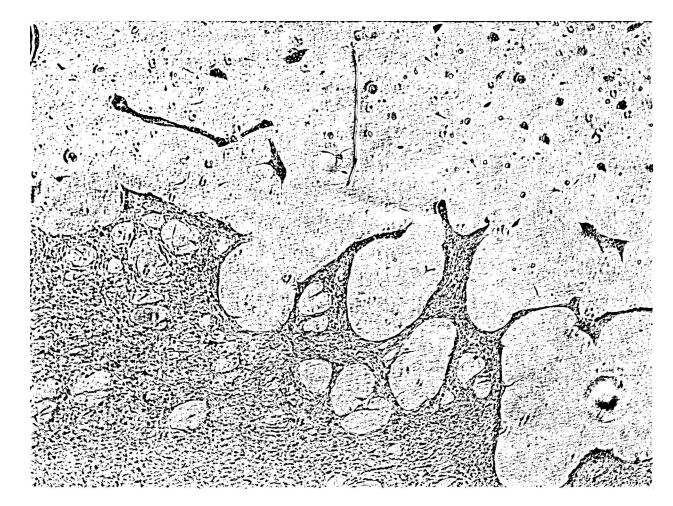
#Imports

```
import cv2
from google.colab.patches import cv2_imshow
import numpy as np
import matplotlib.pyplot as plt
import os
from tensorflow.keras.models import load_model

from google.colab import drive
drive.mount('/content/drive')
Mounted at /content/drive
```

#Filtros

```
image = cv2.imread("/content/drive/MyDrive/7mo Semestre
/TODOSLOSMIOTUBOS/Plate1/Jared/Best/Copia de 2d2dc951-22b0-48df-b1ce-
0157ca9e29fa_A2_02_05_Phi8Color (1).png", cv2.IMREAD_GRAYSCALE)
_, binary_image = cv2.threshold(image, 135, 255, cv2.THRESH_BINARY)
cv2_imshow(binary_image)
```



Erosion

```
kernel = cv2.getStructuringElement(cv2.MORPH_RECT, (3, 3))
erosion = cv2.erode(binary_image, kernel, iterations=1)
cv2_imshow(erosion)
```

Dilate

```
dilatation = cv2.dilate(binary_image, kernel, iterations=1)
cv2_imshow(dilatation)
```

Morphology

```
filter = cv2.morphologyEx(binary_image, cv2.MORPH_OPEN, kernel)
cv2_imshow(filter)
```

```
import os
import cv2
import json
import numpy as np
import shutil
def load image(image path):
    image = cv2.imread(image path)
    return image
def resize image(image, target size=(256, 256)):
    resized image = cv2.resize(image, target size)
    return resized image
def load mask(json path):
    with open(json path, 'r') as f:
        mask data = ison.load(f)
    mask = np.zeros((mask_data['imageHeight'],
mask data['imageWidth']), dtype=np.float32)
    for shape in mask data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 1)
    return mask, mask data
def resize mask and update json(mask, mask data, new image name,
target size=(256, 256)):
    resized mask = cv2.resize(mask, target size)
    scale x = target size[0] / mask data['imageWidth']
    scale y = target size[1] / mask data['imageHeight']
    for shape in mask data['shapes']:
        shape['points'] = [[int(point[0] * scale_x), int(point[1] *
scale y)] for point in shape['points']]
    mask data['imageWidth'] = target size[0]
    mask data['imageHeight'] = target size[1]
    mask data['imagePath'] = new image name
```

```
return resized mask, mask data
def process folder(img folder, json folder, output folder,
target size=(256, 256)):
    if not os.path.exists(output folder):
        os.makedirs(output folder)
    for filename in os.listdir(img folder):
        if filename.endswith('.jpg\overline{g}) or filename.endswith('.png'):
            img path = os.path.join(img folder, filename)
            json path = os.path.join(json folder,
os.path.splitext(filename)[0] + '.json')
            if os.path.exists(json path):
                original image = load image(img path)
                original mask, mask data = load mask(json path)
                resized image = resize image(original image,
target size)
                new filename = os.path.splitext(filename)[0] +
' Resize' + os.path.splitext(filename)[1]
                output image path = os.path.join(output folder,
new filename)
                resized mask, updated mask data =
resize mask and update json(original mask, mask data, new filename,
target size)
                cv2.imwrite(output image path, resized image)
                output json path = os.path.join(output folder,
os.path.splitext(filename)[0] + '_Resize.json')
                with open(output json path, 'w') as f:
                    ison.dump(updated mask data, f)
                print(f"Procesado: {filename} -> {new filename}")
img folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paola/IMG NOR + JSON'
json folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paola/IMG NOR + JSON'
output folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paola/reeeeeee'
```

