

Computational Ocean Acoustics

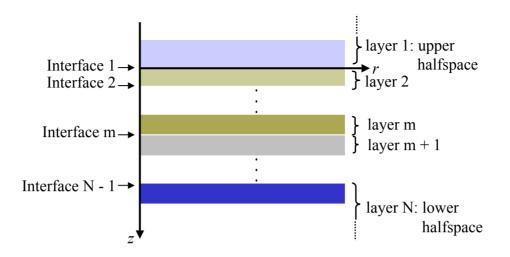
- Ray Tracing
- Wavenumber Integration
- Normal Modes
- Parabolic Equation



Wavenumber Integration

- Range-independent Integral Transform solution
- Exact depth-dependent solution
 - Global Matrix Approach
 - Propagator Matrix Approach
 - Invariant Embedding
- Numerical Integration
 - Fast-Field Program (FFP)
 - Fast Hankel Transform
- Numerical issues:
 - Numerical stability of depth solution
 - Aliasing and wrap-around





Horiztonally stratified environment

Wavenumber Integration Techniques

Integral Transform Solution

Helmholtz Equation for Displacement Potentials

$$\left[\nabla^2 + k_m^2(z)\right] \psi_m(r,z) = f_s(z,\omega) \frac{\delta(r)}{2\pi r} ,$$
 Medium wavenumber: $k_m(z) = \frac{\omega}{c(z)}$

13.853



Hankel Transform Pair

$$f(r,z) = \int_0^\infty f(k_r,z) J_0(k_r r) k_r dk_r ,$$

$$f(k_r,z) = \int_0^\infty f(r,z) J_0(k_r r) r dr ,$$

Integral Transform Solution

Depth-separated Wave Equation

$$\[\frac{d^2}{dz^2} - \left[k_r^2 - k_m^2(z) \right] \] \psi_m(k_r, z) = \frac{f_s(z)}{2\pi} ,$$

Superposition Principle

$$\psi_m(k_r, z) = \underbrace{\hat{\psi}_m(k_r, z)}_{\text{Source}} + \underbrace{A_m^+(k_r) \, \psi_m^+(k_r, z) + A_m^-(k_r) \, \psi_m^-(k_r, z)}_{\text{Homogeneous Solution}},$$



Wavenumber Integration

$$g(r,z) = \int_0^\infty g(k_r,z) J_0(k_r r) k_r dk_r ,$$

Complications

- The *infinite* integration interval.
- The wavenumber discretization giving rise to aliasing and wraparound problems because of the oscillatory nature of the Bessel function, and the variation of the kernel $g(k_r, z)$ which for waveguide problems has poles on or close to the real wavenumber axis.

Fast Field Approximation

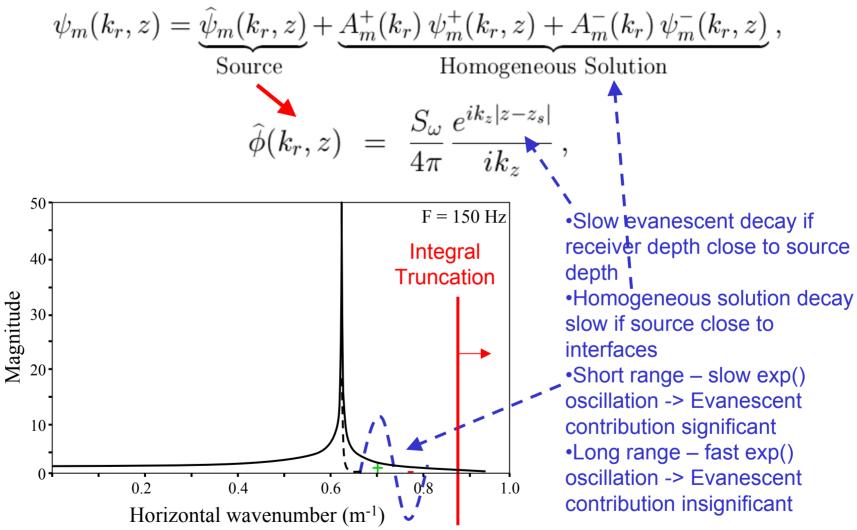
$$J_0(k_r r) = \frac{1}{2} \left[H_0^{(1)}(k_r r) + H_0^{(2)}(k_r r) \right] ,$$

