

# opencv-1

October 14, 2024

```
[1]: !pip install opencv-python
!pip install opencv-python matplotlib
```

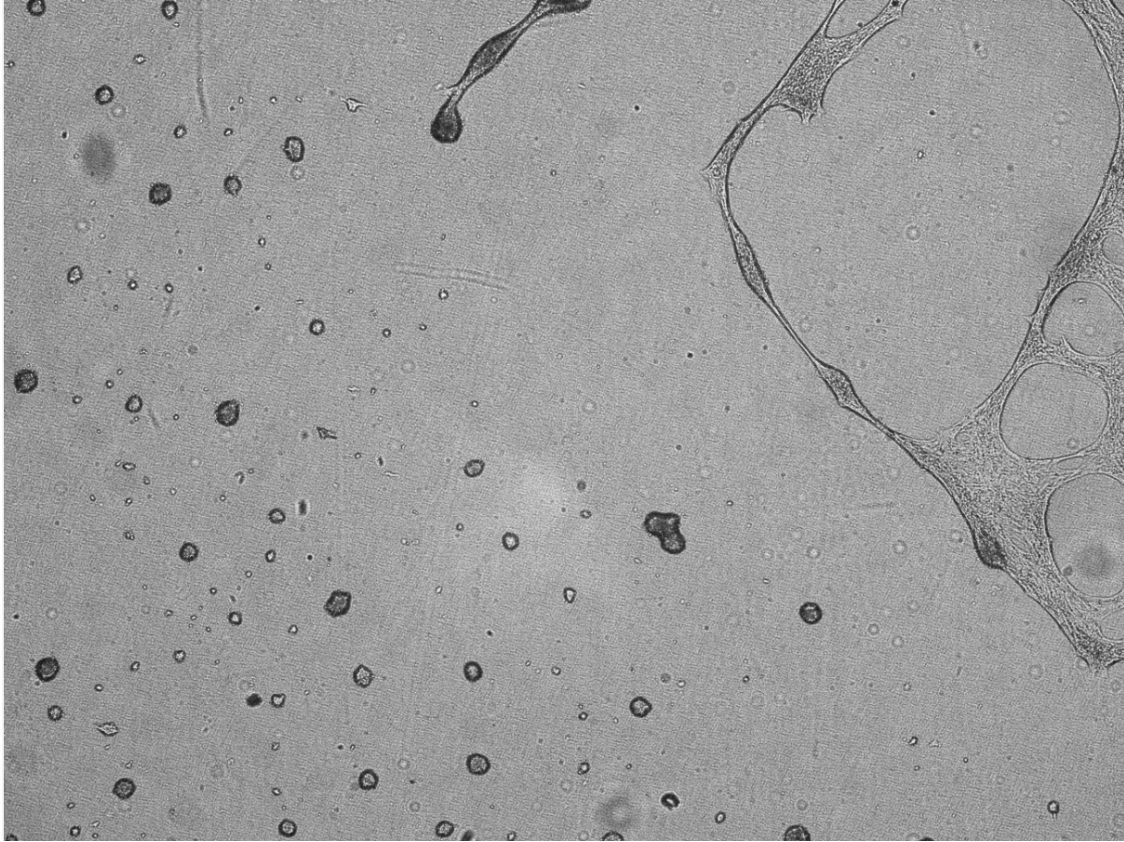
```
Requirement already satisfied: opencv-python in /usr/local/lib/python3.10/dist-packages (4.10.0.84)
Requirement already satisfied: numpy>=1.21.2 in /usr/local/lib/python3.10/dist-packages (from opencv-python) (1.26.4)
Requirement already satisfied: opencv-python in /usr/local/lib/python3.10/dist-packages (4.10.0.84)
Requirement already satisfied: matplotlib in /usr/local/lib/python3.10/dist-packages (3.7.1)
Requirement already satisfied: numpy>=1.21.2 in /usr/local/lib/python3.10/dist-packages (from opencv-python) (1.26.4)
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (1.3.0)
Requirement already satisfied: cyclers>=0.10 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (0.12.1)
Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (4.54.1)
Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (1.4.7)
Requirement already satisfied: packaging>=20.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (24.1)
Requirement already satisfied: pillow>=6.2.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (10.4.0)
Requirement already satisfied: pyparsing>=2.3.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (3.1.4)
Requirement already satisfied: python-dateutil>=2.7 in /usr/local/lib/python3.10/dist-packages (from matplotlib) (2.8.2)
Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.10/dist-packages (from python-dateutil>=2.7->matplotlib) (1.16.0)
```

```
[5]: import cv2
import glob
from google.colab.patches import cv2_imshow

image_path = "/content/img.png"
```

```
images = glob.glob(image_path)

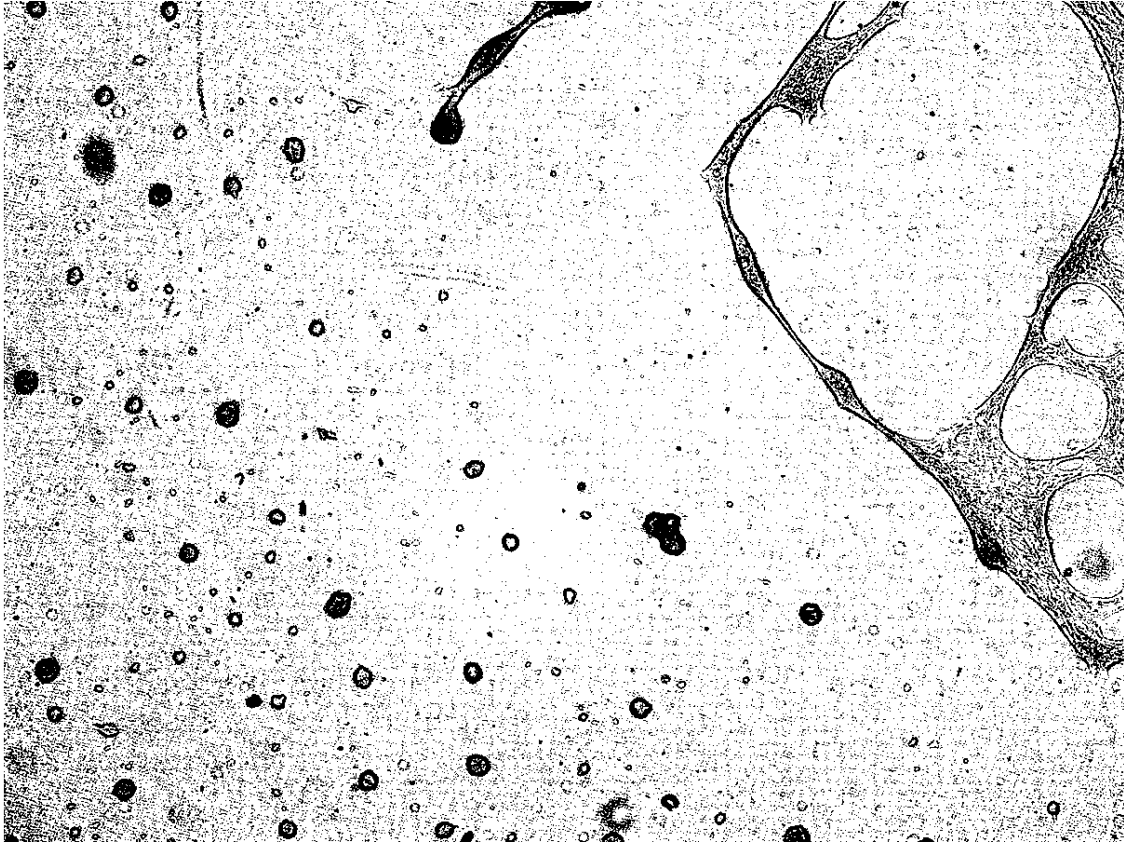
for image_file in images:
    image = cv2.imread(image_file)
    cv2_imshow(image)
```



