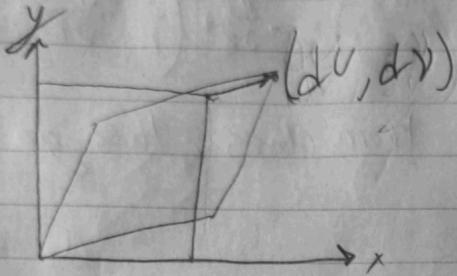


FK



We use  $\frac{\partial u}{\partial x} \div \frac{\partial v}{\partial y}$  to describe the displacement of the corner of the fluid element. This means they can be used to form strain measurements assuming strain rate is defined as a normalized deformation.

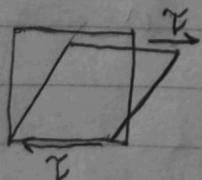
i.e.  $\frac{\Delta L}{L} = S$ . In the  $x \div y$  dimensions this becomes:

$S_x = \frac{\partial u}{\partial x} \text{ at}$ ,  $S_y = \frac{\partial v}{\partial y} \text{ at}$ . However, because fluids deform continuously when subjected to stress, it is more useful to talk about strain rates. This also has the useful advantage of simplifying the above expressions to:

$$\epsilon_x = \frac{\partial u}{\partial x}, \epsilon_y = \frac{\partial v}{\partial y}, \text{ it is easy to imagine}$$

this fluid element in 3-dimensions with the addition of

$\epsilon_z = \frac{\partial w}{\partial z}$ . If the deforming corner moves away from the origin, then the volume of the fluid element will increase. This means we can define the change in volume as  $\frac{\Delta V}{V} = \sum_{xyz} \epsilon$ . This gets the definition "Volumetric strain rate" and directly follows from linear strain rate. If the fluid element deforms but does not change volume then there must be 2 forces acting on the fluid element.



$\gamma$  = shear force on fluid element

$$\epsilon_{xy} = \frac{1}{2} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)$$

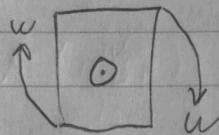
$$\epsilon_{xz} = \frac{1}{2} \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)$$

$$\epsilon_{yz} = \frac{1}{2} \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right)$$

## Fk Page 2

from lecture, we know that vorticity,  $\vec{\omega} = \vec{\nabla} \times \vec{u}$  or  
 $\vec{\omega} = \text{curl}(\vec{u})$

This is simply the nabla vector crossed with the velocity vector and represents a rotation of the fluid about some axis. Vort.



CM 1

$P_{\text{steam}} = \text{Constant}$

Hydrostatic pressure =

$$Pgh = 1000 \cdot 9.8 \cdot 10 \text{ m} = 98000 \text{ Pa}$$

$$\rightarrow P = P_h + P_{\text{amb}} = 199325 \text{ Pa}$$

At ambient T

boiling point from lookup table:  $T_b = 393.3 \text{ K}$

$$T = T_b + 80 = 473.3 \text{ K}$$

$$P = \rho R_{\text{steam}} T = \text{Constant} = 199325 \text{ Pa}$$

$$\rho = 9108 \text{ kg/m}^3$$

$$V_{\text{exit}} = 15 \frac{\text{m}}{\text{s}} = \text{constant}, \quad V_{\text{steam}} = V_e \frac{x}{L}$$

where  $V_e$  is the boundary between the water and steam,  
this creates the ODE  $\dot{x} = V_e \frac{x}{L}$ .

\* See matlab \*

Mass and volume flow rates  
are given by  $\dot{V} = \dot{x} A$ ,  
where  $A = \pi R^2 = \pi \cdot 0.05^2$ .

$$\dot{m} = \dot{V} \rho_{\text{water}} = 1000 \frac{\text{kg}}{\text{m}^3} \cdot 0.05^2 \cdot \dot{x}$$