$$\lim_{Kr \to \infty} H_0^{(1)}(k_r r) = \sqrt{\frac{2}{\pi k_r r}} e^{i[k_r r - \frac{\pi}{4}]},$$

$$g(r,z)\simeq \sqrt{rac{1}{2\pi r}}\,e^{-irac{\pi}{4}}\int_0^\infty g(k_r,z)\,\sqrt{k_r}\,e^{ik_r r}dk_r$$
 . Outgoing waves only

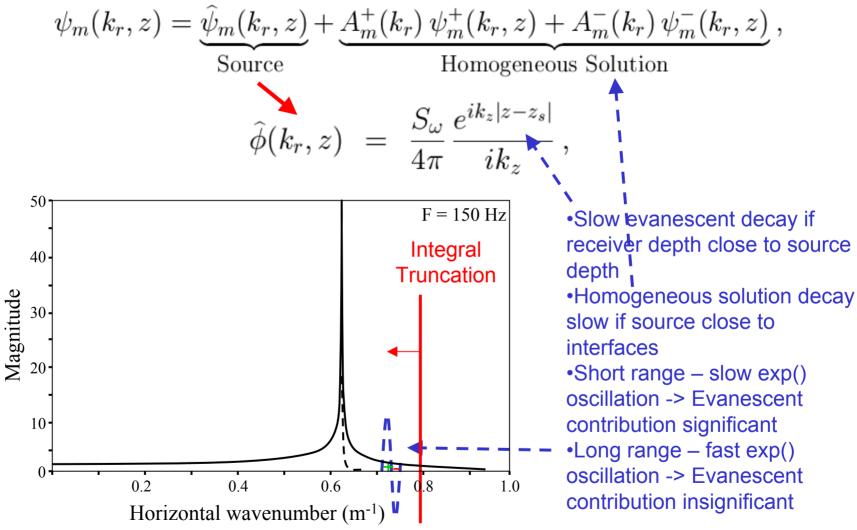


Truncation of Integration Interval





Truncation of Integration Interval



$$g(r,z) \simeq \sqrt{\frac{1}{2\pi r}} e^{-i\frac{\pi}{4}} \int_0^\infty g(k_r,z) \sqrt{k_r} e^{ik_r r} dk_r$$
.

 $Discrete \ wavenumber \ sampling$ $k_{\ell} = k_{\min} + \ell \, \Delta k_r \,, \qquad \ell = 0, 1 \dots (M-1) \,,$ $\Delta k_r = (k_{\max} - k_{\min})/(M-1)$ $Discrete \ FFP \ Approximation$

$$g^*(r,z) = \frac{\Delta k_r}{\sqrt{2\pi r}} e^{i[k_{\min}r - \frac{\pi}{4}]} \sum_{\ell=0}^{M-1} \left[g(k_{\ell},z) \sqrt{k_{\ell}} \right] e^{i\ell\Delta k_r r},$$

Fast Field Discretization Error?

