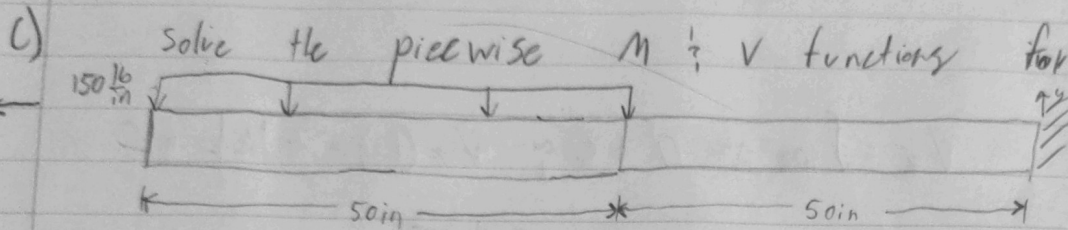
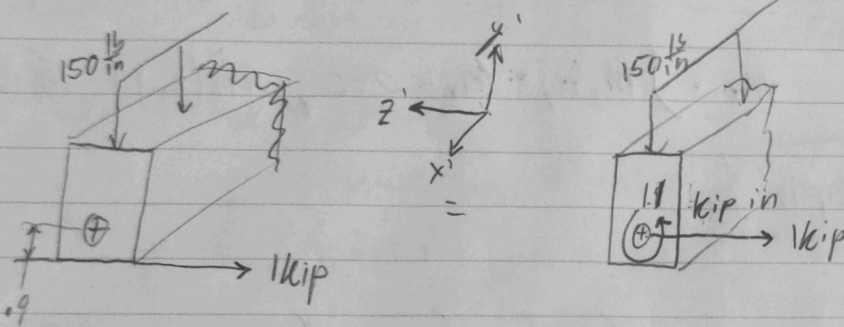


HW5

a) & b) are in Matlab, I wrote a function which computes these values.



$$p_y = \begin{cases} -150 \frac{\text{lb}}{\text{in}} & , x \geq 50 \\ 0 & , x < 50 \end{cases} , \quad p_z = 0 , \quad p_x = 0$$



$$m_y = 0 , \quad m_x = 0 , \quad m_z = 0$$

d) $P_x(L) = 0$, $V_y(L) = 0$, $V_z(L) = -1 \text{ kip}$, $M_x(L) = 1.9 \text{ kip in}$, $M_y(L) = 0$, $M_z(L) = 0$

$$P_x' = -p_x , \quad P_x = 0 + C , \quad P_x(L) = 0 = C , \quad \boxed{P_x = 0}$$

$$V_y' = -p_y , \quad V_y = \int \begin{cases} 150 \frac{\text{lb}}{\text{in}} & , x \geq 50 \\ 0 & , x < 50 \end{cases} = \begin{cases} C_1 + 150 \frac{\text{lb}}{\text{in}} x & , x \geq 50 \\ C_2 & , x < 50 \end{cases}$$

$$V_y(L) = 0 = C_1 + 150 L = C_1 = -150 L , \quad V_y\left(\frac{L}{2}\right) = 150 \frac{\text{lb}}{\text{in}} (x-L) = -150 \frac{\text{lb}}{\text{in}} \frac{L}{2}$$

$$V_y\left(\frac{L}{2}\right) = -150 \frac{\text{lb}}{\text{in}} \frac{L}{2} = C_2 , \quad C_2 = -150 \frac{\text{lb}}{\text{in}} \frac{L}{2}$$

HW5

$$V_y(x) = \begin{cases} 150(x-L), & x \geq 50 \\ -75L, & x < 50 \end{cases}$$

$$V_z' = p_z, \quad V_z = \int p_z = 0 + C, \quad V_z(L) = -1 \text{ kip} = C$$

$$V_z(x) = -1 \text{ kip}$$

$$M_x' = m_x = 0, \quad M_x = \int m_x, \quad M_x = 0 + C, \quad M_x(L) = 1.9 \text{ kip-in} = C$$

$$M_x(x) = 1.9 \text{ kip-in}$$

$$M_y' = -m_y + V_z, \quad M_y = \int m_y + \int V_z = -\int 1 \text{ kip} = -x \text{ kip} + C$$

$$M_y(L) = 0 = -L \text{ kip} + C, \quad C = +L \text{ kip}$$

$$M_y = (L-x) \text{ kip}$$

$$M_z' = -m_z - V_y = \begin{cases} 150(L-x), & x \geq 50 \\ 75L, & x < 50 \end{cases}$$

$$M_z = \int \begin{cases} 150(L-x), & x \geq 50 \\ 75L, & x < 50 \end{cases} = \begin{cases} 150Lx - 75x^2 + C_1, & x \geq 50 \\ 75Lx + C_2, & x < 50 \end{cases}$$

