## 1 Algebraic Topology

**Definition 1.1** (de Rham complex).  $\Omega^*$  is the algebra generated over  $\mathbb{R}$  by  $dx_1, \ldots, dx_n$  subject to

- 1.  $(dx_i)^2 = 0$ ,
- 2.  $dx_i dx_j = -dx_j dx_i, i \neq j$ .

The  $C^{\infty}$  differential forms on  $\mathbb{R}$  are elements of

$$\Omega^*(\mathbb{R}^n) = \{ C^{\infty} \text{ functions on } \mathbb{R}^n \} \otimes_{\mathbb{R}} \Omega^*.$$
 (1)

We have  $\Omega^*(\mathbb{R}^n) = \bigoplus_{q=0}^n \Omega^q(\mathbb{R}^n)$ , where  $\Omega^q(\mathbb{R}^n)$  consists of the  $C^{\infty}$  q-forms on  $\mathbb{R}^n$ . We define

$$d: \Omega^q(\mathbb{R}^n) \to \Omega^{q+1}(\mathbb{R}^n), \tag{2}$$

the exterior differentiation, by

- 1. if  $f \in \Omega^0(\mathbb{R}^n)$ , then  $df = \sum \partial f/\partial x_i dx_i$ ,
- 2. if  $\omega = \sum_{I} f_{I} dx_{I}$ , then  $d\omega = \sum_{I} df_{I} dx_{I}$ , where  $dx_{I} = dx_{i} dx_{j} \dots$

The wedge product is defined by

$$\tau \wedge \omega = \sum \tau_I \omega_J \, dx_I dx_J = (-1)^{\deg \tau \, \deg \omega} \omega \wedge \tau. \tag{3}$$

**Proposition 1.2.** d is an antiderivation,

$$d(\tau \wedge \omega) = (d\tau) \wedge \omega + (-1)^{\deg \tau} \tau \wedge d\omega. \tag{4}$$

Proposition 1.3.  $d^2 = 0$ .

**Definition 1.4.** The q-th de Rham cohomology of  $\mathbb{R}^n$  is the vector space

$$H^q(\mathbb{R}^n) = \{\text{closed } q\text{-forms}\}/\{\text{exact } q\text{-forms}\},$$
 (5)

where closed means in the kernel of d and exact means in the image of d. We denote by  $[\omega]$  the cohomology class of  $\omega$ .

*Remark.* Only the constant functions are relevant for  $\mathbb{R}^n$ ,

$$H^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension 0,} \\ 0 & \text{otherwise.} \end{cases}$$
 (6)

**Definition 1.5.** A differential complex is a direct sum of Vector spaces  $C = \bigoplus_{q \in \mathbb{Z}} C^q$  if there are homomorpisms

$$\ldots \longrightarrow C^{q-1} \stackrel{d}{\longrightarrow} C^i \stackrel{d}{\longrightarrow} C^{q+1} \longrightarrow \ldots$$

with  $d^2=0$ . The cohomology of C is given by  $H(C)=\bigoplus_{q\in\mathbb{Z}}H^q(C)$ , with

$$H^{q}(C) = (\ker d \cap C^{q})/(\operatorname{im} d \cap C^{q}). \tag{7}$$

A map  $f:A\to B$  between two differential complexes is a chain map it it commutes with the differential operators of A and B,  $fd_A=d_Bf$ . A sequence of vector spaces

$$\ldots \longrightarrow V_{q-1} \xrightarrow{f_{i-1}} V_i \xrightarrow{f_i} V_{q+1} \longrightarrow \ldots$$

is said to be exact if the image of  $f_{i-1}$  is the kernel of  $f_i$ . An exact sequence of the form

$$0 \longrightarrow A \stackrel{f}{\longrightarrow} B \stackrel{g}{\longrightarrow} C \longrightarrow 0$$

is called a short exact sequence. Note that f is injective and g surjective. If f, g are chain maps, there is a long exact sequence of cohomology groups

$$H^{q+1}(A) \xrightarrow{f^*} \dots$$

$$\uparrow \qquad \qquad \downarrow d^*$$

$$H^q(A) \xrightarrow{f^*} H^q(B) \xrightarrow{g^*} H^q(C)$$

 $f^*$ ,  $g^*$  are the naturally induced maps and  $d^*[c]$  is obtained through the commutative diagram

$$0 \longrightarrow A^{q+1} \xrightarrow{f} B^{q+1} \xrightarrow{g} C^{q+1} \longrightarrow 0$$

$$\downarrow d \qquad \downarrow 0$$

$$0 \longrightarrow A^{q} \xrightarrow{f} B^{q} \xrightarrow{g} C^{q} \longrightarrow 0$$

Since g is surjective there is  $b \in B^q$  with g(b) = c. Because g(db) = d(gb) = dc = 0, there is  $a \in A^{q+1}$  with db = f(a). Then  $d^*[c] := [a]$ . a is closed because f is injective. To see that the sequence is exact, note that if b is closed then f(a) = 0, and due to injectivity a = 0. On the other hand, f(a) is exact and therefore [f(a)] = 0.

