1 Algebraic Topology

Definition 1.1 (de Rham complex). Ω^* is the algebra generated over \mathbb{R} by dx_1, \ldots, dx_n subject to

- 1. $(dx_i)^2 = 0$,
- 2. $dx_i dx_j = -dx_j dx_i, i \neq j$.

The C^{∞} differential forms on \mathbb{R} are elements of

$$\Omega^*(\mathbb{R}^n) = \{ C^{\infty} \text{ functions on } \mathbb{R}^n \} \otimes_{\mathbb{R}} \Omega^*.$$
 (1)

We have $\Omega^*(\mathbb{R}^n) = \bigoplus_{q=0}^n \Omega^q(\mathbb{R}^n)$, where $\Omega^q(\mathbb{R}^n)$ consists of the C^{∞} q-forms on \mathbb{R}^n . We define

$$d: \Omega^q(\mathbb{R}^n) \to \Omega^{q+1}(\mathbb{R}^n), \tag{2}$$

the exterior differentiation, by

- 1. if $f \in \Omega^0(\mathbb{R}^n)$, then $df = \sum \partial f/\partial x_i dx_i$,
- 2. if $\omega = \sum_{I} f_{I} dx_{I}$, then $d\omega = \sum_{I} df_{I} dx_{I}$, where $dx_{I} = dx_{i} dx_{j} \dots$

The wedge product is defined by

$$\tau \wedge \omega = \sum \tau_I \omega_J \, dx_I dx_J = (-1)^{\deg \tau \, \deg \omega} \omega \wedge \tau. \tag{3}$$

Proposition 1.2. d is an antiderivation,

$$d(\tau \wedge \omega) = (d\tau) \wedge \omega + (-1)^{\deg \tau} \tau \wedge d\omega. \tag{4}$$

Proposition 1.3. $d^2 = 0$.

Definition 1.4. The q-th de Rham cohomology of \mathbb{R}^n is the vector space

$$H^q(\mathbb{R}^n) = \{\text{closed } q\text{-forms}\}/\{\text{exact } q\text{-forms}\},$$
 (5)

where closed means in the kernel of d and exact means in the image of d. We denote by $[\omega]$ the cohomology class of ω .

Remark. Only the constant functions are relevant for \mathbb{R}^n ,

$$H^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension 0,} \\ 0 & \text{otherwise.} \end{cases}$$
 (6)

Definition 1.5. A differential complex is a direct sum of Vector spaces $C = \bigoplus_{q \in \mathbb{Z}} C^q$ if there are homomorpisms

$$\ldots \longrightarrow C^{q-1} \stackrel{d}{\longrightarrow} C^i \stackrel{d}{\longrightarrow} C^{q+1} \longrightarrow \ldots$$

with $d^2=0$. The cohomology of C is given by $H(C)=\bigoplus_{q\in\mathbb{Z}}H^q(C)$, with

$$H^{q}(C) = (\ker d \cap C^{q})/(\operatorname{im} d \cap C^{q}). \tag{7}$$

A map $f:A\to B$ between two differential complexes is a chain map it it commutes with the differential operators of A and B, $fd_A=d_Bf$. A sequence of vector spaces

$$\ldots \longrightarrow V_{q-1} \xrightarrow{f_{i-1}} V_i \xrightarrow{f_i} V_{q+1} \longrightarrow \ldots$$

is said to be exact if the image of f_{i-1} is the kernel of f_i . An exact sequence of the form

$$0 \longrightarrow A \stackrel{f}{\longrightarrow} B \stackrel{g}{\longrightarrow} C \longrightarrow 0$$

is called a short exact sequence. Note that f is injective and g surjective. If f, g are chain maps, there is a long exact sequence of cohomology groups

$$H^{q+1}(A) \xrightarrow{f^*} \dots$$

$$\uparrow \qquad \qquad \downarrow d^*$$

$$H^q(A) \xrightarrow{f^*} H^q(B) \xrightarrow{g^*} H^q(C)$$

 f^* , g^* are the naturally induced maps and $d^*[c]$ is obtained through the commutative diagram

$$0 \longrightarrow A^{q+1} \xrightarrow{f} B^{q+1} \xrightarrow{g} C^{q+1} \longrightarrow 0$$

$$\downarrow d \qquad \downarrow 0$$

$$0 \longrightarrow A^{q} \xrightarrow{f} B^{q} \xrightarrow{g} C^{q} \longrightarrow 0$$