$$M_z(L) = 0 = 150L^2 - 75L^2 + C_1 = 75L^2 + C_1, \quad C_1 = -75L^2$$

HW5

$$M_z \left(\frac{L}{2} \right) = 75L^2 - 75 \frac{L^2}{4} - 75L^2 = \frac{75}{2}L^2 + C_2$$

$$- 75 \left(\frac{L^2}{4} + \frac{L^2}{2} \right) = C_2 = -\frac{3}{4}75L^2 = -\frac{225}{4}L^2$$

$$M_z = \begin{cases} 150Lx - 75x^2 - 75L^2, & x \geq 50 \\ 75Lx - \frac{225}{4}L^2, & x < 50 \end{cases}$$

$$e) \quad \epsilon_{xx} = \frac{P + P^T}{E_1 A^*} - \frac{M_z - M_z^T}{E_1 I_{zz}^*} y + \frac{M_y + M_y^T}{E_1 I_{yy}^*} z$$

$$\sigma_{xx} = E \epsilon_{xx} - E \alpha \Delta T$$

$$E(y) = \begin{cases} 30e6 \text{ psi}, & y < -2 \text{ in} \\ 10e6 \text{ psi}, & y \geq -2 \text{ in} \end{cases}, \quad \alpha(y) = \begin{cases} 6.5e-6, & y < -2 \text{ in} \\ 13e-6, & y \geq -2 \text{ in} \end{cases}$$

$$P^T = \int_A E \alpha \Delta T dA, \quad M_y^T = \int_A E \alpha \Delta T z dA, \quad M_z^T = \int_A E \alpha \Delta T y dA$$

$$P^T = E_1 \alpha_1 \int_{A_1} \Delta T dA_1 + E_2 \alpha_2 \int_{A_2} \Delta T dA_2, \quad \int_{A_1} \Delta T dA_1 = 1.5 \int_{-1}^{1.5} \Delta T dy$$

$$M_y^T = E_1 \alpha_1 \int_{A_1} \Delta T z dA_1 + E_2 \alpha_2 \int_{A_2} \Delta T z dA_2, \quad \int_{A_2} \Delta T dA_2 = 1.5 \int_{-1}^{1.5} \Delta T dy$$

$$M_z^T = E_1 \alpha_1 \int_{A_1} \Delta T y dA_1 + E_2 \alpha_2 \int_{A_2} \Delta T y dA_2$$

$$\text{if } \Delta T = 0 \quad P^T = M_y^T = M_z^T = 0$$

$$\text{if } \Delta T = 10y^2 + y^3 \text{ } ^\circ\text{F}$$

P^T, M_y^T, M_z^T come out as constants, which I have calculated in Matlab

$$u_0' = \frac{P + P^T}{E_1 A^*}$$

$$v_0'' = \frac{(M_z - M_z^T) I_{yy}^* + (M_y + M_y^T) I_{yz}^*}{E_1 (I_{yy}^* I_{zz}^* - I_{yz}^{*2})}$$

$$w_0'' = \frac{(M_y + M_y^T) I_{zz}^* + (M_z - M_z^T) I_{yz}^*}{E_1 (I_{yy}^* I_{zz}^* - I_{yz}^{*2})}$$

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Joshua Oates - HW5 - A331

```
clear all
close all
clc
addpath('C:\joshFunctionsMatlab\')
```

```
global E1 Ei alpha thing
```

problem1

```
Ei = [30e6 10e6];
alpha = [6.e-6 13e-6];
E1 = 10e6;
Ei_E1 = Ei./E1;
```

```
Ai = [1*1.5 2*1.5];
zip = [0 0];
yip = [-2.5 -1];
```

```
b = 1.5;
a1 = 1;
a2 = 2;
```

```
Izoi = [a1^3*b/12 a2^3*b/12];
Iyoi = [a1*b^3/12 a2*b^3/12];
```

```
Iyzoi = [a1*b*(a1^2+b^2)/12 a2*b*(a2^2+b^2)/12];
thing = joshAdvBeam(Ai,yip,zip,Iyoi,Izoi,Iyzoi,Ei_E1,alpha,Ei);
```

```
disp("The location of the modulus weighted centroid in inches is: ( x ,
    "+string(thing.yps)+" , "+string(thing.zps)+" )")
```

