

Name:

Entry No. :

Indian Institute of Technology Delhi
MCL211: Design of Machines
(Semester 1, 2016 – 2017)

MINOR 1

Time: 60 minutes

Max. Marks: 30

You are allowed one A4 size sheet in your own handwriting in the classroom.

- 1) A kinematic slideway design is shown in Figure 1. Three balls are rigidly attached to the slider. Two balls are placed in a V-groove and the third ball is placed on a flat surface.
- a) Explain how a single DOF constraint is provided by a sphere on a flat. (1)
 - b) How many DOFs are constrained when a ball is placed on a V-groove? Explain with proper illustration. (2)
 - c) What is (are) the DOF(s) of the slideway shown in the figure? How the other DOFs are constrained. Explain with proper illustration? (3)
 - d) What will happen if the third ball is placed in another V-groove? Explain how exact-constraint design is better than overconstraint design. (3)
 - e) Design a support using balls so that an object can move only in a plane. What is the DOFs required and what is the minimum number of balls required to achieve the required DOFs? Explain with suitable sketches and drawings. (3)

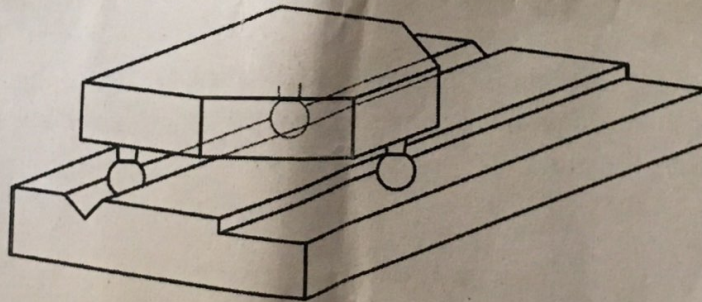


Figure 1

Entry No. :

- | F_a/C_0 | e | $F_a/(VF_r) \leq e$ | | $F_a/(VF_r) > e$ | |
|-----------|------|---------------------|-------|------------------|-------|
| | | X_1 | Y_1 | X_2 | Y_2 |
| 0.084 | 0.28 | 1.00 | 0 | 0.56 | 1.55 |
| 0.110 | 0.30 | 1.00 | 0 | 0.56 | 1.45 |
| 0.17 | 0.34 | 1.00 | 0 | 0.56 | 1.31 |
| 0.28 | 0.38 | 1.00 | 0 | 0.56 | 1.15 |
| 0.42 | 0.42 | 1.00 | 0 | 0.56 | 1.04 |
| 0.56 | 0.44 | 1.00 | 0 | 0.56 | 1.00 |

-
- Note spacers

This technical drawing shows a cross-section of a mechanical assembly. A central shaft with a longitudinal hole is supported by two I-beam structures. The shaft is secured to the I-beams using bolts and washers. The drawing is a symmetrical cross-section, with a dashed centerline indicating the axis of symmetry.

Figure 4.2