

Saarland University  
Faculty of Natural Sciences and Technology I  
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Bachelor's Thesis

# Constructive Formalization of Regular Languages

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# Abstract

We give a constructive formalization of the equivalence between regular expressions, finite automata and the Myhill-Nerode characterization. We give procedures to convert between these characterizations and prove their correctness. Our development is done in the proof assistant COQ. We make use of the SSREFLECT plugin which provides support for finite types and other useful infrastructure for our purpose. Our goal was to make the formalization as concise as possible. The entire development consists of approximately 2700 lines of code.

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# 1 Introduction

Our goal is to give a concise formalization of the theory of regular languages. We include several different characterizations of regular languages and prove them equivalent. These include regular expressions, finite automata and the characterizations usually combined in the Myhill-Nerode theorem. All our proofs are constructive and, thus, constitute procedures to convert between these characterizations. Our formalization also includes decision procedures for the equivalence of finite automata and regular expressions.

Regular languages are a well-studied class of formal languages. In their current form, they were first studied by Kleene [23], who introduced regular expressions. The concept of deterministic finite automata was introduced before Kleene's invention of regular expressions by Huffman [21] and Moore [27]. Rabin and Scott later introduced the concept of non-deterministic finite automata [29], for which they were given the Turing award [4].

We take classical proofs from [24] and translate them to our constructive setting. We employ the proof assistant COQ [26] for our formalization. Additionally, we make use of the SSREFLECT plugin [18]. SSREFLECT offers an extended scripting language and provides support for finite types, which we use for formalizing finite automata. It also comes with a lot of general infrastructure useful for our purpose. For every lemma and theorem proven in this thesis, we provide corresponding statements from the COQ development. Our development does not depend on axioms.

One of the most interesting parts of the formalization was to find a suitable representation of quotient types in COQ, which has no notion of quotient types. Our approach seems to work very well for our purpose.

## 1.1 Related work

There have been many publications on formalizations of the theory of regular languages in recent years. Most of them investigate decidability of equivalence of regular expressions, often with a focus on automatically deciding Kleene algebras.

Coquand and Siles develop a decision procedure for equivalence of regular expressions [16] on the basis of Brzozowski derivatives [14] in COQ (using SSREFLECT) with the goal of providing a practically executable tactic on top of the decision procedure. Their development weighs in at 7,500 lines of code, 700 of which serve as the basis of our formalization.

Krauss and Nipkow give a decision procedure for equivalence of regular expressions in Isabelle/HOL [25]. Their development is very concise with just over 1,000 lines of code. Being interested only in a correct (and efficient) tactic for deciding equivalences, they did not prove completeness and termination.



Another decision procedure for equivalence of regular expressions is developed by Braibant and Pous [12], with the goal of deciding Kleene algebras in COQ. Their formalization is based on matrices and comprises 19,000 lines of code. It encompasses finite automata, regular expressions and the Myhill-Nerode theorem.

Moreira, Pereira and Sousa give a decision procedure for equivalence of regular expressions in COQ [28]. Their development is based on Antimirov’s partial derivatives of regular expressions [2] and contains a refutation step to speed up inequality checking. It consists of 19,000 lines of code.

Asperti formalizes a decision procedure for equivalence of regular expressions [5] based on the notion of pointed regular expressions [6]. This development was done in the Matita proof assistant [7]. It weighs in at 3,400 lines of code.

There is also a paper by Wu, Zhang and Urban on formalizing the Myhill-Nerode theorem using only regular expressions and not, as is commonly done, finite automata [31]. The authors state that this unusual choice stems, at least partly, from the restrictions of Isabelle/HOL (and similar HOL-based theorem provers). In particular, the fact that Isabelle/HOL does not allow for quantification over types prevents straight-forward formalizations of finite automata. Their development consists of roughly 2,000 lines of code.

## 1.2 Contributions

Our formalization is done in constructive type theory. Thus, all our proofs are algorithms that are, in theory, executable. However, our focus is solely on clarity and simplicity. As a result, the algorithms and procedures given in this thesis are very close to the mathematical definitions in [24], but not executable in practice.

Our development shows that COQ (particularly with SSREFLECT) is well suited for this kind of formalization. Furthermore, we have also developed a new characterization derived from the Nerode relation and proven it equivalent to all other characterizations. Our development weighs in at about 2,700 lines of code.

## 1.3 Outline

In Chapter 2 we give a brief introduction to COQ and SSREFLECT and introduce concepts that are relevant to our formalization.

In Chapter 3 we give basic definitions (words, languages, etc.). We also introduce decidable languages, regular languages, and regular expressions. Furthermore, we prove the decidability of regular languages.

In Chapter 4 we introduce finite automata. We prove the equivalence of deterministic and non-deterministic finite automata. We also give a procedure to remove unreachable states from deterministic finite automata. Furthermore, we prove decidability of emptiness and equivalence of finite automata. Finally, we prove that regular expressions and finite automata are equally expressive.

## *1 Introduction*

In Chapter 5 we introduce the Myhill-Nerode theorem. We give three different characterizations of regular languages based on the Myhill-Nerode theorem and prove them all equally expressive to finite automata.

## 2 Coq and SSReflect

We decided to employ the Small Scale Reflection Extension [18] (**SSReflect**<sup>1</sup>) for the **Coq**<sup>2</sup> proof assistant [26]. The most important factors in this decision were SSREFLECT's excellent support for finite types, list operations and graphs. SSREFLECT also introduces an alternative scripting language that can often be used to shorten the book-keeping overhead of proofs considerably.

### 2.1 Coq

The COQ manual [26] states the following about COQ: The COQ system is designed to develop mathematical proofs, and especially to write formal specifications, programs and to verify that programs are correct with respect to their specification. It provides a specification language named Gallina. Terms of Gallina can represent programs as well as properties of these programs and proofs of these properties. Using the so-called Curry-Howard isomorphism, programs, properties and proofs are formalized in the same language, which is a  $\lambda$ -calculus with a rich type system called Calculus of Inductive Constructions. All logical judgments in COQ are typing judgments. The very heart of the COQ system is the type-checking algorithm that checks the correctness of proofs, i.e that a program complies to its specification. COQ also provides an interactive proof assistant to build proofs using specific programs called tactics.

### 2.2 SSReflect

SSREFLECT is a set of extensions to the proof scripting language of the COQ proof assistant. They were originally developed to support small-scale reflection. However, most of them are of quite general nature and improve the functionality of COQ in most basic areas such as script layout and structuring, proof context management and rewriting [18].

SSREFLECT comes with an extensive library [17] covering many mathematical concepts leading up to finite group theory. In fact, we barely scratch the surface of the library in this development. The interested reader may convince herself/himself of the sheer size of the library<sup>3</sup>.

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<sup>1</sup><http://www.msr-inria.inria.fr/Projects/math-components>

<sup>2</sup><http://coq.inria.fr/>

<sup>3</sup><http://coqfinitgroup.gforge.inria.fr/>

### 2.2.1 Boolean Reflection

SSREFLECT offers boolean reflections for decidable propositions, so called “small-scale reflection”. A term of type `reflect P b` is a proof of the equivalence of the boolean statement `b` and the proposition `P`. SSREFLECT has built-in support to change from boolean to propositional statements if they are equivalent. This allows us to always assume the most convenient perspective in our proofs.

### 2.2.2 Boolean Predicates

SSREFLECT has special type for boolean predicates, `pred T := T -> bool`, where `T` is a type. We make use of SSREFLECT’s syntax to specify boolean predicates. This allows us to specify predicates in a way that resembles set-theoretic notation, e.g. `[pred x | <boolean expression in x>]`. Furthermore, we can use the functions `pred1` and `pred0` to specify the singleton predicate and the empty predicate, respectively. The complement of a predicate can be written as `[predC p]`. The syntax for combining predicates is `[pred? p1 & p2]`, with `?` being one of `U` (union), `I` (intersection) or `D` (difference). For predicates given in such a way, we write `y \in p` to express that `y` fulfills `p`. There is also syntax for the preimage of a predicate under a function which can be written as `[preim f of p]`.

There are also applicative (functional) versions of `predC`, `predU`, `predI`, `predD`, which are functions that take predicates as arguments and return predicates. `pred1 x` represents the predicate `[pred y | y == x]`.

### 2.2.3 Finite Types

The most important feature of SSREFLECT for our purpose are finite types. Finite types are types that have a finite number of elements. The type of finite types is `finType`. SSREFLECT offers a number of important operations on finite types. Finite types are closed under basic operations such as `option` and `sum`. SSREFLECT provides boolean versions of the universal and existential quantifiers on finite types, `[forall x, p x]` and `[exists x, p x]`, where `p` is a boolean predicate. We compute the number of elements for which a predicate `p` on a finite type returns true with `#|p|`. `enum p` gives a list of these elements. A finite type in the position of a predicate coerces to a predicate that is always true.

We can also create finite types from lists. Instances of these types can be specified with the `SeqSub` constructor, which takes as arguments an element of the list and a proof that this element is contained in the list.

### 2.2.4 Finite Sets

SSREFLECT also supports finite sets, which are sets over finite types. Finite sets themselves are finite types, which allows us to use them in the construction of finite automata. Additionally, they come with the same syntax for counting and enumerating their elements that we introduced for finite types. The type of a finite set is `{set T}`, where `T` is

a finite type. The function `set1` constructs a singleton set containing its first argument. The type of the resulting finite set can be inferred from the argument. The union over finite sets can be expressed by `\bigcup_(x | P x) F`, which corresponds to the mathematical notation  $\bigcup_{x \in X, Px} F$ , with  $X$  being the (finite) type of  $x$ . More information about these so-called “big operators” can be found in [10].

### 2.2.5 Equality

We can use `f =1 g` to express that the functions `f` and `g` agree in all arguments. If we regard `f` and `g` as sets, we can write `f =i g`, which is defined as `forall x, x \in f = x \in g`. We need to do this because COQ’s equality `=` is intensional, which means that even if we have `f =1 g`, we are not, in general, able to prove `f = g`. Thus, we use `=1` or `=i` in COQ, when we write `=` mathematically. This expresses the notion of extensional equality of classical mathematics.

## 3 Decidable Languages

We give basic definitions for languages, operators on languages and, finally, regular languages. We provide the corresponding formalizations from our development and prove their correctness.

### 3.1 Definitions

We closely follow the definitions from [20]. An **alphabet**  $\Sigma$  is a finite set of symbols. A **word**  $w$  is a finite sequence of symbols chosen from some alphabet. We use  $|w|$  to denote the **length** of a word  $w$ .  $\varepsilon$  denotes the empty word. Given two words  $w_1 = a_1 \cdots a_n$  and  $w_2 = b_1 \cdots b_m$ , the **concatenation** of  $w_1$  and  $w_2$  is defined as  $a_1 \cdots a_n b_1 \cdots b_m$  and denoted  $w_1 \cdot w_2$  or just  $w_1 w_2$ . A **language** is a set of words. The **residual language** of a language  $L$  with respect to symbol  $a$  is the set of words  $u$  such that  $av$  is in  $L$ . The residual is denoted  $res_a(L)$ . We define  $\Sigma^k$  to be the **set of words of length k**. The **set of all words** over an alphabet  $\Sigma$  is denoted  $\Sigma^*$ , i.e.,  $\Sigma^* = \bigcup_{k \in \mathbb{N}} \Sigma^k$ . A language  $L$  is **decidable** if and only if there exists a boolean predicate that decides membership in  $L$ . We will only deal with decidable languages from here on. Throughout the remaining document, we will assume a fixed alphabet  $\Sigma$ .

We employ finite types to formalize alphabets. In most definitions, alphabets will not be made explicit. However, the same name and type will be used throughout the entire development. Words are formalized as sequences over the alphabet. Decidable languages are represented by functions from *word* to *bool*.

**Variable** `char`: `finType`.

**Definition** `word` := `seq char`.

**Definition** `language` := `pred word`.

**Definition** `residual x L : language` := `[preim cons x of L]`.

#### 3.1.1 Operations on Languages

We will later introduce a subset of the decidable language that is based on the following operations. For every operator, we will prove the decidability of the resulting language.

The **concatenation** of two languages  $L_1$  and  $L_2$  is denoted  $L_1 \cdot L_2$  and is defined as the set of words  $w = w_1 w_2$  such that  $w_1$  is in  $L_1$  and  $w_2$  is in  $L_2$ . The **Kleene closure** of a language  $L$  is denoted  $L^*$  and is defined as the set of words  $w = w_1 \cdots w_k$  such that  $w_1 \dots w_k$  are in  $L$ . Note that  $\varepsilon \in L^*$  ( $k = 0$ ). We define the **complement** of a language  $L$  as  $\Sigma^* \setminus L$ , which we write as  $\neg L$ . Furthermore, we make use of the standard set operations **union** and **intersection**.

### 3 Decidable Languages

For our COQ development, we take Coquand and Siles's [16] implementation of these operators. `plus` and `prod` refer to union and intersection, respectively. Additionally, we also introduce the singleton languages (`atom`), the empty language (`void`) and the language containing only the empty word (`eps`).

**Definition** `conc L1 L2 : language :=`  
`fun v => [ exists i : '1_ (size v).+1, L1 (take i v) && L2 (drop i v) ].`

**Definition** `star L : language :=`  
`fix star v := if v is x :: v' then conc (residual x L) star v' else true.`

**Definition** `compl L : language := predC L.`

**Definition** `plus L1 L2 : language := [predU L1 & L2].`

**Definition** `prod L1 L2 : language := [predI L1 & L2].`

**Definition** `atom x : language := pred1 [:: x].`

**Definition** `void : language := pred0.`

**Definition** `eps : language := pred1 [::].`

The definition of `conc` is based on a characteristic property of the concatenation of two languages. The following lemma proves this property.

**Lemma 3.1.1.** *Let  $L_1, L_2, w = a_1 \cdots a_k$  be given. We have that*

$$w \in L_1 \cdot L_2 \iff \exists n \in \mathbb{N}. 0 < n \leq k \wedge a_1 \cdots a_{n-1} \in L_1 \wedge a_n \cdots a_k \in L_2.$$

*Proof.* “ $\Rightarrow$ ” From  $w \in L_1 \cdot L_2$  we have  $w_1, w_2$  such that  $w = w_1 w_2 \wedge w_1 \in L_1 \wedge w_2 \in L_2$ . We choose  $n := |w_1| + 1$ . We then have that  $a_1 \cdots a_{n-1} = a_1 \cdots a_{|w_1|} = w_1$  and  $w_1 \in L_1$  by assumption. Similarly,  $a_n \cdots a_k = a_{|w_1|+1} \cdots a_k = w_2$  and  $w_2 \in L_2$  by assumption.