The location of the modulus weighted centroid in inches is: (x , -1.9 , 0)

for functions, compute constants

```
global PT MyT MzT
PT = 1.5679e+04;
```

```
MyT = 0;
MzT = 2.1631e+04;

% PT = 6.2840e+05;
% MyT = 0;
% MzT = 6.3424e+05;
```

part e/i

```
xdim = 100;
ydim = 3;
zdim = 1.5;

xn = 100;
yn = 50;
zn = 50;

dx = xdim/xn;
dy = ydim/yn;
dz = zdim/zn;

sigMat1 = zeros(xn+1,yn+1,zn+1);
sigMat2 = zeros(xn+1,yn+1,zn+1);
unwrappedi =1;

for i = 1:xn+1
    for j = 1:yn+1
        for k = 1:zn+1

            x = (i-1)*dx;
            y = (j-1)*dy;
            z = (k-1)*dz;

            y = y-1.1;
            z = z-zdim/2;
            sig = sigxx1(x,y,z);
            sigMat1(i,j,k) = sig;
            SIG1(unwrappedi) = sig;

            sig = sigxx2(x,y,z);
            sigMat2(i,j,k) = sig;
            SIG2(unwrappedi) = sig;

            X(unwrappedi) = x;
            Y(unwrappedi) = y;
            Z(unwrappedi) = z;

            unwrappedi = unwrappedi+1;
        end
    end
end
```

```
% without temp
sigMag1 = abs(sigMat1);
[sigMax1,I1] = max(sigMag1,[],'all');
[i1,j1,k1] = ind2sub(size(sigMag1),I1);
```

```
x1 = (i1-1)*dx;
y1 = (j1-1)*dy;
z1 = (k1-1)*dz;

% y1 = y1+thing.yps;
y1 = y1 - 1.1;
z1 = z1-zdim/2;
```

```
% with temp
sigMag2 = abs(sigMat2);
[sigMax2,I2] = max(sigMag2,[],'all');
[i2,j2,k2] = ind2sub(size(sigMag2),I2);
```

```
x2 = (i2-1)*dx;
y2 = (j2-1)*dy;
z2 = (k2-1)*dz;
```

```
y2 = y2 - 1.1;
z2 = z2-zdim/2;
```

output

```
disp("I calculated the sigxx at many discrete locations in the beam and found
the max to be the following:")
```

```
% without temp %%%%%%%%%
```

```
disp("If the temperature gradient is zero:")
```

```
close all
```

```
disp("Sig Max in psi is: "+string(sigMax1))
```

```
disp("Sig Max in inches occurs at: ( "+string(x1)+" , "+string(y1)+" ,
"+string(z1)+" )")
```

```
% disp("Index: ( "+string(i1)+" , "+string(j1)+" , "+string(k1)+" )")
```

```
figure
```

```
scatter3(X,Y,Z,20,SIG1,'filled')
```

```
colormap('turbo')
```

```
colorbar
```

```
title("No Temp gradient")
```

```
legend('Sigxx')
```

```
xlabel('x')
```

```
ylabel('y')
```

```
zlabel('z')
```

```
axis('equal')
```

```
% with temp %%%%%%%%%
```

```

disp("If the temperature gradient is applied: ")
disp("Sig Max in psi is: "+string(sigMax2))
disp("Sig Max in inches occurs at: ( "+string(x2)+" , "+string(y2)+" , "+string(z2)+" )")
% disp("Index: ( "+string(i2)+" , "+string(j2)+" , "+string(k2)+" )")

```

```

figure
scatter3(X,Y,Z,20,SIG2,'filled')
colormap('turbo')
colorbar
title("Temp gradient")
legend('Sigxx')
xlabel('x')
ylabel('y')
zlabel('z')
axis('equal')

```

I calculated the sigxx at many discrete locations in the beam and found the max to be the following:

If the temperature gradient is zero:

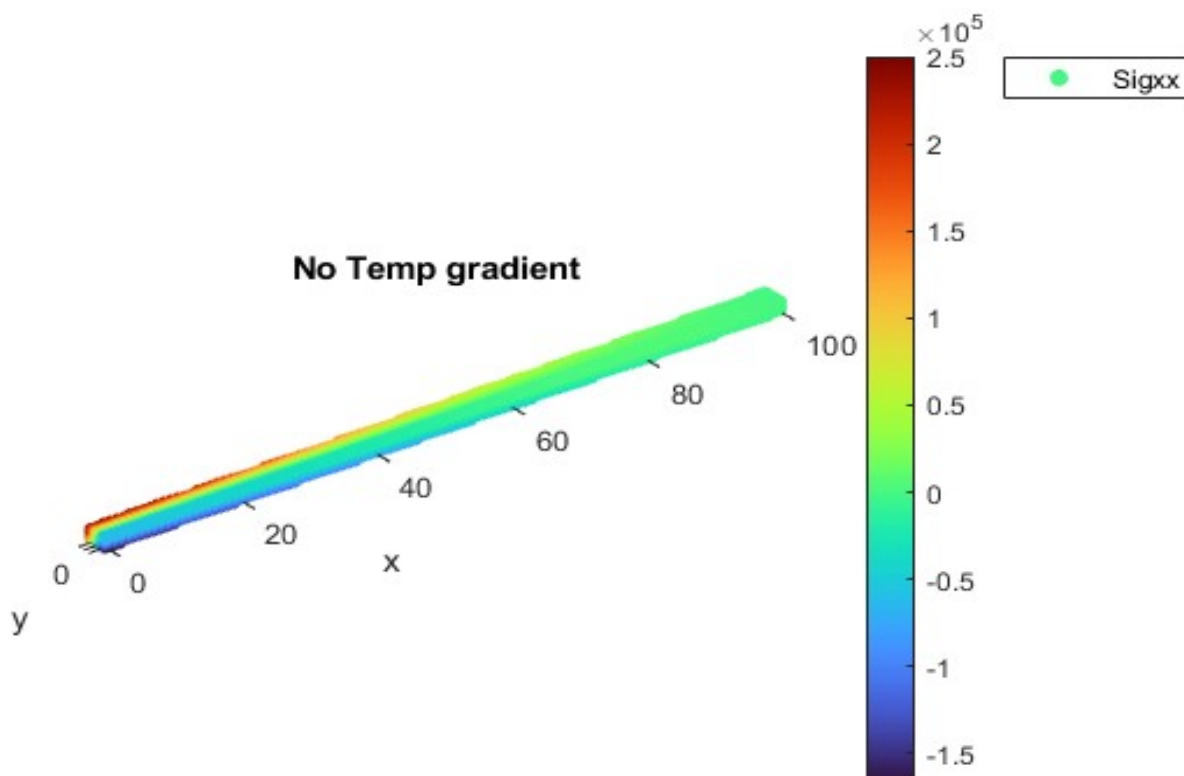
Sig Max in psi is: 250337.9416

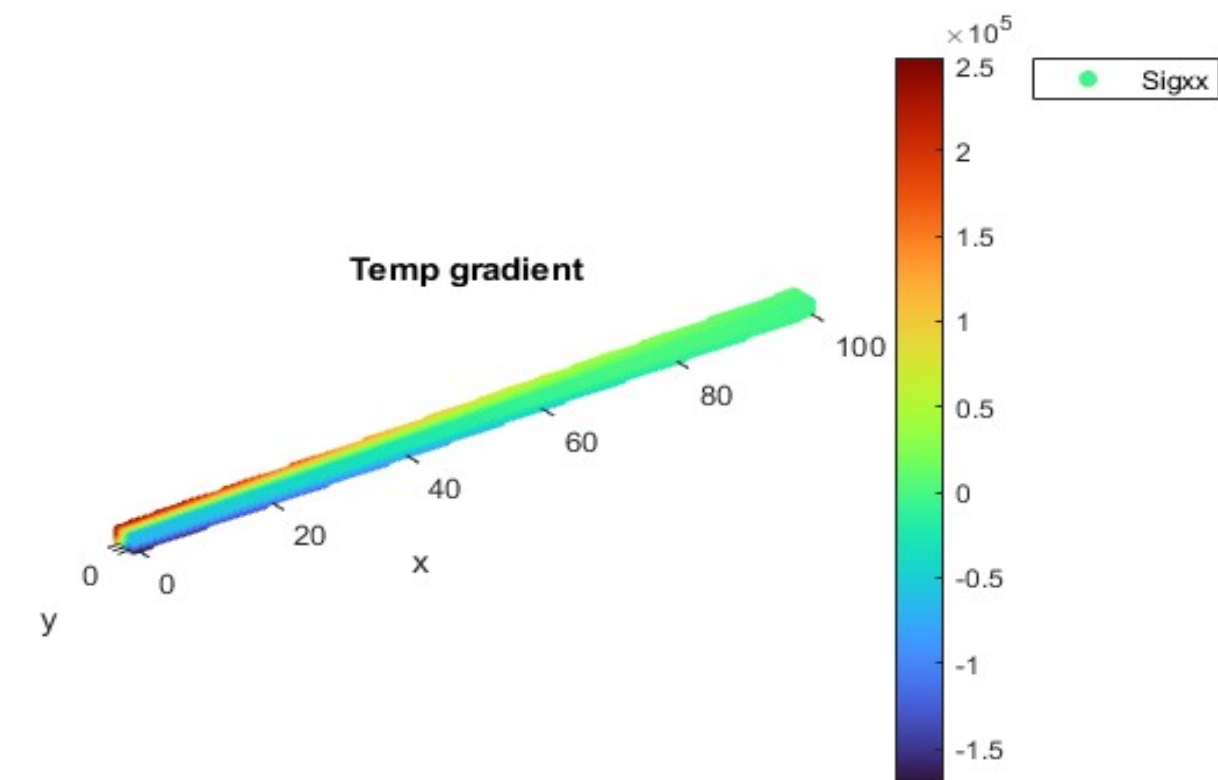
Sig Max in inches occurs at: (0 , 1.9 , 0.75)