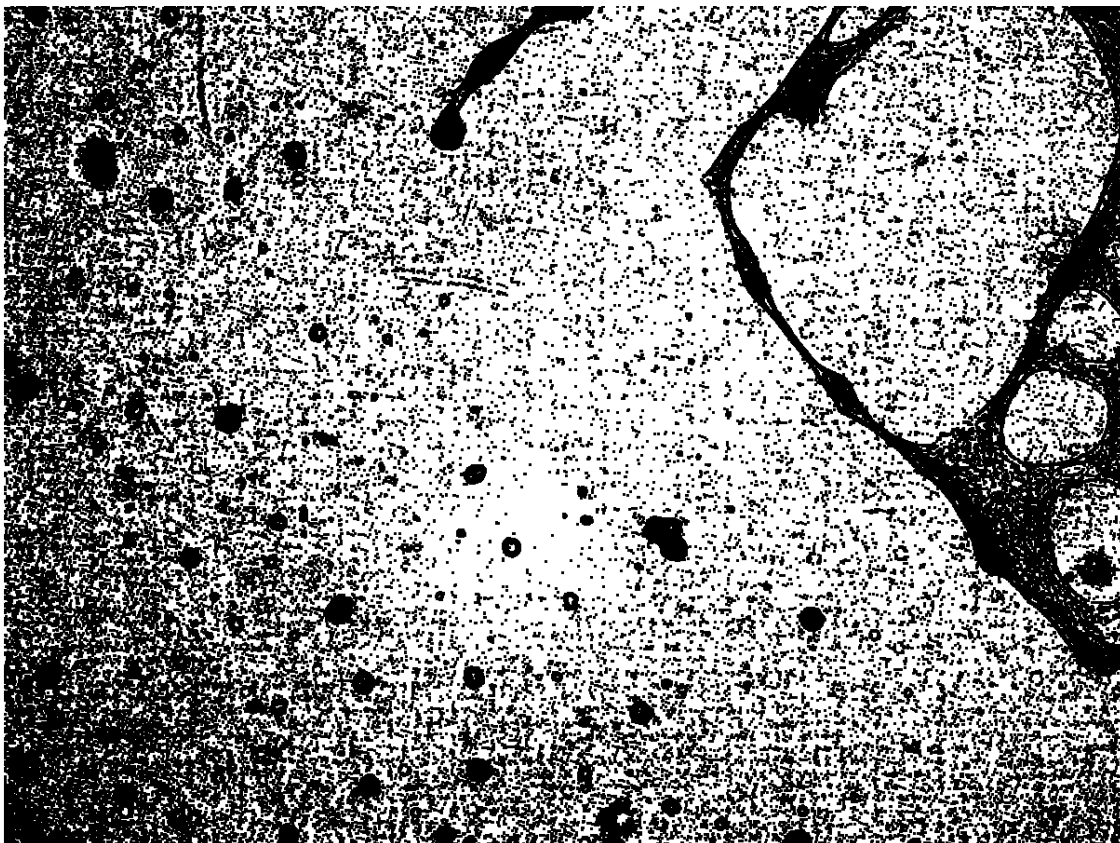
## 1 FILTROS

```
[6]: image = cv2.imread("/content/img.png", cv2.IMREAD_GRAYSCALE)
```

```
[7]: _, binary_image = cv2.threshold(image, 135, 255, cv2.THRESH_BINARY)
     cv2_imshow(binary_image)
```