where  $\dot{x}$  is given from above  
ode

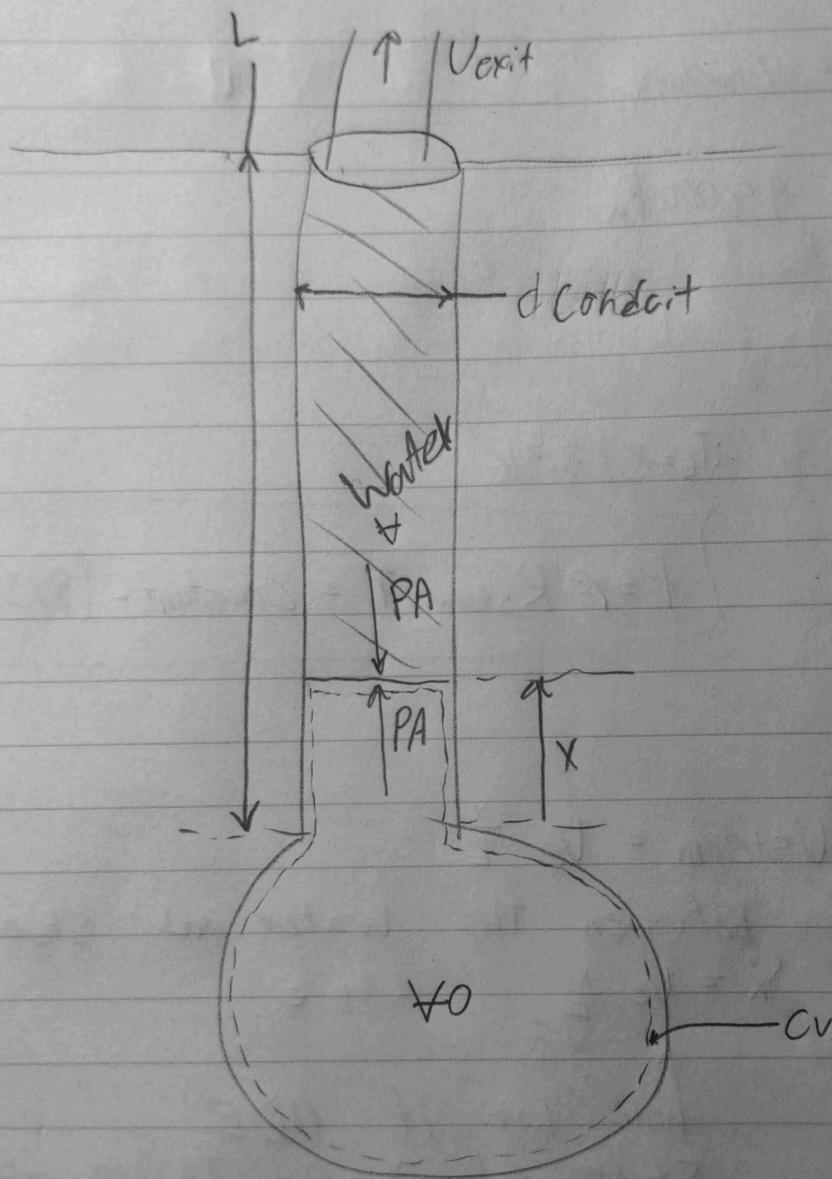
↑  
note how if ODE  
starts at  $x=0$ , It will always  
remain, but it is an unstable  
equilibrium, if pressure increases  
slightly more, the system will  
go off. I model this with  
a small but positive  $x$  initial

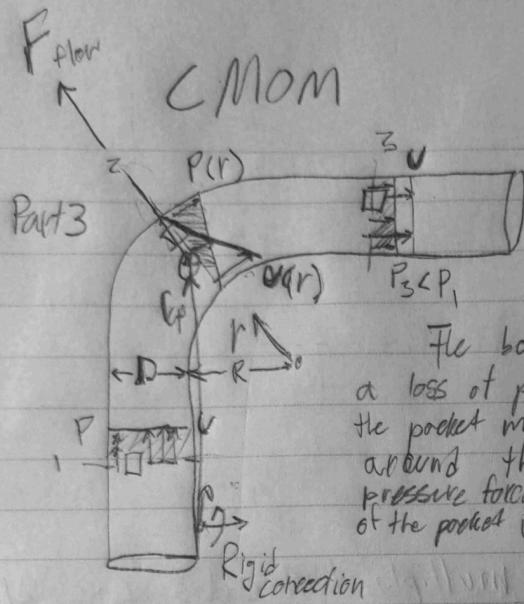
\* Plot in matlab \*

$$P \text{ of } .75 \text{ s is } \approx .023 \frac{\text{kg}}{\text{m}^2}$$

$\dot{x}(.75 \text{ s}) = 9.2407 \approx 10 \text{ m}$  so the show is almost over  
after .75s, this is much shorter than a full old faithful  
show but maybe close to one spout.

