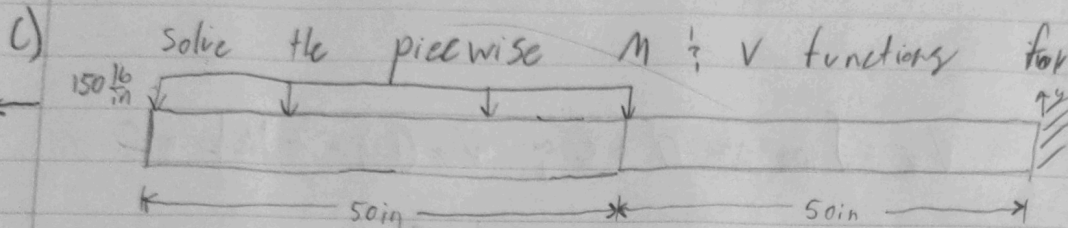
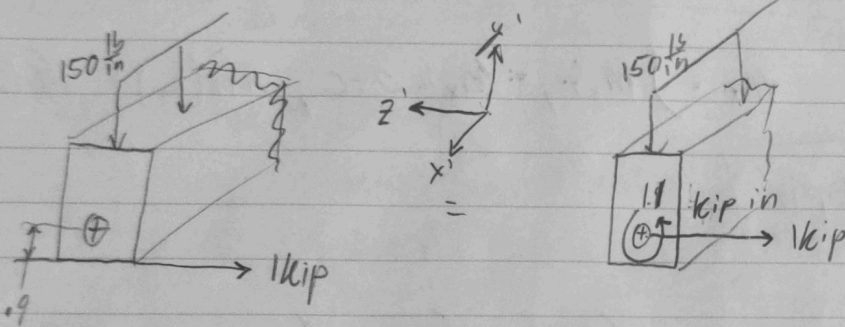


HW5

a) & b) are in Matlab, I wrote a function which computes these values.



$$p_y = \begin{cases} -150 \frac{\text{lb}}{\text{in}} & , x \geq 50 \\ 0 & , x < 50 \end{cases} , \quad p_z = 0 , \quad p_x = 0$$



$$m_y = 0 , \quad m_x = 0 , \quad m_z = 0$$

d) $P_x(L) = 0$, $V_y(L) = 0$, $V_z(L) = -1 \text{ kip}$, $M_x(L) = 1.9 \text{ kip in}$, $M_y(L) = 0$, $M_z(L) = 0$

$$P_x' = -p_x , \quad P_x = 0 + C , \quad P_x(L) = 0 = C , \quad \boxed{P_x = 0}$$

$$V_y' = -p_y , \quad V_y = \int \begin{cases} 150 \frac{\text{lb}}{\text{in}} & , x \geq 50 \\ 0 & , x < 50 \end{cases} = \begin{cases} C_1 + 150 \frac{\text{lb}}{\text{in}} x & , x \geq 50 \\ C_2 & , x < 50 \end{cases}$$

$$V_y(L) = 0 = C_1 + 150 L = C_1 = -150 L , \quad V_y\left(\frac{L}{2}\right) = 150 \frac{\text{lb}}{\text{in}} (x - L) = -150 \frac{\text{lb}}{\text{in}} \frac{L}{2}$$

$$V_y\left(\frac{L}{2}\right) = -150 \frac{\text{lb}}{\text{in}} \frac{L}{2} = C_2 , \quad C_2 = -150 \frac{\text{lb}}{\text{in}} \frac{L}{2}$$