Since g is surjective there is $b \in B^q$ with g(b) = c. Because g(db) = d(gb) = dc = 0, there is $a \in A^{q+1}$ with db = f(a). Then $d^*[c] := [a]$. a is closed because f is injective. To see that the sequence is exact, note that if b is closed then f(a) = 0, and due to injectivity a = 0. On the other hand, f(a) is exact and therefore [f(a)] = 0.

Definition 1.6. $\Omega_c^*(\mathbb{R}^n)$ is the de Rham complex for functions of compact support, $H_c^*(\mathbb{R})$ is its cohomology.

Remark. Only the n-forms whose integrals are different from zero are relevant, since if it was zero then its antiderivative can have compact support,

$$H_c^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension n,} \\ 0 & \text{otherwise.} \end{cases}$$
 (8)

Definition 1.7. $f: \mathbb{R}^m \to \mathbb{R}^n$ induces a pullback on functions

$$f^*(g) = g \circ f. \tag{9}$$

On forms the pullback is defined as

$$f^*(\sum g_I dy_{i_1} \dots dy_{i_q}) = \sum (g_I \circ f) df_{i_1} \dots df_{i_q},$$
 (10)

with $f_i = y_i \circ f$ the i-th component of f, y_i the standard coordinates.

Proposition 1.8. f^* commutes with d. This shows that the cohomology is a diffeomorphism invariant.

Definition 1.9. Let $M = U \cup V$ with U, V open. Then we have the inclusions

$$M \leftarrow U \sqcup V \leftarrow U \cap V \tag{11}$$

where \sqcup is the disjoint union (each element has a label indicating wether it's from U or V). Using the inclusions as pullbacks we get

$$\Omega^*(M) \to \Omega^*(U) \oplus \Omega^*(V) \to \Omega^*(U \cap V).$$
 (12)

The Mayer-Vietoris sequence is given by

$$0 \to \Omega^*(M) \to \Omega^*(U) \oplus \Omega^*(V) \to \Omega^*(U \cap V) \to 0, \quad (13)$$

with

$$\Omega^*(U) \oplus \Omega^*(V) \to \Omega^*(U \cap V); (\omega, \tau) \mapsto \tau - \omega.$$
 (14)

Proposition 1.10. The Mayer-Vietoris sequence is exact. This is achieved through partitions of unity ρ ,

$$(\rho_U \omega) - (-\rho_V \omega) = \omega. \tag{15}$$

long exact sequence with the same name:

$$H^{q+1}(M) \longleftrightarrow H^{q+1}(U) \oplus H^{q+1}(V) \longrightarrow H^{q+1}(U \cap V)$$

$$H^q(M) \longrightarrow H^q(U) \oplus H^q(V) \longrightarrow H^q(U \cap V)$$

Explicitly

$$d^*[\omega] = \begin{cases} [-d(\rho_V \omega)] & \text{on } U, \\ [d(\rho_U \omega)] & \text{on } V. \end{cases}$$
 (16)

Definition 1.12. If $j:U\to M$ is the inclusion of U in M, then let $j_*: \Omega_c^*(U) \to \Omega_c^*(M)$ the map which extends a form to M by zero. Because pullbacks of compact forms are in general not compact, we instead use the inclusions

$$\Omega_c^*(M) \xleftarrow{\text{sum}} \Omega_c^*(U) \oplus \Omega_c^*(V) \xleftarrow{\delta} \Omega_c^*(U \cap V)$$
$$\delta : \omega \mapsto (-j_*\omega, j_*\omega). \tag{17}$$

We then get the Mayer-Vietoris sequence

$$0 \leftarrow \Omega_c^*(M) \leftarrow \Omega_c^*(U) \oplus \Omega_c^*(V) \leftarrow \Omega_c^*(U \cap V) \leftarrow 0, \quad (18)$$

which induces

$$H_c^{q+1}(M) \longleftarrow H_c^{q+1}(U) \oplus H_c^{q+1}(V) \longleftarrow H_c^{q+1}(U \cap V)$$

$$H_c^q(M) \longleftarrow H_c^q(U) \oplus H_c^q(V) \longleftarrow H_c^q(U \cap V)$$

and we now instead get

$$d^*[\omega] = \begin{cases} [d(\rho_U \omega)] & \text{on } U, \\ [d(\rho_V \omega)] & \text{on } V. \end{cases}$$
 (19)

Proposition 1.13. The Mayer-Vietoris sequence of forms with compact support is exact.