13.853 Lecture 9



$Range-depth\ factorization$

$$g(r,z) \simeq h(r)f(r,z),$$

 $Geometric\ spreading\ factor$

$$h(r) = \sqrt{\frac{1}{2\pi r}} e^{-i\frac{\pi}{4}}$$

Wavenumber integral

$$f(r,z) = \int_0^\infty g(k_r,z) \sqrt{k_r} e^{ik_r r} dk_r.$$

Discrete factorization

$$g^*(r,z) = h(r)e^{ik_{\min}r}f^*(r,z),$$

$$f^*(r,z) = \Delta k_r \sum_{\ell=0}^{M-1} g(k_\ell,z) \sqrt{k_\ell} e^{ir\ell \Delta k_r}.$$



Periodicity

$$R = \frac{2\pi}{\Delta k_r}$$

$$f^{*}(r+nR,z) \equiv f^{*}(r,z), n = -\infty, \dots, 0, \dots \infty.$$

$$\frac{\partial^{m} f^{*}}{\partial r^{m}}|_{r} = \frac{\partial^{m} f^{*}}{\partial r^{m}}|_{r+nR}$$

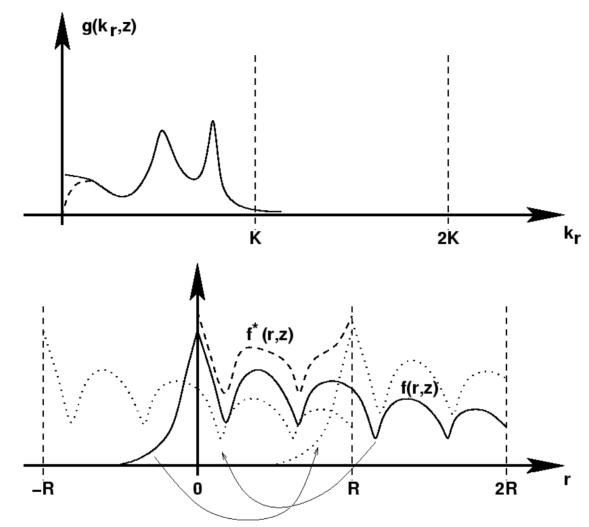
$$\Rightarrow$$

$$\frac{\partial^{m} f^{*}}{\partial r^{m}}|_{r_{\min}} = \frac{\partial^{m} f^{*}}{\partial r^{m}}|_{r_{\min}+nR}$$

Wrap-around - Aliasing

$$g^*(r,z) = h(r)e^{ik_{\min}r}f^*(r,z) = h(r)\sum_{n=-\infty}^{\infty}f(r+nR,z),$$





Aliasing associated with discrete wavenumber integration for typical Pekeris waveguide problem. The wavenumber kernel showing the presence of a two attenuated modes is sketched in the upper plot, with the squareroot singularity introduced by the geometric $\sqrt{k_r}$ indicated by the dashed curve near the origin. The discrete wavenumber integration yields the periodic result shown in the lower frame by a dashed curve, approximating the correct continuous result shown as a solid curve. The discrete result is a superposition of the 'true' field produced by the mirror sources in all the range windows.



FFP: Fast Field Program

Range Discretization

$$r_j = r_{\min} + j \, \Delta r \,, \qquad j = 0, 1 \dots (M-1) \,,$$

$$\Delta r \, \Delta k_r = \frac{2\pi}{M} \,,$$

Discrete Approximation

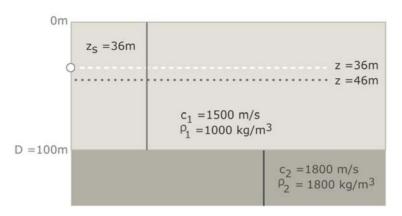
$$g^*(r_j, z) = \frac{\Delta k_r}{\sqrt{2\pi r_j}} e^{i\left[k_{\min}r_j - (m + \frac{1}{2})\frac{\pi}{2}\right]} \sum_{\ell=0}^{M-1} \left[g(k_\ell, z) e^{ir_{\min}\ell \Delta k_r} \sqrt{k_\ell}\right] e^{i\frac{2\pi\ell j}{M}},$$

Negative Spectrum wrap-around

$$e^{i(-\ell\Delta k_r)(j\Delta r)} = e^{i(2\pi - \ell\Delta k_r(j\Delta r))} = e^{i(M-\ell)\Delta k_r(j\Delta r)}.$$