HW5

$$V_y(x) = \begin{cases} 150(x-L), & x \geq 50 \\ -75L, & x < 50 \end{cases}$$

$$V_z' = p_z, \quad V_z = \int p_z = 0 + C, \quad V_z(L) = -1 \text{ kip} = C$$

$$V_z(x) = -1 \text{ kip}$$

$$M_x' = m_x = 0, \quad M_x = \int m_x, \quad M_x = 0 + C, \quad M_x(L) = 1.9 \text{ kip-in} = C$$

$$M_x(x) = 1.9 \text{ kip-in}$$

$$M_y' = -m_y + V_z, \quad M_y = \int m_y + \int V_z = -\int 1 \text{ kip} = -x \text{ kip} + C$$

$$M_y(L) = 0 = -L \text{ kip} + C, \quad C = +L \text{ kip}$$

$$M_y = (L-x) \text{ kip}$$

$$M_z' = -m_z - V_y = \begin{cases} 150(L-x), & x \geq 50 \\ 75L, & x < 50 \end{cases}$$

$$M_z = \int \begin{cases} 150(L-x), & x \geq 50 \\ 75L, & x < 50 \end{cases} = \begin{cases} 150Lx - 75x^2 + C_1, & x \geq 50 \\ 75Lx + C_2, & x < 50 \end{cases}$$

$$M_z(L) = 0 = 150L^2 - 75L^2 + C_1 = 75L^2 + C_1, \quad C_1 = -75L^2$$

HW5

$$M_z \left(\frac{L}{2} \right) = 75L^2 - 75 \frac{L^2}{4} - 75L^2 = \frac{75}{2}L^2 + C_2$$

$$- 75 \left(\frac{L^2}{4} + \frac{L^2}{2} \right) = C_2 = -\frac{3}{4}75L^2 = -\frac{225}{4}L^2$$

$$M_z = \begin{cases} 150Lx - 75x^2 - 75L^2, & x \geq 50 \\ 75Lx - \frac{225}{4}L^2, & x < 50 \end{cases}$$

$$e) \quad \epsilon_{xx} = \frac{P + P^T}{E_1 A^*} - \frac{M_z - M_z^T y}{E_1 I_{zz}^*} + \frac{M_y + M_y^T z}{E_1 I_{yy}^*}$$

$$\sigma_{xx} = E \epsilon_{xx} - E \alpha \Delta T$$

$$E(y) = \begin{cases} 30e6 \text{ psi}, & y < -2 \text{ in} \\ 10e6 \text{ psi}, & y \geq -2 \text{ in} \end{cases}, \quad \alpha(y) = \begin{cases} 6.5e-6, & y < -2 \text{ in} \\ 13e-6, & y \geq -2 \text{ in} \end{cases}$$

$$P^T = \int_A E \alpha \Delta T dA, \quad M_y^T = \int_A E \alpha \Delta T z dA, \quad M_z^T = \int_A E \alpha \Delta T y dA$$

$$P^T = E_1 \alpha_1 \int_{A_1} \Delta T dA_1 + E_2 \alpha_2 \int_{A_2} \Delta T dA_2, \quad \int_{A_1} \Delta T dA_1 = 1.5 \int_{-1}^{1.5} \Delta T dy$$

$$M_y^T = E_1 \alpha_1 \int_{A_1} \Delta T z dA_1 + E_2 \alpha_2 \int_{A_2} \Delta T z dA_2, \quad \int_{A_2} \Delta T dA_2 = 1.5 \int_{-1}^{1.5} \Delta T dy$$

$$M_z^T = E_1 \alpha_1 \int_{A_1} \Delta T y dA_1 + E_2 \alpha_2 \int_{A_2} \Delta T y dA_2$$

$$\text{if } \Delta T = 0 \quad P^T = M_y^T = M_z^T = 0$$

$$\text{if } \Delta T = 10y^2 + y^3 \text{ } ^\circ\text{F}$$

P^T, M_y^T, M_z^T come out as constants, which I have calculated in Matlab

$$u_0' = \frac{P + P^T}{E_1 A^*}$$

$$v_0'' = \frac{(M_z - M_z^T) I_{yy}^* + (M_y + M_y^T) I_{yz}^*}{E_1 (I_{yy}^* I_{zz}^* - I_{yz}^{*2})}$$

$$w_0'' = \frac{(M_y + M_y^T) I_{zz}^* + (M_z - M_z^T) I_{yz}^*}{E_1 (I_{yy}^* I_{zz}^* - I_{yz}^{*2})}$$