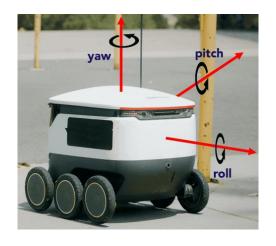
## Robot S1 Movements



gimbal\_ctrl.yaw\_ctrl(degrees) Range: +/- 250 degrees





Range: -20 to 35 degrees

gimbal\_ctrl.pitch\_ctrl(degrees)