If the temperature gradient is applied:

Sig Max in psi is: 254419.6391

Sig Max in inches occurs at: (0 , 1.9 , 0.75)





displacements case1

```
syms x u(x) v(x) w(x)
L = 100;

% symbolic expressions for forces
MySym = (L-x)*1000;
Mz1 = 75*L*x-(225/4)*L^2;
Mz2 = 150*L*x-75*x^2-75*L^2;

% boundary conditions
eqn4 = u(0) == 0;
eqn5 = v(0) == 0;
eqn6 = w(0) == 0;

dv = diff(v,x);
dw = diff(w,x);
eqn7 = dv(0) == 0;
eqn8 = dw(0) == 0;

% no heat, base of beam
eqn1 = diff(u,x) == 0;
eqn2 = diff(w,x,2) == ( (MySym)*thing.Izzs+(Mz1)*thing.Iyzs ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);
```

```

eqn3 = diff(v,x,2) == ( (MySym)*thing.Iyzs+(Mz1)*thing.Iyys ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);

sol1Base = dsolve([eqn1,eqn2,eqn3,eqn4,eqn5,eqn6,eqn7,eqn8]);

% heat, base of beam
eqn1 = diff(u,x) == (PT)/(E1*thing.As);
eqn2 = diff(w,x,2) == ( (MySym+MyT)*thing.Izzs+(Mz1-MzT)*thing.Iyzs ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);
eqn3 = diff(v,x,2) == ( (MySym+MyT)*thing.Iyzs+(Mz1-MzT)*thing.Iyys ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);

sol2Base = dsolve([eqn1,eqn2,eqn3,eqn4,eqn5,eqn6,eqn7,eqn8]);

% no heat, tip of beam
eqn1 = diff(u,x) == 0;
eqn2 = diff(w,x,2) == ( (MySym)*thing.Izzs+(Mz2)*thing.Iyzs ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);
eqn3 = diff(v,x,2) == ( (MySym)*thing.Iyzs+(Mz2)*thing.Iyys ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);

eqn4 = u(L/2) == subs(sol1Base.u,x,L/2);
eqn5 = v(L/2) == subs(sol1Base.v,x,L/2);
eqn6 = w(L/2) == subs(sol1Base.w,x,L/2);

dv1 = diff(v,x);
dw1 = diff(w,x);
dv2 = diff(sol1Base.v);
dw2 = diff(sol1Base.w);

eqn7 = dv1(L/2) == subs(dv2,x,L/2);
eqn8 = dw1(L/2) == subs(dw2,x,L/2);

sol1Tip = dsolve([eqn1,eqn2,eqn3,eqn4,eqn5,eqn6,eqn7,eqn8]);

% heat tip of beam
eqn1 = diff(u,x) == (PT)/(E1*thing.As);
eqn2 = diff(w,x,2) == ( (MySym+MyT)*thing.Izzs+(Mz2-MzT)*thing.Iyzs ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);
eqn3 = diff(v,x,2) == ( (MySym+MyT)*thing.Iyzs+(Mz2-MzT)*thing.Iyys ) /
    E1*(thing.Iyys*thing.Izzs-thing.Iyzs^2);

eqn4 = u(L/2) == subs(sol2Base.u,x,L/2);
eqn5 = v(L/2) == subs(sol2Base.v,x,L/2);
eqn6 = w(L/2) == subs(sol2Base.w,x,L/2);

dv1 = diff(v,x);
dw1 = diff(w,x);
dv2 = diff(sol2Base.v);
dw2 = diff(sol2Base.w);

eqn7 = dv1(L/2) == subs(dv2,x,L/2);

```

```
eqn8 = dw1(L/2) == subs(dw2,x,L/2);

sol2Tip = dsolve([eqn1,eqn2,eqn3,eqn4,eqn5,eqn6,eqn7,eqn8]);

% to matlab function handles
u1base = matlabFunction(sol1Base.u);
w1base = matlabFunction(sol1Base.w);
v1base = matlabFunction(sol1Base.v);

u2base = matlabFunction(sol2Base.u);
w2base = matlabFunction(sol2Base.w);
v2base = matlabFunction(sol2Base.v);

u1tip = matlabFunction(sol1Tip.u);
w1tip = matlabFunction(sol1Tip.w);
v1tip = matlabFunction(sol1Tip.v);

u2tip = matlabFunction(sol2Tip.u);
w2tip = matlabFunction(sol2Tip.w);
v2tip = matlabFunction(sol2Tip.v);
```