“ $\Leftarrow$ ” We choose  $w_1 := a_1 \cdots a_{n-1}$  and  $w_2 := a_n \cdots a_k$ . By assumption we have that  $w = w_1 w_2$ . We also have that  $a_1 \cdots a_{n-1} \in L_1$  and  $a_n \cdots a_k \in L_2$ . It follows that  $w_1 \in L_1$  and  $w_2 \in L_2$ .  $\square$

**Lemma** `concP : forall {L1 L2 v},`  
`reflect (exists2 v1, v1 \in L1 & exists2 v2, v2 \in L2 & v = v1 ++ v2)`  
`(v \in conc L1 L2).`

The implementation of `star` makes use of a property of the Kleene closure, which is that any nonempty word in  $L^*$  can be seen as the concatenation of a nonempty word in  $L$  and a (possibly empty) word in  $L^*$ . This property allows us to implement `star` as a structurally recursive predicate. The following lemma proves the correctness of this property.

**Lemma 3.1.2.** *Let  $L, w = a_1 \cdots a_k$  be given. We have that*

$$w \in L^* \iff \begin{cases} a_2 \cdots a_k \in res_{a_1}(L) \cdot L^*, & \text{if } |w| > 0; \\ w = \varepsilon, & \text{otherwise.} \end{cases}$$

*Proof.* “ $\Rightarrow$ ” We do a case distinction on  $|w| = 0$ .

1.  $|w| = 0$ . It follows that  $w = \varepsilon$ .

### 3 Decidable Languages

2.  $|W| \neq 0$ , i.e.  $|w| > 0$ . From  $w \in L^*$  we have  $w = w_1 \cdots w_l$  such that  $w_1 \cdots w_l$  are in  $L$ . There exists a minimal  $n$  such that  $|w_n| > 0$  and for all  $m < n$ ,  $|w_m| = 0$ . Let  $w_n = b_1 \cdots b_p$ . We have that  $b_2 \cdots b_p \in \text{res}_{b_1}(L)$ . Furthermore, we have that  $w_{n+1} \cdots w_l \in L^*$ . We also have  $a_1 = b_1$  and  $w = a_1 \cdots a_k = w_n \cdots w_l$ . Therefore, we have  $a_2 \cdots a_k \in \text{res}_{a_1}(L) \cdot L^*$ .

“ $\Leftarrow$ ” We do a case distinction on the disjunction.

1.  $w = \varepsilon$ . Then  $w \in L^*$  by definition.
2.  $a_2 \cdots a_k \in \text{res}_{a_1}(L) \cdot L^*$ . By Lemma 3.1.1 we have  $n$  such that  $a_2 \cdots a_{n-1} \in \text{res}_{a_1}(L)$  and  $a_n \cdots a_k \in L^*$ . By definition of  $\text{res}$ , we have  $a_1 \cdots a_{n-1} \in L$ . Furthermore, we also have  $a_n \cdots a_k = w_1 \cdots w_l$  such that  $w_1 \cdots w_l$  are in  $L$ . We choose  $w_0 := a_1 \cdots a_{n-1}$ . It follows that  $w = w_0 w_1 \cdots w_l$  with  $w_0, w_1, \dots, w_l$  in  $L$ . Therefore,  $w \in L^*$ .

□

The formalization of Lemma 3.1.2 connects the formalization of `star` to the mathematical definition. The propositional formula given here appears slightly more restrictive than our mathematical definition as it requires all words from  $L$  to be nonempty. Mathematically, however, this is no restriction.

**Lemma** `starP` : `forall {L v},`  
`reflect (exists2 vv, all [predD L & eps] vv & v = flatten vv)`  
`(v \in star L).`

**Theorem 3.1.3.** *The decidable languages are closed under concatenation, Kleene star, union, intersection and complement.*

*Proof.* We have already given algorithms for all operators. It remains to show that they are correct. For concatenation and the Kleene star, we have shown in Lemma 3.1.1 and Lemma 3.1.2 that the formalizations are equivalent to the mathematical definitions. The remaining operators (union, intersection, complement) can be applied directly to the result of the languages’ boolean decision functions. □

## 3.2 Regular Languages

**Definition 3.2.1.** *The set of regular languages  $REG$  is defined to be exactly those languages generated by the following inductive definition:*

$$\begin{array}{c}
 \frac{}{\emptyset \in REG} \qquad \frac{}{\{\varepsilon\} \in REG} \qquad \frac{a \in \Sigma}{\{a\} \in REG} \qquad \frac{L \in REG}{L^* \in REG} \\
 \\
 \frac{L_1 \in REG \quad L_2 \in REG}{L_1 \cup L_2 \in REG} \qquad \frac{L_1 \in REG \quad L_2 \in REG}{L_1 \cdot L_2 \in REG}
 \end{array}$$



### 3.2.1 Regular Expressions

Regular expressions mirror the definition of regular languages very closely.

**Definition 3.2.2.** We will consider *extended regular expressions* that include negation (Not), intersection (And) and a single-symbol wildcard (Dot). Therefore, we have the following syntax for regular expressions:

$$r, s := \emptyset \mid \varepsilon \mid \cdot \mid a \mid r^* \mid r + s \mid r \& s \mid rs \mid \neg r$$

The language of an extended regular expression is defined as follows:

$$\begin{aligned} \mathcal{L}(\emptyset) &= \emptyset & \mathcal{L}(r^*) &= \mathcal{L}(r)^* \\ \mathcal{L}(\varepsilon) &= \{\varepsilon\} & \mathcal{L}(r + s) &= \mathcal{L}(r) \cup \mathcal{L}(s) \\ \mathcal{L}(\cdot) &= \Sigma & \mathcal{L}(r \& s) &= \mathcal{L}(r) \cap \mathcal{L}(s) \\ \mathcal{L}(a) &= \{a\} & \mathcal{L}(rs) &= \mathcal{L}(r) \cdot \mathcal{L}(s) \end{aligned}$$

**Definition 3.2.3.** We say that two regular expressions  $r$  and  $s$  are equivalent if and only if

$$\mathcal{L}(r) = \mathcal{L}(s).$$

We will later show that equivalence of regular expressions is decidable. We take the implementation of regular expressions from Coquand and Siles's development [16], which is also based on SSREFLECT and comes with helpful infrastructure for our proofs. The semantics defined in Definition 3.2.2 can be given as a boolean function.

**Inductive** regular\_expression :=  
 | Void  
 | Eps  
 | Dot  
 | Atom of symbol  
 | Star of regular\_expression  
 | Plus of regular\_expression & regular\_expression  
 | And of regular\_expression & regular\_expression  
 | Conc of regular\_expression & regular\_expression  
 | Not of regular\_expression .

**Fixpoint** mem\_reg e :=  
**match** e **with**  
 | Void => void  
 | Eps => eps  
 | Dot => dot  
 | Atom x => atom x  
 | Star e1 => star (mem\_reg e1)  
 | Plus e1 e2 => plus (mem\_reg e1) (mem\_reg e2)  
 | And e1 e2 => prod (mem\_reg e1) (mem\_reg e2)  
 | Conc e1 e2 => conc (mem\_reg e1) (mem\_reg e2)  
 | Not e1 => compl (mem\_reg e1)  
**end.**

### 3 Decidable Languages

We will later prove that extended regular expressions are equivalent to the inductive definition of regular languages in 3.2.1. In order to do that, we introduce a predicate on regular expressions that distinguishes **standard regular expressions** from **extended regular expressions** (as introduced above). The grammar of standard regular expression is as follows:

$$r, s := \emptyset \mid \varepsilon \mid a \mid r^* \mid r + s \mid rs$$

Note that standard regular expressions are equivalent to regular languages. We realize standard regular expressions as a predicate on extended regular expressions.

```
Fixpoint standard (e: regular_expression char) :=  
  match e with  
    | Not _ => false  
    | And _ _ => false  
    | Dot => false  
    | _ => true  
  end.
```

## 4 Finite Automata

Another way of characterizing regular languages are finite automata. We will show that the languages of finite automata are exactly those recognized by regular expressions. Furthermore, we will also derive a decision procedure for emptiness of an automaton's language. Based on that, we will give a decision procedure for equivalence of regular expressions. Finally, we prove that extended regular expressions and standard regular expressions are equally expressive and, thereby, that extended regular expressions are equivalent to regular languages.

### 4.1 Definition

A finite automaton [20] consists of

1. finite set of states  $Q$ ,
2. a starting state  $s \in Q$ ,
3. a set of final states  $F \subseteq Q$
4. and a state-transition relation  $\delta$ .

We define a **run** of a word  $w \in \Sigma^*$  on an automaton  $A = (Q, s, F, \delta)$  as a sequence of states  $\sigma$  such that for every two consecutive positions  $i, i+1$  in  $\sigma$  we have  $(\sigma_i, w_i, \sigma_{i+1}) \in \delta$ . A word  $w$  is **accepted** by  $A$  in state  $x$  if and only if there exists a run  $\sigma$  of  $w$  on  $A$  such that  $\sigma_0 = x \wedge \sigma_{|\sigma|-1} \in F$ . The resulting set of accepted words is denoted by  $\mathcal{L}_x(A)$ . The **language** of  $A$  is exactly  $\mathcal{L}_s(A)$  and is denoted  $\mathcal{L}(A)$ .

#### 4.1.1 Non-Deterministic Finite Automata

Finite automata can be **non-deterministic** (NFA) in the sense that there may exist multiple distinct runs for a word.

**Record** `nfa` : Type :=

```
{ nfa_state :> finType;  
  nfa_s : nfa_state;  
  nfa_fin : pred nfa_state;  
  nfa_step : nfa_state -> char -> pred nfa_state }.
```

**Fixpoint** `nfa_accept` (x: A) w :=

```
match w with  
| [] => nfa_fin A x  
| a :: w => [ exists y, ( nfa_step A x a y ) && nfa_accept y w ]  
end.
```

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**Definition**  $\text{nfa\_lang} := [\text{pred } w \mid \text{nfa\_accept } (\text{nfa\_s } A) w]$ .

The acceptance criterion given here avoids the matter of runs. In many cases, this will help us with proofs by induction on the accepted word. However, we will need runs in some of the proofs. Due to the fact that runs are not unique on NFAs, we give a predicate that decides if a sequence of states is a run on  $A$  for a word  $w$ . We then show that the acceptance criterion given above corresponds to the mathematical definition in terms of runs.

**Fixpoint**  $\text{nfa\_run } x \text{ (xs : seq } A) \text{ (w: word) \{struct xs\} :=}$   
**match**  $\text{xs, w}$  **with**  
 |  $y :: \text{xs}', a :: w' \Rightarrow \text{nfa\_step } A \ x \ a \ y \ \&\& \ \text{nfa\_run } y \ \text{xs}' \ w'$   
 |  $[], [] \Rightarrow \text{true}$   
 |  $-, - \Rightarrow \text{false}$   
**end.**

**Lemma**  $\text{nfa\_run\_accept } x \ w:$   
 reflect  $(\text{exists2 } \text{xs}, \text{nfa\_run } x \ \text{xs } w \ \& \ \text{last } x \ \text{xs} \ \backslash \text{in } \text{nfa\_fin } A)$   
 $(\text{nfa\_accept } x \ w).$

### $\varepsilon$ -Transitions

Non-deterministic finite automata with  $\varepsilon$ -transitions are based on the non-deterministic automata described above. In addition to all possible transitions of a normal NFA, they also allow for transitions that can be taken regardless of the input. These transitions are marked with the  $\varepsilon$  character. They do not “consume” a character of the input and can be taken arbitrarily often. The main disadvantage is that the properties of  $\varepsilon$ -transitions do not warrant a one-to-one correspondence between run length and word length. Specifically, runs may be much longer than their corresponding words. Thus, induction on runs no longer directly translates to induction on the size of the word. To avoid nested inductions, we decided not to include  $\varepsilon$ -transitions in our formalization.

Note that finite automata  $\varepsilon$ -transitions and finite automata without these transitions are equally expressive.

### 4.1.2 Deterministic Finite Automata

For functional  $\delta$ , we speak of **deterministic** finite automata (DFA). In this case, we write  $\delta$  as a function in our COQ development.

**Record**  $\text{dfa} : \text{Type} :=$   
 {  $\text{dfa\_state} :> \text{finType};$   
 $\text{dfa\_s} : \text{dfa\_state};$   
 $\text{dfa\_fin} : \text{pred } \text{dfa\_state};$   
 $\text{dfa\_step} : \text{dfa\_state} \rightarrow \text{char} \rightarrow \text{dfa\_state} \}$ .

**Fixpoint**  $\text{dfa\_accept } x \ w :=$   
**match**  $w$  **with**  
 |  $[], [] \Rightarrow \text{dfa\_fin } A \ x$   
 |  $a :: w \Rightarrow \text{dfa\_accept } (\text{dfa\_step } A \ x \ a) \ w$   
**end.**

**Definition**  $\text{dfa\_lang} := [\text{pred } w \mid \text{dfa\_accept } (\text{dfa\_s } A) w]$ .

Again, we avoid runs in our formalization of the acceptance criterion in favor of an acceptance criterion that is easier to work with in proofs. In this case, however, we can give a function that computes the unique run of a word on  $A$ . This allows us to give an alternative acceptance criterion that is closer to the mathematical definition. We also prove that both criteria are equivalent.

**Fixpoint**  $\text{dfa\_run}' (x: A) (w: \text{word}) : \text{seq } A :=$   
**match**  $w$  **with**  
 |  $[\cdot]$   $\Rightarrow [\cdot]$   
 |  $a :: w \Rightarrow (\text{dfa\_step } A \times a) :: \text{dfa\_run}' (\text{dfa\_step } A \times a) w$   
**end.**

**Lemma**  $\text{dfa\_run\_accept } x w: \text{last } x (\text{dfa\_run}' x w) \setminus \text{in } \text{dfa\_fin } A = (w \setminus \text{in } \text{dfa\_accept } x)$ .

## Equivalence of Automata

**Definition 4.1.1.** We say that two automata are *equivalent* if and only if their languages are equal.

## 4.2 Equivalence of DFA and NFA

Deterministic and non-deterministic finite automata are equally expressive. One direction is trivial since every DFA can be seen as an NFA.