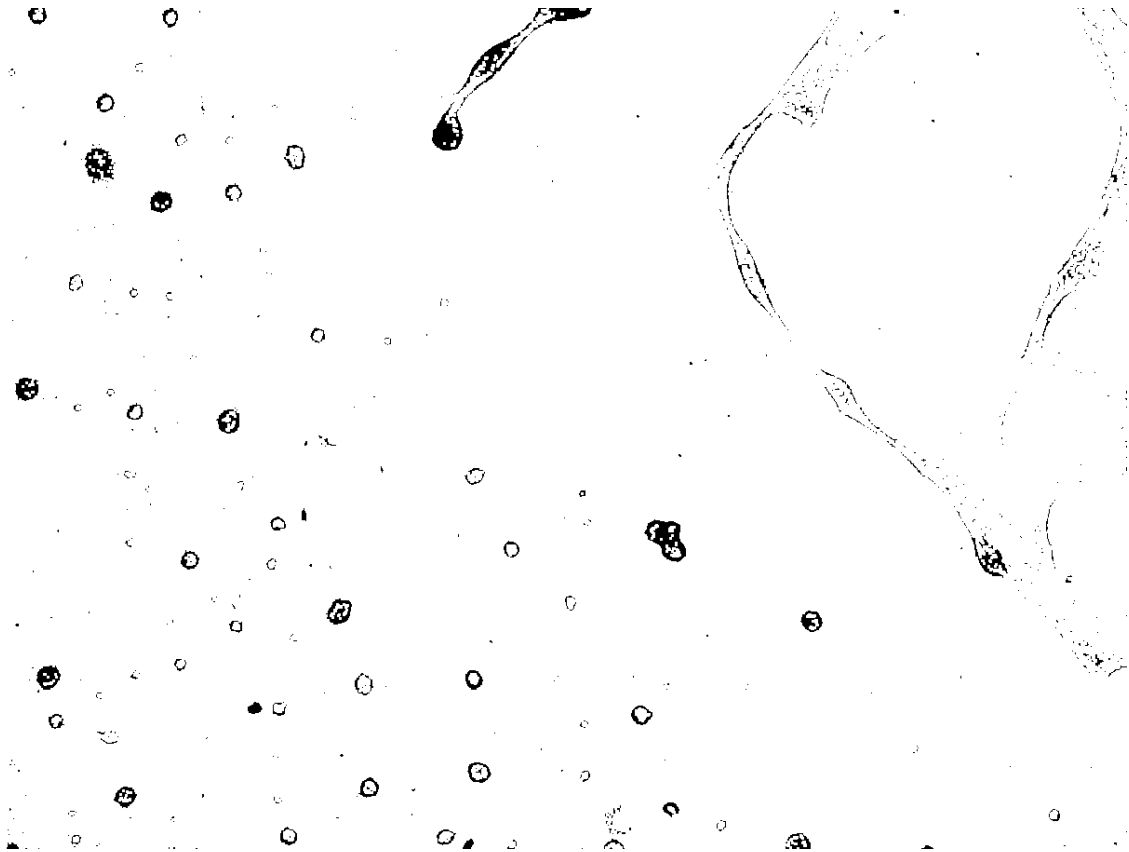


```
[8]: kernel = cv2.getStructuringElement(cv2.MORPH_RECT, (3, 3))  
  
erosion = cv2.erode(binary_image, kernel, iterations=1)  
  
cv2_imshow(erosion)
```



```
[9]: dilatation = cv2.dilate(binary_image, kernel, iterations=1)

cv2_imshow(dilatation)
```



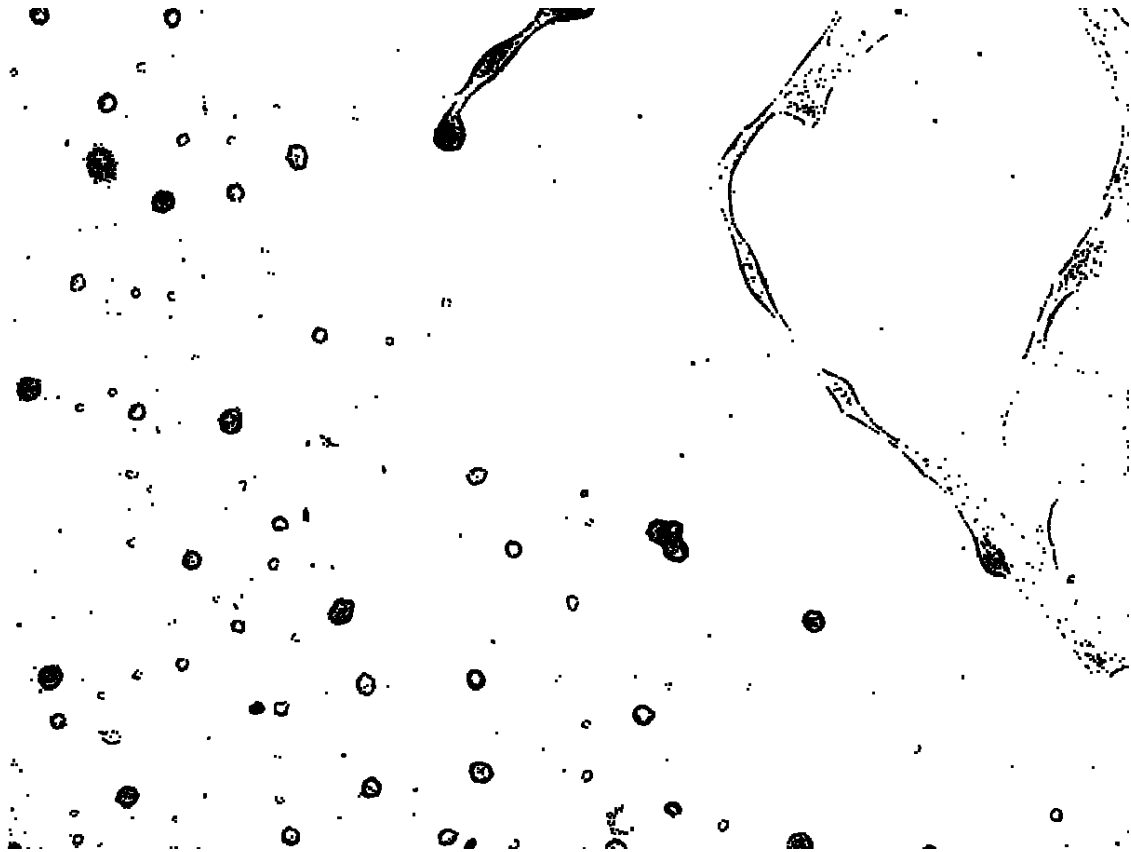
```
[10]: filter = cv2.morphologyEx(binary_image, cv2.MORPH_OPEN, kernel)
      cv2_imshow(filter)
```





```
[11]: filter2 = cv2.morphologyEx(binary_image, cv2.MORPH_CLOSE, kernel)

cv2_imshow(filter2)
```