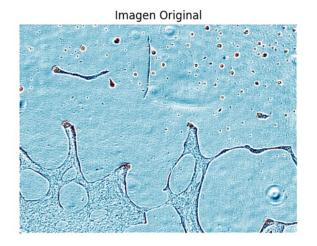
```
process folder(img folder, json folder, output folder,
target size=(256, 256))
print(f"Redimensionado completado. Los archivos redimensionados se han
guardado en: {output folder}")
Procesado: P 4.png -> P 4 Resize.png
Procesado: P = 10.png \rightarrow P = 10 Resize.png
Procesado: P_31.png -> P_31_Resize.png
Procesado: P 2.png -> P 2 Resize.png
Procesado: P_29.png -> P_29_Resize.png
Procesado: P_5.png -> P_5_Resize.png
Procesado: P 24.png -> P 24 Resize.png
Procesado: P 3.png -> P 3 Resize.png
Procesado: P_19.png -> P 19 Resize.png
Procesado: P_1.png -> P_1_Resize.png
Procesado: P 6.png -> P 6 Resize.png
Procesado: P 33.png -> P 33 Resize.png
Procesado: P 30.png -> P 30 Resize.png
Procesado: P_26.png -> P_26_Resize.png
Procesado: P_16.png -> P_16_Resize.png
Procesado: P 35.png -> P 35 Resize.png
Procesado: P 38.png -> P 38 Resize.png
Procesado: P 17.png -> P 17 Resize.png
Procesado: P 37.png -> P 37 Resize.png
Procesado: P 9.png -> P 9 Resize.png
Procesado: P 20.png -> P 20 Resize.png
Procesado: P 36.png -> P 36 Resize.png
Procesado: P 14.png -> P 14 Resize.png
Procesado: P 7.png -> P 7 Resize.png
Procesado: P 34.png -> P 34 Resize.png
Procesado: P 39.png -> P 39 Resize.png
Procesado: P 21.png -> P 21 Resize.png
Procesado: P_23.png -> P_23_Resize.png
Procesado: P_12.png -> P_12_Resize.png
Procesado: P 28.png -> P 28 Resize.png
Procesado: P 22.png -> P 22 Resize.png
Procesado: P 18.png -> P 18 Resize.png
Procesado: P 25.png -> P 25 Resize.png
Procesado: P 13.png -> P 13 Resize.png
Procesado: P 32.png -> P 32 Resize.png
Procesado: P_27.png -> P_27_Resize.png
Procesado: P 8.png -> P 8 Resize.png
Procesado: P_15.png -> P_15_Resize.png
Procesado: P 11.png -> P 11 Resize.png
Procesado: P 40.png -> P 40 Resize.png
Redimensionado completado. Los archivos redimensionados se han
```

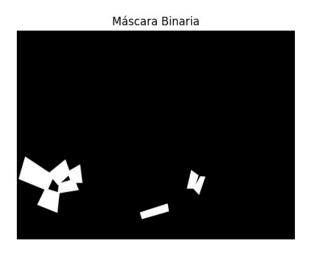
```
guardado en: /content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paola/reeeeeee
```