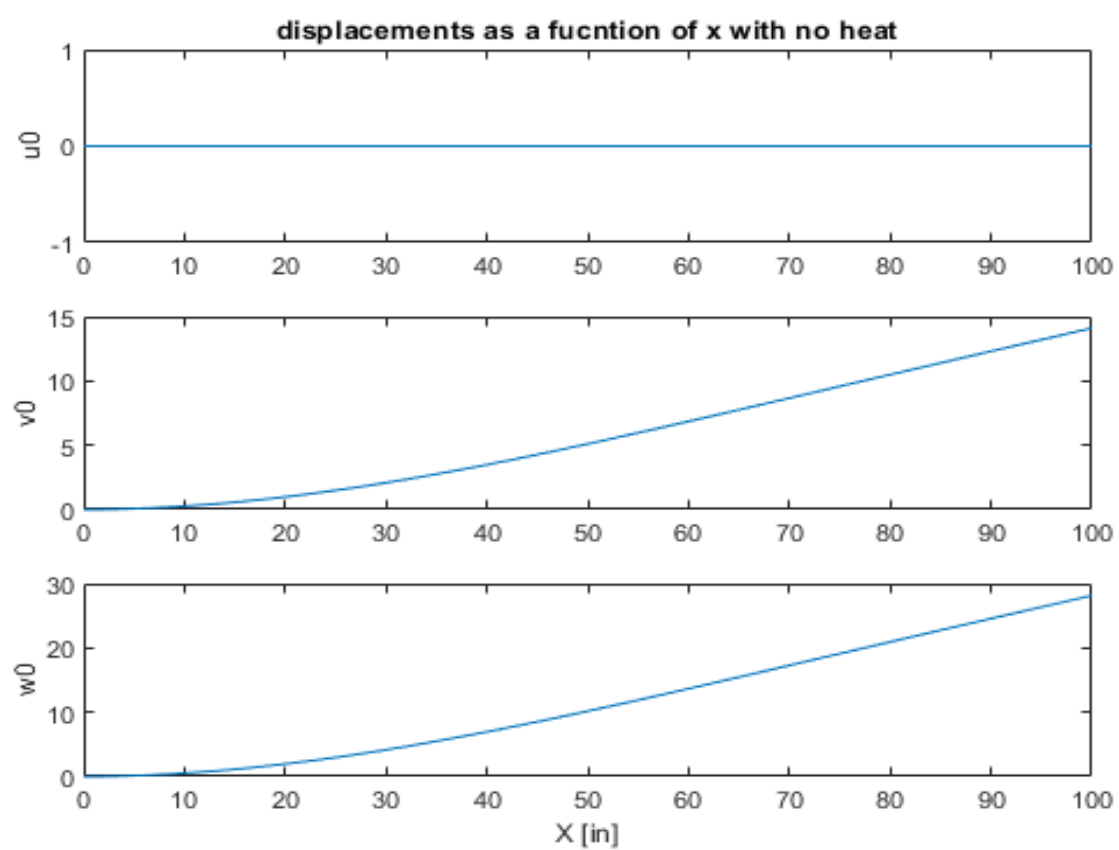
plots of displacements

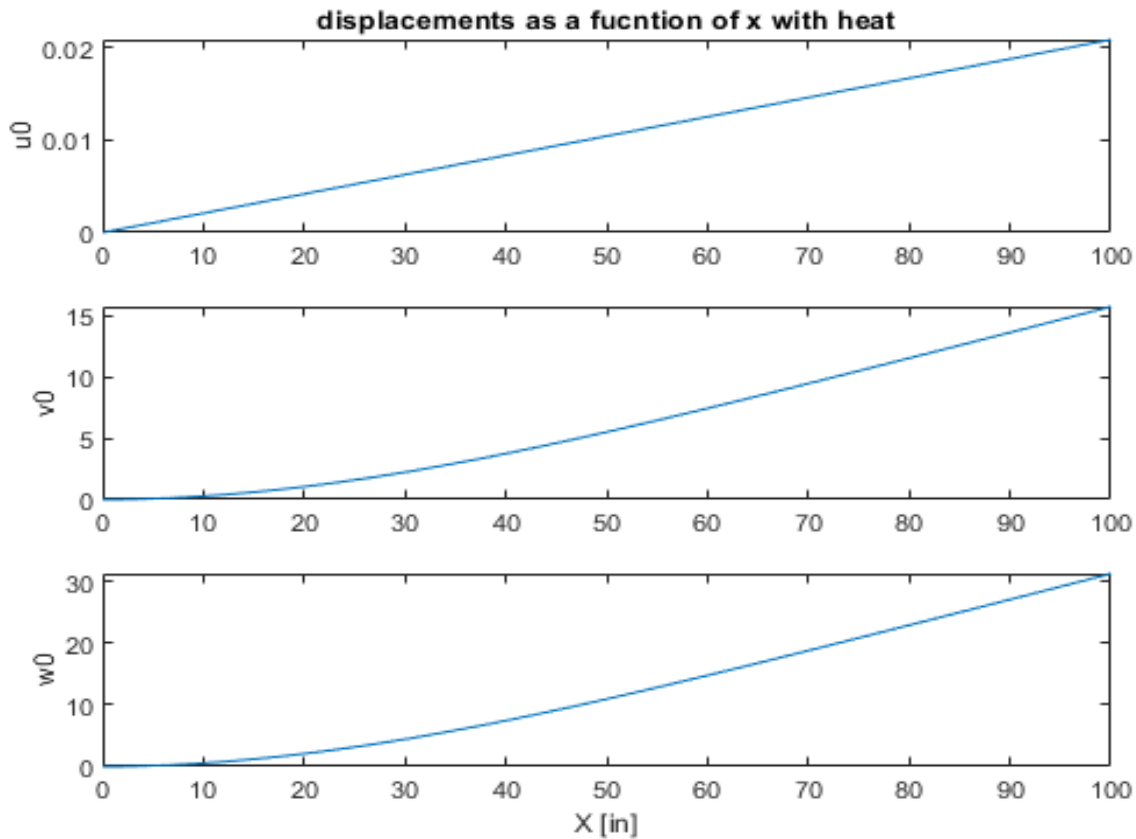
```
Xbase = linspace(0,50);
Xtip = linspace(50,100);

figure
subplot(3,1,1)
plot([Xbase,Xtip],zeros(1,length([Xbase,Xtip])))
title("displacements as a fucntion of x with no heat")
ylabel("u0")
subplot(3,1,2)
plot([Xbase,Xtip],[v1base(Xbase),v1tip(Xtip)])
ylabel("v0")
subplot(3,1,3)
plot([Xbase,Xtip],[w1base(Xbase),w1tip(Xtip)])
ylabel("w0")
xlabel("X [in]")
```

```
figure
subplot(3,1,1)
plot([Xbase,Xtip],[u2base(Xbase),u2tip(Xtip)])
title("displacements as a fucntion of x with heat")
ylabel("u0")
subplot(3,1,2)
plot([Xbase,Xtip],[v2base(Xbase),v2tip(Xtip)])
ylabel("v0")
subplot(3,1,3)
plot([Xbase,Xtip],[w2base(Xbase),w2tip(Xtip)])
ylabel("w0")
xlabel("X [in]")
```

```
% plot([Xbase,Xtip],[ulbase(Xbase),ultip(Xtip)])
```





displacement functions

```
function out = u1vec(x) if x>=50 out = [0,v1tip(x),w1tip(x)]; else out = [0,v1base(x),w1base(x)]; end end
```

```
function out = u2vec(x) if x>=50 out = [u2tip(x),v2tip(x),w2tip(x)]; else out = [u2base(x),v2base(x),w2base(x)]; end end