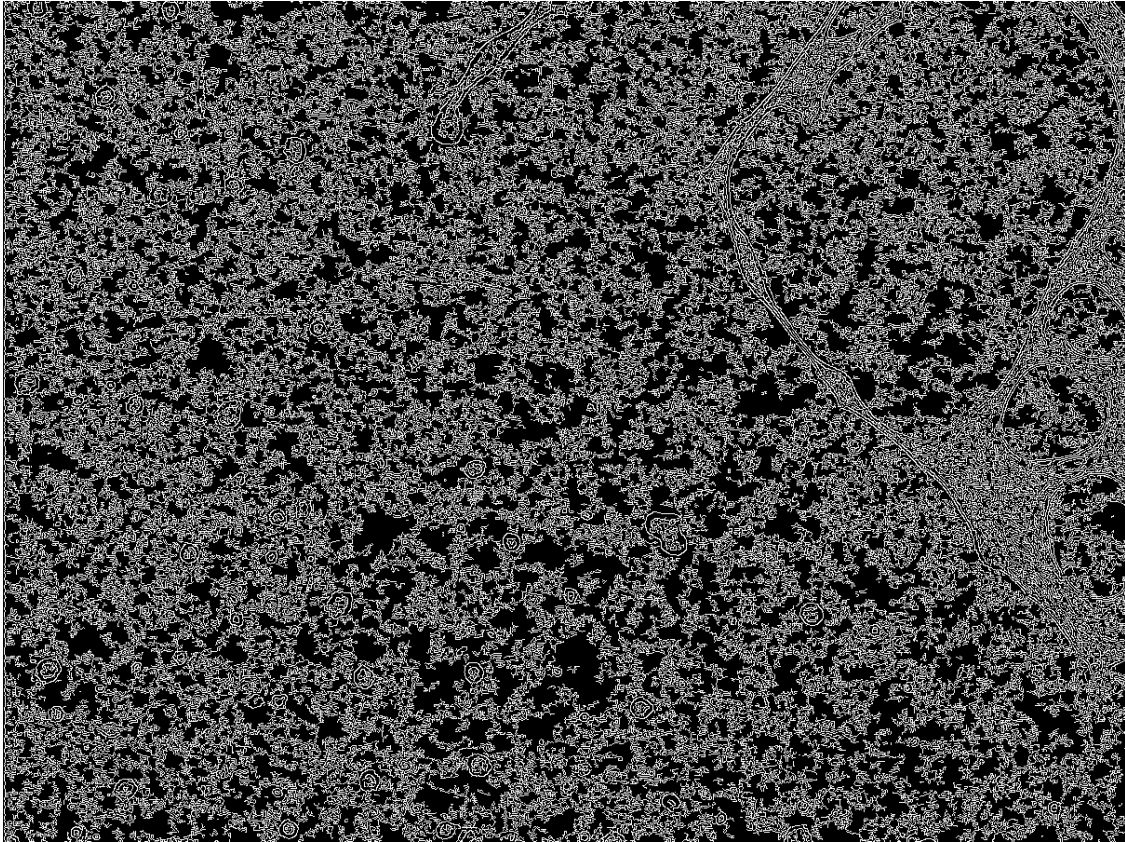
```
[13]: filtro4 = cv2.morphologyEx(binary_image, cv2.MORPH_GRADIENT, kernel)

cv2_imshow(filtro4)
```

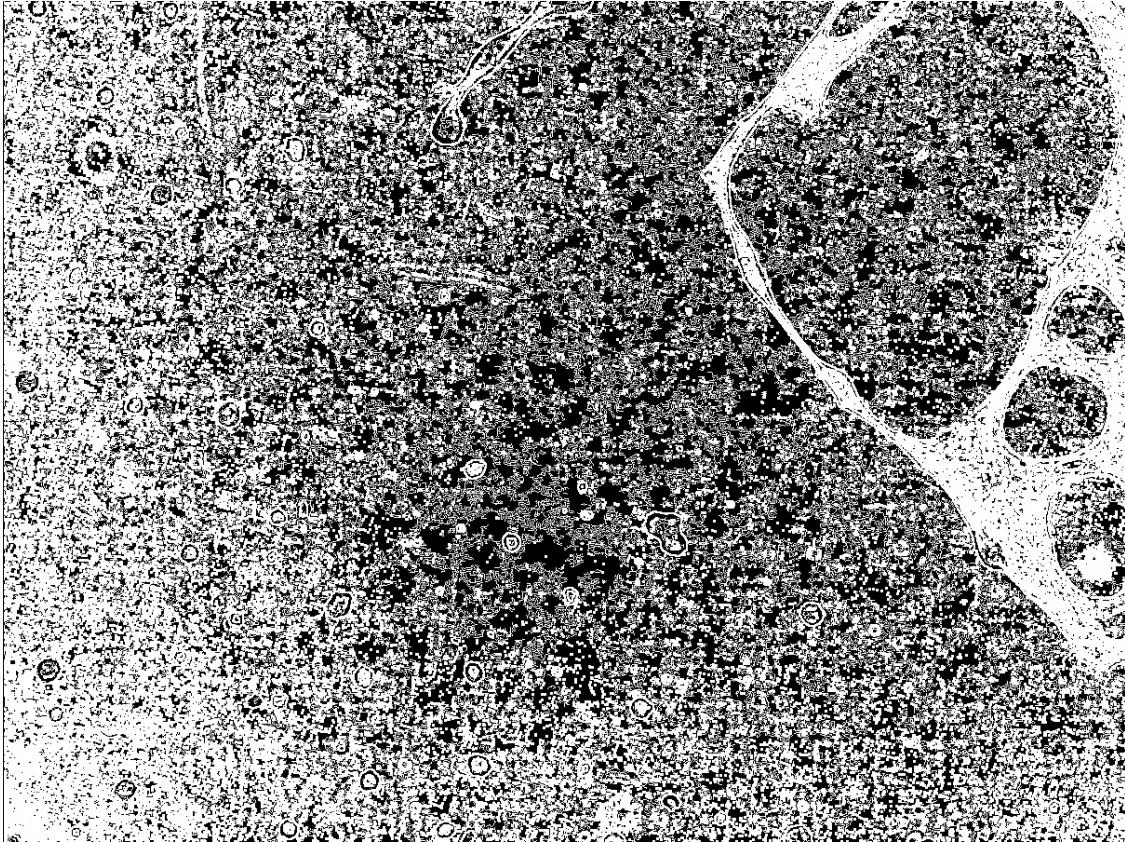


```
[12]: edges = cv2.Canny(image, 255, 1)
      cv2_imshow(edges)
```

