

```

clc
clear all
close all
pause('off')

```

## Assignment 3

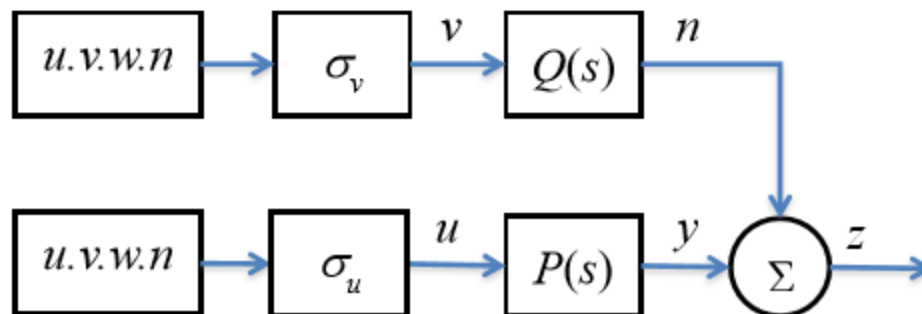
### Japnit Sethi

Two continuous time dynamic systems,  $P(s)$  and  $Q(s)$ , are given by the following transfer functions:

$$P(s) = \frac{60.655s^2 + 1524.4s + 9.674e5}{s^3 + 955.04s^2 + 12870s + 9.674e5}$$

$$Q(s) = \frac{58.214s^2 + 43892s + 4.5964e6}{s^3 + 1105.8s^2 + 44581s + 4.5964e6}$$

As indicated in the block diagram below,  $P(s)$  is excited by a normally distributed white noise signal  $u(t)$  of unknown standard deviation  $\sigma_u$ . The output  $y(t)$  is corrupted by an additive noise signal  $n(t)$  to produce a measurement  $z(t)$ . The noise signal  $n(t)$  is the output of  $Q(s)$ , which is excited by a different normally distributed white noise signal  $v(t)$  of unknown standard deviation  $\sigma_v$ . Both white noise signals are assumed to be generated by independent unity-variance white noise ( $u.v.w.n.$ ) signal generators such as what the Matlab `randn()` function produces. The output  $z(t)$  will be sampled at 2000 Hz; however, both  $P(s)$  and  $Q(s)$  already include analog anti-alias filters so you do not need to design your own.



1. In a first experiment, no signal is applied to  $P(s)$  (i.e.  $u = 0$  and  $n \neq 0$ ). From this data set, you are given that the standard deviation of  $z(t)$  is estimated to be  $\sigma_z = 12$  (this is NOT a dB value!). Determine the approximate standard deviation  $\sigma_v$  of the excitation to the noise filter.

## Solution

We need to find standard deviation of  $v(t)$   $\{\sigma_v\}$  given standard deviation of  $z(t)$   $\{\sigma_z\}$

**Note:** If for example we feed in noise  $v$  with standard deviation  $\sigma_v^* = 1$ , we get a signal output with variance  $k$ , after that we just scale  $\sigma_v^*$  by  $\sigma_z/k$  to get  $\sigma_v$

This is based on the assumption that the noise standard deviation scales with magnitude as it is fed through the transfer function  $Q$

```
% To actually find the magnitude of noise from phi_z to phi_v, we can
% assume the noise standard dev scales with magnitude as we feed it
% through the transfer function Q. If we feed noise v in with standard
% deviation phi_v_star = 1, and get a signal output with variance k,
% then the we just need to scale phi_v_star by phi_z/k to get phi_v.
```

```
fs = 2000;      ts = 1/fs;
```

```
% Defining the Plant Filter
```

```
nump = [0, 60.655, 1524.4, 9.674e+05];
denp = [1, 955.04, 12870, 9.674e+05];
P = tf(nump, denp);
```

```
% Defining the Noise Filter
```

```
numq = [0, 58.214, 43892, 4.5964e+06];
denq = [1, 1105.8, 44571, 4.5964e+06];
Q = tf(numq, denq);
```

```
Sn_measured = 12;          % measured: Sv = Sn
```

```
N = 2^22;
t = ts * [0:N-1];
```

```
Sv_guess = 1;              % Initial guess
v = Sv_guess * randn(1, N);
Sv_check = std(v)
```

```
Sv_check = 1.0004
```

```
n = lsim(Q, v, t);         % generate noise sequence
Sn_estimated = std(n)       % actual
```

```
Sn_estimated = 0.1926
```

```
Sv_estimated = Sn_measured / Sn_estimated    % Estimated Standard Deviation v
```

```
Sv_estimated = 62.3171
```

```
v = Sv_estimated * randn(1, N);  
Sv_check = std(v)
```

```
Sv_check = 62.3284
```

```
n = lsim(Q, v, t);           % generate noise sequence  
Sn_estimated = std(n);       % actual  
Sn_measured
```

```
Sn_measured = 12
```