```

functions

```
% temp gradients
% function out = DT1(y)
% out = 0;
% end
```

```
function out = DT2(y)
out = 10*y^2+y^3;
end
```

```
% z Moments
function out = Mz(x)
L = 100;
if x>=50
    out = 150*L*x-75*x^2-75*L^2;
else
    out = 75*L*x-(225/4)*L^2;
```

```

%      out = 7500*x-562500;
end
end

% y moments
function out = My(x)
L = 100;
out = (L-x)*1000;
end

% P force
function out = P(x)
out = 0;
end

% E and alpha as a function of position
function out = E(y)
if y< -2
    out = 30e6;
else
    out = 10e6;
end
end

function out = alphaFun(y)
if y< -2
    out = 6.5e-6;
else
    out = 13e-6;
end
end

% epsilon functions
function out = epsxx1(x,y,z)
global thing E1
out = (P(x))/(E1*thing.As) - (Mz(x))/(E1*thing.Izxs)*y + My(x)/
(E1*thing.Iyys)*z;
end

function out = epsxx2(x,y,z)
global thing PT MyT MzT E1
out = (P(x)+PT) / (E1*thing.As) - (Mz(x)-MzT) / (E1*thing.Izxs)*y +
(My(x)+MyT) / (E1*thing.Iyys)*z;
end

% sigma functions
function out = sigxx1(x,y,z)
out = E(y)*(epsxx1(x,y,z));
end

function out = sigxx2(x,y,z)