**Theorem 4.2.1.** Let  $A = (Q, s, F, \delta)$  be a DFA. Then  $A$  is also an NFA.

*Proof.*  $(Q, s, F, \delta)$  fulfills the definition of an NFA. Thus,  $A$  is an NFA.  $\square$

Formally, we have to construct an equivalent NFA, since DFAs and NFAs are different types. The construction is straight-forward.

**Definition**  $\text{dfa\_to\_nfa} : \text{nfa} :=$   
 $\{ \mid \text{nfa\_s} := \text{dfa\_s } A;$   
 $\text{nfa\_fin} := \text{dfa\_fin } A;$   
 $\text{nfa\_step} := \text{fun } x \text{ a } y \Rightarrow y == \text{dfa\_step } A \times a \mid \}$ .

**Lemma**  $\text{dfa\_to\_nfa\_correct} : \text{dfa\_lang } A = \text{nfa\_lang } (\text{dfa\_to\_nfa } A)$ .

We prove the other direction using the powerset construction.

**Definition 4.2.2.** Given NFA  $A$ , we construct an equivalent DFA  $A_{\text{det}}$  in the following way:

$$\begin{aligned} Q_{\text{det}} &:= \{P \mid P \subseteq Q\} \\ s_{\text{det}} &:= \{s\} \\ F_{\text{det}} &:= \{P \in Q_{\text{det}} \mid P \cap F \neq \emptyset\} \\ \delta_{\text{det}} &:= \{(P, a, \bigcup_{p \in P} \{q \in Q \mid (p, a, q) \in \delta\}) \mid P \in Q_{\text{det}}, a \in \Sigma\}. \\ A_{\text{det}} &:= (Q_{\text{det}}, s_{\text{det}}, F_{\text{det}}, \delta_{\text{det}}). \end{aligned}$$

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The formalization of  $A_{det}$  is straight-forward. The set of states is an implicit argument of the DFA constructor and thus not shown.

**Definition**  $nfa\_to\_dfa :=$

```
{| dfa_s := set1 (nfa_s A);
   dfa_fin := [ pred X: {set A} | [ exists x: A, (x \in X) && nfa_fin A x ] ];
   dfa_step := [ fun X a => \bigcup_{x | x \in X} finset (nfa_step A x a) ] |}.
```

**Lemma 4.2.3.** *For all powerset states  $X$  and for all states  $x$  with  $x \in X$  we have that*

$$\mathcal{L}_x(A) \subseteq \mathcal{L}_X(A_{det}).$$

*Proof.* Let  $w \in \mathcal{L}_x(A)$ . We prove by induction on  $w$  that  $w \in \mathcal{L}_X(A_{det})$ .

- For  $w = \varepsilon$  and  $\varepsilon \in \mathcal{L}_x(A)$  we get  $x \in F$  from  $\varepsilon \in \mathcal{L}_x(A)$ . From  $x \in X$  we get  $X \cap F \neq \emptyset$  and therefore  $\varepsilon \in \mathcal{L}_X(A_{det})$ .
- For  $w = aw'$  and  $aw' \in \mathcal{L}_x(A)$  we get  $y$  such that  $w' \in \mathcal{L}_y(A)$  and  $(x, a, y) \in \delta$ . The latter gives us  $y \in Y$  where  $Y$  is such that  $(X, a, Y) \in \delta_{det}$ . With  $y \in Y$  and  $w' \in \mathcal{L}_y(A)$  we get  $w' \in \mathcal{L}_Y(A_{det})$  by inductive hypothesis. With  $(X, a, Y) \in \delta_{det}$  we get  $aw' \in \mathcal{L}_X(A_{det})$ .

□

**Lemma 4.2.4.** *For all powerset states  $X$  and all words  $w \in \mathcal{L}_X(A_{det})$  there exists a state  $x$  such that*

$$x \in X \wedge w \in \mathcal{L}_x(A).$$

*Proof.* By induction on  $w$ .

- For  $w = \varepsilon$  and  $\varepsilon \in \mathcal{L}_X(A_{det})$  we get  $X \cap F \neq \emptyset$ . Therefore, there exists  $x$  such that  $x \in X$  and  $x \in F$ . Thus, we have  $\varepsilon \in \mathcal{L}_x(A)$ .
- For  $w = aw'$  and  $aw' \in \mathcal{L}_X(A_{det})$  we get  $Y$  such that  $w' \in \mathcal{L}_Y(A_{det})$  and  $(X, a, Y) \in \delta_{det}$ . From the inductive hypothesis we get  $y$  such that  $y \in Y$  and  $w' \in \mathcal{L}_y(A)$ . From  $y \in Y$  and  $(X, a, Y) \in \delta_{det}$  we get  $x$  such that  $x \in X$  and  $(x, a, y) \in \delta$ . Thus,  $aw' \in \mathcal{L}_x(A)$ .

□

**Theorem 4.2.5.** *The powerset automaton  $A_{det}$  accepts the same language as  $A$ , i.e.*

$$\mathcal{L}(A) = \mathcal{L}(A_{det}).$$

*Proof.* “ $\subseteq$ ” This follows directly from Lemma 4.2.3 with  $x := s$  and  $X := s_{det}$ .

“ $\supseteq$ ” From Lemma 4.2.4 with  $X = s_{det}$  we get  $\mathcal{L}_{s_{det}}(A_{det}) \subseteq \mathcal{L}_s(A)$ , which proves the claim. □

The formalization of this proof is straight-forward and follows the plan laid out above. The corresponding Lemmas are:

**Lemma** `nfa_to_dfa_aux2` ( $x$ :  $A$ )  $w$  ( $X$ : `nfa_to_dfa`):  
 $x \setminus \text{in } X \rightarrow \text{nfa\_accept } A \ x \ w \rightarrow \text{dfa\_accept } \text{nfa\_to\_dfa } X \ w.$

**Lemma** `nfa_to_dfa_aux1` ( $X$ : `nfa_to_dfa`)  $w$ :  
 $\text{dfa\_accept } \text{nfa\_to\_dfa } X \ w \rightarrow [\text{exists } x, (x \setminus \text{in } X) \ \&\& \ \text{nfa\_accept } A \ x \ w].$

**Lemma** `nfa_to_dfa_correct` : `nfa_lang`  $A = i$  `dfa_lang` `nfa_to_dfa` .

### 4.3 Connected Components

Finite automata can have isolated subsets of states that are not reachable from the starting state. Removing these states does not change the language. It will later be useful to have automata that only contain reachable states. Therefore, we define a procedure to extract the connected component containing the starting state from a given automaton.

**Definition 4.3.1.** Let  $A = (Q, s, F, \delta)$  be a DFA. We define `reachable1` such that for all  $x$  and  $y$ ,  $(x, y) \in \text{reachable1} \iff \exists a, (x, a, y) \in \delta$ . We define `reachable` :=  $\{y \mid (s, y) \in \text{reachable1}^*\}$ , where `reachable1*` denotes the transitive closure of `reachable1`. With this, we can define the connected automaton  $A_c$ :

$$\begin{aligned} Q_c &:= Q \cap \text{reachable} \\ s_c &:= s \\ F_c &:= F \cap \text{reachable} \\ \delta_c &:= \{(x, a, y) \mid (x, a, y) \in \delta \wedge x, y \in Q_c\} \\ A_c &:= (Q_c, s_c, F_c, \delta_c). \end{aligned}$$

We make use of SSREFLECT's `connect` predicate to extract a sequence of all states reachable from  $s$ . From this, we construct a finite type and use that as the new set of states. These new states carry a proof of reachability. We also have to give a transition function which ensures that transitions always end in reachable states.

**Definition** `reachable1` :=  $[\text{fun } x \ y \Rightarrow [\text{exists } a, \text{dfa\_step } A1 \ x \ a == y]]$ .

**Definition** `reachable` := `enum (connect reachable1 (dfa_s A1))`.

**Lemma** `reachable0` : `dfa_s`  $A1 \setminus \text{in } \text{reachable}$ .

**Lemma** `reachable_step`  $x \ a$  :  $x \setminus \text{in } \text{reachable} \rightarrow \text{dfa\_step } A1 \ x \ a \setminus \text{in } \text{reachable}$ .

**Definition** `dfa_connected` :=  
 $\{ | \text{dfa\_s} := \text{SeqSub } \text{reachable0};$   
 $\text{dfa\_fin} := \text{fun } x \Rightarrow \text{match } x \text{ with } \text{SeqSub } x \_ \Rightarrow \text{dfa\_fin } A1 \ x \ \text{end};$   
 $\text{dfa\_step} := \text{fun } x \ a \Rightarrow \text{match } x \text{ with}$   
 $\quad | \text{SeqSub } \_ \ Hx \Rightarrow \text{SeqSub } (\text{reachable\_step } \_ \ a \ Hx)$   
 $\text{end } | \}$ .

**Lemma 4.3.2.** *For every state  $x \in \text{reachable}$  we have that*

$$\mathcal{L}_x(A_c) = \mathcal{L}_x(A).$$

*Proof.* “ $\subseteq$ ” Trivial. “ $\supseteq$ ” By induction on  $w$ .

- For  $w = \varepsilon$  we have  $\varepsilon \in \mathcal{L}_x(A)$  and therefore  $x \in F$ . With  $x \in \text{reachable}$  we get  $x \in F_c$ . Thus,  $\varepsilon \in \mathcal{L}_x(A_c)$ .
- For  $w = aw'$  we have  $y \in Q$  such that  $(x, a, y) \in \delta$  and  $w' \in \mathcal{L}_y(A)$ . From  $x \in \text{reachable}$  we get  $y \in \text{reachable}$  by transitivity. Therefore,  $(x, a, y) \in \delta_c$ . The inductive hypothesis gives us  $w' \in \mathcal{L}_y(A_c)$ . Thus,  $aw' \in \mathcal{L}_x(A_c)$ .

□

**Theorem 4.3.3.** *The language of the connected automaton  $A_c$  is identical to that of the original automaton  $A$ , i.e.*

$$\mathcal{L}(A) = \mathcal{L}(A_c).$$

*Proof.* By reflexivity, we have  $s \in \text{reachable}$ . We use Lemma 4.3.2 with  $x := s$  to prove the claim. □

The formalization of Lemma 4.3.2 and Theorem 4.3.3 is straight-forward.

**Lemma** `dfa_connected_correct' x (Hx: x \in reachable) :`  
`dfa_accept dfa_connected (SeqSub Hx) =i dfa_accept A1 x.`

**Lemma** `dfa_connected_correct: dfa_lang dfa_connected =i dfa_lang A1.`

To make use of the fact that  $A_c$  is fully connected, we will prove a characteristic property of  $A_c$ . We will need this property of  $A_c$  in Chapter 5.

**Definition 4.3.4.** *A **representative** of a state  $x$  is a word  $w$  such that the unique run of  $w$  on  $A_c$  ends in  $x$ .*

**Lemma 4.3.5.** *There is a representative for every state  $x \in Q_c$ .*

*Proof.*  $x$  carries a proof of reachability. From this, we get a path through the graph of `reachable1` that ends in  $x$ . We build the representative by extracting the edges of the path and building a word from those. □

**Lemma** `dfa_connected_repr x :`  
`exists w, last (dfa_s dfa_connected) (dfa_run dfa_connected w) = x.`

## 4.4 Emptiness

Given an automaton  $A$ , we can check if  $\mathcal{L}(A) = \emptyset$ . We simply obtain the connected automaton of  $A$  and check if there are any final states left.



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**Theorem 4.4.1.** *The language of the connected automaton  $A_c$  is empty if and only if its set of final states  $F_c$  is empty, i.e.*

$$\mathcal{L}(A) = \emptyset \iff F_c = \emptyset.$$

*Proof.* By Theorem 4.3.3 we have  $\mathcal{L}(A) = \mathcal{L}(A_c)$ . Therefore, it suffices to show

$$\mathcal{L}(A_c) = \emptyset \iff F_c = \emptyset.$$

“ $\Rightarrow$ ” We have  $\mathcal{L}(A_c) = \emptyset$  and have to show that for all  $x \in Q_c$ ,  $x \notin F_c$ . Let  $x \in Q_c$ . By Lemma 4.3.5 we get  $w$  such that the unique run of  $w$  on  $A_c$  ends in  $x$ . We use  $\mathcal{L}(A_c) = \emptyset$  to get  $w \notin \mathcal{L}(A_c)$ , which implies that the run of  $w$  on  $A_c$  ends in a non-final state. By substituting the last state of the run by  $x$  we get  $x \notin F_c$ .

“ $\Leftarrow$ ” We have  $F_c = \emptyset$  and have to show that for all words  $w$ ,  $w \notin \mathcal{L}(A_c)$ . We use  $F_c = \emptyset$  to show that the last state of the run of  $w$  on  $A_c$  is non-final. Thus,  $w \notin \mathcal{L}(A_c)$ .  $\square$

Thus, emptiness is decidable.

**Definition** `dfa_lang_empty := #|dfa_fin dfa_connected| == 0.`

**Lemma** `dfa_lang_empty_correct:`  
`reflect (dfa_lang A1 == pred0)`  
`dfa_lang_empty.`

## 4.5 Deciding Equivalence of Finite Automata

Given finite automata  $A_1$  and  $A_2$ , we construct DFA  $A$  such that the language of  $A$  is the symmetric difference of the languages of  $A_1$  and  $A_2$ , i.e.,

$$\mathcal{L}(A) := \mathcal{L}(A_1) \ominus \mathcal{L}(A_2) = \mathcal{L}(A_1) \cap \neg \mathcal{L}(A_2) \cup \mathcal{L}(A_2) \cap \neg \mathcal{L}(A_1).$$

**Theorem 4.5.1.** *The equivalence of  $A_1$  and  $A_2$  is decidable, i.e.*

$$\mathcal{L}(A_1) = \mathcal{L}(A_2) \text{ if and only if } \mathcal{L}(A) \text{ is empty.}$$

*Proof.* The correctness of this procedure follows from the properties of the symmetric difference operator, i.e.

$$\mathcal{L}(A_1) \ominus \mathcal{L}(A_2) = \emptyset \Leftrightarrow \mathcal{L}(A_1) = \mathcal{L}(A_2).$$

$\square$

Thus, equivalence is decidable.

