Jardel Metodos Numericos Unidade 1 Semana 2

October 6, 2020

**

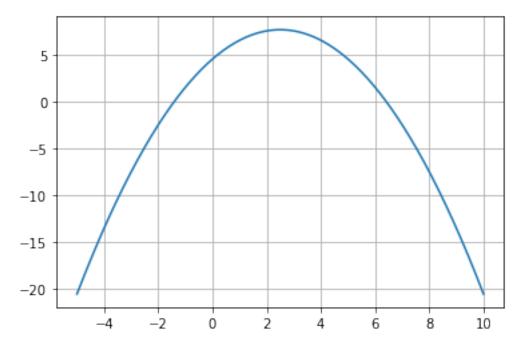
```
Disciplina:** Métodos Numéricos
    Semestre:** 2020.2
    Aluno:** Jardel Brandon de Araujo Regis
    Mátricula:** 201621250014
    2ª Unidade:** RAÍZES E OTIMIZAÇÃO
[1]: import scipy
     import numpy as np
     import scipy.optimize as opt
     import pandas as pd
     import matplotlib.pyplot as plt
     %matplotlib inline
     from mpmath import *
     from sympy import *
     from itertools import *
[2]: #funções auxiliares
     erro_total = lambda valor_verdadeiro, aproximacao: valor_verdadeiro -u
     →aproximacao
     erro_relativo_fracionario = lambda valor_verdadeiro, aproximacao:
      →(valor_verdadeiro - aproximacao) / valor_verdadeiro
     erro_relativo_percentual = lambda valor_verdadeiro, aproximacao:
     →(valor_verdadeiro - aproximacao) / valor_verdadeiro * 100
     def imprimir_tabela(dados, index = None):
```

```
pd.set_option("display.precision", 20)
df = pd.DataFrame(dados, index)
print(df.to_string())
```

0.0.1 Problema 1

$$f(x) = -0.5x^2 + 2.5x + 4.5$$

a)
[3]: f = lambda x: -0.5 * x ** 2 + 2.5 * x + 4.5
x = np.linspace(-5, 10,10000)
plt.plot(x,f(x))
plt.grid(True)



(-1.40512483795333, 6.40512483795333)

```
c)
[5]: def bissecao(funcao, x inicial, x final, ITERACOES = np.inf, TOLERANCIA = np.
      →NINF):
         ponto_medio = (x_inicial + x_final) / 2
         if abs(x_final - x_inicial) < TOLERANCIA or funcao(ponto_medio) == 0 or_{\sqcup}
      →bissecao.counter == ITERACOES:
                 bissecao.counter = 0
                 return [ponto medio]
         else: bissecao.counter += 1
         if funcao(ponto_medio) * funcao(x_inicial) < 0:</pre>
             return [ponto_medio] + bissecao(funcao, x_inicial, ponto_medio,__
      →ITERACOES, TOLERANCIA)
         else:
             return [ponto_medio] + bissecao(funcao, ponto_medio, x_final,_
      →ITERACOES, TOLERANCIA)
     bissecao.counter = 0
[6]: x_i = 5
     x u = 10
     iteracoes = 3
     valores = bissecao(f, x_i, x_u, iteracoes)
```

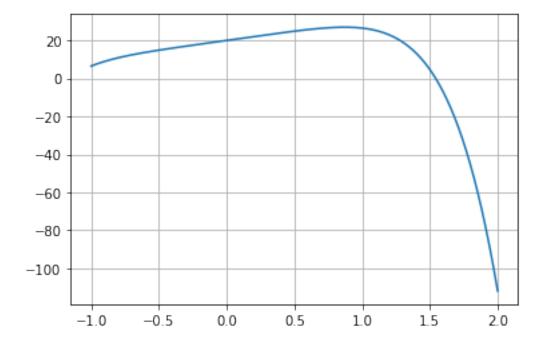
```
Erro total
                                           Erro Fracionario
       Raiz maior valor_i
                                                            Erro
Percentual
0 6.40512483795333
                 7.5000
                          1.09487516204667
                                          0.145983354939556
14.5983354939556
1 6.40512483795333
                  -2.48199740725323
2 6.40512483795333
                  6.8750 0.469875162046673 0.0683454781158797
6.83454781158797
```

3 6.40512483795333 6.5625 0.157375162046673 0.0239809770737787 2.39809770737787

0.0.2 Problema 2

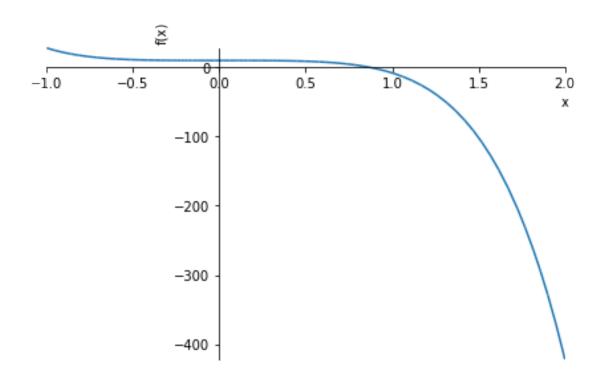
$$f(x) = -2X^6 - 1.5x^4 + 10x + 20$$

```
[7]: f = lambda x: -2 * x ** 6 - 1.5 * x ** 4 + 10 * x + 20 
x = np.linspace(-1, 2,10000) 
plt.plot(x,f(x)) 
plt.grid(True)
```



```
[8]: x = symbols('x')
f = lambda x: -2 * x ** 6 - 1.5 * x ** 4 + 10 * x + 20
derivada = diff(f(x))
print(derivada)
plot(derivada, (x, -1, 2))
```