Comprobacion

```
import cv2
import json
import numpy as np
import matplotlib.pyplot as plt
import os
def load image(image path):
    image = cv2.imread(image path)
    return image
def create mask from json(json path, image shape):
    with open(json path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image shape[0], image shape[1]), dtype=np.uint8)
    # Dibujar las formas del JSON en la máscara
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
    return mask
def display image and mask(image, mask):
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR BGR2RGB))
    plt.title("Imagen Original")
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.imshow(mask, cmap='gray')
    plt.title("Máscara Binaria")
    plt.axis('off')
    plt.show()
image path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG NOR + JSON/PA 10.png'
```

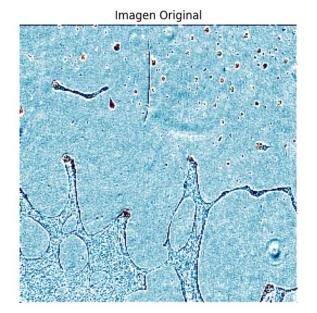
```
json_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG NOR + JSON/PA_10.json'
image = load_image(image_path)
mask = create_mask_from_json(json_path, image.shape)
display_image_and_mask(image, mask)
```

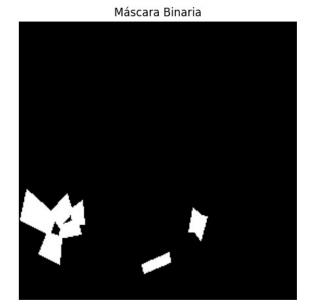




```
import cv2
import json
import numpy as np
import matplotlib.pyplot as plt
import os
def load image(image path):
    image = cv2.imread(image path)
    return image
def create_mask_from_json(json_path, image_shape):
    with open(json_path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image shape[0], image shape[1]), dtype=np.uint8)
    # Dibujar las formas del JSON en la máscara
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
```

```
return mask
def display_image_and_mask(image, mask):
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR_BGR2RGB))
    plt.title("Imagen Original")
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.imshow(mask, cmap='gray')
    plt.title("Máscara Binaria")
    plt.axis('off')
    plt.show()
image path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON
RESIZE/PA 10 Resize.png'
json_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON
RESIZE/PA 10 Resize.json'
image = load image(image path)
mask = create_mask_from_json(json_path, image.shape)
display image and mask(image, mask)
```





#DATA AUGMENTATION

FLIP

```
def load image(image path):
    return cv2.imread(image path)
def load json(json path):
    with open(json_path, 'r') as f:
        mask data = json.load(f)
    return mask data
def flip image and json(image, mask data):
    flipped image = cv2.flip(image, 1)
    image_width = mask_data['imageWidth']
    for shape in mask data['shapes']:
        shape['points'] = [[image_width - point[0], point[1]] for
point in shape['points']]
    return flipped image, mask data
def save image and json(flipped image, flipped json, output folder,
original filename):
    image name = os.path.splitext(original filename)[0] + ' flip' +
os.path.splitext(original filename)[1]
    json name = os.path.splitext(original filename)[0] + ' flip.json'
    flipped json['imagePath'] = image name
```

```
cv2.imwrite(os.path.join(output folder, image name),
flipped image)
    with open(os.path.join(output folder, json name), 'w') as f:
        ison.dump(flipped ison, f)
def process folder(img folder, json folder, output folder):
    if not os.path.exists(output folder):
        os.makedirs(output folder)
    for filename in os.listdir(img folder):
        if filename.endswith('.png') or filename.endswith('.jpg'):
            img path = os.path.join(img folder, filename)
            ison path = os.path.join(json_folder,
os.path.splitext(filename)[0] + '.json')
            if os.path.exists(json path):
                image = load image(img path)
                mask data = load json(json path)
                flipped image, flipped ison =
flip image and json(image, mask data)
                save image and json(flipped image, flipped json,
output folder, filename)
                print(f"Flip aplicado y guardado: {filename}")
img folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
json folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
output folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation'
process folder(img folder, json folder, output folder)
print("Flip de todas las imágenes y JSONs completado.")
Flip aplicado y quardado: PA 6 Resize.png
Flip aplicado y guardado: PA 3 Resize.png
Flip aplicado y guardado: PA_10_Resize.png
Flip aplicado y guardado: PA 14 Resize.png
```

```
Flip aplicado y guardado: PA 2 Resize.png
Flip aplicado y guardado: PA 11 Resize.png
Flip aplicado y guardado: PA 12 Resize.png
Flip aplicado y quardado: PA 5 Resize.png
Flip aplicado y quardado: PA 8 Resize.png
Flip aplicado y guardado: PA_7_Resize.png
Flip aplicado y guardado: PA 1 Resize.png
Flip aplicado y quardado: PA 4 Resize.png
Flip aplicado y guardado: PA 16 Resize.png
Flip aplicado y quardado: PA 17 Resize.png
Flip aplicado y guardado: PA_18_Resize.png
Flip aplicado y guardado: PA_27_Resize.png
Flip aplicado y guardado: PA 23 Resize.png
Flip aplicado y guardado: PA 35 Resize.png
Flip aplicado y guardado: PA 19 Resize.png
Flip aplicado y guardado: PA 20 Resize.png
Flip aplicado y guardado: PA 32 Resize.png
Flip aplicado y guardado: PA_25_Resize.png
Flip aplicado y quardado: PA 36 Resize.png
Flip aplicado y guardado: PA 28 Resize.png
Flip aplicado y guardado: PA 31 Resize.png
Flip aplicado y guardado: PA 24 Resize.png
Flip aplicado y guardado: PA 21 Resize.png
Flip aplicado y guardado: PA 29 Resize.png
Flip aplicado y guardado: PA 34 Resize.png
Flip de todas las imágenes y JSONs completado.
```