**Definition** `dfa_sym_diff A1 A2 :=`  
`dfa_disj (dfa_conj A1 (dfa_compl A2)) (dfa_conj A2 (dfa_compl A1)).`

**Definition** `dfa_equiv A1 A2 := dfa_lang_empty (dfa_sym_diff A1 A2).`

**Lemma** `dfa_equiv_correct A1 A2:`  
`dfa_equiv A1 A2 <=> dfa_lang A1 == dfa_lang A2.`

## 4.6 Regular Expressions to Finite Automata

We prove that there exists an equivalent automaton for every extended regular expression. The structure of this proof is given by the inductive nature of regular expressions.

**Theorem 4.6.1.** *Let  $r$  be an extended regular expression on  $\Sigma$ . Then we can give DFA  $A$  such that*

$$\mathcal{L}(r) = \mathcal{L}(A).$$

Depending on the constructor of the regular expression, we will construct a corresponding operation on DFAs or NFAs. Void, Eps, Dot, Atom, Plus, And and Not are very easy to implement on DFAs, whereas Star and Conc lend themselves well to NFAs.

We show our implementation for Void, Not, and Conc. We also give a short overview of the automaton corresponding to Star.

### 4.6.1 Void

**Definition 4.6.2.** *We define an empty DFA with a single, non-accepting state, i.e.*

$$A_\emptyset := (\{t\}, t, \emptyset, \{(t, a, t) \mid a \in \Sigma\}).$$

**Lemma 4.6.3.** *The language of the empty DFA is empty, i.e.*

$$\mathcal{L}(E) = \emptyset.$$

*Proof.*  $A_\emptyset$  has no final states, i.e. no run can end in a final state. □

**Definition** `dfa_void :=`

```
{| dfa_s := tt;
   dfa_fin := pred0;
   dfa_step := [fun x a => tt] |}.
```

**Lemma** `dfa_void_correct x w: ~ ~ dfa_accept dfa_void x w.`

### 4.6.2 Not

**Definition 4.6.4.** *Given DFA  $A = (Q, s, F, \delta)$ , the complement automaton  $A_\neg$  is constructed by swapping accepting and non-accepting states, i.e.*

$$A_\neg := (Q, s, Q \setminus F, \delta).$$

**Lemma 4.6.5.** *For every state  $x \in Q$ , we have that  $w \in \Sigma^*$  is accepted in  $x$  by  $A_\neg$  if and only if it is not accepted in  $x$  by  $A$ , i.e.  $\mathcal{L}_x(A_\neg) = \Sigma^* \setminus \mathcal{L}_x(A)$*

*Proof.* By induction on  $w$ . For  $w = \varepsilon$  we have  $\varepsilon \in \mathcal{L}_x(A_\neg) \iff \varepsilon \in \mathcal{L}_x(A)$  from  $x \in F \iff x \notin Q \setminus F$ . For  $w = aw'$  we get  $(y, a, x) \in \delta$ . By inductive hypothesis,  $w' \in \mathcal{L}_x(A_\neg) \iff w' \notin \mathcal{L}_x(A)$ . Thus,  $aw' \in \mathcal{L}_y(A_\neg) \iff aw' \notin \mathcal{L}_y(A)$ . □

**Lemma 4.6.6.**  *$A_\neg$  accepts the complement language of  $A$ , i.e.  $\mathcal{L}(A_\neg) = \Sigma^* \setminus \mathcal{L}(A)$ .*

*Proof.* This follows directly from Lemma 4.6.5 with  $x := s$ . □

### 4.6.3 Conc

The most common approach to build the concatenation automaton is to connect the final states of the first automaton to the starting state of the second automaton by an  $\varepsilon$ -transition. We do not allow  $\varepsilon$ -transitions in our automata. The reason for this is that we do not want to lose the direct correspondence of the length of the word to the length of its run on an automaton. Thus, in order to build the concatenation automaton, we duplicate all edges from the starting state of the second automaton and add them to all final states of the first automaton. Since the final states may already have edges with the same labels, we chose to implement this operation on NFAs.

**Definition 4.6.7.** *Given two NFAs  $A_1 = (Q_1, s_1, F_1, \delta_1)$  and  $A_2 = (Q_2, s_2, F_2, \delta_2)$  we construct the concatenation automaton in the following way:*

$$\begin{aligned}
 Q_{\text{Conc}} &:= Q_1 \cup Q_2 \\
 s_{\text{Conc}} &:= s_1 \\
 F_{\text{Conc}} &:= \begin{cases} F_2 & \text{if } s_2 \notin F_2 \\ F_2 \cup F_1 & \text{if } s_2 \in F_2 \end{cases} \\
 \delta_{\text{Conc}} &:= \delta_1 \cup \delta_2 \cup \{(x, a, y) \mid x \in Q_1, y \in Q_2, (s_2, a, y) \in \delta_2\} \\
 A_{\text{Conc}} &:= (Q_{\text{Conc}}, s_{\text{Conc}}, F_{\text{Conc}}, \delta_{\text{Conc}}).
 \end{aligned}$$

**Definition** `nfa_conc : nfa :=`  
`{ | nfa_s := inl _ (nfa_s A1);`  
`nfa_fin := [fun x =>`  
`match x with`  
`| inl x => nfa_fin A1 x && nfa_fin A2 (nfa_s A2)`  
`| inr x => nfa_fin A2 x`  
`end];`  
`nfa_step := fun x a y =>`  
`match x,y with`  
`| inl x, inl y => nfa_step A1 x a y`  
`| inl x, inr y => nfa_fin A1 x && nfa_step A2 (nfa_s A2) a y`  
`| inr x, inr y => nfa_step A2 x a y`  
`| inr x, inl y => false`  
`end |}.`

Before we prove the correctness of  $A_{\text{Conc}}$ , we need a number of auxiliary lemmas.

**Lemma 4.6.8.** *Every run of  $A_2$  can be mapped to a run in  $A_{\text{Conc}}$ .*

*Proof.* Let  $\sigma$  be a run starting in  $x$  for  $w \in \Sigma^*$  on  $A_2$ . By induction on  $\sigma$ .

1. For  $\sigma = x$  we have  $w = \varepsilon$ . Therefore, we have that  $\sigma$  is also a run starting in  $x$  for  $\varepsilon$  on  $A_{\text{Conc}}$ .
2. For  $\sigma = xy\sigma'$  we have  $w = aw'$ ,  $(x, a, y) \in \delta_2$ . By definition of  $\delta_{\text{Conc}}$  we also have  $(x, a, y) \in \delta_{\text{Conc}}$ . By inductive hypothesis, we have that  $y\sigma'$  is a run for  $w'$  starting in  $y$  on  $A_{\text{Conc}}$ . Thus,  $xy\sigma'$  is a run for  $aw'$  starting in  $x$  on  $A_{\text{Conc}}$ .

□

**Lemma** `nfa_conc_cont x xs w:`

`nfa_run A2 x xs w`  
 $\rightarrow$  `nfa_run nfa_conc (inl _ x) (map (@inr A1 A2) xs) w.`

The next lemma shows that, in  $A_{Conc}$ , the final states of  $A_1$  have all transitions that the starting state of  $A_2$  also has. Consequently, they accept the same words.

**Lemma 4.6.9.** *Let  $x \in F_1$ . Let  $w \in \mathcal{L}(A_2)$ . Then  $w \in \mathcal{L}_x(A_{Conc})$ .*

*Proof.* By induction on  $w$ .

1. For  $w = \varepsilon$  we have get  $s \in F_2$  by  $\varepsilon \in \mathcal{L}(A_2)$  and, thus,  $x \in F_{Conc}$  by definition.
2. For  $w = aw'$  we have  $y \in Q_2$  such that  $(s, a, y) \in \delta_2$  and thus  $(x, a, y) \in \delta_{Conc}$ . We also have  $w' \in \mathcal{L}_y(A_2)$  and thus, by Lemma 4.6.8,  $w' \in \mathcal{L}_y(A_{Conc})$ . Thus,  $aw' \in \mathcal{L}_x(A_{Conc})$ .

□

**Lemma** `nfa_conc_fin1 x1 w:`

`nfa_fin A1 x1  $\rightarrow$`   
`nfa_lang A2 w  $\rightarrow$`   
`nfa_accept nfa_conc (inl _ x1) w.`

The following lemma is one direction of the proof of correctness of  $A_{Conc}$ .

**Lemma 4.6.10.** *Let  $x \in Q_1$ ,  $w_1 \in \mathcal{L}_x(A_1)$ , and  $w_2 \in \mathcal{L}(A_2)$ . Then  $w_1w_2 \in \mathcal{L}_x(A_{Conc})$ .*

*Proof.* By induction on  $w_1$ .

1. For  $w_1 = \varepsilon$  we get  $x \in F_1$  and thus, by Lemma 4.6.9, the claim follows.
2. For  $w_1 = aw'_1$  we get  $(x, a, y) \in \delta_1$  and thus  $(x, a, y) \in \delta_{Conc}$ . By inductive hypothesis, the claim follows.

□

**Lemma** `nfa_conc_aux2 x w1 w2:`

`nfa_accept A1 x w1  $\rightarrow$`   
`nfa_lang A2 w2  $\rightarrow$`   
`nfa_accept nfa_conc (inl _ x) (w1 ++ w2).`

The next lemma constitutes the other direction. Its statement is very general, even though we will only need one of the two cases for the proof of correctness of  $A_{Conc}$ . However, with the second case, there is no straight-forward inductive proof.

**Lemma 4.6.11.** *Let  $x \in Q_{Conc}$ . Let  $w \in \mathcal{L}_x(A_{Conc})$ . Then, either*

$$x \in Q_1 \wedge \exists w_1. \exists w_2. w = w_1w_2 \wedge w_1 \in \mathcal{L}_x(A_1) \wedge w_2 \in \mathcal{L}(A_2), \quad (*)$$

or

$$x \in Q_2 \wedge w \in \mathcal{L}_x(A_2). \quad (**)$$

*Proof.* By induction on  $w$ .

1. For  $w = \varepsilon$  we get either  $x \in F_1$  and  $s_2 \in F_2$  or  $x \in F_2$ . In the first case, we need to prove (\*), which we do by choosing  $w_1 := \varepsilon$  and  $w_2 := \varepsilon$ . In the second case, we need to prove  $\varepsilon \in \mathcal{L}_x(A_2)$  and thus  $x \in F_2$  which we have by assumption.
2. For  $w = aw'$  we get  $y$  such that  $(x, a, y) \in \delta_{Conc}$  and  $w' \in \mathcal{L}_y(A_{Conc})$ . We are left with four cases, depending on the origin of  $x$  and  $y$ .
  - a) For  $x, y \in Q_2$  we have  $(x, a, y) \in Q_2$  and claim (\*\*) follows.
  - b) For  $x, y \in Q_1$  we prove (\*). By inductive hypothesis we get  $w_1$  and  $w_2$  such that (\*) holds for  $y$ .
  - c) For  $x \in Q_1$  and  $y \in Q_2$  the claim follows with  $w_1 := \varepsilon$  and  $w_2 := aw'$  by inductive hypothesis.
  - d) For  $x \in Q_2$  and  $y \in Q_1$  we have  $(x, a, y) \in \delta_{Conc}$ , which is a contradiction.

□

**Lemma** `nfa_conc_aux1` X w :  
`nfa_accept nfa_conc X w ->`  
**match** X with  
| inl x => **exists** w1, **exists** w2, (w == w1 ++ w2) && (nfa\_accept A1 x w1) && nfa\_lang A2 w2  
| inr x => nfa\_accept A2 x w  
**end.**

**Corollary 4.6.12.** *The language of  $A_{Conc}$  is the concatenation of the languages of  $A_1$  and  $A_2$ , i.e.  $\mathcal{L}(A_{Conc}) = \mathcal{L}(A_1) \cdot \mathcal{L}(A_2)$ .*

*Proof.* Follows directly from Lemma 4.6.10 and Lemma 4.6.11. □

**Lemma** `nfa_conc_correct`: `nfa_lang nfa_conc =i conc (nfa_lang A1) (nfa_lang A2)`.

#### 4.6.4 Star

The most common construction for the star automaton works by adding the starting state to the set of final states and connecting all final states to the starting state by  $\varepsilon$ -transitions.

Again, our construction differs from this. First, we construct an automaton that accepts the Kleene closure of the language of the given automaton, excluding the empty word, which we call `nfa_repeat`. The reason for this is that we can easily construct this automaton much in the same way we constructed the concatenation automaton.

We duplicate all edges from the starting state and add them to the final states. The resulting automaton accepts the Kleene closure of the language of the given automaton, but not the empty word. Since we have already constructed an automaton that accepts the empty word, and a disjunction operation on automata, we simply combine those with our newly constructed automaton to form the star automaton.

**Definition**  $\text{nfa\_star} := (\text{dfa\_disj } \text{dfa\_eps } (\text{nfa\_to\_dfa } \text{nfa\_repeat })).$

**Lemma**  $\text{nfa\_star\_correct}: \text{dfa\_lang } \text{nfa\_star} = \text{i star } (\text{nfa\_lang } A1).$

We give a procedure to build an equivalent DFA for every extended regular expression and prove it correct. Note that the operations are named after the type of arguments they take, regardless of their return types. Thus,  $\text{nfa\_star}$  takes an NFA but returns a DFA, whereas  $\text{nfa\_conc}$  expects *and* returns NFAs.

**Fixpoint**  $\text{re\_to\_dfa} (r: \text{regular\_expression } \text{char}): \text{dfa char} :=$   
 $\text{match } r \text{ with}$   
 $| \text{Void} \Rightarrow \text{dfa\_void char}$   
 $| \text{Eps} \Rightarrow \text{dfa\_eps char}$   
 $| \text{Dot} \Rightarrow \text{dfa\_dot char}$   
 $| \text{Atom } a \Rightarrow \text{dfa\_char char } a$   
 $| \text{Star } s \Rightarrow \text{nfa\_star } (\text{dfa\_to\_nfa } (\text{re\_to\_dfa } s))$   
 $| \text{Plus } s \ t \Rightarrow \text{dfa\_disj } (\text{re\_to\_dfa } s) (\text{re\_to\_dfa } t)$   
 $| \text{And } s \ t \Rightarrow \text{dfa\_conj } (\text{re\_to\_dfa } s) (\text{re\_to\_dfa } t)$   
 $| \text{Conc } s \ t \Rightarrow \text{nfa\_to\_dfa } (\text{nfa\_conc } (\text{dfa\_to\_nfa } (\text{re\_to\_dfa } s)) (\text{dfa\_to\_nfa } (\text{re\_to\_dfa } t)))$   
 $| \text{Not } s \Rightarrow \text{dfa\_compl } (\text{re\_to\_dfa } s)$   
 $\text{end.}$

**Lemma**  $\text{re\_to\_dfa\_correct } r: \text{dfa\_lang } (\text{re\_to\_dfa } r) = \text{i } r.$

## 4.7 Deciding Equivalence of Regular Expressions

Based on our procedure to construct an equivalent automaton from a regular expression, we can decide equivalence of regular expressions. Given  $r_1$  and  $r_2$ , we construct equivalent DFAs  $A_1$  and  $A_2$  as above. Based on our decision procedure for the equivalence of DFAs, we only need to check if  $A_1$  and  $A_2$  are equivalent.

