Stand-up Balloon Juice

Jared Dyreson

Q1) In this iteration, I worked on the movement generation for our bot, adhering to the properties described in the rubric.

Q2) Next iteration, me and Mason will finish connecting the traversal code and the adjacency matrix to ensure the bot can properly move

Q3) No roadblocks as of now

Mason Godfrey

Q1) This iteration, I implemented connections based on our understanding of the requirements, and helped Jared with updating the DPV values based on our understanding of requirements for D, P, and V's maximum sizes.

Q2) Next iteration, I intend to help Jared finish his implementation of his traversal algorithm, and help him display the traversal.

Q3) As of right now, the only roadblock is other group projects we both have; however, I feel we are making significant progress regardless.