```

```
out = E(y) * (epsxx2(x,y,z) - alphaFun(y) * DT2(y)) ;  
end
```

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```

function [out] =
    joshAdvBeam(Ai,yi_prime,zi_prime,Iyoiyoi,Izoizoi,Iyoizoi,Ei_E1,alphai,Ei)
% this function takes several

arguments
    Ai {mustBeReal}
    yi_prime {mustBeReal}
    zi_prime {mustBeReal}
    Iyoiyoi {mustBeReal}
    Izoizoi {mustBeReal}
    Iyoizoi {mustBeReal}
    Ei_E1 {mustBeReal}
    alphai {mustBeReal} = nan
    Ei {mustBeReal} = nan
end

A = Ai;
yp = yi_prime;
zp = zi_prime;
Iz0 = Izoizoi;
Iy0 = Iyoiyoi;
Iyz0 = Iyoizoi;

n = length(A);
if length(yp) ~= n | length(zp) ~= n | length(Iz0) ~= n | length(Iy0) ~= n
    | length(Iyz0) ~= n | length(Ei_E1) ~= n
    throw(MException('joshAdvBeam:invalidInput','At least one of the input
    vectors is not the correct length'))
end

% Ai*(Ei/E1)
AE_E1 = Ei_E1.*Ai;
% A*
As = sum(AE_E1);

% A*(E/E1)*y'
AE_E1yp = AE_E1.*yp;
% y'*
yps = sum(AE_E1yp)/As;

% Ai*(Ei/E1)*zi'
AE_E1zp = AE_E1.*zp;
% z'*
zps = sum(AE_E1zp)/As;

% YY
% (Ei/E1)*(Iyoiyoi+Ai'*zi'^2)
var1 = (Ei_E1.*(Iy0+A.*zp.^2));

```

```

% I*y'y'
Iyps = sum(var1);
% I*yy = I*y'y' - A*(z')^2
Iys = Iyps - As.*zps.^2;

% zz
var2 = (Ei_El.*(Iz0+A.*yp.^2));
Izps = sum(var2);
Izs = Izps - As.*yps.^2;

% yz
var3 = (Ei_El.*(Iyz0+A.*zps.*yps));
Iyzps = sum(var3);
Iyzs = Iyzps - As.*zps.*yps;

% y and z
y = yp-yps;
z = zp-zps;

out.y = y;
out.z = z;
out.As = As;
out.yps = yps;
out.zps = zps;

% out.Iyyyps = Iyps;
out.Iyyys = Iys;

% out.Izzps = Izps;
out.Izzs = Izs;

% out.Iyzps = Iyzps;
out.Iyzs = Iyzs;

if (~isnan(alphai)) & (~isnan(Ei))

    if length(alphai) ~= n | length(Ei) ~= n
        throw(MException('joshAdvBeam:invalidInput','Either alphai or Ei is
the wrong length'))
    end
    E = Ei;

    EalphaA = E.*alphai.*A;
    EalphaAy = E.*alphai.*A.*y;
    EalphaAz = E.*alphai.*A.*z;

    PT_DT = sum(EalphaA);
    Mz_DT = sum(EalphaAy);
    My_DT = sum(EalphaAz);

    out.PT_DT = PT_DT;
    out.MzT_DT = Mz_DT;
    out.MyT_DT = My_DT;
end

```

end

Error using joshAdvBeam
Invalid argument list. Function requires 7 more input(s).

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```
% constants for HW5
clear all
close all
clc

syms y z
E1 = 30e6;
E2 = 10e6;
a1 = 6.5e-6;
a2 = 13e-6;
DT = 10*y^2+y^3;

PT =
    int(int(E1*a1*DT,y,-1.1,-.1),z,-.75,.75)+int(int(E2*a2*DT,y,-.1,1.9),z,-.75,.75);

MyT =
    int(int(E1*a1*DT*z,y,-1.1,-.1),z,-.75,.75)+int(int(E2*a2*DT*z,y,-.1,1.9),z,-.75,.75);

MzT =
    int(int(E1*a1*DT*y,y,-1.1,-.1),z,-.75,.75)+int(int(E2*a2*DT*y,y,-.1,1.9),z,-.75,.75);

PT = double(vpa(PT));
MyT = double(vpa(MyT));
MzT = double(vpa(MzT));

disp("If the temperature is applied then: ")
disp("PT = "+string(PT)+" lbs")
disp("MyT = "+string(MyT)+" lbs-in")
disp("MzT = "+string(MzT)+" lbs-in")

If the temperature is applied then:
PT = 6284.005 lbs
MyT = 0 lbs-in
MzT = 6342.4433 lbs-in
```

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