

Minor-I Examination on Control Theory and Applications (MCI.212)

$$TF = \frac{1}{\left(\frac{1}{R} + CS\right)R}$$

$$= \frac{1}{1 + CRS}$$

Full Marks: 20
Time: 1 hour

Problem-1

A lumped-parameter model of an electromechanical system is shown in figure-1, where the coil is modelled by its resistance R and inductance L and a current $i(t)$ is driven through it when subject to a time varying e.m.f. $e(t)$, 't' being the time. The coil is placed between the poles of a stationary permanent magnet (N-S). So the coil experiences a force F_c , which is supposed to be proportional to the coil current such that $F_c = K_c * i(t)$, K_c being the coil constant. Under the influence of the force, the coil moves and so a back e.m.f. is also induced in the coil and is given by $E_b(t) = K_b dx(t)/dt$, where K_b is the back e.m.f. constant and $x(t)$ is the motion of the coil with respect to the fixed magnetic poles. This force on the coil, which is on a core, is utilized to excite a mechanical system, represented by its mass M , stiffness K and a viscous damping constant C , where $F_d(t)$ is any time varying disturbance force acting on the system.

(a) Write the equations in the Laplace domain and draw the block diagram of the electro-mechanical system to show how the inputs $E(s)$ and $F_d(s)$ generate the displacement $X(s)$ of the mass.

(4+6)

(b) Find the transfer function $X(s)/E(s)$, considering $F_d(s) = 0$ (5)

(c) Find the Transfer function $X(s)/F_d(s)$, considering $E(s) = 0$ (5)

$E(s)$, $F_d(s)$, $X(s)$ are the Laplace Transforms of the corresponding terms.