-12*x**5 - 6.0*x**3 + 10



[8]: <sympy.plotting.plot.Plot at 0x221f4e95848>

```
[9]: x_i = 0
x_u = 1

f = lambdify(x, derivada, 'numpy')
valores = bissecao(f, x_i, x_u, iteracoes, 0.05)
print(valores)
```

[0.5, 0.75, 0.875, 0.8125]

0.0.3 Problema 3

```
falsa_posicao.counter = 0
    return estimativas

if(funcao_ponto_inicial * funcao_ponto_estimado > 0):
        x_inicial = estimativas[falsa_posicao.counter]
    else:
        x_final = estimativas[falsa_posicao.counter]
    falsa_posicao.counter += 1
    falsa_posicao.counter = 0
    return estimativas

falsa_posicao.counter = 0
```

0.0.4 Testando o método da falsa posição para o problema 1 letra c)

```
[11]: f = lambda x: -0.5 * x ** 2 + 2.5 * x + 4.5
     x_i = 5
     x_u = 10
     iteracoes = 3
     tolerancia = np.inf
     valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
     print(valores)
     erros_totais = [erro_total(valor, SEGUNDA_RAIZ) for valor in valores]
     erros_relativos_fracionarios = [erro_relativo_fracionario(valor, SEGUNDA_RAIZ)_
      →for valor in valores]
     erros_relativos_percentuais = [erro_relativo_percentual(valor, SEGUNDA_RAIZ)_
      →for valor in valores]
     tabela = {'Raiz maior': SEGUNDA RAIZ,
                'valor i':
                           valores,
                'Erro total':
                                     erros_totais,
                'Erro Fracionario': erros_relativos_fracionarios,
                'Erro Percentual': erros_relativos_percentuais}
     imprimir_tabela(tabela)
```

```
[5.9, 6.238532110091742, 6.351836734693878]

Raiz maior valor_i Erro total Erro
Fracionario Erro Percentual

0 6.40512483795333 5.900000000000005527 -0.505124837953327
-0.0856143793141231 -8.56143793141231

1 6.40512483795333 6.23853211009174213331 -0.166592727861585
-0.0267038343189893 -2.67038343189893

2 6.40512483795333 6.35183673469387777288 -0.0532881032594492
```

-0.00838940065452066 -0.838940065452066

Como pode-se observar, o metódo da falsa posição retornou um valor mais aproximado do real, com 1 repetição a menos, de acordo com a tabela de erros apresentadas

0.0.5 Testando o método da falsa posição para o problema 2

```
[12]: f = lambda x: -12 * x ** 5 - 6.0 * x ** 3 + 10

x_i = 0
x_u = 1
iteracoes = np.inf
tolerancia = 0.05

valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
print(valores)
```

[0.555555555555566, 0.7823501604757047, 0.8500227697940591, 0.8665353042945969, 0.8703139832359249, 0.8711651152704326, 0.8713561353559485, 0.8713989710953532, 0.8714085751329356, 0.871410728328975, 0.8714112110645322, 0.8714113192911553, 0.8714113435549503, 0.8714113489947548, 0.871411350214328, 0.8714113504877493, 0.8714113505490488, 0.8714113505627918, 0.871411350565873, 0.8714113505667632, 0.8714113505667633, 0.8714113505667633, 0.8714113505667632, 0.8714113505667633]

Como é possível observar, para atingir uma tolerância de erro de 5%, foram necessárias somente duas iterações, de tal forma que esse método para essa equação foi melhor que o método da bisseção

0.0.6 Testando o método da falsa posição para o exemplo 2 da nota de aula

$$e^x = x + 2$$

```
valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
print(valores)
```

```
[-1.7615941559557646, -1.8402501723136198, -1.841389489184834, -1.8414054342273545, -1.8414056572726762, -1.8414056603926976, -1.8414056604363414, -1.841405660436952, -1.8414056604369604, -1.8414056604369609]
```

0.0.7 Testando o método da falsa posição para o exemplo 3 da nota de aula

$$\sqrt{x} = \cos(x)$$

```
[16]: def f(x): return np.cos(x) - np.sqrt(x)
[17]: vp = opt.root_scalar(f,method='bisect',bracket=[0,1], xtol=1e-40).root
    r = []
```

```
for i in range(1,7):
    x = opt.root_scalar(f,method='bisect',bracket=[0,1], maxiter=i).root
    r.append(x)
    e.append(np.around(np.absolute(x - vp) * 100 / 2, decimals=2))
```

import pandas as pd
pd.DataFrame({'Iterações': range(0,6), 'Raiz': r, 'Erro':e}).