2. In a second experiment, an excitation signal is applied to  $P(s)$  (i.e.  $u \neq 0$  and  $n \neq 0$ ). The noise standard deviation  $\sigma_n$  is assumed to be the same in this experiment as in the first experiment. Given that the SNR measured at  $z$  is +10 dB, determine the approximate standard deviation of the excitation to the plant  $\sigma_u$  for this condition.

## Solution

Signal-to-noise ratio (SNR) = +10dB  $\implies 20 \cdot \log_{10}(x) = 10 \implies 3.16228$

Noise standard deviation  $\sigma_n = 12$

Magnitude of Signal output  $y = 3.16228 \cdot 12 = 37.947$

Now with knowledge of standard deviation of  $y$ , we can find:

$\sigma_u = ?$

```
% Problem 2
```

```
SNR_desired = 10;      % dB
```

```
Sy_desired = Sn_measured * 10^(SNR_desired/20)
```

```
Sy_desired = 37.9473
```

```
Su_guess = 1           % initial guess
```

```
Su_guess = 1
```

```
u = Su_guess * randn(1, N);
```

```
y = lsim(P, u, t);
Sy_estimated = std(y) % actual
```

```
Sy_estimated = 0.1359
```

```
Su_guess = Sy_desired / Sy_estimated % actual % Required Answer
```

```
Su_guess = 279.1591
```

```
u = Su_guess * randn(1, N);
```

```
y = lsim(P, u, t);
Sy_estimated = std(y)
```

```
Sy_estimated = 38.2195
```

```
SNR_actual = 20*log10(Sy_estimated / Sn_measured)
```

```
SNR_actual = 10.0621
```

```
SNR_desired
```

```
SNR_desired = 10
```

3. Use the Matlab function `fft()` to compute the spectrum of the sampled noise signal  $n$  from problem 1. Also use the Matlab function `pwelch()` to compute the spectrum of the sampled noise signal  $n$  from problem 1. Plot both properly

scaled spectrums on a single axes using dB magnitude and log frequency scales. On the same axes, overlay the frequency response magnitude of the filter  $Q$ . All three curves should overlay fairly closely. Make sure you properly label both the axes and generate an appropriate legend for this figure.