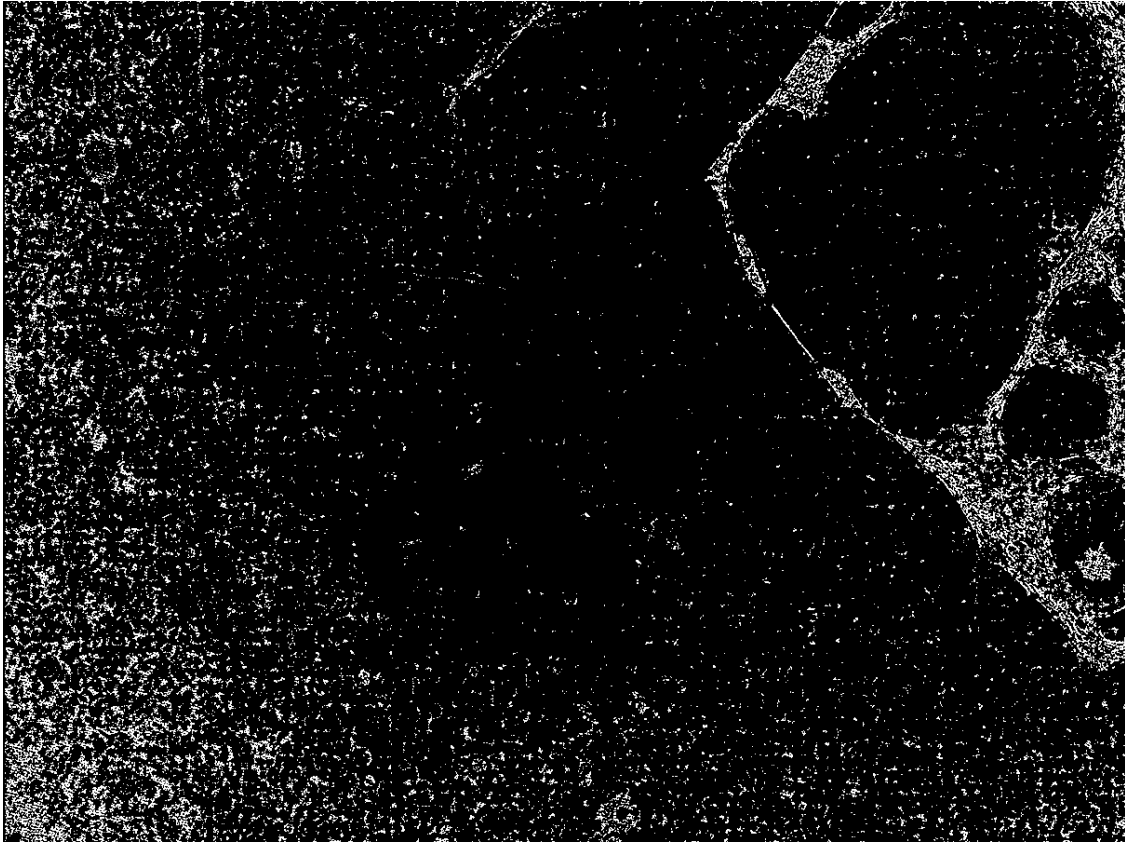




```
[14]: f = filtro4 + edges  
      cv2_imshow(f)
```

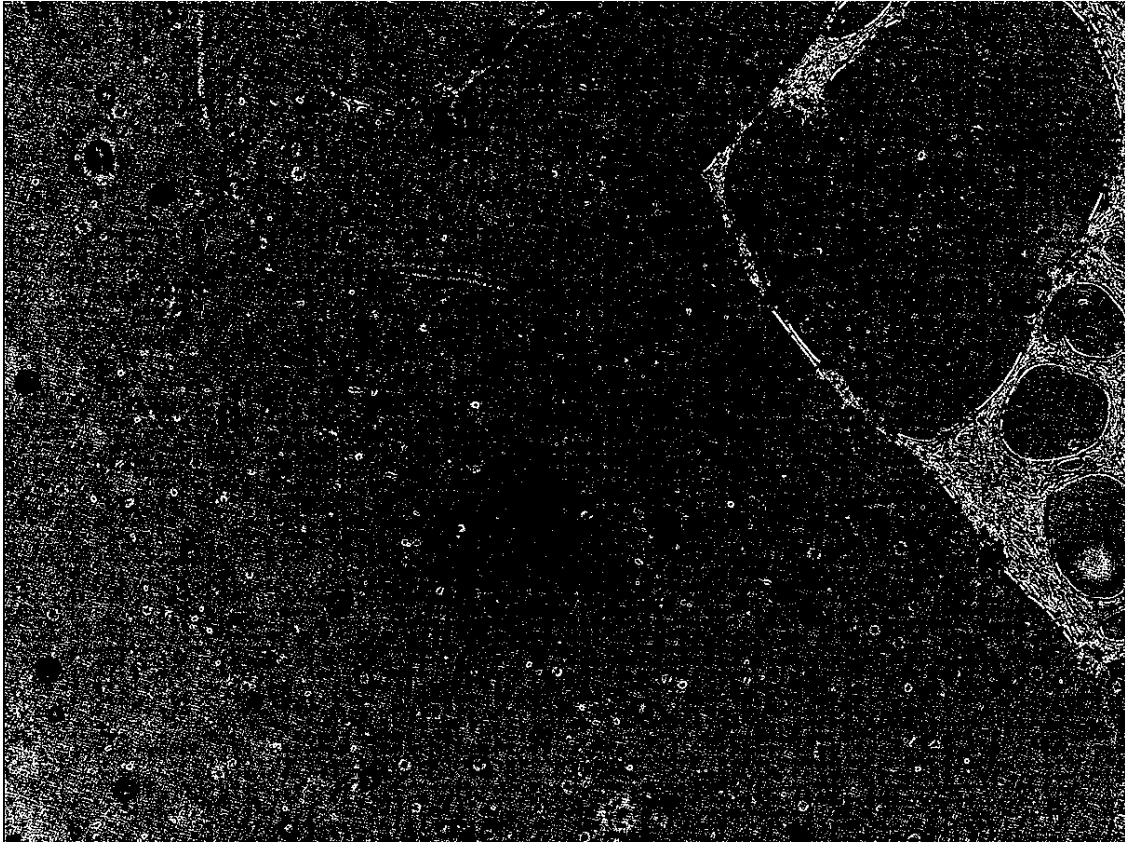


```
[15]: filtro5 = cv2.morphologyEx(binary_image, cv2.MORPH_TOPHAT, kernel)
      cv2_imshow(filtro5)
```