**Theorem 4.7.1.** *Let  $r, s$  be regular expressions on  $\Sigma$  and  $A_1, A_2$  their corresponding, equivalent automata. We then have that*

$$\mathcal{L}(r) = \mathcal{L}(s) \iff \mathcal{L}(A_1) = \mathcal{L}(A_2).$$

*Proof.* Follows directly from 4.6.1 and 4.5.1. □

Thus, equivalence is decidable.

**Definition**  $\text{re\_equiv } r \ s := \text{dfa\_equiv } (\text{re\_to\_dfa } r) (\text{re\_to\_dfa } s).$

**Lemma**  $\text{re\_equiv\_correct } r \ s: \text{re\_equiv } r \ s \iff r = \text{i } s.$

## 4.8 Finite Automata to Regular Expressions

We prove that there is an equivalent standard regular expression for every finite automaton. There are three ways to prove this.

The first one is a method called “**state removal**” [13] (reformulated in [19]), which works by sequentially building up regular expressions on the edges between states. In every step, one state is removed and its adjacent states’ edges are updated to incorporate the missing state into the regular expression. Finally, only two states remain. The resulting edges can be combined to form a regular expression that recognizes the language of the initial automaton.

The formalization of this method is rather complicated, due to the fact that we need generalized finite automata, i.e., finite automata whose edges are labeled by regular expressions. Thus, we decided against this method.

The second method is known as “**Brzowski’s method**” [14] and builds upon Brzowski derivatives of regular expressions. This method is algebraic in nature and arrives at a regular expression by solving a system of linear equations on regular expressions. Every state is assigned an unknown regular expression. The intuition of these unknown regular expressions is that they recognize the words accepted in their associated state. The system is solved by substitution and Arden’s lemma [3]. The regular expression associated with the starting state recognizes the language of the automaton.

Brzowski’s method requires infrastructure for algebraic equations and term rewriting, which we estimated to be a considerable overhead. Thus, we decided against this method.

The third method, which we chose for our development, is due to Kleene [23]. It is known as the “**transitive closure method**”. This method recursively constructs a regular expression that is equivalent to the given automaton. For the remainder of this chapter, we assume that we are given a DFA  $(Q, s, F, \delta)$ .

The idea of the transitive closure method is that we can give a regular expression to describe the path between any two states  $x$  and  $y$ . This regular expression accepts every word whose run  $\sigma$  on  $A$  starting in  $x$  ends in  $y$ . In fact, we can even give such a regular expression if we limit the set of paths through which the run is allowed to pass. We will call this set  $X$ . Here, passing through means that the restriction applies only to states that are traversed, i.e. not to the beginning or end of the run.

If we take  $X$  to be the empty set, we only consider two types of runs. First, if  $x \neq y$ , every transition from  $x$  to  $y$  constitutes one (singleton) word. Conversely, if there is a word which does not pass through a state and whose run on  $A$  starts in  $x$  and ends in  $y$ , it can only be a singleton word consisting of one of the transitions from  $x$  to  $y$ . Therefore, the corresponding regular expression is the disjunction of all transitions from  $x$  to  $y$ . These transitions constitute all possible words that lead from  $x$  to  $y$  without passing through any state.

If  $x = y$ , we also have to consider the empty word, since its run on  $A$  starts in  $x$  and ends in  $y$ . Thus, the corresponding regular expression is the disjunction of all transitions from  $x$  to  $y$  and  $\varepsilon$ .

In the case of a non-empty  $X$ , we make the following observation. If we pick an element  $z \in X$ , then any run  $\sigma$  from  $x$  to  $y$  either passes through  $z$ , or does not pass through  $z$ . If it does, we can split it into three parts.

- (i) The first part contains the prefix of  $\sigma$  which contains all states up to the first

occurrence of  $z$  that is not the starting state.

- (ii) The second part contains that part of the remainder of  $\sigma$  which contains all further occurrences of  $z$  with the exception of the last state if that is  $z$ .
- (iii) The third part contains the remainder.

Parts (i) and (iii) can easily be expressed in terms of  $X \setminus \{z\}$ . Part (ii) can be further decomposed into runs from  $z$  to  $z$  that do not pass through  $z$ . Thus, part (ii) can also be expressed in terms of  $X \setminus \{z\}$  with the help of the  $*$  operator.

If  $\sigma$  does not pass through  $z$ , it is covered by the regular expression for paths from  $x$  to  $y$  restricted to  $X \setminus \{z\}$ .

In order to define  $R$  recursively, we need to pick an element  $z \in X$  if  $X \neq \emptyset$ . For this purpose, we assume an ordering on  $Q$ . We will then pick  $z \in X$  such that  $z$  is the smallest element in  $X$  with respect to this ordering.

**Definition 4.8.1.** Let  $X \subseteq Q$ . Let  $x, y \in Q$ . We define  $R$  recursively on  $|X|$ :

$$R_{x,y}^X := \begin{cases} \sum_{\substack{a \in \Sigma \\ (x,a,y) \in \delta}} a & \text{if } X = \emptyset \wedge x \neq y; \\ \sum_{\substack{a \in \Sigma \\ (x,a,y) \in \delta}} a + \varepsilon & \text{if } X = \emptyset \wedge x = y; \\ R_{x,z}^{X \setminus \{z\}} (R_{z,z}^{X \setminus \{z\}})^* R_{z,y}^{X \setminus \{z\}} + R_{x,y}^{X \setminus \{z\}} & \text{if } X \neq \emptyset \wedge z \text{ minimal in } X. \end{cases}$$

The formalization of  $R$  is more involved than its mathematical definition. We give some auxiliary definitions to keep the definition of  $R$  as compact and readable as possible. `nPlus` is  $\sum$  on regular expressions. `dfa_step_any` is the list chars of that contains all transitions from  $x$  to  $y$ . `R0` covers the case of  $X = \emptyset$ .

**Definition** `nPlus rs := foldr (@Plus char) (Void _) rs`.

**Definition** `dfa_step_any x y := enum ( [pred a | dfa_step A x a == y] )`.

**Definition** `R0 x y := let r := nPlus (map (@Atom _) (dfa_step_any x y)) in if x == y then Plus r (Eps _) else r`.

**Function** `R (X: {set A}) (x y: A) {measure [fun X => #|X|] X} := match [pick z in X] with | None => R0 x y | Some z => let X' := X \ z in Plus (Conc (R X' x z) (Conc (Star (R X' z z)) (R X' z y))) (R X' x y) end`.

We now express  $\mathcal{L}(A)$  using  $R$ . Based on the observation that every accepted word has a run from  $s$  to some state  $f \in F$ , we only have to combine the corresponding regular expressions  $R_{s,f}^Q$  to form a regular expression for  $\mathcal{L}(A)$ . The goal of this chapter is to prove the following theorem.



## 4 Finite Automata

**Theorem 4.8.2.**  $\mathcal{L}(A)$  is recognizable by a regular expression, i.e.

$$\mathcal{L}\left(\sum_{f \in F} R_{s,f}^Q\right) = \mathcal{L}(A).$$

In order to prove this theorem, we will first define a predicate on words that corresponds to  $\mathcal{L}(R_{x,y}^X)$ . We call this predicate  $L_{x,y}^X$  and define it such that it includes those words whose runs on  $A$  starting in  $x$  only pass through states in  $X$  and end in  $y$ .

**Definition 4.8.3.** Let  $w \in \Sigma^*$ . Let  $X \subseteq Q$ , and  $x, y \in X$ . Let  $\sigma$  be the run of  $w$  on  $A$  starting in  $x$ . We define  $L_{x,y}^X$  such that

$$w \in L_{x,y}^X \iff \sigma_{|\sigma|-1} = y \wedge \forall i \in [1, |\sigma| - 2]. \sigma_i \in X.$$

The formalization of  $L$  requires some infrastructure. To check the second condition of  $L$ , we want to be able to state properties of all but the last items in a run. We define a function `belast` to remove the last element from a sequence. Note that, mathematically, runs include the starting state. In our formalization, this is not the case. Thus, we do not need to remove the first state from a run to retrieve all states the run passes through.

**Definition** `allbutlast xs := all p (belast xs)`.

**Definition** `L (X: {set A}) (x y: A) :=  
[pred w | (last x (dfa_run' A x w) == y)  
&& allbutlast (mem X) (dfa_run' A x w) ]`.

We now prove properties of  $L$  that we will need for our proof of Theorem 4.8.2.

**Lemma 4.8.4.**  $L$  is monotone in  $X$ , i.e.

$$\forall X \subseteq Q, z \in X, x, y \in Q. L_{x,y}^X \subseteq L_{x,y}^{X \cup \{z\}}.$$

*Proof.* This follows directly from  $X \subset X \cup \{z\}$ . □

**Lemma** `L_monotone (X: {set A}) (x y z: A): {subset L^X x y <= L^(z | X) x y}`.

**Lemma 4.8.5.** The empty word is contained in  $L_{x,y}^X$  if and only if  $x = y$ .

*Proof.* This follows immediately from the definition of  $L$ . □

**Lemma** `L_nil X x y: reflect (x = y) ([::] \in L^X x y)`.

Next, we will prove that words whose run passes through a state  $z$  can be split into two words. The run of the first word will end in  $z$ , i.e. not pass through  $z$ .

**Lemma 4.8.6.** Let  $w \in \Sigma^*$ . Let  $x, z \in Q$ . Let  $\sigma$  be the run of  $w$  on  $A$  starting in  $x$ . Let  $z \in \sigma_1 \dots \sigma_{|\sigma|-1}$ . Then there exist  $w_1, w_2 \in \Sigma^*$  such that

$$w = w_1 w_2 \wedge |w_2| < |w| \wedge z \notin \sigma_1 \dots \sigma_{|w_1|-1} \wedge \sigma_{|w_1|} = z.$$

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*Proof.* Let  $i$  be the first occurrence of  $z$  in  $\sigma_1 \dots \sigma_{|\sigma|-1}$  such that  $\sigma_i = z$  and  $i > 0$ . Let  $w_1 := w_0 \dots w_{i-1}$  and  $w_2 := w_i \dots w_{|w|-1}$ . The claim follows.  $\square$

**Lemma** `run_split`  $x \ z \ w$ :  $z \ \backslash \text{in} \ \text{dfa\_run}' \ A \times w \rightarrow$   
`exists`  $w_1$ , `exists`  $w_2$ ,  
 $w = w_1 ++ w_2 \wedge$   
 $\text{size } w_2 < \text{size } w \wedge$   
 $z \ \backslash \text{notin} \ \text{belast} \ (\text{dfa\_run}' \ A \times w_1) \wedge$   
 $\text{last } x \ (\text{dfa\_run}' \ A \times w_1) = z$ .

We will make use of this fact in the next lemma, which splits words in  $L^X$  into two parts, the first of which is again in  $L^X$ . This will be quintessential later, when we split words in  $L^X$  into three parts that correspond to the recursive definition of  $R^X$ .

**Lemma 4.8.7.** *Let  $X \subseteq Q$  and  $x, y, z \in Q$ . Let  $w \in L_{x,y}^{X \cup \{z\}}$ . We have that either*

$$w \in L_{x,y}^X$$

*or there exist  $w_1$  and  $w_2$  such that*

$$w = w_1 w_2 \wedge |w_2| < |w| \wedge w_1 \in L_{x,z}^X \wedge w_2 \in L_{z,y}^{X \cup \{z\}}.$$

*Proof.* We first eliminate the case of  $z \in X$ , which is solved trivially. Let  $\sigma$  be the run of  $w$  on  $A$  starting in  $x$ . We do a case distinction on  $z \in \sigma_1 \dots \sigma_{|\sigma|-1}$ .

1. For  $z \notin \sigma_1 \dots \sigma_{|\sigma|-1}$  we can easily show  $w \in L_{x,y}^X$ .
2. For  $z \in \sigma_1 \dots \sigma_{|\sigma|-1}$  we use Lemma 4.8.6 to split  $w$  in  $w_1$  and  $w_2$ . From  $w \in L_{x,y}^{X \cup \{z\}}$  and  $\sigma_{|w_1|} = z$  we immediately get  $w_2 \in L_{z,y}^{X \cup \{z\}}$ . We have  $z \notin \sigma_1 \dots \sigma_{|\sigma|-1}$ . We also have that  $X = (X \cup \{z\}) \setminus \{z\}$  from  $z \notin X$ . Thus, we get  $w_1 \in L_{x,z}^X$ . The remainder of the claim follows directly from Lemma 4.8.6.  $\square$

Before we show that  $L^X$  respects the defining equation of  $R^X$ , we have to show that we can combine words from  $L_{x,z}^X$ ,  $(L_{z,z}^X)^*$ , and  $L_{z,y}^X$  to form a word in  $L_{x,y}^{X \cup \{z\}}$ . We prove a general concatenation lemma for  $L^X$ .

**Lemma 4.8.8.** *Let  $X \subseteq Q$ ,  $x, y \in Q$ , and  $z \in X$ . Let  $w_1 \in L_{x,z}^X$  and  $w_2 \in L_{z,x}^X$ . Then we have*

$$w_1 w_2 \in L_{x,y}^X.$$

*Proof.* By  $z \in X$ ,  $w_1 \in L_{x,y}^X$ , and  $\sigma_{|w_1|} = z$  we get  $\sigma_1, \dots, \sigma_{|w_1|} \in X$ . We also have  $\sigma_{|w_1|+1}, \dots, \sigma_{|\sigma|-2} \in X$  and  $\sigma_{|\sigma|-1} = y$ . Thus,  $w_1 w_2 \in L_{x,y}^X$ .  $\square$

**Lemma** `L_cat`  $(X: \{\text{set } A\}) \times y \ z \ w_1 \ w_2$ :  
 $z \ \backslash \text{in } X \rightarrow$   
 $w_1 \ \backslash \text{in } L^X \times z \rightarrow$   
 $w_2 \ \backslash \text{in } L^X \ z \ y \rightarrow$   
 $w_1 ++ w_2 \ \backslash \text{in } L^X \times y$ .