→set_index('Iterações')

[17]: Raiz Erro
Iterações
0 0.500000 7.0899999999999985789
1 0.500000 7.089999999999985789

e = []

2 0.625000 0.8399999999999996891 3 0.625000 0.83999999999999998891 4 0.625000 0.8399999999999998891

5 0.640625 0.050000000000000278

```
[18]: x_i = 0
x_u = 1
iteracoes = 7
tolerancia = np.inf

valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
print(valores)

erros_totais = [erro_total(valor, SEGUNDA_RAIZ) for valor in valores]
erros_relativos_fracionarios = [erro_relativo_fracionario(valor, SEGUNDA_RAIZ)_
→for valor in valores]
```

[0.6850733573260451, 0.6503949801283647, 0.6435565520339048, 0.6421098575945017, 0.6417994835090949, 0.641732697569524, 0.6417183174755584]

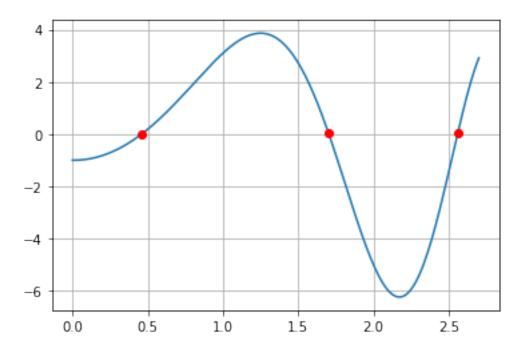
```
Raiz maior
                                    valor_i
                                                     Erro total
                                                                  Erro
Fracionario
               Erro Percentual
0 \quad 6.40512483795333 \quad 0.68507335732604512923 \quad -5.72005148062728
-8.34954595658718 -834.954595658718
1 \quad 6.40512483795333 \quad 0.65039498012836471919 \quad -5.75472985782496
-8.84805392669111 -884.805392669111
2 6.40512483795333 0.64355655203390482733 -5.76156828591942
-8.95269928914636 -895.269928914636
3 6.40512483795333 0.64210985759450167620 -5.76301498035883
-8.97512304506346 -897.512304506346
4 6.40512483795333 0.64179948350909488131 -5.76332535444423
-8.97994701231722 -897.994701231722
5 6.40512483795333 0.64173269756952400211 -5.76339214038380
-8.98098563811985 -898.098563811985
6 6.40512483795333 0.64171831747555840852 -5.76340652047777
-8.98120929935475 -898.120929935475
```

0.0.8 Testando o método da falsa posição para o exemplo 4 da nota de aula

$$f(x) = 5\sin(x^2) - \exp\left(\frac{x}{10}\right)$$

```
[19]: def f(x): return 5 * np.sin(x ** 2) - np.exp(x/10)

[20]: x = np.linspace(0,2.7,200)
    plt.plot(x,f(x))
    plt.plot([0.46, 1.7, 2.56], [f(0.46), f(1.7), f(2.56)], 'o', color='r')
    plt.grid(True)
```



```
np.sign(f(1.7) * f(1.8))
      np.sign(f(2.5) * f(2.6))
[21]: -1.0
[22]: print('1ª raiz positiva: ',opt.root_scalar(f,method='bisect', bracket=[0.4,0.
       \hookrightarrow5],xtol=1e-5).root)
      print('2ª raiz positiva: ',opt.root_scalar(f,method='bisect', bracket=[1.7,1.
       \rightarrow8],xtol=1e-5).root)
      print('3ª raiz positiva: ',opt.root_scalar(f,method='bisect', bracket=[2.5,2.
       \hookrightarrow6],xtol=1e-5).root)
      1^{\underline{a}} raiz positiva: 0.459307861328125
      2^{\underline{a}} raiz positiva: 1.703570556640625
      3^{\underline{a}} raiz positiva: 2.558209228515625
[23]: x_i = 0.4
      x_u = 0.5
      tolerancia = 1e-5
      valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
      print(valores)
      x_i = 1.7
      x_u = 1.8
```

[21]: np.sign(f(0.4) * f(0.5))

```
valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
print(valores)

x_i = 2.5
x_u = 2.6

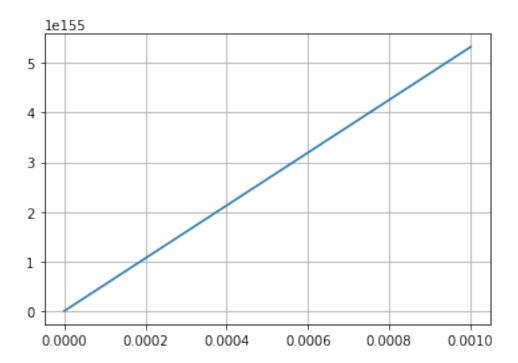
valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
print(valores)
```

[0.45679945731437466, 0.4592075958565898, 0.45930181111377394, 0.4593054847551961, 0.4593056279789401, 0.45930563356275533, 0.4593056337804496] [1.703400048170842, 1.7035660686767091, 1.7035740592360833, 1.70357444354882, 1.7035744620320366, 1.7035744629209708, 1.703574462963723] [2.5592348966927574, 2.5582261535765185, 2.5582128138589724, 2.558212641075543, 2.558212638838176, 2.5582126388092044, 2.55821263880829]