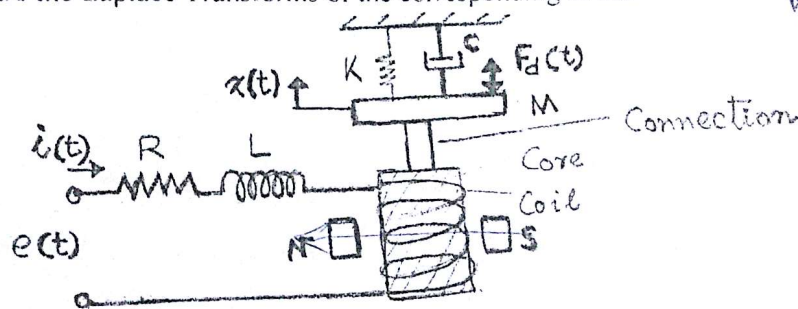


Figure-1: Electromechanical System

Problem-2

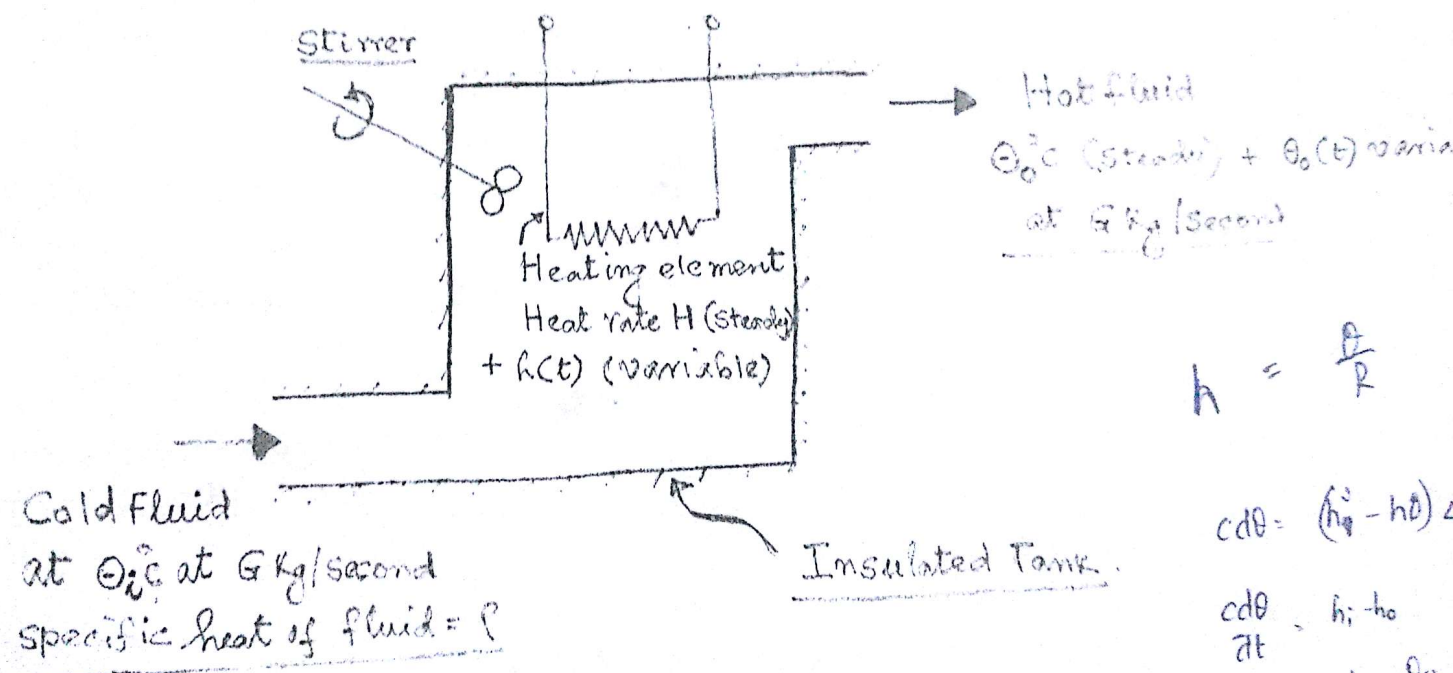
Figure-2 shows the schematic diagram of a thermal system, an insulated fluid heater, which is initially in the steady state, gets a fluid (of specific heat p) at a flow rate of G Kg/second and at a constant temperature Θ_i , heats it with the heat added by a heating element at a constant rate H and discharges fluid (at a rate G Kg/second) at a temperature Θ_o . A stirrer is used to ensure that the fluid is heated uniformly such that the temperature of the fluid everywhere inside the tank is Θ_o . Suppose that the heat input from the heating element changes with respect to time, and at any instant 't' it is given by $H + h(t)$ and all other conditions remain same. The temperature of the outgoing fluid also undergoes a change and, at the instant 't' it is given by $\Theta_o + \theta_o(t)$.

P.T.O.

(a) Supposing that the heat capacitance of the system as $C = 503000 \text{ Joule/}^{\circ}\text{C}$ and the resistance of the system as $R = 0.01^{\circ}\text{C/J/second}$, find out the transfer function between the output $\theta_o(s)$ and the input $h(s)$, where $\theta_o(s)$ and $h(s)$ are the Laplace transforms of $\theta_o(t)$ and $h(t)$ respectively. (5)

(b) Draw an equivalent op-amp circuit to simulate the same transfer function between the output voltage $E_o(s)$ and input voltage $E_i(s)$. Give a set of possible values of the electrical elements (resistance, capacitance) for this purpose. (3+2)

$C = m \rho$



$$h = \frac{P}{R}$$

$$C d\theta = (h_i - h_o) \Delta t$$

$$C \frac{d\theta}{dt} = h_i - h_o = h_i - \frac{\theta_o}{R}$$

$$C (\theta_o + \theta(t) - \theta_i) = (H + h(t)) \Delta t$$

$$C \left(\frac{d\theta(t)}{dt} \right) = \frac{\Delta h}{\Delta t}$$