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**Lemma 4.8.9.** *Let  $n \in \mathbb{N}$ . Let  $w_0, \dots, w_{n-1} \in L_{z,z}^X$ . We have that*

$$w_0 \dots w_{n-1} \in L_{z,z}^{X \cup \{z\}}.$$

*Proof.* By induction on  $n$ .

1. For  $n = 0$  we have to prove  $\varepsilon \in L_{z,z}^{X \cup \{z\}}$  which holds by Lemma 4.8.5.
2. For  $n = n' + 1$  we have  $w_0 \dots w_{n-2} \in L_{z,z}^{X \cup \{z\}}$  by inductive hypothesis. We also have  $w_0, \dots, w_{n-1} \in L_{z,z}^X$  by assumption, and, thus,  $w_{n-1} \in L_{z,z}^X$ . By Lemma 4.8.8 we get  $w_0 \dots w_{n-1} \in L_{z,z}^{X \cup \{z\}}$ .

□

**Lemma**  $\text{L\_flatten } (X: \{\text{set } A\}) \text{ } z \text{ } vv: \text{ all } (L^X z \text{ } z) \text{ } vv \text{ } \rightarrow$   
 $\text{flatten } vv \text{ } \backslash \text{in } L^X(z \text{ } |: X) \text{ } z \text{ } z.$

Finally, we can show that  $L^X$  respects the defining equation of  $R^X$ . With all the lemmas we have in place now, this can now be shown with relative ease.

**Lemma 4.8.10.** *Let  $X \subseteq Q$ ,  $x, y \in Q$ , and  $z \in X$ . We have that*

$$L_{x,y}^{X \cup \{z\}} = L_{x,z}^X (L_{z,z}^X)^* L_{z,y}^X + L_{x,y}^X.$$

*Proof.* “ $\Rightarrow$ ” By induction on  $|w|$ .

1. For  $|w| = 0$  we get  $w \in L_{x,y}^X$  by Lemma 4.8.5.
2. For  $|w| > 0$  we get  $w_1$  and  $w_2$  such that  $w = w_1 w_2$ ,  $w_1 \in L_{x,z}^X$  and  $w_2 \in L_{z,y}^{X \cup \{z\}}$ . By inductive hypothesis we get

$$w_2 \in L_{z,z}^X (L_{z,z}^X)^* L_{z,y}^X \vee w_2 \in L_{z,y}^X$$

The latter gives us  $w \in L_{x,y}^{X \cup \{z\}}$  by Lemma 4.8.8. With the former, we have  $w_3$ ,  $w_4$ , and  $w_5$  such that  $w_2 = w_3 w_4 w_5$ ,  $w_3 \in L_{z,z}^X$ ,  $w_4 \in (L_{z,z}^X)^*$  and  $w_5 \in L_{z,y}^X$ . We merge  $w_3$  and  $w_4$  such that  $w_3 w_4 \in (L_{z,z}^X)^*$ . This gives us  $w_2 \in (L_{z,z}^X)^* L_{z,y}^X$ . Thus,  $w_1 w_2 \in L_{x,z}^X (L_{z,z}^X)^* L_{z,y}^X$ .

“ $\Leftarrow$ ” We have  $w_1 \in L_{x,z}^X$ ,  $w_2 \in (L_{z,z}^X)^*$ , and  $w_3 \in L_{z,y}^X$ . By Lemma 4.8.9 we get  $w_2 \in L_{z,z}^{X \cup \{z\}}$ . Thus,  $w_1 w_2 w_3 \in L_{x,y}^{X \cup \{z\}}$  by Lemma 4.8.8. □

**Lemma**  $\text{L\_rec } (X: \{\text{set } A\}) \text{ } x \text{ } y \text{ } z:$

$$L^X(z \text{ } |: X) \text{ } x \text{ } y = \text{plus } (\text{conc } (L^X x \text{ } z) \text{ } (\text{conc } (\text{star } (L^X z \text{ } z)) \text{ } (L^X z \text{ } y))) \\ (L^X x \text{ } y).$$

All that remains to complete the proof of Lemma 4.8.2 is a proof of  $L_{x,y}^X = \mathcal{L}(R_{x,y}^X)$ .

**Lemma 4.8.11.** *Let  $X \subseteq Q$ . Let  $x, y \in Q$ . We have that*

$$L_{x,y}^X = R_{x,y}^X.$$

*Proof.* By induction on  $|X|$ .

1. For  $|X| = 0$ , the claim follows immediately from the definitions of  $L$  and  $R$ .
2. For  $|X| = n + 1$  for some  $n \in \mathbb{N}$  we get  $\exists z \in X$  and thus

$$R_{x,y}^X = R_{x,z}^{X \setminus \{z\}} (R_{z,z}^{X \setminus \{z\}})^* R_{z,y}^{X \setminus \{z\}} + R_{x,y}^{X \setminus \{z\}}.$$

By Lemma 4.8.10 we also know that

$$L_{x,y}^X = L_{x,z}^{X \setminus \{z\}} (L_{z,z}^{X \setminus \{z\}})^* L_{z,y}^{X \setminus \{z\}} + L_{x,y}^{X \setminus \{z\}}.$$

The claim follows by inductive hypothesis. □

**Lemma** `L_R n (X: {set A}) × y: #|X| = n → L^X × y =i R^X × y.`

This concludes the proof of Theorem 4.8.2.

**Definition** `dfa_to_re : regular_expression char :=  
nPlus (map (R^setT (dfa_s A)) (enum (dfa_fin A))).`

**Lemma** `dfa_to_re_correct: dfa_lang A =i dfa_to_re .`

In preparation of the final result of this chapter, we prove that  $R$  is a standard regular expression.

**Lemma 4.8.12.** *Let  $X \subseteq Q$  and  $x, y \in Q$ .  $R_{x,y}^X$  is a standard regular expression.*

*Proof.* All regular expressions used in  $R$  are standard. □

**Lemma** `R_standard (X: {set A}) × y: standard char (R^X × y).`

The proof of Theorem 4.8.2 was by far the most technically involved proof presented in this thesis. The mathematical content is rather straight-forward and intuitive. However, especially due to the need for the `allbutlast` predicate, the implementation contains a lot of quite general infrastructure. In fact, a little more than one third of the implementation (150 out of 550 lines) is taken up by `allbutlast`.

### 4.8.1 Extended Regular Expressions to Regular Languages

We can now prove that extended regular expressions are equivalent to regular languages. We show that  $R$  is a standard regular expression, which are a subset of extended regular expression which corresponds to the definition of regular languages.

**Theorem 4.8.13.** *Extended regular expressions and regular languages are equally expressive, i.e. for all  $L$ , we have  $L$  is a regular language if and only if there exists an extended regular expression that recognizes  $L$ .*

*Proof.* “ $\Rightarrow$ ” Let  $L$  be regular. Then, by definition of regular languages, there is an equivalent standard regular expression.

“ $\Leftarrow$ ” Let  $r$  be an extended regular expression. By Theorem 4.6.1 we have DFA  $A$  such that  $\mathcal{L}(A) = \mathcal{L}(r)$ . By Theorem 4.8.2 we have regular expression  $s$  such that  $\mathcal{L}(s) = \mathcal{L}(A)$ . By Lemma 4.8.12,  $s$  is a standard regular expression. Thus, by definition of standard regular expressions,  $\mathcal{L}(r)$  is a regular language.  $\square$

**Definition** `ext_re_to_std_re (r: regular_expression char) := dfa_to_re (re_to_dfa r).`

**Lemma** `ext_re_to_std_re_standard r: standard char ( ext_re_to_std_re r).`

**Lemma** `ext_re_to_std_re_correct r: ( ext_re_to_std_re r ) =i r.`

## Remarks

All in all, our formalization of the results presented in this chapter add up to 1,400 lines of code. More than one half of that is due to the construction of finite automata. Although most of these constructions are straight-forward, proving them correct requires a lot of attention to detail. Additionally, we opted to give a corresponding automaton for every *extended* regular expression, which, of course, adds to the expected size of the development.

## 5 Myhill-Nerode

In this chapter, we consider three additional characterizations of regular languages:

1. Myhill relations,
2. weak Nerode relations,
3. and Nerode relations.

We will show that these three characterizations can be used to characterize regular languages by proving them equivalent to the existence of a (deterministic) finite automaton.

### 5.1 Definitions

Before we can state the Myhill-Nerode theorem, we need a number of auxiliary definitions. We roughly follow [24].

**Definition 5.1.1.** *Let  $\equiv$  be an equivalence relation. The **equivalence class** of  $u \in \Sigma^*$  with respect to  $\equiv$  is the set of all  $v$  such that  $u \equiv v$ . It is denoted by  $[u]_{\equiv}$ .*

**Definition 5.1.2.** *Let  $\equiv$  be an equivalence relation.  $\equiv$  is of **finite index** if and only if the set of  $\{[u]_{\equiv} \mid u \in \Sigma^*\}$  is finite.*

Due to the lack of native support for quotient types in Coq, we formalize equivalence relations of finite index as surjective functions from  $\Sigma^*$  to a finite type  $X$ .

**Definition 5.1.3.** *Let  $X$  be finite. Let  $f : \Sigma^* \mapsto X$  be surjective. Let  $u, v \in \Sigma^*$ .  $f$  is an **equivalence relation of finite index**.  $u$  and  $v$  are equivalent with respect to  $f$  if and only if  $f(u) = f(v)$ .  $f(u)$  is the equivalence class of  $u$  with respect to  $f$ .*

**Record** Fin\_Eq\_Cls :=  
 { fin\_type : finType;  
 fin\_func :> word -> fin\_type;  
 fin\_surjective : surjective fin\_func }.

**Definition 5.1.4.** *Let  $f$  be as above. Let  $x \in X$ .  $w \in \Sigma^*$  is a **representative** of  $x$  if and only if  $f(w) = x$ . Since  $f$  is surjective, every  $w$  has a representative. We write  $cr(x)$  to denote the **canonical representative** of  $x$ , which we obtain by constructive choice.*

**Definition** cr (f: Fin\_Eq\_Cls) x := xchoose ( fin\_surjective f x).

### 5.1.1 Myhill Relations

**Definition 5.1.5.** Let  $\equiv$  be an equivalence relation of finite index.  $\equiv$  is a **Myhill relation** [24] for  $L$  if and only if

(i)  $\equiv$  is **right congruent**, i.e. for all  $u, v \in \Sigma^*$  and  $a \in \Sigma$ ,

$$u \equiv v \Rightarrow u \cdot a \equiv v \cdot a.$$

(ii)  $\equiv$  **refines**  $L$ , i.e. for all  $u, v \in \Sigma^*$ ,

$$u \equiv v \Rightarrow (u \in L \iff v \in L).$$

Myhill relations are commonly referred to as “Myhill-Nerode relations”. In this thesis, it makes sense to split the concept of a Myhill relation from that of the Nerode relation. Apart from the Nerode relation, which can be seen as the coarsest Myhill relation, we also define weak Nerode relations that have no direction connection to Myhill relations. Thus, we strictly separate the characterizations.

Mathematically, Myhill relations are required to be of finite index. We only formalize equivalence relations of finite index. Thus, proving that a Myhill relation is of finite index mathematically corresponds to constructing a Myhill relation in our formalization.

**Definition** `right_congruent {X} (f: word → X) :=`  
`forall u v a, f u = f v → f (rcons u a) = f (rcons v a).`

**Definition** `refines {X} (f: word → X) :=`  
`forall u v, f u = f v → u \in L = (v \in L).`

**Record** `Myhill_Rel :=`  
`{ myhill_func :> Fin_Eq_Cls;`  
`myhill_congruent : right_congruent myhill_func ;`  
`myhill_refines : refines myhill_func }.`

Myhill relations correspond to the equivalence relations defined as the pairs of words  $(u, v)$  whose runs on a DFA  $A$  end in the same state. These relations are right congruent, refine  $\mathcal{L}(A)$  and are of finite index as  $A$  has finitely many states. We will later give a formal proof of this.

### 5.1.2 Nerode Relations

**Definition 5.1.6.** Let  $u, v \in \Sigma^*$ . Let  $L$  be a language. We define the **Nerode relation**  $\dot{=}_L$  for  $L$  such that

$$u \dot{=}_L v \iff \forall w \in \Sigma^*. uw \in L \iff vw \in L.$$

The Nerode relation given above is a propositional statement in COQ. To prove that the Nerode relation is of finite index, we require an equivalence relation, i.e. a function  $f$  from words to a finite type, such that  $f$  is equivalent to  $\dot{=}_L$ .

**Definition** `equiv_suffix {X} (f: word → X) :=`  
**forall** `u v, f u = f v <=> suffix_equal u v.`

**Record** `Nerode_Rel :=`  
`{ nerode_func :> Fin.Eq_Cls;`  
`nerode_equiv: equiv_suffix nerode_func }.`

**Definition 5.1.7.** *Let  $L$  be a language and let  $\equiv$  be an equivalence relation. We say that  $\equiv$  is a **weak Nerode relation** for  $L$  if and only if*

$$\forall u, v \in \Sigma^*. u \equiv v \implies u \dot{=}_L v.$$

**Definition** `suffix_equal u v :=`  
**forall** `w, u ++ w \in L = (v ++ w \in L).`

**Definition** `imply_suffix {X} (f: word → X) :=`  
**forall** `u v, f u = f v → suffix_equal u v.`

**Record** `Weak_Nerode_Rel :=`  
`{ weak_nerode_func :> Fin.Eq_Cls;`  
`weak_nerode_imply: imply_suffix weak_nerode_func }.`

It appears that the notion of a weak Nerode relation is not found in the literature. We will later prove them weaker than Myhill relations, in the sense that every Myhill relation is also a weak Nerode relation.

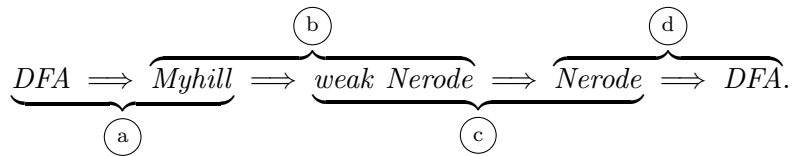
### 5.1.3 Myhill-Nerode Theorem

We can now move on to the statement of the Myhill-Nerode theorem [24].