0.0.9 Testando o método da falsa posição para o exemplo 5 da nota de aula

$$I_d = I_R \left[exp\left(\frac{v_d}{v_d}\right) - 1 \right]$$

C:\Users\jarde\Anaconda3\lib\site-packages\ipykernel_launcher.py:1:
RuntimeWarning: overflow encountered in exp
 """Entry point for launching an IPython kernel.



```
C:\Users\jarde\Anaconda3\lib\site-packages\ipykernel_launcher.py:1:
RuntimeWarning: overflow encountered in exp
    """Entry point for launching an IPython kernel.

[26]: 6.495182024082167e-05

[27]: def f(vd, vs, R): return 1e-12 * np.exp(((1.60217653e-19 * vd) / (4.
    -1419509e-25))-1) - ((vs - vd)/(R))

[28]: vs = 300e-3
    R = 1e+3
    opt.root_scalar(f, args=(vs,R), method='bisect', bracket=[0,0.1]).root

C:\Users\jarde\Anaconda3\lib\site-packages\ipykernel_launcher.py:1:
RuntimeWarning: overflow encountered in exp
    """Entry point for launching an IPython kernel.

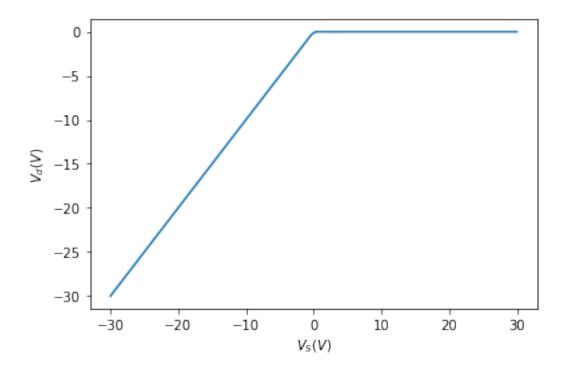
[28]: 5.304607184370981e-05
```

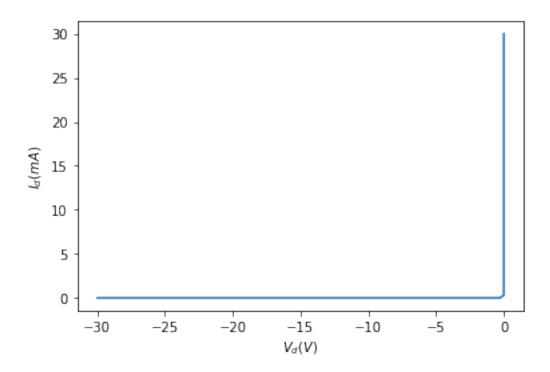
[26]: opt.root_scalar(fa,method='bisect', bracket=[0,0.1]).root

[29]: vs = np.array([30, 3, 3, 300e-3, -300e-3, -30, -30])

R = np.array([1e+3, 1e+3, 1e+4, 1e+3, 1e+3, 1e+3, 1e+4])

```
[30]: vd = []
      for i in range(len(vs)):
         Vs = vs[i]
          r = R[i]
          if Vs>0:
              a,b = 0,.1
          else:
              a,b = -32,.1
          x = opt.root_scalar(f, args=(Vs,r), method='bisect', bracket=[a,b]).root
          vd.append(x)
      vd
     C:\Users\jarde\Anaconda3\lib\site-packages\ipykernel_launcher.py:1:
     RuntimeWarning: overflow encountered in exp
       """Entry point for launching an IPython kernel.
[30]: [6.495182024082167e-05,
      5.899912648601458e-05,
       5.3046482207719243e-05,
       5.304607184370981e-05,
       -0.29999999999072,
       -30.00000000000098,
       -30.0000000000098]
[31]: plt.plot(vs,vd)
      plt.xlabel('$V_S (V)$')
      plt.ylabel('$V_d (V)$')
[31]: Text(0, 0.5, '$V_d (V)$')
```





0.0.10 Problema 4

$$f(x) = 2\sin(\sqrt{x}) - x$$

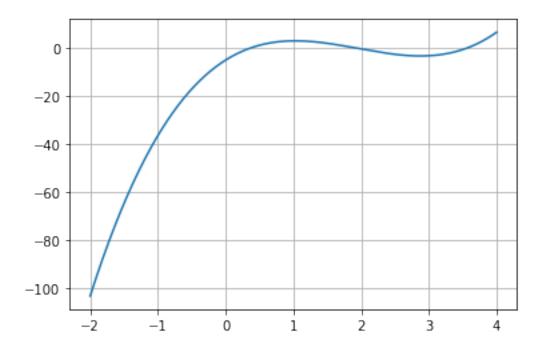
```
[34]: f = lambda x: 2 * np.sin(np.sqrt(x)) - x
```