**Definition 1.6.**  $\Omega_c^*(\mathbb{R}^n)$  is the de Rham complex for functions of compact support,  $H_c^*(\mathbb{R})$  is its cohomology.

Remark. Only the n-forms whose integrals are different from zero are relevant, since if it was zero then its antiderivative can have compact support,

$$H_c^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension n,} \\ 0 & \text{otherwise.} \end{cases}$$
 (8)

**Definition 1.7.**  $f: \mathbb{R}^m \to \mathbb{R}^n$  induces a pullback on functions

$$f^*(g) = g \circ f. \tag{9}$$

On forms the pullback is defined as

$$f^*(\sum g_I dy_{i_1} \dots dy_{i_q}) = \sum (g_I \circ f) df_{i_1} \dots df_{i_q},$$
 (10)

with  $f_i = y_i \circ f$  the i-th component of f,  $y_i$  the standard coordinates.

**Proposition 1.8.**  $f^*$  commutes with d. This shows that the cohomology is a diffeomorphism invariant.

**Definition 1.9.** Let  $M = U \cup V$  with U, V open. Then we have the inclusions

$$M \leftarrow U \sqcup V \leftarrow U \cap V \tag{11}$$

where  $\sqcup$  is the disjoint union (each element has a label indicating wether it's from U or V). Using the inclusions as pullbacks we get

$$\Omega^*(M) \to \Omega^*(U) \oplus \Omega^*(V) \to \Omega^*(U \cap V).$$
 (12)

The Mayer-Vietoris sequence is given by

$$0 \to \Omega^*(M) \to \Omega^*(U) \oplus \Omega^*(V) \to \Omega^*(U \cap V) \to 0, \quad (13)$$

with

$$\Omega^*(U) \oplus \Omega^*(V) \to \Omega^*(U \cap V); (\omega, \tau) \mapsto \tau - \omega.$$
 (14)

**Proposition 1.10.** The Mayer-Vietoris sequence is exact. This is achieved through partitions of unity  $\rho$ ,

$$(\rho_U \omega) - (-\rho_V \omega) = \omega. \tag{15}$$

long exact sequence with the same name:

$$H^{q+1}(M) \xrightarrow{H^{q+1}(U) \oplus H^{q+1}(V)} \longrightarrow H^{q+1}(U \cap V)$$

$$H^q(M) \longrightarrow H^q(U) \oplus H^q(V) \longrightarrow H^q(U \cap V)$$

Explicitly

$$d^*[\omega] = \begin{cases} [-d(\rho_V \omega)] & \text{on } U, \\ [d(\rho_U \omega)] & \text{on } V. \end{cases}$$
 (16)

**Definition 1.12.** If  $j:U\to M$  is the inclusion of U in M, then let  $j_*: \Omega_c^*(U) \to \Omega_c^*(M)$  the map which extends a form to M by zero. Because pullbacks of compact forms are in general not compact, we instead use the inclusions

$$\Omega_c^*(M) \xleftarrow{\text{sum}} \Omega_c^*(U) \oplus \Omega_c^*(V) \xleftarrow{\delta} \Omega_c^*(U \cap V)$$
$$\delta : \omega \mapsto (-j_*\omega, j_*\omega). \tag{17}$$

We then get the Mayer-Vietoris sequence

$$0 \leftarrow \Omega_c^*(M) \leftarrow \Omega_c^*(U) \oplus \Omega_c^*(V) \leftarrow \Omega_c^*(U \cap V) \leftarrow 0, \quad (18)$$

which induces

$$H^{q+1}_c(M) \longleftarrow H^{q+1}_c(U) \oplus H^{q+1}_c(V) \longleftarrow H^{q+1}_c(U \cap V)$$

$$H^q_c(M) \longleftarrow H^q_c(U) \oplus H^q_c(V) \longleftarrow H^q_c(U \cap V)$$

and we now instead get

$$d^*[\omega] = \begin{cases} [-d(\rho_U \omega)] & \text{on } U, \\ [d(\rho_V \omega)] & \text{on } V. \end{cases}$$
 (19)

Proposition 1.13. The Mayer-Vietoris sequence of forms with compact support is exact.

