Report 3

Best Training Result on 20 frame long scenes.
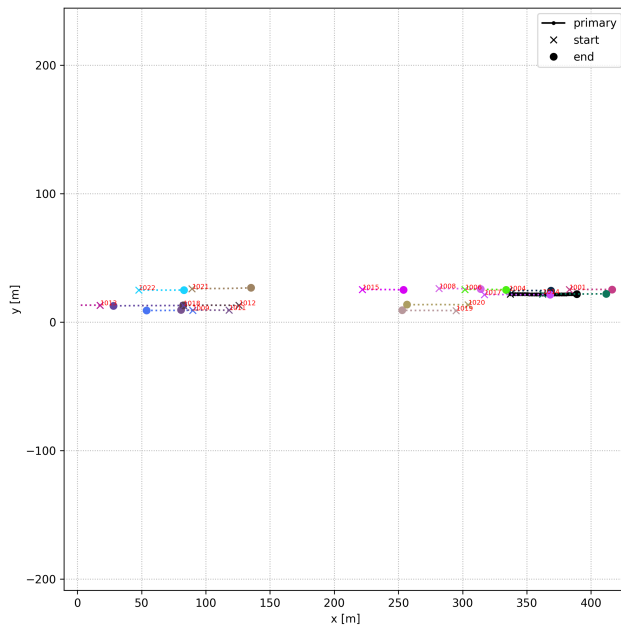
Prediction	**Ground Truth**
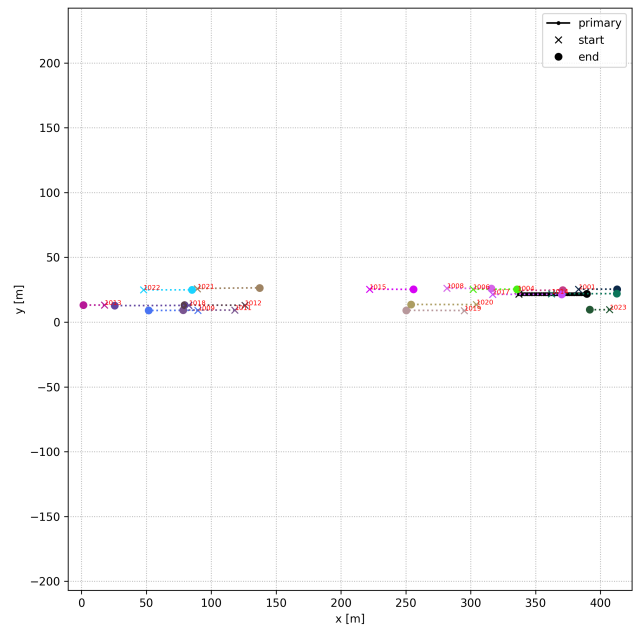
- Almost identical
- Rather short scenes
- No lane changes

Questions and Ideas:

- Dataset possibly too straight forward (not enough interactions between cars) ?
- Other Datasets from **levelXdata** might be interesting in that case
- Filter highD scenes to include more lane changes

Next Steps:

1. Evaluate a scene from a different dataset (woven planet or intersection dataset by **levelXdata**) to see what the model is actually doing: Is it just continuing its direction at the same velocity?
2. Currently am taking a closer look at how Trajnet++ is structured
3. Design the more structured network and figure out how to integrate it into Trajnet++