[35]: 0.768018090595916

0.0.11 Problema 5

$$f(x) = 2x^3 - 11.7x^2 + 17.7x - 5$$

```
a)
[36]: f = lambda x: 2 * x ** 3 - 11.7 * x ** 2 + 17.7 * x - 5
x = np.linspace(-2, 4,10000)
plt.plot(x,f(x))
plt.grid(True)
```



```
b)
[37]: # maxiter=3 -> Error
      g = lambda x: (2 * x ** 3 - 11.7 * x ** 2 - 5) / -17.7
      raiz = opt.fixed_point(g, x0=3)
      raiz
[37]: array(3.56316082)
     c)
[38]: x = symbols('x')
      f = lambda x: 2 * x ** 3 - 11.7 * x ** 2 + 17.7 * x - 5
      derivada = diff(f(x))
      f_1 = lambdify(x, derivada, 'numpy')
      opt.root_scalar(f, fprime=f_1, x0=3, method='newton', maxiter=3, xtol=1e-10)
[38]:
            converged: False
                 flag: 'convergence error'
       function_calls: 6
           iterations: 3
                root: 3.7929344806432264
     d)
[39]: opt.root_scalar(f, x0=3, x1=4, xtol = 1e-10, maxiter=3, method='secant')
```

[39]: converged: False

flag: 'convergence error'

function_calls: 5
 iterations: 3

root: 3.5862753847117346

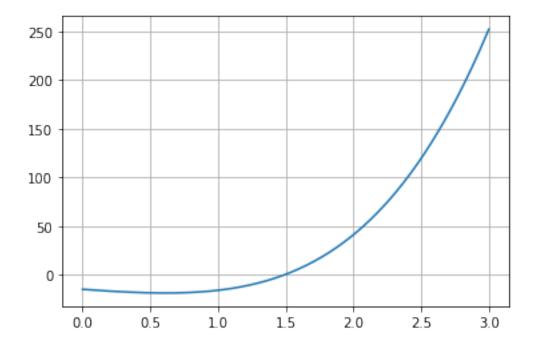
0.0.12 Problema 6

a)

$$f_1(x) = 2x^4 + 4x^3 + 3x^2 - 10x - 15, \cos x^* \in [0, 3]$$

[40]: f = lambda x: 2 * x ** 4 + 4 * x ** 3 + 3 * x ** 2 - 10 * x - 15

[41]: x = np.linspace(0, 3,10000)
 plt.plot(x,f(x))
 plt.grid(True)



Método da bisseção

[42]: %timeit opt.root_scalar(f,method='bisect', bracket=[0,3], maxiter=200, ⇒xtol=1e-10)

opt.root_scalar(f,method='bisect', bracket=[0,3], maxiter=200, xtol=1e-10)

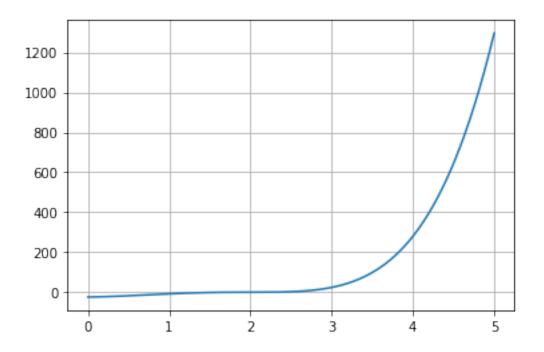
52.6 $\mu s \pm 2.2 \mu s$ per loop (mean \pm std. dev. of 7 runs, 10000 loops each)

```
[42]:
            converged: True
                 flag: 'converged'
       function calls: 37
           iterations: 35
                 root: 1.4928787086100783
     Método da falsa posição
[43]: x_i = 0
      x_u = 3
      iteracoes = 200
      tolerancia = 1e-10
      valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
      valores[-1]
[43]: 1.4928787086636037
     Método do ponto fixo
[44]: g = lambda x: (2 * x ** 4 + 4 * x ** 3 + 3 * x ** 2 - 15) / 10
[45]: %timeit opt.fixed_point(g, 3, xtol=1e-10, maxiter=200)
      opt.fixed_point(g, 3, xtol=1e-10, maxiter=200)
     17.7 \text{ ms} \pm 1.07 \text{ ms} per loop (mean \pm std. dev. of 7 runs, 100 loops each)
[45]: array(1.49287871)
     Método de Newton-Raphson
[46]: x = symbols('x')
      derivada = diff(f(x))
      f_1 = lambdify(x, derivada, 'numpy')
      opt.root_scalar(f, fprime=f_1, x0=3, method='newton', maxiter=200, xtol=1e-10)
[46]:
            converged: True
                 flag: 'converged'
       function_calls: 14
           iterations: 7
                 root: 1.4928787086636037
[47]: | %timeit opt.root_scalar(f, fprime=f_1, x0=3, method='newton', maxiter=200, ___
       \rightarrowxtol=1e-10)
```

Método da secante

346 $\mu s \pm 50.4 \mu s$ per loop (mean \pm std. dev. of 7 runs, 1000 loops each)

```
[48]: | %timeit opt.root_scalar(f, x0=3, x1=0, xtol = 1e-10, maxiter=200,__
       →method='secant')
      opt.root_scalar(f, x0=3, x1=0, xtol = 1e-10, maxiter=200, method='secant')
     500 \mu s \pm 13.3 \mu s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)
[48]:
            converged: True
                 flag: 'converged'
       function_calls: 12
           iterations: 11
                 root: -1.3003841326439196
[49]: | %timeit opt.root_scalar(f, x0=3, x1=1, xtol = 1e-10, maxiter=200,__
       →method='secant')
      opt.root_scalar(f, x0=3, x1=1, xtol = 1e-10, maxiter=200, method='secant')
     448 \mus \pm 21.8 \mus per loop (mean \pm std. dev. of 7 runs, 1000 loops each)
[49]:
            converged: True
                 flag: 'converged'
       function_calls: 11
           iterations: 10
                 root: 1.4928787086636035
     b)
                            f_2(x) = (x+3)(x+1)(x-2)^3, \cos x^* \in [0,5]
[50]: f = lambda x: (x + 3) * (x + 1) * (x - 2) ** 3
[51]: x = np.linspace(0, 5,10000)
      plt.plot(x,f(x))
      plt.grid(True)
```