CM 1 Page 2

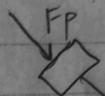




The bend causes a loss of pressure because 2)  
the pocket must be accelerated around the bend by some pressure force, the momentum of the pocket will resist this 3)

Part 2  
1)

no acceleration



ac < centripetal acceleration

no acceleration

Part 2  
We are making the assumptions that there is no boundary condition on velocity, i.e. this is an inviscid flow and there is a slip condition. This means there will be linear velocity functions.

$$\text{Bend: } P(F_p = m a_c = dP \frac{dU}{dr}) = \frac{\rho dA dr U(r)^2}{r}$$

$$\int dP = \int \frac{\rho}{r} U(r)^2 dr = P(R) = \frac{1}{r} \int U(r)^2 dr = P_1 r U(r)^2$$

$$F_f = \frac{d(mv)}{dt} = F_x = \frac{d}{dt} (m \bar{U} \hat{x}), F_y = \frac{d}{dt} (m \bar{U} \hat{y})$$

$$F_f = \frac{d}{dt} QP \quad \frac{d}{dt} m \bar{U} = PQ \bar{U} \quad F_x = PQ \bar{U} \hat{x}, \quad F_y = PQ \bar{U} \hat{y}$$

$$F_{\text{ball bearing}} = (F_x, -F_y)$$

$$M_{\text{ball bearing}} = F_{\text{centrifugal}} \times F_f$$

These forces are created by exchange of momentum between gas and pipe

Part 4) assuming viscous compressible flow,  $P_e$   $T_e$  and therefore

$U_e$  should be solved for using isentropic relations.

$$\text{where } \frac{T_i}{T_e} = 1 + M_a^2 \frac{\gamma-1}{2} \quad \frac{P_i}{P_e} = \frac{T_i}{T_e} \left( \frac{\gamma}{\gamma-1} \right)$$

## NSE 2

$$\rho \left( \frac{\partial u_z}{\partial t} + u_r \frac{\partial u_z}{\partial r} + \frac{u_r}{r} \frac{\partial u_z}{\partial \theta} + u_z \frac{\partial u_z}{\partial z} \right) = - \frac{\partial P}{\partial z} + \left( \frac{1}{r} \frac{\partial (r \tau_{rz})}{\partial r} + \frac{1}{r} \frac{\partial \tau_{rz}}{\partial \theta} + \frac{\partial \tau_{rz}}{\partial z} \right)$$

From class, these go to zero

$$\Rightarrow \frac{\partial P}{\partial z} = \frac{1}{r} \frac{\partial (r \tau_{rz})}{\partial r}$$

$$\tau_{rz} = \mu \frac{\partial u_z}{\partial r}$$

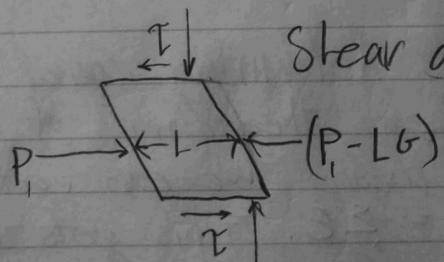
$$\frac{\partial P}{\partial z} = \frac{1}{r} \frac{\partial}{\partial r} \left( \frac{\partial u_z}{\partial r} \right) \quad , \quad \frac{\partial P}{\partial z} = G = \text{pressure gradient}$$

Solve for  
NSE  
PDE

$$u_z = \frac{G}{4\mu} (R^2 - r^2)$$

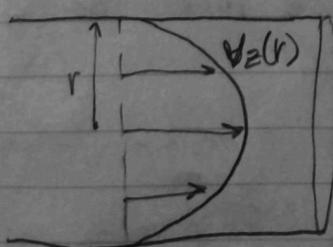
where  $R$  is radius of pipe,  
 $r$  is position in pipe

Using "no slip" boundary condition,  
i.e.  $u_z(R) = 0$  and the assumption  
that the profile of velocity is not  
changing with  $z$  i.e.  $\frac{\partial u_z}{\partial z} = 0$



Shear acting on a fluid element  
and pressure acting such  
that there is a net pressure  
moving the element in the  
(+)z direction.

flow velocity in pipe



$$Q = \bar{u} A = \pi R^2 \frac{1}{2} u_{\max} = \pi R^2 \frac{1}{2} \frac{G R^2}{4\mu}$$

$$= \pi R^4 \frac{1}{8} G \mu$$

$$Q P = \dot{m}$$

NSE PDE

$$\int r \frac{\partial P}{\partial z} dr = \int \frac{\partial}{\partial r} \left( r \frac{\partial u_z}{\partial r} \right) dr$$

$$\frac{\partial P}{\partial z} \int r dr = \mu \int \frac{d}{dr} \left( r \frac{\partial u_z}{\partial r} \right) dr$$

$$C_1 + \frac{\partial P}{\partial z} \frac{r^2}{2} = \mu \left( r \frac{\partial u_z}{\partial r} \right)$$

$$\int \frac{C_1}{r} dr + \int \frac{\partial P}{\partial z} \frac{r}{2} dr = \int \mu \frac{d}{dr} u_z dr$$

$$C_1 \int \frac{1}{r} dr + G \int \frac{r}{2} dr = \mu \int d u_z$$

$$C_1 \ln(r) + G r^2 \frac{1}{4} = \mu u_z + C_2$$

from this integral solve  $C_1$  &  $C_2$  using boundary conditions