

4)  $V = PE + KE,$

$$KE = \frac{1}{2} m V_1^2 + \frac{1}{2} m V_2^2, \quad V_1 = \dot{\theta}(l-p), \quad V_2 = \dot{\theta}(l+p)$$

$$KE = \frac{1}{2} m \dot{\theta}^2 (l^2 + p^2)$$

$$PE = 2mgh = 2mgp(1 - \cos\theta)$$

$$V = \frac{1}{2} m \dot{\theta}^2 (l^2 + p^2) + 2mgp(1 - \cos\theta)$$

$V(Q) = 0$ , first part of Lyapunov

$$\nabla V = \begin{pmatrix} 2mpg \sin\theta \\ 2m\dot{\theta}(l^2 + p^2) \end{pmatrix}, \quad \dot{V} = (\nabla V)^T \dot{x}$$

$$\dot{V} = \begin{pmatrix} 2mpg \sin\theta \\ 2m\dot{\theta}(l^2 + p^2) \end{pmatrix} \begin{bmatrix} -p\dot{\theta} \sin\theta \\ \dot{\theta} \end{bmatrix} = 2mpg \dot{\theta} \sin\theta - \frac{B \dot{\theta}^2}{2m}$$

$\dot{V} = 0$  for any  $\dot{\theta} = 0$ , so there are  $x \neq Q$  which

$\dot{V}$  is not less than zero, so we cannot conclude global asymptotic stability.

5) 
$$\underline{A} = \begin{bmatrix} \frac{\partial \dot{x}_1}{\partial x_1} & \frac{\partial \dot{x}_1}{\partial x_2} \\ \frac{\partial \dot{x}_2}{\partial x_1} & \frac{\partial \dot{x}_2}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ \frac{-pg \cos\theta}{l^2 + p^2} & \frac{-B}{2m(l^2 + p^2)} \end{bmatrix}$$

$$\underline{A} = \begin{bmatrix} 0 & 1 \\ \frac{-pg}{l^2 + p^2} & \frac{-B}{2m(l^2 + p^2)} \end{bmatrix}$$