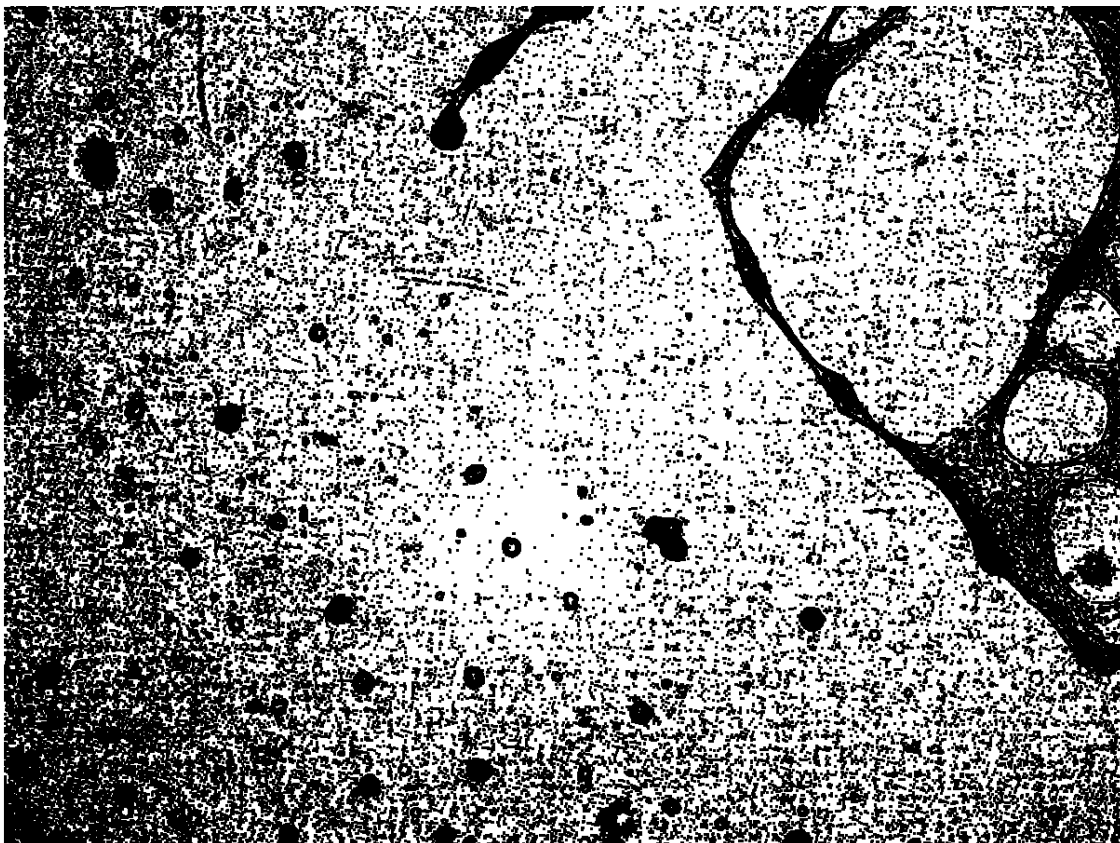


```
[16]: filtro6 = cv2.morphologyEx(binary_image, cv2.MORPH_BLACKHAT, kernel)
      cv2_imshow(filtro6)
```





```
[17]: filtro8 = cv2.morphologyEx(binary_image, cv2.MORPH_HITMISS, kernel)
      cv2_imshow(filtro8)
```



## 2 Modelo

```
[18]: image = cv2.imread('/content/img.png', cv2.IMREAD_GRAYSCALE)
```

```
[19]: import cv2
import matplotlib.pyplot as plt
import numpy as np
```

```
image = cv2.imread('/content/img.png', cv2.IMREAD_GRAYSCALE)
```

```
sobelx = cv2.Sobel(image, cv2.CV_64F, 1, 0, ksize=5)
```

```
sobely = cv2.Sobel(image, cv2.CV_64F, 0, 1, ksize=5)
```

```
edges_canny = cv2.Canny(image, 100, 200)
```

```
plt.figure(figsize=(10, 7))

plt.subplot(2, 2, 1), plt.imshow(image, cmap='gray')
plt.title('Imagen original'), plt.axis('off')

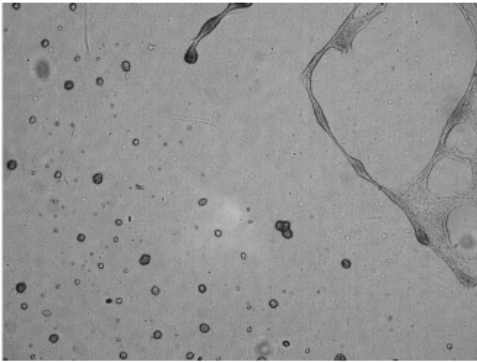
plt.subplot(2, 2, 2), plt.imshow(sobelx, cmap='gray')
plt.title('Sobel - Eje X'), plt.axis('off')

plt.subplot(2, 2, 3), plt.imshow(sobely, cmap='gray')
plt.title('Sobel - Eje Y'), plt.axis('off')

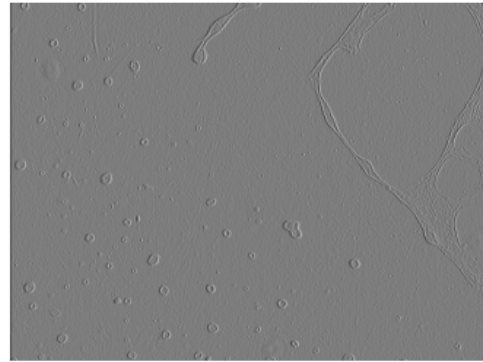
plt.subplot(2, 2, 4), plt.imshow(edges_canny, cmap='gray')
plt.title('Detección de bordes - Canny'), plt.axis('off')

plt.show()
```

