

 $2 \times 10^8 \text{ m/s} \times (512 \text{ bits}) \times 0.5 / 1000 \text{Mbps} = 51.2 \text{ metre}$ 



#### **Q16.** How collision can be detected in CSMA/CA networks?

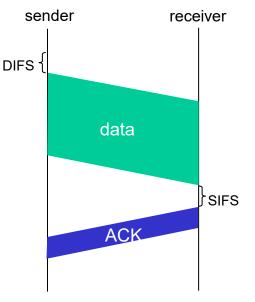
#### A collision in CSMA/CA is detected by using an ACK

#### Sender

- 1 if sense channel idle for **DIFS** then transmit entire frame (no CD)
- 2 if sense channel busy then start random backoff time timer counts down while channel idle transmit when timer expires if no ACK, increase random backoff interval, repeat 2

#### Receiver

if frame received OK return ACK after **SIFS** (ACK needed due to hidden terminal problem)



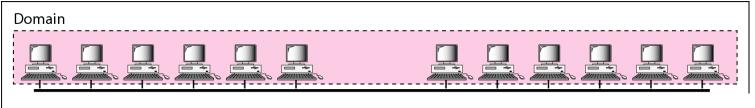
#### Sender

1 if ACK is not received – collision detected increase random backoff interval, repeat 2

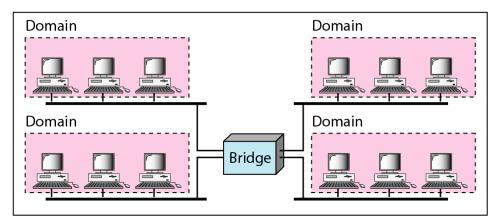
DIFS=distributed inter frame space SIFS=short inter frame space



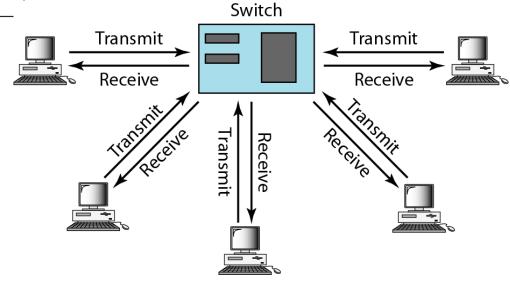
Q17. Consider 3 network configurations below. Assuming the cables/lines provide a capacity of 100 Mbps. What will be the throughput for each configuration?



a. Without bridging



b. With bridging



- □ 100 Mbps/12
- □ 100 Mbps/4
- ☐ 100 Mbps