**Theorem 5.1.8.** (*Myhill-Nerode*) *Let  $L$  be a language. The following four statements are equivalent:*

1. *there exists a deterministic finite automaton that accepts  $L$ ;*
2. *there exists a Myhill relation for  $L$ ;*
3. *there exists a weak Nerode relation for  $L$ ;*
4. *the Nerode relation for  $L$  is of finite index.*

Our proof of equivalence will have the following structure:



We will first show  $\textcircled{a}$ ,  $\textcircled{b}$ , and  $\textcircled{d}$ . We will then give a proof of  $\textcircled{c}$ , which is the most challenging proof and formalization in this chapter.



## 5.2 Finite Automata to Myhill relations

We assume we are given a DFA  $A$ . We will be using the states of  $A$  as equivalence classes. Our goal is to construct a Myhill relation, for which we will need an equivalence relation of finite index. Therefore, we first need to ensure that the mapping from words to equivalence classes is surjective. Thus, we consider the equivalent, connected automaton  $A_c = (Q_c, s_c, F_c, \delta_c)$  (Definition 4.3.1), which has only reachable states. This enables us to construct a surjective function from words to the states of  $A_c$ .

**Definition 5.2.1.** Let  $u \in \Sigma^*$ . Let  $\sigma$  be the run of  $u$  on  $A_c$ . We define  $f_M : \Sigma^* \mapsto Q_c$  such that  $f_M(u)$  is the last state in  $\sigma$ , i.e.

$$f_M(u) := \sigma_{|\sigma|-1}.$$

Note that  $f_M$  is surjective (follows directly from Lemma 4.3.5) and, thus, an equivalence relation of finite index.

**Definition**  $f\_M := \text{fun } w \Rightarrow \text{last } (\text{dfa\_s } A\_c) (\text{dfa\_run } A\_c w).$

**Lemma**  $f\_M.\text{surjective} : \text{surjective } f\_M.$

**Definition**  $f\_fin : \text{Fin\_Eq\_Cls} :=$   
 $\{ | \text{ fin\_func } := f\_M;$   
 $\text{ fin\_surjective } := f\_M.\text{surjective} \}.$

In order to show that  $f_M$  is a Myhill relation, we prove that it fulfills Definition 5.1.5.

**Lemma 5.2.2.**  $f_M$  is right congruent.

*Proof.* Let  $u, v \in \Sigma^*$  such that  $f_M(u) = f_M(v)$ . Let  $a \in \Sigma$ . Since  $A$  is deterministic, we get  $f_M(ua) = f_M(va)$ .  $\square$

**Lemma 5.2.3.**  $f_M$  refines  $\mathcal{L}(A_c)$ .

*Proof.* Let  $u, v \in \Sigma^*$  such that  $f_M(u) = f_M(v)$ . By definition of  $f_M$ , the runs  $u$  and  $v$  on  $A$  end in the same state. Thus, either  $u$  and  $v$  are both accepted, or both not accepted.  $\square$

**Theorem 5.2.4.**  $f_M$  is a Myhill relation for  $\mathcal{L}(A)$ .

*Proof.* By Lemma 4.3.3, we have  $\mathcal{L}(A_c) = \mathcal{L}(A)$ . Thus, it suffices to show that  $f_M$  is a Myhill relation for  $\mathcal{L}(A_c)$ . This follows with Lemma 5.2.2 and Lemma 5.2.3.  $\square$

We only have extensional equality on  $\mathcal{L}(A_c)$  and  $\mathcal{L}(A)$  in Coq. Thus, we first show that  $f_M$  is a Myhill relation for  $\mathcal{L}(A_c)$ . Then, we show that we can get a Myhill relation for  $\mathcal{L}(A)$  from a Myhill relation for  $\mathcal{L}(A_c)$ .

**Definition**  $\text{dfa\_to\_myhill}' : \text{Myhill\_Rel } (\text{dfa\_lang } A\_c) :=$   
 $\{ | \text{ myhill\_func } := f\_fin ;$   
 $\text{ myhill\_congruent } := f\_M.\text{right\_congruent} ;$   
 $\text{ myhill\_refines } := f\_M.\text{refines} \}.$

**Lemma**  $\text{myhill\_lang\_eq } L1 L2 : L1 =_i L2 \rightarrow \text{Myhill\_Rel } L1 \rightarrow \text{Myhill\_Rel } L2.$

**Lemma**  $\text{dfa\_to\_myhill} : \text{Myhill\_Rel } (\text{dfa\_lang } A).$

This concludes the proof of step (a).

### 5.3 Myhill relations to weak Nerode relations

We show that if we are given a Myhill relation for a language, we can also give a weak Nerode relation for that language. In fact, we will prove that any Myhill relation *is* a weak Nerode relation.

**Theorem 5.3.1.** *Let  $f$  be a Myhill relation for a language  $L$ . Then  $f$  is a weak Nerode relation for  $L$ .*

*Proof.* Let  $u, v \in \Sigma^*$  such that  $u =_f v$ . We have to show that for all  $w \in \Sigma^*$ ,  $uw \in L \Leftrightarrow vw \in L$ . By induction on  $w$ .

1. For  $w = \varepsilon$ , we get  $u \in L \Leftrightarrow v \in L$  as  $f$  refines  $L$ .
2. For  $w = aw'$ , we get  $ua =_f va$  by congruence of  $f$  and thus, by inductive hypothesis,  $uaw' \in L \Leftrightarrow vaw' \in L$ .

□

**Lemma** myhill\_suffix: imply\_suffix  $L$   $f$ .

**Lemma** myhill\_to\_weak\_nerode: Weak\_Nerode\_Rel  $L$ .

*Proof.* exact

{| weak\_nerode\_func :=  $f$ ;  
weak\_nerode\_imply := myhill\_suffix |}.

Defined.

This concludes step (b) of Theorem 5.1.8.

### 5.4 Nerode relations to Finite Automata

We prove step (d) of Theorem 5.1.8. If the Nerode relation for a language  $L$  is of finite index, we can construct a DFA that accepts  $L$ . The construction is very straightforward and uses the equivalence classes of the Nerode relation as the set of states for the automaton.

**Definition 5.4.1.** *Let  $L$  be a language. Let  $X$  be a finite type. Let  $f : \Sigma^* \mapsto X$  be the equivalence relation which proves that the Nerode relation for  $L$  is of finite index. We construct DFA  $A$  such that*

$$\begin{aligned} s &:= f(\varepsilon) \\ F &:= \{x \mid x \in X \wedge cr(x) \in L\} \\ \delta &:= \{(x, a, f(cr(x)a)) \mid x \in X, a \in \Sigma\} \\ A &:= (X, s, F, \delta). \end{aligned}$$

**Definition** `nerode_to_dfa` :=

```
{| dfa_s := f [|];
  dfa_fin := [pred x | cr f x \in L ];
  dfa_step := [fun x a => f (rcons (cr f x) a)] |}.
```

In order to show that  $A$  accepts the language  $L$ , we first need to connect runs on  $A$  to the equivalence classes, i.e. the range of  $f$ . The following lemma gives a direct connection.

**Lemma 5.4.2.** *Let  $w \in \Sigma^*$ . Let  $\sigma$  be the run of  $w$  on  $A$  starting in  $s$ . We have that the last state of  $\sigma$  is the equivalence class of  $w$ , i.e.*

$$\sigma_{|\sigma|-1} = f(w).$$

*Proof.* We proceed by induction on  $w$  from right to left.

1. For  $w = \varepsilon$  we have  $s = f(\varepsilon)$ .
2. For  $w = w'a$  we know that the run of  $w'$  on  $A$  starting in  $s$  ends in  $f(w')$ . It remains to show that  $(f(w'), a, f(w)) \in \delta$ . We have  $cr(f(w'))a =_f w$ , i.e.  $f(cr(f(w'))a) = f(w)$  by definition of  $f$ . Thus, it suffices to show  $(f(w'), a, f(cr(f(w'))a)) \in \delta$ , which holds by definition of  $\delta$ .

□

**Theorem 5.4.3.**  *$A$  accepts  $L$ , i.e.  $\mathcal{L}(A) = L$ .*

*Proof.* Let  $w \in \Sigma^*$ . Let  $\sigma$  be the run of  $w$  on  $A$  starting in  $s$ .  $w$  is accepted if and only if  $\sigma_{|\sigma|-1} \in F$ , i.e. if and only if  $cr(\sigma_{|\sigma|-1}) \in L$ . We have  $w =_f cr(\sigma_{|\sigma|-1})$  and therefore  $w \in L \Leftrightarrow cr(\sigma_{|\sigma|-1}) \in L$ . Thus  $w$  is accepted if and only if  $w \in L$ . □

The resulting automaton is minimal, i.e. there exists no other automaton that accepts the same language and has less states than  $A$ .

This concludes step (d) of Theorem 5.1.8.

## 5.5 Minimizing Equivalence Classes

Finally, we prove that if there is a weak Nerode relation for a language  $L$ , the Nerode relation is of finite index. For this purpose, we employ a table-filling algorithm [21] to find states indistinguishable under the Myhill-Nerode relation. This algorithm was originally intended to be used on automata. It identifies (un)distinguishable states based on their successors. We use the finite type  $X$ , i.e. the equivalence classes, instead of states.

For the remainder of this section, we assume we are given a language  $L$  and a weak Nerode relation  $f_0$ .

We employ a fixed-point construction to find equivalence classes that are  $\equiv_L$ -equivalent. In each step, we add those equivalence classes that are distinguishable based on equivalence classes that were distinguishable in the previous step. The initial set of distinguishable equivalence classes are distinguishable by the inclusion of their canonical representative in  $L$ . We denote this initial set  $dist_0$ .

$$dist_0 := \{(x, y) \in F \times F \mid cr(x) \in L \Leftrightarrow cr(y) \notin L\}.$$

**Definition** `distinguishable` := [ fun x y => (cr f\_0 x) \in L != ((cr f\_0 y) \in L) ].

**Definition** `dist0` := [ set x | distinguishable x.1 x.2 ].

To find more distinguishable equivalence classes, we have to identify equivalence classes that “lead to” distinguishable equivalence classes. In analogy to the minimization procedure on automata, we define successors of equivalence classes with respect to a single character. The intuition is that two states are distinguishable if they are succeeded by a pair of distinguishable states. Conversely, if a pair of states is not distinguishable, then their predecessors can not be distinguished by those states. Thus, two states are indistinguishable if none of their succeeding pairs of states are distinguishable.

**Definition 5.5.1.** Let  $x, y \in X$  and  $a \in \Sigma$ . We define  $succ_a$  and  $psucc_a$ .  $succ_a(x) := f_0(cr(x) \cdot a)$  and  $psucc_a(x, y) := (succ_a(x), succ_a(y))$ .

**Definition** `succ` := [ fun x a => f\_0 ((cr f\_0 x) ++ [:a]) ].

**Definition** `psucc` := [ fun x y => [ fun a => (succ x a, succ y a) ] ].

The fixed-point algorithm tries to extend the set of distinguishable equivalence classes by looking for a pair of equivalence classes that transitions to a pair of distinguishable equivalence classes. Given a set of pairs of equivalence classes  $dist$ , we define the set of pairs of distinguishable equivalence classes that have successors in  $dist$  as

$$dist_S(dist) := \{(x, y) \mid \exists a. psucc_a(x, y) \in dist\}.$$

**Definition** `distS` (`dist` : {set  $X \times X$ }) :=  
[ set (x,y) | x in X, y in X & [ exists a, psucc x y a \in dist ] ].

**Definition 5.5.2.** Let  $dist$  be a subset of  $X \times X$ . We define *one-step-dist* such that

$$one\_step\_dist(dist) := dist_0 \cup dist \cup dist_S(dist).$$

**Definition** `one_step_dist` `dist` := `dist0` :|: `dist` :|: (`distS` `dist`).

**Lemma 5.5.3.** *one-step-dist* is monotone and has a fixed-point.

*Proof.* Monotonicity follows directly from the monotonicity of  $\cup$ . The number of sets in  $X \times X$  is finite. Therefore, *one-step-dist* has a fixed point. We iterate *one-step-dist*  $|X \times X| + 1 = |X|^2 + 1$  times on the empty set. Since there can only ever be  $|X \times X|$  items

in the result of *one-step-dist*, we will find the fixed point in no more than  $|X * X| + 1$  steps.

Let *distinct* be the fixed point of *one-step-dist* and let it be denoted by  $\not\cong$ . We write *equiv* for the complement of *distinct* and denote it  $\cong$ .  $\square$

**Definition**  $\text{lf}p := \text{iter } \#|T|. + 1 \text{ F set0.}$

**Definition**  $\text{distinct} := \text{lf}p \text{ one\_step\_dist.}$

We now show that  $\cong$  is equivalent to the Nerode relation. Formally, this means constructing a function that fulfills our definition of an equivalence relation of finite index. Then, we prove that this equivalence relation is equivalent to the the Nerode relation. First, we will prove that  $\cong$  is an equivalence relation. Then, we will prove it equivalent to the Nerode relation in two separate steps, since the two directions require different strategies.

**Lemma 5.5.4.**  *$\cong$  is an equivalence relation.*

*Proof.* We first state transitivity of  $\cong$  in terms of  $\not\cong$ :

$$\forall x, y, z \in X. \neg(x \not\cong y) \implies \neg(y \not\cong z) \implies \neg(x \not\cong z). \quad (*)$$

It suffices to show that *distinct* is anti-reflexive, symmetric and fulfills (\*). Note that complementary transitivity, anti-reflexivity and symmetry are closed under union. We proceed by fixed-point induction.

1. For  $\text{one-step-dist}(\text{dist}) = \emptyset$  we have anti-reflexivity, symmetry and (\*) by the properties of  $\emptyset$ .
2. For  $\text{one-step-dist}(\text{dist}) = \text{dist}'$  we have *dist* anti-reflexive, symmetric and (\*). It remains to show that  $\text{dist}_0$  and  $\text{distinct}_S(\text{dist})$  are anti-reflexive, symmetric and fulfill (\*).

$\text{dist}_0$  is anti-reflexive, symmetric and fulfills (\*) by definition.

$\text{distinct}_S(\text{dist})$  can be seen as an intersection of a symmetric subset of  $X \times X$  defined by  $\text{psucc}_a$  and *dist*, the latter of which is anti-reflexive, symmetric and fulfills (\*). Thus,  $\text{distinct}_S(\text{dist})$  is anti-reflexive, symmetric and fulfills (\*).