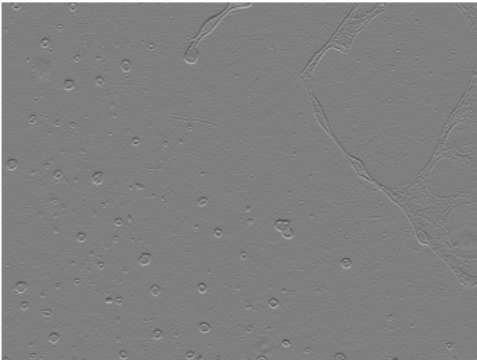
Imagen original



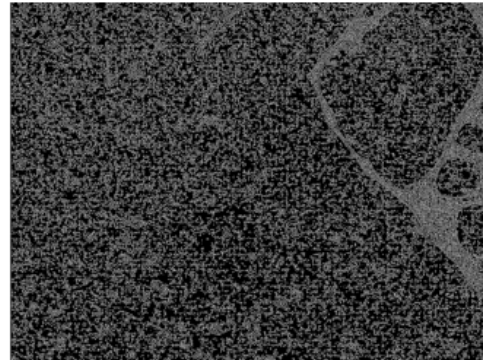
Sobel - Eje X



Sobel - Eje Y



Detección de bordes - Canny





### 3 SAM2

```
[ ]: pip install git+https://github.com/facebookresearch/segment-anything.git
```

```
[ ]: from segment_anything import SamPredictor, sam_model_registry
import cv2
import matplotlib.pyplot as plt
import numpy as np

image = cv2.imread('sample_data/img.png')

sam = sam_model_registry["vit_b"](checkpoint="/content/sample_data/
↳sam_vit_b_01ec64.pth")
predictor = SamPredictor(sam)

predictor.set_image(image)

input_point = np.array([[100, 150]])
input_label = np.array([1])

masks, scores, logits = predictor.predict(point_coords=input_point,
↳point_labels=input_label, multimask_output=True)

plt.imshow(masks[0], cmap='gray')
plt.title('Miotubos segmentados')
plt.show()
```

### 4 Binary mask

```
[24]: import json
import numpy as np
import cv2
import os

image = cv2.imread('/content/img.png')
```

```

with open('/content/imgET.json') as f:
    annotations = json.load(f)

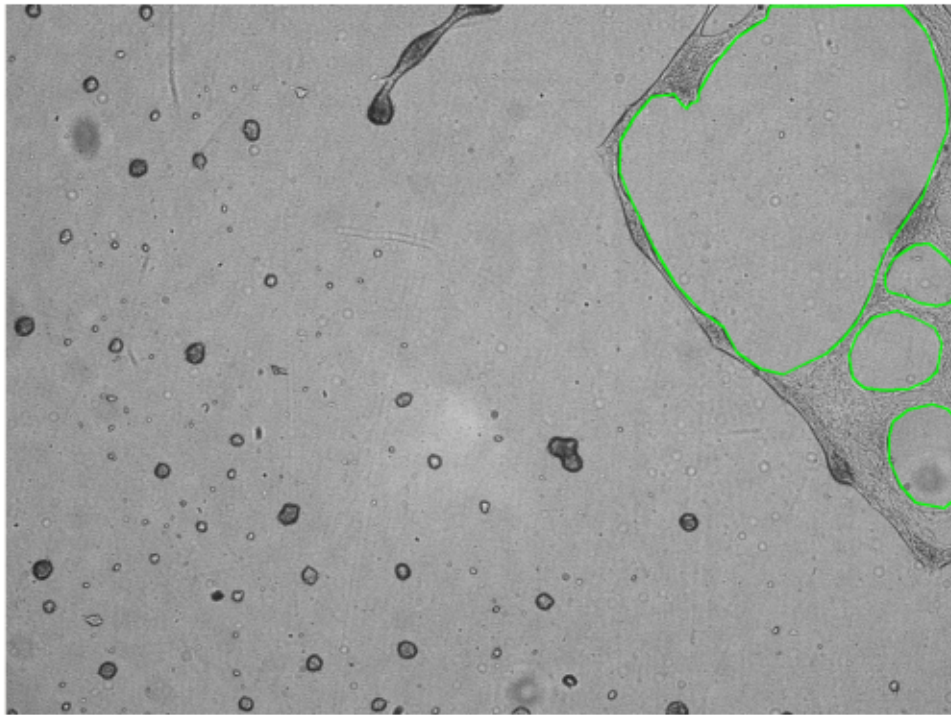
for shape in annotations['shapes']:
    if shape['label'] == 'miotubo':
        points = np.array(shape['points'], dtype=np.int32)

        cv2.polylines(image, [points], isClosed=True, color=(0, 255, 0),
            ↪thickness=2)

image_rgb = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)

plt.imshow(image_rgb)
plt.axis('off')
plt.show()

```



```

[25]: def json_to_mask(json_path, output_path):

        with open(json_path, 'r') as f:

```

```

data = json.load(f)

img_height = data['imageHeight']
img_width = data['imageWidth']

mask = np.zeros((img_height, img_width), dtype=np.uint8)

for shape in data['shapes']:
    points = np.array(shape['points'], dtype=np.int32)
    cv2.fillPoly(mask, [points], color=255)

cv2.imwrite(output_path, mask)

json_file = "/content/imgET.json"
output_mask = "sample_data/mask.png"

json_to_mask(json_file, output_mask)

```

```

[26]: import cv2
import matplotlib.pyplot as plt

image = cv2.imread("/content/img.png")
mask = cv2.imread("/content/sample_data/mask.png", cv2.IMREAD_GRAYSCALE)

plt.figure(figsize=(10, 5))

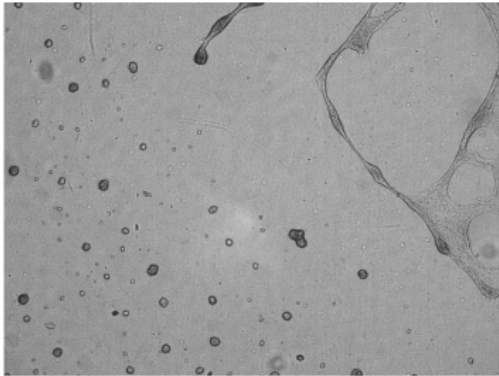
plt.subplot(1, 2, 1)
plt.imshow(cv2.cvtColor(image, cv2.COLOR_BGR2RGB))
plt.title("Imagen Original")
plt.axis('off')

plt.subplot(1, 2, 2)
plt.imshow(mask, cmap='gray')
plt.title("Máscara")
plt.axis('off')

plt.show()