$$\text{abs}\left(\frac{\text{fft}(n)}{\sqrt{\text{Length of Signal } n}}\right)$$

```
% Problem 3
```

```
NOISE_FFT = fft(n) / sqrt(N); % complex
```

```
F = fs/N;
```

```
fr1 = F * [0:N-1];
```

```
nfft = 2^16; % tuning parameter
```

```
wndo = nfft;
```

```
ovlp = nfft/2;
```

```

% fr2 is 0 to fs/2
% NOISE_PWELCH is Power spectral density
[NOISE_PWELCH, fr2] = pwelch(n, wndo, ovlp, nfft, fs);

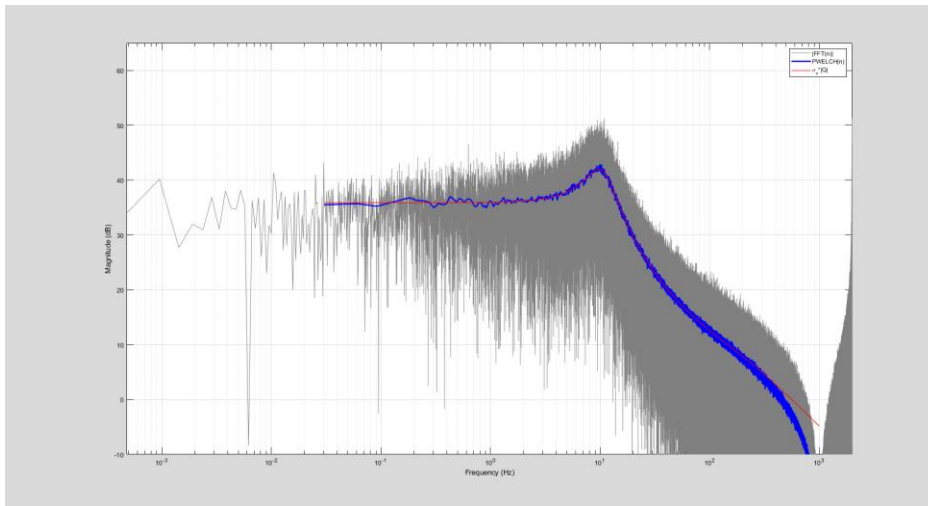
NOISE_PWELCH = NOISE_PWELCH * (fs/2);

Q_MAG = Sv_estimated * squeeze(freqresp(Q, 2*pi*fr2));

figure()
whitebg(gcf, 'w');
subplot(1,1,1);
semilogx(fr1, 20*log10(abs(NOISE_FFT)), 'color', 0.5*[1 1 1])
grid on
hold on
semilogx(fr2, 10*log10(abs(NOISE_PWELCH)), 'b', 'linewidth', 2)
semilogx(fr2, 20*log10(abs(Q_MAG)), 'r', 'linewidth', 1)
xlabel('Frequency (Hz)')
ylabel('Magnitude (dB)')
xlim([fr1(2), max(fr1)])
ylim([-10, 65])
legend('|FFT(n)|', 'PWELCH(n)', '\sigma_v*|Q|')

% In order to maximize the figure window in Windows
set(gcf, 'Units', 'Normalized', 'OuterPosition', [0, 0.04, 1, 0.96]);

```



4. Use the Matlab function `fft()` to compute the spectrum of the sampled output signal  $y$  from problem 2. Also use the Matlab function `pwelch()` to compute the spectrum of the sampled signal  $y$  from problem 2. Plot both properly scaled spectrums on a single axes using dB magnitude and log frequency scales. On the same axes, overlay the frequency response magnitude of the filter  $P$ . All three curves should overlay fairly closely. Make sure you properly label both the axes and generate an appropriate legend for this figure.

```
% Problem 4

Y_FFT = fft(y) / sqrt(N);

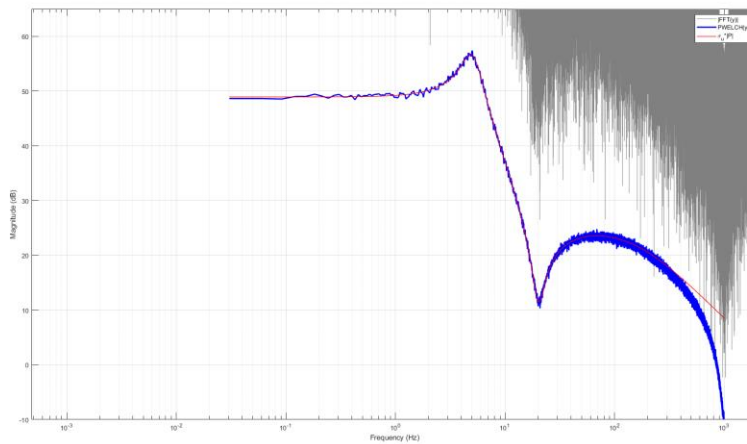
[Y_PWELCH, fr2] = pwelch(y, wndo, ovlp, nfft, fs);

Y_PWELCH = Y_PWELCH * (fs/2);

P_MAG = Su_guess * squeeze(freqresp(P, 2*pi*fr2));

figure()
subplot(1,1,1);
semilogx(fr1, 20*log10(abs(Y_FFT)), 'color', 0.5*[1 1 1])
grid on
hold on
semilogx(fr2, 10*log10(abs(Y_PWELCH)), 'b', 'linewidth', 2)
semilogx(fr2, 20*log10(abs(P_MAG)), 'r', 'linewidth', 1)
xlabel('Frequency (Hz)')
ylabel('Magnitude (dB)')
xlim([fr1(2), max(fr1)])
ylim([-10, 65])
legend('|FFT(y)|', 'PWELCH(y)', '\sigma_u*|P|')

% In order to maximize the figure window in Windows
set(gcf, 'Units', 'Normalized', 'OuterPosition', [0, 0.04, 1, 0.96]);
```



5a. Determine the exact autocorrelation for the following pseudo-random periodic signal:

$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	$x_8$	...
1	1	1	-1	1	-1	-1	$x_0$	$x_1$	...