13.853 Lecture 9

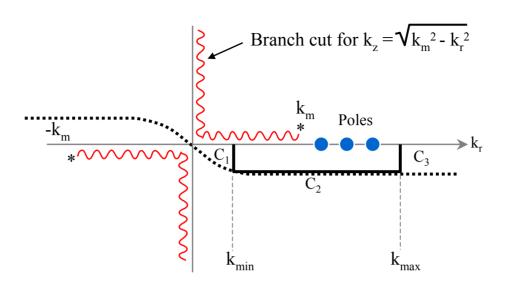




Example: Pekeris waveguide with pressure-release surface and penetrable fluid bottom

See Fig 4.5 in Jensen, Kuperman, Porter and Schmidt. *Computational Ocean Acoustics.* New York: Springer-Verlag, 2000.





Complex integration contours for evaluation of wavenumber integral. The contour C2 is used for FFP integration, while the 'exact' hyperbolic tangent contour indicated by the dashed line is used for trapezoidal rule integration

Complex Contour Integration

$$g(r,z) \simeq h(r) \int_C g(k_r,z) \sqrt{k_r} e^{ik_r r} dk_r,$$

 $\simeq h(r) \int_{k_{\min}}^{k_{\max}} g(k_r - i\epsilon, z) \sqrt{k_r - i\epsilon} e^{i(k_r - i\epsilon)r} dk_r.$

13.853 Lecture 9



Complex Contour Integration

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 $\simeq h(r) \int_{k_{\min}}^{k_{\max}} g(k_r - i\epsilon, z) \sqrt{k_r - i\epsilon} e^{i(k_r - i\epsilon)r} dk_r .$

$$g(r,z) e^{-\epsilon r} \simeq h(r) f(r,z) e^{-\epsilon r}$$

= $h(r) \int_{k_{\min}}^{k_{\max}} g(k_r - i\epsilon, z) \sqrt{k_r - i\epsilon} e^{ik_r r} dk_r$.

$$g^{*}(r_{j}, z) e^{-\epsilon r} = h(r_{j}) e^{ik_{\min}r_{j}} f^{*}(r_{j}, z) e^{-\epsilon r}$$

$$= h(r_{j}) \sum_{n=-\infty}^{\infty} f(r_{j} + nR, z) e^{-\epsilon (r_{j} + nR)}$$

$$\simeq h(r_{j}) \Delta k_{r} e^{ik_{\min}r_{j}} \sum_{\ell=0}^{M-1} \left[g(k_{\ell} - i\epsilon, z) e^{ir_{\min}\ell \Delta k_{r}} \sqrt{k_{\ell} - i\epsilon} \right] e^{i\frac{2\pi\ell j}{M}},$$

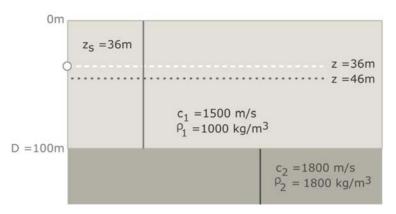
$$g(r_{j}, z) \simeq h(r_{j}) f(r_{j}, z)$$

$$= e^{\epsilon r_{j}} h(r_{j}) \Delta k_{r} e^{ik_{\min}r_{j}} \sum_{\ell=0}^{M-1} \left[g(k_{\ell} - i\epsilon, z) e^{ir_{\min}\ell \Delta k_{r}} \sqrt{k_{\ell} - i\epsilon} \right] e^{i\frac{2\pi\ell j}{M}}$$

$$- h(r_{j}) \sum_{n \neq 0} f(r_{j} + nR, z) e^{-\epsilon nR}.$$

$$\epsilon = \frac{3}{R \log e} = \frac{3}{2\pi (M - 1) \log e} (k_{\text{max}} - k_{\text{min}}),$$





Example: Pekeris waveguide with pressure-release surface and penetrable fluid bottom

[See Jensen, Fig. 4.7]