Método da bisseção

```
[52]: %timeit opt.root_scalar(f,method='bisect', bracket=[0,5], maxiter=200, 

→xtol=1e-10)
opt.root_scalar(f,method='bisect', bracket=[0,5], maxiter=200, xtol=1e-10)
```

 $35 \mu s \pm 934 ns per loop (mean \pm std. dev. of 7 runs, 10000 loops each)$

[52]: converged: True

flag: 'converged'

function_calls: 38
 iterations: 36

root: 2.000000000436557

Método da falsa posição

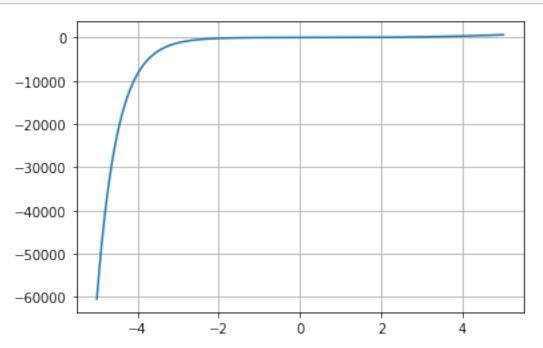
```
[53]: x_i = 0
x_u = 5
iteracoes = 200
tolerancia = 1e-10

valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
valores[-1]
```

[53]: 1.714409136227648

```
Método do ponto fixo x^5 - 2x^4 - 9x^3 + 22x^2 + 4x - 24
[54]: g = lambda x: (x ** 5 - 2 * x ** 4 - 9 * x ** 3 + 22 * x ** 2 - 24) / -4
[55]: %timeit opt.fixed_point(g, 3, xtol=1e-10, maxiter=200)
      opt.fixed_point(g, 3, xtol=1e-10, maxiter=200)
     364 \mu s \pm 28 \mu s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)
[55]: array(-3.)
     Método de Newton-Raphson
[56]: x = symbols('x')
      derivada = diff(f(x))
      f_1 = lambdify(x, derivada, 'numpy')
      opt.root_scalar(f, fprime=f_1, x0=3, method='newton', maxiter=200, xtol=1e-10)
[56]:
             converged: True
                  flag: 'converged'
       function_calls: 112
            iterations: 56
                  root: 2.000000001726277
[57]: | %timeit opt.root_scalar(f, fprime=f_1, x0=3, method='newton', maxiter=200, ___
       \rightarrowxtol=1e-10)
     2.37 ms \pm 93.6 \mus per loop (mean \pm std. dev. of 7 runs, 100 loops each)
     Método da secante
[58]: | %timeit opt.root_scalar(f, x0=5, x1=0, xtol = 1e-10, maxiter=200,
       →method='secant')
      opt.root_scalar(f, x0=5, x1=0, xtol = 1e-10, maxiter=200, method='secant')
     3.06 \text{ ms} \pm 73.4 \text{ } \mu \text{s} \text{ per loop (mean} \pm \text{ std. dev. of 7 runs, 100 loops each)}
[58]:
             converged: True
                  flag: 'converged'
       function_calls: 79
            iterations: 78
                  root: 2.0000000002448965
     c)
                        f_3(x) = 5x^3 + x^2 - e^{1-2x} + \cos(x) + 20, \cos x^* \in [-5, 5]
[59]: f = lambda x: 5 * x ** 3 + x ** 2 - np.exp(1 - 2 * x) + np.cos(x) + 20
```

```
[60]: x = np.linspace(-5, 5,10000)
plt.plot(x,f(x))
plt.grid(True)
```



Método da bisseção

```
[61]: %timeit opt.root_scalar(f,method='bisect', bracket=[-5,5], maxiter=200, 

⇒xtol=1e-10)

opt.root_scalar(f,method='bisect', bracket=[-5,5], maxiter=200, xtol=1e-10)
```

174 μ s \pm 13.4 μ s per loop (mean \pm std. dev. of 7 runs, 10000 loops each)