**Proposition 1.14.** A manifold of dimension n is orientable iff it has a global nowhere vanishing n-form.

**Definition 1.15.** Let  $\mathbb{H}^n = \{x_n \geq 0\} \subset \mathbb{R}^n$  with standard orientation  $dx_1 \dots dx_n$ . The induced orientation of  $\partial \mathbb{H}^n = \{x_n = 0\}$  is given by the equivalence class of  $(-1)^n dx_1 \dots dx_{n-1}$ . For an orientation-preserving diffeomorphism  $\phi$  we define for manifolds

$$[\partial M] = \phi^* [\partial \mathbb{H}^n]. \tag{20}$$

Remark. This definition is due to  $\omega|_{\partial M} := i_{\hat{n}}\omega$  for the normal

**Theorem 1.16** (Stokes'). Let  $\omega$  be an (n-1)-form with compact support on an oriented manifold M, then

$$\int_{M} d\omega = \int_{\partial M} \omega. \tag{21}$$

**Definition 1.17.** Let  $\pi: \mathbb{R}^n \times \mathbb{R}^1 \to \mathbb{R}^n$ ;  $\pi(x,t) = x$  and  $s: \mathbb{R}^n \to \mathbb{R}^n \times \mathbb{R}^1$ ; s(x) = (x, 0). Trivially  $\pi \circ s = 1$ ,  $s^* \circ \pi^* = 1$ , but  $s \circ \pi \neq 1$ . K is called a homotopy operator if

$$1 - \pi^* \circ s^* = \pm (dK \pm Kd). \tag{22}$$

 $dK \pm Kd$  maps closed forms to exact forms, therefore induces zero in cohomology. If K exists,  $\pi^* \circ s^*$  is said to be chain homotopic to the identity. We define  $K: \Omega^q(\mathbb{R}^n \times \mathbb{R}) \to$  $\Omega^{q-1}(\mathbb{R}^n \times \mathbb{R})$  by

$$(\pi^*\phi)f(x,t)\mapsto 0, \quad (\pi^*\phi)f(x,t)dt\mapsto (\pi^*\phi)\int_0^t dt f \quad (23)$$

with  $\phi$  a form on  $\mathbb{R}^n$ .

**Definition 1.11.** The Mayer-Vietoris sequence induces a **Proposition 1.18.** K is a homotopy operator. The maps  $\pi^*, s^*$  on  $H^*(\mathbb{R}^n \times \mathbb{R}) \leftrightarrow H^*(\mathbb{R}^n)$  are isomorphisms.

Corollary 1.19 (Poincaré Lemma).

$$H^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension 0,} \\ 0 & \text{otherwise.} \end{cases}$$
 (24)

More generally  $H^*(M \times \mathbb{R}^1) \simeq H^*(M$ 

Corollary 1.20 (Homotopy Axiom for de Rham Cohomology). Homotopic maps induce the same map in cohomology.

**Definition 1.21.** Two Manifolds M, N have the same homotopy type if there are  $C^{\infty}$  maps  $f: M \to N, g: N \to M$ such that  $g \circ f$ ,  $f \circ g$  are  $C^{\infty}$  homotopic to the identity on M, N respectively. A manifold is called contractible if it has the homotopy type of a point.

Corollary 1.22. Manifolds with the same homotopy type have the same de Rham cohomology.

**Definition 1.23.**  $r: M \to A$  is called a retraction of M onto A if  $r \circ i : A \to A$  is the identity, with  $i : A \subset M$  the inclusion. If  $i \circ r : M \to M$  is homotopic to the identity on M, then r is called a deformation retraction of M onto A, and it follows that M, A have the same homotopy type.

Corollary 1.24. If A is a deformation retract of M, then A, M have the same de Rham cohomology.