```

Imagen Original



Máscara



```
[27]: import numpy as np

binary_mask = np.where(mask > 0, 1, 0)

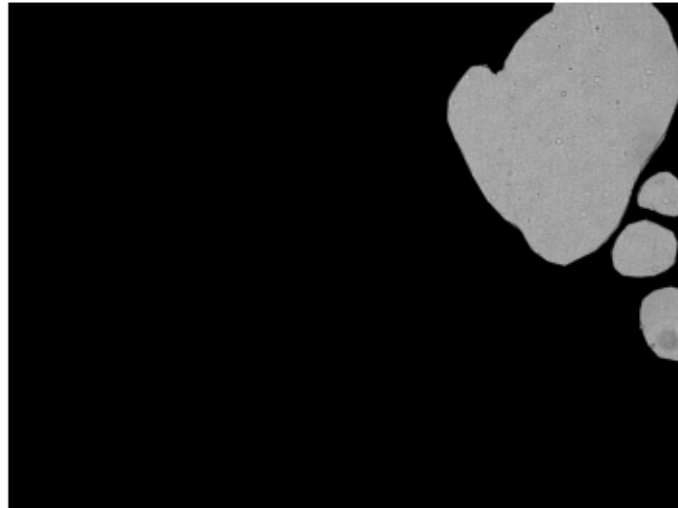
segmented_image = cv2.bitwise_and(image, image, mask=binary_mask.astype(np.
    ↪uint8))

plt.figure(figsize=(10, 5))

plt.subplot(1, 2, 1)
plt.imshow(cv2.cvtColor(segmented_image, cv2.COLOR_BGR2RGB))
plt.title("Imagen Segmentada")
plt.axis('off')

plt.show()
```

Imagen Segmentada



```
[28]: contours, _ = cv2.findContours(binary_mask.astype(np.uint8), cv2.RETR_EXTERNAL,
    ↪cv2.CHAIN_APPROX_SIMPLE)

widths = []
heights = []

for contour in contours:

    x, y, w, h = cv2.boundingRect(contour)

    widths.append(w)
    heights.append(h)

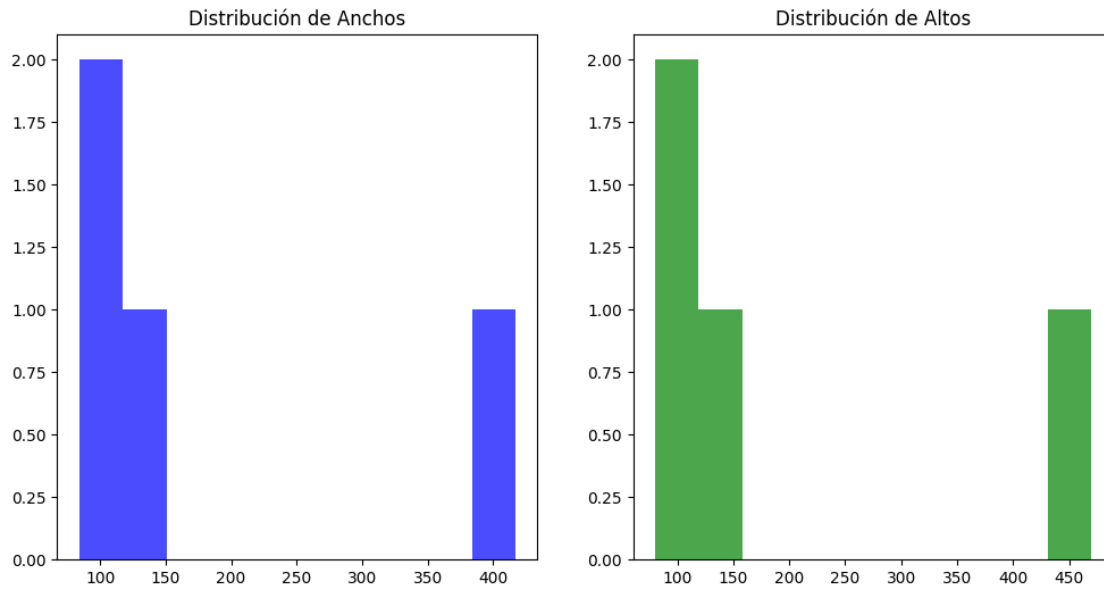
plt.figure(figsize=(12, 6))

plt.subplot(1, 2, 1)
plt.hist(widths, bins=10, color='blue', alpha=0.7)
plt.title("Distribución de Anchos")

plt.subplot(1, 2, 2)
plt.hist(heights, bins=10, color='green', alpha=0.7)
plt.title("Distribución de Altos")

plt.show()
```

```
print(f"Tamaño de la muestra: {len(widths)}")
```



Tamaño de la muestra: 4

```
[29]: contours, _ = cv2.findContours(binary_mask.astype(np.uint8), cv2.RETR_EXTERNAL,
    ↪cv2.CHAIN_APPROX_SIMPLE)

centroids = []

for contour in contours:
    M = cv2.moments(contour)
    if M["m00"] != 0:
        cx = int(M["m10"] / M["m00"])
        cy = int(M["m01"] / M["m00"])
        centroids.append((cx, cy))

image_with_distances = image.copy()

for i in range(len(centroids)):
    for j in range(i + 1, len(centroids)):
```



```

        distance = np.sqrt((centroids[j][0] - centroids[i][0])**2 +
↪(centroids[j][1] - centroids[i][1])**2)

        cv2.line(image_with_distances, centroids[i], centroids[j], (0, 255, 0),
↪1)

        mid_point = ((centroids[i][0] + centroids[j][0]) // 2, (centroids[i][1]
↪+ centroids[j][1]) // 2)
        cv2.putText(image_with_distances, f'{int(distance)}', mid_point, cv2.
↪FONT_HERSHEY_SIMPLEX, 0.4, (255, 0, 0), 1)

plt.figure(figsize=(10, 10))
plt.imshow(cv2.cvtColor(image_with_distances, cv2.COLOR_BGR2RGB))
plt.title("Distancias entre blobs visualizadas")
plt.axis('off')
plt.show()

```

Distancias entre blobs visualizadas