[61]: converged: True

flag: 'converged'

function_calls: 39
 iterations: 37

root: -0.9295604598446516

Método da falsa posição

```
[62]: x_i = -5
x_u = 5
iteracoes = 200
tolerancia = 1e-10

valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
```

```
valores[-1]
[62]: 1.568769261078004
     Método do ponto fixo
[63]: g = lambda x: (5 * x ** 3 - np.exp(1 - 2 * x) + np.cos(x) + 20) / -x
[64]: %timeit opt.fixed_point(g, -5, xtol=1e-10, maxiter=200)
      opt.fixed_point(g, -5, xtol=1e-10, maxiter=200)
     C:\Users\jarde\Anaconda3\lib\site-packages\ipykernel_launcher.py:1:
     RuntimeWarning: overflow encountered in exp
       """Entry point for launching an IPython kernel.
     207 \mu s \pm 6.41 \mu s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)
[64]: array(-5.)
     Método de Newton-Raphson
[65]: x = symbols('x')
      f = lambda x: 5 * x ** 3 + x ** 2 - exp(1 - 2 * x) + cos(x) + 20
      derivada = diff(f(x))
      f 1 = lambdify(x, derivada, 'numpy')
      f = lambda x: 5 * x ** 3 + x ** 2 - np.exp(1 - 2 * x) + np.cos(x) + 20
      opt.root_scalar(f, fprime=f_1, x0=-5, method='newton', maxiter=200, xtol=1e-10)
[65]:
            converged: True
                 flag: 'converged'
       function calls: 26
           iterations: 13
                 root: -0.9295604598378413
[66]: | %timeit opt.root_scalar(f, fprime=f_1, x0=-5, method='newton', maxiter=200,__
       \rightarrowxtol=1e-10)
     750 \mu s \pm 8.59 \mu s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)
     Método da secante
[67]: | %timeit opt.root_scalar(f, x0=-5, x1=5, xtol = 1e-10, maxiter=200,__
      →method='secant')
      opt.root_scalar(f, x0=-5, x1=5, xtol = 1e-10, maxiter=200, method='secant')
     1.2 ms \pm 31.5 \mus per loop (mean \pm std. dev. of 7 runs, 1000 loops each)
```

[67]: converged: True

flag: 'converged'

function_calls: 25 iterations: 24

root: -0.9295604598378412

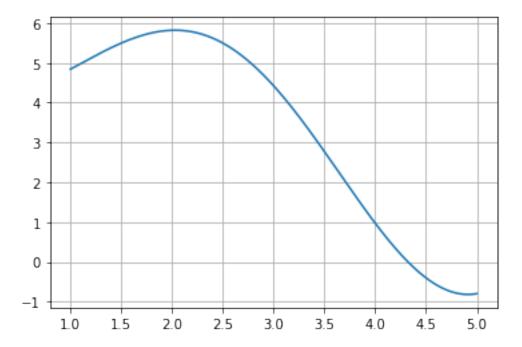
d)

$$f_4(x) = \sin(x)x + 4, \cos x^* \in [1, 5]$$

[68]: f = lambda x: np.sin(x) * x + 4

[69]: x = np.linspace(1, 5,10000)plt.plot(x,f(x))

plt.grid(True)



Método da bisseção

[70]: | %timeit opt.root_scalar(f,method='bisect', bracket=[1,5], maxiter=200,__ \rightarrow xtol=1e-10) opt.root_scalar(f,method='bisect', bracket=[1,5], maxiter=200, xtol=1e-10)

93 $\mu s \pm 9.71 \ \mu s$ per loop (mean \pm std. dev. of 7 runs, 10000 loops each)

[70]: converged: True

flag: 'converged'

function_calls: 38

iterations: 36

root: 4.323239543766249

Método da falsa posição

```
[71]: x_i = 1
x_u = 5
iteracoes = 200
tolerancia = 1e-10

valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
valores[-1]
```

[71]: 4.323239543713714

Método do ponto fixo

```
[72]: g = lambda x: -4 / np.sin(x)
```

```
[73]: %timeit opt.fixed_point(g, 1, xtol=1e-10, maxiter=200) opt.fixed_point(g, 1, xtol=1e-10, maxiter=200)
```

1.19 ms \pm 25.1 μ s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)

[73]: array(-4.32323954)

Método de Newton-Raphson

```
[74]: x = symbols('x')
f = lambda x: sin(x) * x + 4
derivada = diff(f(x))

f_1 = lambdify(x, derivada, 'numpy')
f = lambda x: np.sin(x) * x + 4
opt.root_scalar(f, fprime=f_1, x0=-5, method='newton', maxiter=200, xtol=1e-10)
```

[74]: converged: True

flag: 'converged'

function_calls: 14
 iterations: 7

root: -5.461308012588998

```
[75]: %timeit opt.root_scalar(f, fprime=f_1, x0=-5, method='newton', maxiter=200, 

→xtol=1e-10)
```

357 μ s \pm 7.1 μ s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)

Método da secante

```
[76]: %timeit opt.root_scalar(f, x0=5, x1=1, xtol = 1e-10, maxiter=200, 

→method='secant')
opt.root_scalar(f, x0=5, x1=1, xtol = 1e-10, maxiter=200, method='secant')
```

330 $\mu s \pm 6.47 \ \mu s$ per loop (mean \pm std. dev. of 7 runs, 1000 loops each)

[76]: converged: True

flag: 'converged'

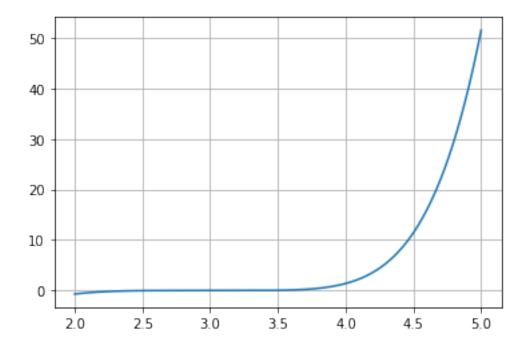
function_calls: 8
 iterations: 7

root: 4.323239543713714

e)

$$f_5(x) = (x-3)^5 \ln(x) \mid , \cos x^* \in [2,5]$$

[77]: f = lambda x: (x - 3) ** 5 * np.log(x)