Corollary 1.25.

$$H^*(S^n) = \begin{cases} R & \text{in dimension 0, n} \\ 0 & \text{otherwise.} \end{cases}$$
 (25)

**Definition 1.26.** Let  $\pi: M \times \mathbb{R}^1 \to M$  be the projection. We define the push-forward for compact forms  $\pi_*: \Omega^*_c(M \times \mathbb{R}^1) \to$  $\Omega_c^{*-1}(M)$ , called integration along the fiber by

$$\pi^* \phi f(x,t) \mapsto 0, \quad \pi^* \phi f(x,t) dt \mapsto \phi \int_{-\infty}^{\infty} dt f$$
 (26)

where  $\phi$  is a form on M. Let e = e(t)dt be a compactly supported 1-form on  $\mathbb{R}^1$  with total integral 1 and define

$$e_*: \Omega_c^*(M) \to \Omega_c^{*+1}(M \times \mathbb{R}^1); \quad \phi \to (\pi^*\phi) \wedge e.$$
 (27)

The homotopy operator  $K: \Omega_c^*(M \times \mathbb{R}^1) \to \Omega_c^{*-1}(M \times \mathbb{R}^1)$  is defined by

$$\pi^* \phi f \mapsto 0, \quad \pi^* \phi f dt \mapsto \pi^* \phi \int_{-\infty}^t f - \pi^* \phi \int_{-\infty}^t e \int_{-\infty}^\infty f.$$
 (28)

**Proposition 1.27.** d commutes with both  $\pi_*$  and  $e_*$ .

**Proposition 1.28.**  $1-e_*\pi_*=(-1)^{q-1}(dK-Kd)$  on  $\Omega^q_c(M\times\mathbb{R}^1)$ . The maps  $H^*_c(M\times\mathbb{R}^1)\leftrightarrow H^{*-1}_d(M)$  are isomorphisms.

Corollary 1.29 (Poincaré Lemma for Compact Supports).

$$H_c^*(\mathbb{R}^n) = \begin{cases} R & \text{in dimension n} \\ 0 & \text{otherwise.} \end{cases}$$
 (29)

The generator is an n-form of compact support with integral

**Definition 1.30.** A map is proper if the inverse image of every compact set is compact.

**Theorem 1.31** (Sard's). The set of critical values of a smooth map  $f: M \to N$  has measure zero.

**Definition 1.32.** Let  $f: \mathbb{R}^n \to \mathbb{R}^n$  be proper. Let  $\alpha$  be a generator of  $H^n_c(\mathbb{R}^n)$  (integrates to 1), then

$$\deg f = \int_{\mathbb{R}^n} f^* \alpha \tag{30}$$

is the degree of f.

**Proposition 1.33.** Let  $f: \mathbb{R}^n \to \mathbb{R}^n$  be proper. If f is not surjective, then it has degree 0.

**Theorem 1.34.** Let  $f: \mathbb{R}^n \to \mathbb{R}^n$  be proper. The degree of f is an integer.

**Definition 1.35.** An open cover is called a good cover if all nonempty finite intersections  $U_{p_1} \cap \cdots \cap U_{p_n}$  are diffeomorphic to  $\mathbb{R}^n$ . A manifold with a finite good cover is said to be of finite type. If  $\mathcal{U}$ ,  $\mathcal{V}$  are two covers,  $\mathcal{U}$  is called the refinement of  $\mathcal{V}$  if every  $U_p$  is contained in some  $V_q$  and write  $\mathcal{V} < \mathcal{U}$ .

**Theorem 1.36.** Every manifold has a good cover. If it is compact, the cover can be chosen to be finite. Every open cover has a refinement which is a good cover.

**Corollary 1.37.** The good covers are cofinal in the set of all covers of a manifold (For directed sets,  $J \subset I$  is cofinal in I if for every  $i \in I$  there is  $j \in J$  with i < j).

**Proposition 1.38.** If a manifold has a finite good cover, then its (compact) cohomology is finite dimensional.

**Lemma 1.39.** The pairing  $\langle , \rangle : V \otimes W \to \mathbb{R}$  for finite vector spaces is nondegenerate iff  $v \mapsto \langle v, \rangle$  is an isomorphism  $V \to W^*$ .

Lemma 1.40. Given a commutative diagram of Abelian groups and group homomorphisms

where the rows are exact, if a, b, d, e are isomorphisms, so is c.

