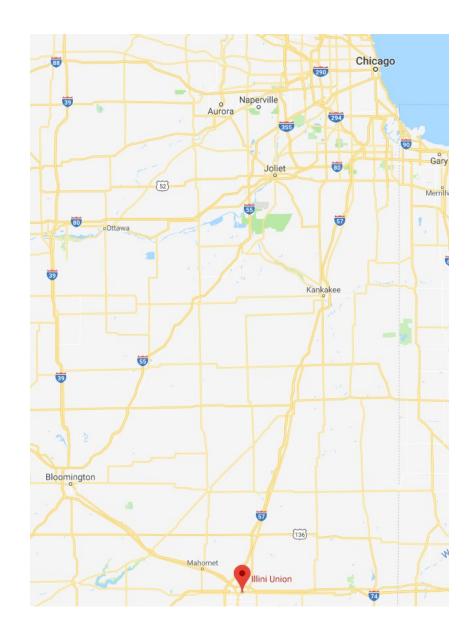
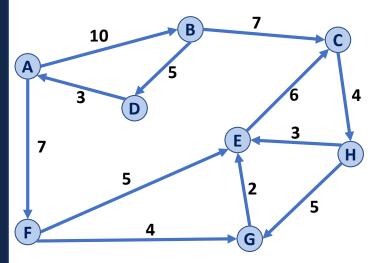
CS 225

**Data Structures** 

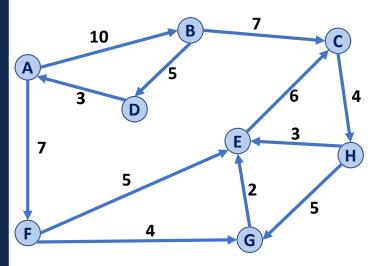
April 7 – Dijkstra's Algorithm
G Carl Evans

#### **Shortest Path**

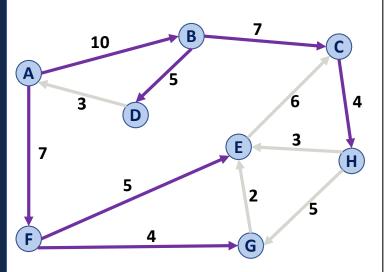




```
PrimMST(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
12
     Q.buildHeap(G.vertices())
13
14
     repeat n times:
15
       Vertex u = Q.removeMin()
16
       foreach (Vertex v : neighbors of u not in T):
17
          if cost(u, v) < d[v]:
           d[v] = cost(u, v)
18
19
           p[v] = u
20
21
```

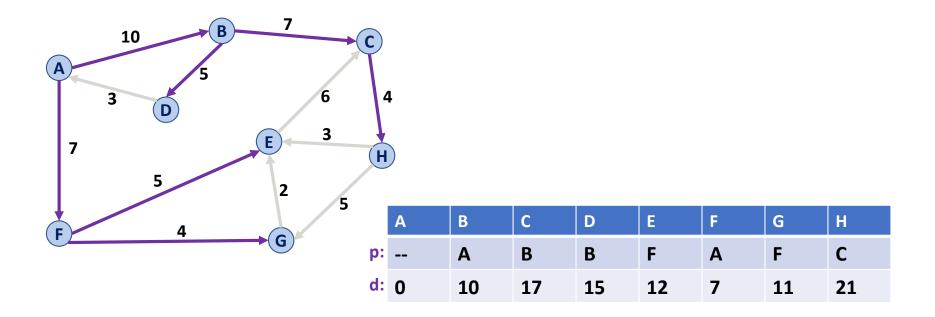


```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
12
     Q.buildHeap(G.vertices())
13
     Graph T
                      // "labeled set"
14
15
     repeat n times:
16
       Vertex u = Q.removeMin()
17
       T.add(u)
18
       foreach (Vertex v : neighbors of u not in T):
19
         if
                             < d[v]:
20
           d[v] =
21
           p[v] = u
```