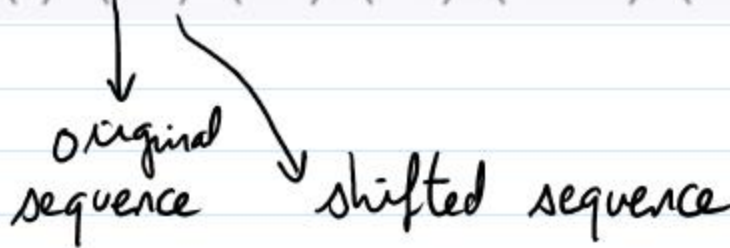
5b. Determine the power of this signal.

5c. Sketch the approximate spectral magnitude of this signal.

**Solution:**

**5a)**

$$\begin{aligned}
 \rho_{xx}(0) &= (1 \times 1) + (1 \times 1) + (1 \times 1) + (-1 \times -1) + (1 \times 1) + (-1 \times -1) + (-1 \times -1) = 7 \\
 \rho_{xx}(1) &= (1 \times 1) + (1 \times 1) + (1 \times -1) + (-1 \times 1) + (1 \times -1) + (-1 \times -1) + (-1 \times 1) = -1 \\
 \rho_{xx}(2) &= (1 \times 1) + (1 \times -1) + (1 \times 1) + (-1 \times -1) + (1 \times -1) + (-1 \times 1) + (-1 \times 1) = -1 \\
 \rho_{xx}(3) &= (1 \times -1) + (1 \times 1) + (1 \times -1) + (-1 \times -1) + (1 \times 1) + (-1 \times 1) + (-1 \times 1) = -1 \\
 \rho_{xx}(4) &= (1 \times 1) + (1 \times -1) + (1 \times -1) + (-1 \times 1) + (1 \times 1) + (-1 \times 1) + (-1 \times -1) = -1 \\
 \rho_{xx}(5) &= (1 \times -1) + (1 \times -1) + (1 \times 1) + (-1 \times 1) + (1 \times 1) + (-1 \times -1) + (-1 \times 1) = -1 \\
 \rho_{xx}(6) &= (1 \times -1) + (1 \times 1) + (1 \times 1) + (-1 \times 1) + (1 \times -1) + (-1 \times 1) + (-1 \times -1) = -1 \\
 \rho_{xx}(7) &= (1 \times 1) + (1 \times 1) + (1 \times 1) + (-1 \times -1) + (1 \times 1) + (-1 \times -1) + (-1 \times -1) = 7
 \end{aligned}$$


  
 original sequence      shifted sequence

$$\sigma_x^2 = R_{xx}(0) = E[x_k^2] = \left( \frac{\rho_{xx}(0)}{N} \right) = \left( \frac{7}{7} \right) = 1$$

5b)

5c)

$$N = 7 \qquad W = e^{-j2\pi/N} = (0.623 - j0.782) \qquad X(mF) = \sum_{n=0}^6 x_n W^{mn}$$

```
% Problem 5
```

```
% Part_A
```

```
xk = [1 1 1 -1 1 -1 -1];
```

```
N = 7;
```



```
col = xk';
row = [xk(end), xk(1:end-1)];
```

```
Y = hankel(col, row)
```

```
Y = 7x7
    1     1     1    -1     1    -1    -1
    1     1    -1     1    -1    -1     1
    1    -1     1    -1    -1     1     1
   -1     1    -1    -1     1     1     1
    1    -1    -1     1     1     1    -1
   -1    -1     1     1     1    -1     1
   -1     1     1     1    -1     1    -1
```

```
Rxy = (1/N) * Y * xk'
```

```
Rxy = 7x1
    1.0000
   -0.1429
   -0.1429
   -0.1429
   -0.1429
   -0.1429
   -0.1429
```

```
% Part C
```

```
W = exp(-1i*2*pi/N)
```

```
W = 0.6235 - 0.7818i
```

```
for m = 1:N
    X(m) = 0;
    for n = 1:N
        X(m) = X(m) + xk(n)*W^((m-1)*(n-1));
    end
end
abs(X)
```

```
ans = 1x7
    1.0000    2.8284    2.8284    2.8284    2.8284    2.8284    2.8284
```