Therefore,  $\text{dist}'$  is anti-reflexive, symmetric and fulfills (\*).  $\square$

**Lemma**  $\text{equiv\_refl } x: x \sim x.$

**Lemma**  $\text{equiv\_sym } x \ y: x \sim y \rightarrow y \sim x.$

**Lemma**  $\text{equiv\_trans } x \ y \ z: x \sim y \rightarrow y \sim z \rightarrow x \sim z.$

**Lemma 5.5.5.** *Let  $u, v \in \Sigma^*$ .  $f_0(u) \cong f_0(v) \implies u \dot{=}_L v$ .*

## 5 Myhill-Nerode

*Proof.* Let  $w \in \Sigma^*$ . We then show the contraposition of the claim:

$$uw \in L \not\Rightarrow vw \in L \implies f_0(u) \not\equiv f_0(v).$$

By induction on  $w$ .

1. For  $w = \varepsilon$  we have  $u \in L \not\Rightarrow v \in L$  which gives us  $(f_0(u), f_0(v)) \in \text{dist}_0$ . Thus,  $f_0(u) \not\equiv f_0(v)$ .
2. For  $w = aw'$  we have  $uaw \in L \not\Rightarrow vaw \in L$ . We have to show  $f_0(u) \not\equiv f_0(v)$ , i.e.  $(f_0(u), f_0(v)) \in \text{distinct}$ . By definition of *distinct*, it suffices to show  $(f_0(u), f_0(v)) \in \text{one-step-dist}(\text{distinct})$ .

For this, we prove  $(f_0(u), f_0(v)) \in \text{distinct}_S(\text{distinct})$ . By  $uaw \in L \not\Rightarrow vaw \in L$  we have  $(f_0(cr(u)a), f_0(cr(v)a)) \in \text{dist}_0$ .

It remains to show that  $f_0(cr(u)a) \not\equiv f_0(cr(v)a)$  which we get by inductive hypothesis. For this, we need to show that  $cr(u)aw \in L \not\Rightarrow cr(v)aw \in L$ .

By the properties of  $f$ , we get  $cr(u)aw \in L \Leftrightarrow uaw \in L$  and  $cr(v)aw \in L \Leftrightarrow vaw \in L$ . Thus,  $cr(u)aw \in L \not\Rightarrow cr(v)aw \in L$ .

□

**Lemma 5.5.6.** *Let  $u, v \in \Sigma^*$ . If  $f_0(u) \not\equiv f_0(v)$ , then  $u$  and  $v$  are **not** equivalent with respect to the Nerode relation, i.e.  $f_0(u) \not\equiv f_0(v) \implies u \not\equiv_L v$ .*

*Proof.* We do a fixed-point induction.

1. For  $\text{one-step-dist}(\text{dist}) = \emptyset$  we have  $(f_0(u), f_0(v)) \in \emptyset$  and thus a contradiction.
2. For  $\text{one-step-dist}(\text{dist}) = \text{dist}'$  we have  $(f_0(u), f_0(v)) \in \text{dist}'$ . We do a case distinction on  $\text{dist}'$ .
  - a)  $(f_0(u), f_0(v)) \in \text{dist}_0$ . We have  $u \in L \not\Rightarrow v \in L$ . Thus,  $u \not\equiv_L v$  as witnessed by  $w = \varepsilon$ .
  - b)  $(f_0(u), f_0(v)) \in \text{dist}$ . By inductive hypothesis,  $u \not\equiv_L v$ .
  - c)  $(f_0(u), f_0(v)) \in \text{distinct}_S(\text{dist})$ . We have  $a \in \Sigma$  with  $\text{psucc}_a(f_0(u), f_0(v)) \in \text{dist}$ . By inductive hypothesis, we get  $cr(u)a \not\equiv_L cr(v)a$  as witnessed by  $w \in \Sigma^*$  such that  $cr(u)aw \in L \not\Rightarrow cr(v)aw \in L$ .

By the properties of  $f$ , we get  $cr(u)aw \in L \Leftrightarrow uaw \in L$  and  $cr(v)aw \in L \Leftrightarrow vaw \in L$ . Thus, we have  $u \not\equiv_L v$  as witnessed by  $aw$ .

□

**Corollary 5.5.7.** *Let  $u, v \in \Sigma^*$ . We have that*

$$f_0(u) \cong f_0(v) \iff u \dot{\equiv}_L v.$$

*Proof.* Follows immediately with Lemma 5.5.5 and Lemma 5.5.6. □

**Lemma** `equiv_suffix_equal u v`:  $u \sim_{f_0} v \rightarrow \text{suffix\_equal } L \ u \ v$ .

**Lemma** `distinct_not_suffix_equal u v`:

$u \not\sim_{f_0} v \rightarrow$

**exists**  $w, u ++ w \notin L \neq (v ++ w \notin L)$ .

**Lemma** `equivP u v`:

`reflect (suffix_equal L u v)`

`(u  $\sim_{f_0}$  v).`

**Definition 5.5.8.** Let  $w \in \Sigma^*$ . We define

$$f_{min}(w) := \{x \mid x \in X, f_0(w) \cong x\}.$$

Note that the range of  $f_{min}$  is finite (since  $X$  is finite) and does not contain the empty set (due to reflexivity of  $\cong$ ).

**Lemma 5.5.9.**  $f_{min}$  is surjective.

*Proof.* Let  $s \in \text{range}(f_{min})$ . Since  $s \neq \emptyset$ , there exists  $x \in X$  such that  $x \in s$ . We have  $f_0(x) = f_0(cr(x))$  and therefore  $f_0(x) \cong f_0(cr(x))$  by reflexivity of  $\cong$ . Thus,  $f_0(cr(x)) = s$  since  $f_{min}(x) = f_{min}(cr(x)) = s$ .  $\square$

**Lemma 5.5.10.** For all  $u, v \in \Sigma^*$  we have

$$f_{min}(u) = f_{min}(v) \iff f_0(u) \cong f_0(v).$$

*Proof.* “ $\Rightarrow$ ” We have  $f_{min}(u) = f_{min}(v)$  and thus  $f_0(u) \cong f_0(v)$ .

“ $\Leftarrow$ ” We have  $f_0(u) \cong f_0(v)$ . Let  $x \in X$ . It suffices to show that  $f_0(u) \cong x$  if and only if  $f_0(v) \cong x$ . This follows with symmetry and transitivity of  $\cong$ .  $\square$

**Lemma 5.5.11.**  $f_{min}$  is equivalent to the Nerode relation, i.e.  $f_{min}$  is surjective and for all  $u, v \in \Sigma^*$  we have

$$f_{min}(u) = f_{min}(v) \iff u \dot{=}_L v.$$

*Proof.* We have proven surjectivity in Lemma 5.5.9. By Lemma 5.5.10 we have  $f_{min}(u) = f_{min}(v)$  if and only if  $f_0(u) \cong f_0(v)$ . By corollary 5.5.7 we have  $f_0(u) \cong f_0(v)$  if and only if  $u \dot{=}_L v$ . Thus,  $f_{min}(u) = f_{min}(v)$  if and only if  $u \dot{=}_L v$ .  $\square$

The formalization of  $f_{min}$  is slightly more involved than the mathematical construction. We first need to define the finite type of  $f_{min}$ ’s range, which we do by enumerating all possible values of  $f_{min}$ .

**Definition** `equiv_repr x` := `[set y | x  $\sim_{f_0}$  y]`.

**Definition** `X_min` := `map equiv_repr (enum (fin_type f_0))`.

**Definition** `f_min w` := `SeqSub (equiv_repr_mem (f_0 w))`.

We then prove lemmas 5.5.9, 5.5.10 and Theorem 5.5.11 which are consequential and straight-forward.

**Lemma** `f_min_surjective`: `surjective f_min`.

**Lemma** `f_minP` `u v`:  
`reflect (f_min u = f_min v)`  
`(u ~=f.0 v)`.

**Lemma** `f_min_correct`: `equiv_suffix L f_min`.

**Definition** `f_min_fin` : `Fin_Eq_Cls` :=  
`{| fin_surjective := f_min_surjective |}`.

We can now state the result of this section.

**Theorem 5.5.12.** *The Nerode relation is of finite index.*

*Proof.* This follows directly from Lemma 5.5.4 and Lemma 5.5.11. □

**Lemma** `weak_nerode_to_nerode`: `Nerode_Rel L`.

This concludes step ③ of Theorem 5.1.8 and, thus, this chapter.

## Remarks

The characterizations presented here are very compact, mathematically. Interestingly, they also lend themselves very well to formalization. Even with the fixed-point algorithm, this entire chapter is formalized in less than 530 lines of code. This is a very reasonable size, considering that we introduce three different characterizations and prove them all equally expressive to finite automata.



## 6 Conclusion

We give a short overview of the theorems presented in this thesis and their corresponding statements in the Coq development. We then evaluate our choice of the SSREFLECT plugin. Finally, we discuss opportunities for future work.

### 6.1 Results

Theorem 4.2.1 and Theorem 4.2.5 show that deterministic and non-deterministic finite automata are equally expressive. For this, we construct two functions `dfa_to_nfa` and `nfa_to_dfa` to convert between the two characterizations.

**Lemma** `dfa_to_nfa_correct` (A: dfa): `dfa_lang A =i nfa_lang (dfa_to_nfa A)`.

**Lemma** `nfa_to_dfa_correct` (A: nfa): `nfa_lang A =i dfa_lang (nfa_to_dfa A)`.

We show in Theorem 4.6.1 that there is an equivalent DFA for every extended regular expression. For this, we construct a function `re_to_dfa` to compute an equivalent DFA from an extended regular expressions.

**Lemma** `re_to_dfa_correct` (r: regular\_expression char) : `dfa_lang (re_to_dfa r) =i r`.

Building on that, we prove the decidability of equivalence of regular expressions in Theorem 4.7.1 with the help of a decision procedure for equivalence of finite automata. We give a function `re_equiv` to decide the equivalence of regular expressions.

**Lemma** `re_equiv_correct` (r s: regular\_expression char): `re_equiv r s <-> r =i s`.

Theorem 4.8.2 shows that we can give an equivalent regular expression for every automaton. We construct a function `dfa_to_re` to compute the regular expression.

**Lemma** `dfa_to_re_correct` (A: dfa): `dfa_lang A =i (dfa_to_re A)`.

Based on this and the results from previous chapters, we also show that extended and standard regular expressions are equally expressive and, thus, that extended regular expressions and regular languages are equally expressive. We give a function `ext_re_to_std_re` which constructs an equivalent standard regular expression for every extended regular expression.

**Lemma** `ext_re_to_std_re_standard` (r: regular\_expression char): `standard char (ext_re_to_std_re r)`.

**Lemma** `ext_re_to_std_re_correct` (r: regular\_expression char): `(ext_re_to_std_re r) =i r`.

With Theorem 5.2.4, we prove that we can construct a Myhill relation for a language from a DFA for that language.

**Lemma** `dfa_to_myhill` (A: dfa): `Myhill_Rel (dfa_lang A)`.

## 6 Conclusion

We prove in Theorem 5.3.1 that every Myhill relations is also a weak Nerode relation.

**Lemma** `myhill_to_weak_nerode` (`L`: language char): `Myhill_Rel L → Weak_Nerode_Rel L`.

Theorem 5.5.12 shows that, if there is a weak Nerode relation, the Nerode relation is of finite index.

**Lemma** `weak_nerode_to_nerode` (`L`: language char): `Weak_Nerode_Rel L → Nerode_Rel L`.

Finally, we prove in Theorem 5.4.1 that, if we are given a Nerode relation of finite index for a language, we can construct a DFA that accepts this language.

**Lemma** `nerode_to_dfa_correct` (`L`: language char) (`f_N`: `Nerode_Rel L`):  
`L =i dfa_lang (nerode_to_dfa f_N)`.

## 6.2 SSReflect

We make extensive use of SSREFLECT’s features in our development. The formalization of finite automata depends crucially on finite types (and, to a lesser extent, finite sets).

We also employ the `reflect` paradigm whenever possible. It offers a very convenient way of working with propositional and boolean predicates at the same time. The built-in support for changing from propositional to boolean statements lets us choose the most appropriate representation for the task at hand.

Furthermore, the very extensive library of general purpose lemmas in SSREFLECT enables us to focus on high-level proofs. The sole exception to this is the `allbutlast` predicate we need for Theorem 4.8.2. However, even in this case, we can mostly rely on the lemmas for `all` provided by SSREFLECT. All we need to do is provide a thin layer between the two predicates.

Additionally, the scripting language offered by SSREFLECT leads to very concise proof scripts. It succeeds in removing some of the bookkeeping overhead.

There are several disadvantages to SSREFLECT. One is that it not as widely used as COQ itself. This means that the group of people who can understand the proof scripts is small. However, in some cases, it might be sufficient to explain a small subset of SSREFLECT in order to give an understandable presentation of the formalized statements.

We also lose practical executability. Specifically, the implementation underlying finite types does not lend itself to computation. Since practical executability is not always a requirement, this restriction may not be relevant to some projects, as is the case with our development.

Based on these considerations, we believe that the use of SSREFLECT is very beneficial to formalizations that do not require executability, especially if there is algorithmic content.

## 6.3 Future Work

There are several possible extensions to our development. Additionally, there are some topics that are not so much extensions but rather candidates for future formalizations.

### 6.3.1 $\varepsilon$ -Transitions

We have avoided  $\varepsilon$ -transitions in our formalization. Non-deterministic finite automata with  $\varepsilon$ -transitions and regular expressions are equally expressive. They are, as we have shown, unnecessary to derive the results proven in this thesis. Nonetheless, it would be very interesting to add them to the list of formalized characterizations of regular languages.

### 6.3.2 Pumping Lemma

The Pumping Lemma [8] gives a sufficient condition for the non-regularity of a language. It is a well-known part of the theory of regular languages and, thus, a good candidate for an extension to our development.

### 6.3.3 Regular Grammars

Another characterization of regular languages is given by regular grammars. Regular grammars seem to enjoy less popularity than other characterizations. A formalization of formal grammars in general would also be a good starting point to formalize other parts of the Chomsky Hierarchy [15]. The context-free languages could be a good candidate for a formalization. We speculate that pushdown automata could be formalized similarly to how we formalized finite automata.

### 6.3.4 $\omega$ -regular languages

A possible next step after the formalization of regular languages is a formalization of  $\omega$ -regular languages. There does not seem much literature on formalizing this topic. Such a development could include all commonly used acceptance criteria on  $\omega$ -automata. This would also make for a good opportunity to study COQ's co-inductive definitions.

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