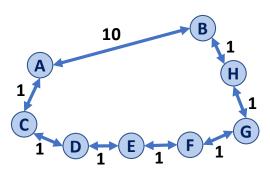


```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
12
     Q.buildHeap(G.vertices())
13
14
     repeat n times:
15
       Vertex u = Q.removeMin()
16
       foreach (Vertex v : neighbors of u not in T):
         if cost(u, v) + d[u] < d[v]:
17
18
           d[v] = cost(u, v) + d[u]
19
           p[v] = u
20
21
```

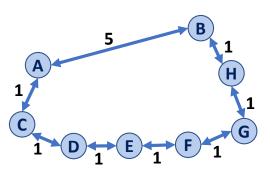
Dijkstra gives us the shortest path from our path (single source) to **every** connected vertex!



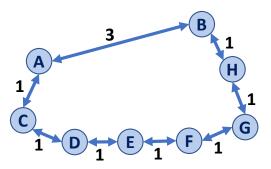
**Q:** How does Dijkstra handle a single heavy-weight path vs. many light-weight paths?



Q: How does Dijkstra handle a single heavy-weight path vs. many light-weight paths?



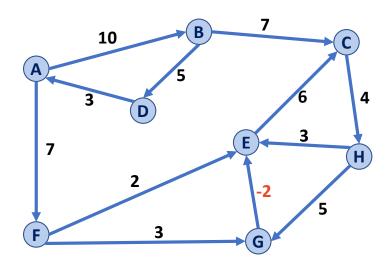
Q: How does Dijkstra handle undirected graphs?



What is Dijkstra's running time?

```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
12
     Q.buildHeap(G.vertices())
13
14
     repeat n times:
15
       Vertex u = Q.removeMin()
16
       foreach (Vertex v : neighbors of u not in T):
17
         if cost(u, v) + d[u] < d[v]:
           d[v] = cost(u, v) + d[u]
18
19
           p[v] = u
20
21
     return T
22
23
```

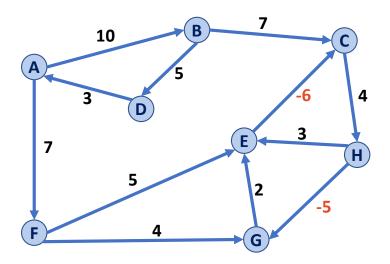
Q: How does Dijkstra handle negative weight edges?



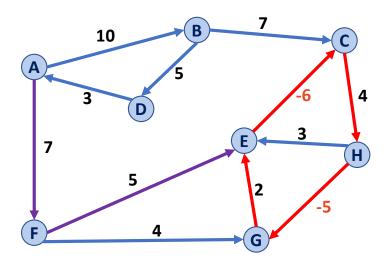
#### Modified Dijkstra's Algorithm (SSSP)

```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
     Q.buildHeap(G.vertices())
12
                      // "labeled set"
13
     Graph T
14
15
     repeat until Q.empty() times:
16
       Vertex u = Q.removeMin()
       foreach (Vertex v : neighbors of u not in T):
17
         if cost(u, v) + d[u] < d[v]:
18
19
           d[v] = cost(u, v) + d[u]
20
           p[v] = u
           Q.push(v)
21
22
23
     return T
```

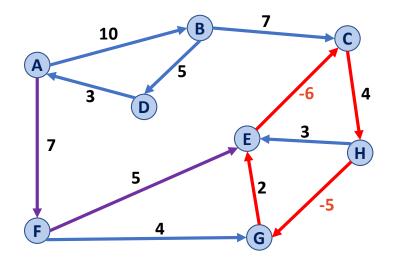
Q: How does Dijkstra handle negative weight cycles?



Q: How does Dijkstra handle negative weight cycles?



Q: How does Dijkstra handle negative weight cycles?



Shortest Path (A  $\rightarrow$  E):  $A \rightarrow F \rightarrow E \rightarrow (C \rightarrow H \rightarrow G \rightarrow E)^*$ 

Length: 12 Length: -5 (repeatable)