Proposition 1.14. A manifold of dimension n is orientable iff it has a global nowhere vanishing n-form.

Definition 1.15. Let $\mathbb{H}^n = \{x_n \geq 0\} \subset \mathbb{R}^n$ with standard orientation $dx_1 \dots dx_n$. The induced orientation of $\partial \mathbb{H}^n = \{x_n = 0\}$ is given by the equivalence class of $(-1)^n dx_1 \dots dx_{n-1}$. For an orientation-preserving diffeomorphism ϕ we define for manifolds

$$[\partial M] = \phi^* [\partial \mathbb{H}^n]. \tag{20}$$

Remark. This definition is due to $\omega|_{\partial M} := i_{\hat{n}}\omega$ for the normal

Theorem 1.16 (Stokes'). Let ω be an (n-1)-form with compact support on an oriented manifold M, then

$$\int_{M} d\omega = \int_{\partial M} \omega. \tag{21}$$

Definition 1.17. Let $\pi: \mathbb{R}^n \times \mathbb{R}^1 \to \mathbb{R}^n$; $\pi(x,t) = x$ and $s: \mathbb{R}^n \to \mathbb{R}^n \times \mathbb{R}^1$; s(x) = (x, 0). Trivially $\pi \circ s = 1$, $s^* \circ \pi^* = 1$, but $s \circ \pi \neq 1$. K is called a homotopy operator if

$$1 - \pi^* \circ s^* = \pm (dK \pm Kd). \tag{22}$$

 $dK \pm Kd$ maps closed forms to exact forms, therefore induces zero in cohomology. If K exists, $\pi^* \circ s^*$ is said to be chain homotopic to the identity. We define $K: \Omega^q(\mathbb{R}^n \times \mathbb{R}) \to$ $\Omega^{q-1}(\mathbb{R}^n \times \mathbb{R})$ by

$$(\pi^*\phi)f(x,t) \mapsto 0, \quad (\pi^*\phi)f(x,t)dt \mapsto (\pi^*\phi)\int_0^t dt f \quad (23)$$

with ϕ a form on \mathbb{R}^n .

Definition 1.11. The Mayer-Vietoris sequence induces a **Proposition 1.18.** K is a homotopy operator. The maps π^*, s^* on $H^*(\mathbb{R}^n \times \mathbb{R}) \leftrightarrow H^*(\mathbb{R}^n)$ are isomorphisms.

Corollary 1.19 (Poincaré Lemma).

$$H^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension 0,} \\ 0 & \text{otherwise.} \end{cases}$$
 (24)

More generally $H^*(M \times \mathbb{R}^1) \simeq H^*(M$

Corollary 1.20 (Homotopy Axiom for de Rham Cohomology). Homotopic maps induce the same map in cohomology.

Definition 1.21. Two Manifolds M, N have the same homotopy type if there are C^{∞} maps $f: M \to N, g: N \to M$ such that $g \circ f$, $f \circ g$ are C^{∞} homotopic to the identity on M, N respectively. A manifold is called contractible if it has the homotopy type of a point.

Corollary 1.22. Manifolds with the same homotopy type have the same de Rham cohomology.

Definition 1.23. $r: M \to A$ is called a retraction of M onto A if $r \circ i : A \to A$ is the identity, with $i : A \subset M$ the inclusion. If $i \circ r : M \to M$ is homotopic to the identity on M, then r is called a deformation retraction of M onto A, and it follows that M, A have the same homotopy type.

Corollary 1.24. If A is a deformation retract of M, then A, M have the same de Rham cohomology.