Método da bisseção

```
opt.root_scalar(f,method='bisect', bracket=[2,5], maxiter=200, xtol=1e-10)
     99.9 \mus \pm 22.6 \mus per loop (mean \pm std. dev. of 7 runs, 10000 loops each)
[79]:
            converged: True
                 flag: 'converged'
       function_calls: 37
           iterations: 35
                 root: 3.000000000029104
     Método da falsa posição
[80]: x_i = 2
      x_u = 5
      iteracoes = 200
      tolerancia = 1e-10
      valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
      valores[-1]
[80]: 2.593909764205461
     Método do ponto fixo
[81]: g = lambda x: np.exp((x ** 5 * np.log(x) - 15 * x ** 4 * np.log(x) + 90 * x **_{\sqcup})
       \rightarrow3 * np.log(x) - 270 * x ** 2 * np.log(x) + 405 * x * np.log(x)) / 243)
[82]: # maxiter = 200 -> Error
      %timeit opt.fixed_point(g, 5, xtol=1e-10, maxiter=9000)
      opt.fixed_point(g, 5, xtol=1e-10, maxiter=9000)
     1.65 \text{ s} \pm 46.5 \text{ ms} per loop (mean \pm std. dev. of 7 runs, 1 loop each)
[82]: array(3.0255312)
     Método de Newton-Raphson
[83]: x = symbols('x')
      f = lambda x: (x - 3) ** 5 * ln(x)
      derivada = diff(f(x))
      f_1 = lambdify(x, derivada, 'numpy')
      f = lambda x: (x - 3) ** 5 * np.log(x)
      opt.root_scalar(f, fprime=f_1, x0=2, method='newton', maxiter=200, xtol=1e-10)
[83]:
            converged: True
                 flag: 'converged'
       function_calls: 194
```

```
iterations: 97
```

root: 2.9999999964898

```
[84]: %timeit opt.root_scalar(f, fprime=f_1, x0=2, method='newton', maxiter=200, 

→xtol=1e-10)
```

 $4.93 \text{ ms} \pm 221 \text{ µs}$ per loop (mean \pm std. dev. of 7 runs, 100 loops each)

Método da secante

```
[85]: %timeit opt.root_scalar(f, x0=5, x1=2, xtol = 1e-10, maxiter=200, 

→method='secant')
opt.root_scalar(f, x0=5, x1=2, xtol = 1e-10, maxiter=200, method='secant')
```

 $6.16 \text{ ms} \pm 119 \text{ µs}$ per loop (mean \pm std. dev. of 7 runs, 100 loops each)

[85]: converged: True

flag: 'converged'

function_calls: 139
 iterations: 138

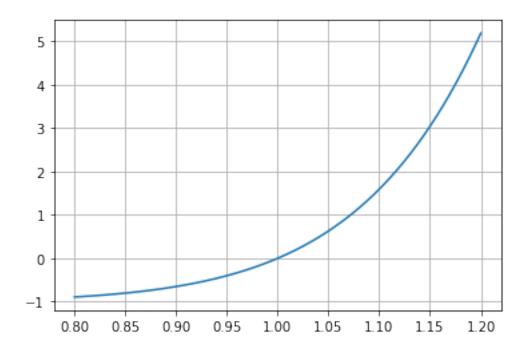
root: 2.99999999418057

f)

$$f_6(x) = x^{10} - 1, \operatorname{com} x^* \in [0.8, 1.2]$$

Método da bisseção

[86]:
$$f = lambda x: x ** 10 - 1$$



Método da falsa posição

```
[88]: x_i = 0.8
x_u = 1.2
iteracoes = 200
tolerancia = 1e-10

valores = falsa_posicao(f, x_i, x_u, iteracoes, tolerancia)
valores[-1]
```

[88]: 0.99999999999998

Método do ponto fixo

455 μ s \pm 16.5 μ s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)

[90]: array(0.)

Método de Newton-Raphson

```
[91]: x = symbols('x')
derivada = diff(f(x))
```

```
f_1 = lambdify(x, derivada, 'numpy')
      opt.root_scalar(f, fprime=f_1, x0=0.8, method='newton', maxiter=200, xtol=1e-10)
[91]:
            converged: True
                 flag: 'converged'
       function_calls: 20
           iterations: 10
                 root: 1.0
     Método da secante
[92]: | %timeit opt.root_scalar(f, x0=1.2, x1=0.8, xtol = 1e-10, maxiter=200,__
      →method='secant')
      opt.root_scalar(f, x0=1.2, x1=0.8, xtol = 1e-10, maxiter=200, method='secant')
     484 \mu s \pm 16.4 \mu s per loop (mean \pm std. dev. of 7 runs, 1000 loops each)
[92]:
            converged: True
                 flag: 'converged'
       function_calls: 12
           iterations: 11
                 root: 1.0
```