**Lemma 1.41.** The Mayer-Vietoris sequences may be paired together to form a sign-commutative diagram

where sign-commutativity means that

$$\int_{U \cap V} \omega \wedge d_* \tau = \pm \int_{U \cup V} (d^* \omega) \wedge \tau, \tag{31}$$

with  $\omega \in H^q(U \cap V)$ ,  $\tau \in H^{n-q-1}_c(U \cup V)$ . This is equivalent to the sign-commutative diagram

**Theorem 1.42** (Poincaré Duality). If M is orientable and has a finite good cover, then

$$\int H^{q}(M) \otimes H_{c}^{n-q}(M) \to \mathbb{R}$$
 (32)

is nondegenerate, or equivalently

$$H^q(M) \simeq (H_c^{n-q}(M))^*. \tag{33}$$

Corollary 1.43. If M is connected, oriented with dimension n, then  $H_c^n(M) \simeq \mathbb{R}$ . If M is also compact then  $H^n(M) \simeq \mathbb{R}$ .

**Definition 1.44.** Let G be a topological group acting effectively(only  $1 \in G$  acts trivially) on a space F on the left. A surjection  $\pi: E \to B$  between topological spaces is a fiber bundle with fiber F and structure group G(also called a G-bundle) if B has an open cover  $\{U_a\}$  such that there are fiber-preserving homeomorphisms

$$\phi_a: E|_{U_a} \mapsto U_a \times F,\tag{34}$$

called trivialisations, and continuous transition functions with values in  ${\cal G}$ 

$$g_{ab} = \phi_a \phi_b^{-1}|_{\{x\} \times F} \in G.$$
 (35)

 $E_x = \pi^{-1}(x)$  is called the fiber at x. E, B are called total and base space respectively. If G is not explicitly defined then it is understood to be the group of diffeomorphisms of F.

Remark. The transition functions satisfy the cocycle condition

$$g_{ab} \cdot g_{bc} = g_{ac}. \tag{36}$$

Given a cocycle  $\{g_{ab}\}$  we can construct a fiber bundle with  $\{g_{ab}\}$  as its transition function,

$$E = \left(\coprod U_a \times F\right) / (x, y) \sim (x, g_{ab}(x)y). \tag{37}$$

**Theorem 1.45** (Künneth Formula). For two manifolds M, F, with at least one having a good finite cover, we have

$$H^*(M \times F) = H^*(M) \otimes H^*(F), \tag{38}$$

which means

$$H^{n}(M \times F) = \bigoplus_{p+q=n} H^{p}(M) \otimes H^{q}(F). \tag{39}$$

Also holds in the compact cohomology case.

**Theorem 1.46** (Leray-Hirsch). Let E be a fiber bundle over M with fiber F. Suppose M has a finite good cover. If there are global cohomology classes  $e_1, \ldots, e_r$  on E which restricted to each fiber freely generate the cohomology of the fiber, then  $H^*(E)$  is a free module over  $H^*(M)$  with basis  $\{e_1, \ldots, e_r\}$  meaning that

$$H^*(E) \simeq H^*(M) \otimes \mathbb{R}\{e_1, \dots, e_r\} \simeq H^*(M) \otimes H^*(F).$$
 (40)

**Definition 1.47.** A (real) vector bundle of rank n is a fiber bundle with fiber  $\mathbb{R}^n$  and structure group  $GL(n,\mathbb{R})$ . A section of the vector bundle E over  $U \subset B$  open is a map  $s: U \to E$  such that  $\pi \circ s$  is the identity on U. The space of all sections over U is denoted by  $\Gamma(U, E)$ . A frame on U is a collection of sections  $s_1, \ldots, s_n$  over U such that they form a basis for each  $E_x = \pi^{-1}(x), x \in U$ .

**Lemma 1.48.** If the cocycle  $\{g'_{ab}\}$  comes from another trivialization, then there are maps  $\lambda_a:U_a\to GL(n,\mathbb{R})$  such that

$$g_{ab} = \lambda_a g'_{ab} \lambda_b^{-1}. \tag{41}$$

The two cocycles are then said to be equivalent.

**Proposition 1.49.** Two vector bundles on M are isomorphic iff their cocycles are equivalent.

**Definition 1.50.** A bundle map is a fiber-preserving smooth map  $f: E \to E'$  of vector bundles which is linear on the fibers. If it is possible to find an equivalent cocycle with values in a subgroup  $H \subset GL(n,\mathbb{R})$  we say that the structure group of E may be reduced to H. A vector bundle is orientable if its structure group may be reduced to  $GL^+(n,\mathbb{R})$  (determinants are positive). A trivialisation is said to be oriented if the transition functions have positive determinant.

**Proposition 1.51.** The structure group of a real vector bundle of rank n can be reduced to O(n). It can be reduced to SO(n) iff the bundle is orientable.