Corollary 1.25.

$$H^*(S^n) = \begin{cases} R & \text{in dimension 0, n} \\ 0 & \text{otherwise.} \end{cases}$$
 (25)

Definition 1.26. Let $\pi: M \times \mathbb{R}^1 \to M$ be the projection. We define the push-forward for compact forms $\pi_*: \Omega^*_c(M \times \mathbb{R}^1) \to$ $\Omega_c^{*-1}(M)$, called integration along the fiber by

$$\pi^* \phi f(x,t) \mapsto 0, \quad \pi^* \phi f(x,t) dt \mapsto \phi \int_{-\infty}^{\infty} dt f$$
 (26)

where ϕ is a form on M. Let e = e(t)dt be a compactly supported 1-form on \mathbb{R}^1 with total integral 1 and define

$$e_*: \Omega_c^*(M) \to \Omega_c^{*+1}(M \times \mathbb{R}^1); \quad \phi \to (\pi^*\phi) \wedge e.$$
 (27)

The homotopy operator $K: \Omega_c^*(M \times \mathbb{R}^1) \to \Omega_c^{*-1}(M \times \mathbb{R}^1)$ is defined by

$$\pi^* \phi f \mapsto 0, \quad \pi^* \phi f dt \mapsto \pi^* \phi \int_{-\infty}^t f - \pi^* \phi \int_{-\infty}^t e \int_{-\infty}^\infty f.$$
 (28)

Proposition 1.27. d commutes with both π_* and e_* .

Proposition 1.28. $1-e_*\pi_*=(-1)^{q-1}(dK-Kd)$ on $\Omega^q_c(M\times\mathbb{R}^1)$. The maps $H^*_c(M\times\mathbb{R}^1)\leftrightarrow H^{*-1}_d(M)$ are isomorphisms.

Corollary 1.29 (Poincaré Lemma for Compact Supports).

$$H_c^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension n} \\ 0 & \text{otherwise.} \end{cases}$$
 (29)

The generator is an n-form of compact support with integral

Definition 1.30. A map is proper if the inverse image of every compact set is compact.

Theorem 1.31 (Sard's). The set of critical values of a smooth map $f: M \to N$ has measure zero.

Definition 1.32. Let $f: \mathbb{R}^n \to \mathbb{R}^n$ be proper. Let α be a generator of $H_c^n(\mathbb{R}^n)$ (integrates to 1), then

$$\deg f = \int_{\mathbb{D}^n} f^* \alpha \tag{30}$$

is the degree of f.

Proposition 1.33. Let $f: \mathbb{R}^n \to \mathbb{R}^n$ be proper. If f is not surjective, then it has degree 0.

Theorem 1.34. Let $f: \mathbb{R}^n \to \mathbb{R}^n$ be proper. The degree of f is an integer.

Definition 1.35. An open cover is called a good cover if all nonempty finite intersections $U_{p_1} \cap \cdots \cap U_{p_n}$ are diffeomorphic to \mathbb{R}^n . A manifold with a finite good cover is said to be of finite type. If \mathcal{U} , \mathcal{V} are two covers, \mathcal{U} is called the refinement of \mathcal{V} if every U_p is contained in some V_q and write $\mathcal{V} < \mathcal{U}$.

Theorem 1.36. Every manifold has a good cover. If it is compact, the cover can be chosen to be finite. Every open cover has a refinement which is a good cover.

Corollary 1.37. The good covers are cofinal in the set of all covers of a manifold (For directed sets, $J \subset I$ is cofinal in I if for every $i \in I$ there is $j \in J$ with i < j).

Proposition 1.38. If a manifold has a finite good cover, then its (compact) cohomology is finite dimensional.

Lemma 1.39. The pairing $\langle , \rangle : V \otimes W \to \mathbb{R}$ for finite vector spaces is nondegenerate iff $v \mapsto \langle v, \rangle$ is an isomorphism $V \to W^*$.

Lemma 1.40. Given a commutative diagram of Abelian groups and group homomorphisms

where the rows are exact, if a, b, d, e are isomorphisms, so is c.

Lemma 1.41. The Mayer-Vietoris sequences may be paired together to form a sign-commutative diagram