ROTACION de 90,180,270

```
import os
import cv2
import json

def load_image(image_path):
    return cv2.imread(image_path)

def load_json(json_path):
    with open(json_path, 'r') as f:
        mask_data = json.load(f)
    return mask_data

def rotate_image_and_json_90(image, mask_data):
    rotated_image = cv2.rotate(image, cv2.ROTATE_90_COUNTERCLOCKWISE)
    image_height, image_width = image.shape[:2]

for shape in mask_data['shapes']:
        shape['points'] = [[point[1], image_height - point[0]] for
```

```
point in shape['points']]
    mask data['imageHeight'], mask data['imageWidth'] = image width,
image height
    return rotated image, mask data
def save image and json(rotated image, rotated json, output folder,
original filename):
    image name = os.path.splitext(original filename)[0] + ' 90' +
os.path.splitext(original filename)[1]
    ison name = os.path.splitext(original filename)[0] + ' 90.json'
    rotated json['imagePath'] = image name
    cv2.imwrite(os.path.join(output folder, image name),
rotated image)
    with open(os.path.join(output folder, json name), 'w') as f:
        json.dump(rotated json, f)
def process folder(img folder, json folder, output folder):
    if not os.path.exists(output folder):
        os.makedirs(output folder)
    for filename in os.listdir(img folder):
        if filename.endswith('.png') or filename.endswith('.jpg'):
            img path = os.path.join(img folder, filename)
            json path = os.path.join(json_folder,
os.path.splitext(filename)[0] + '.json')
            if os.path.exists(json path):
                image = load image(img path)
                mask data = load json(json path)
                rotated_image, rotated json =
rotate image and json 90(image, mask data)
                save image and json(rotated image, rotated json,
output folder, filename)
                print(f"Rotación de 90 grados aplicada y guardada:
{filename}")
```

```
img folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
json folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
output folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation'
process folder(img folder, json folder, output folder)
print("Rotación de 90 grados de todas las imágenes y JSONs
completada.")
Rotación de 90 grados aplicada y guardada: PA_6_Resize.png
Rotación de 90 grados aplicada y guardada: PA_3_Resize.png
Rotación de 90 grados aplicada y guardada: PA 10 Resize.png
Rotación de 90 grados aplicada y guardada: PA_14_Resize.png
Rotación de 90 grados aplicada y guardada: PA 2 Resize.png
Rotación de 90 grados aplicada y guardada: PA 11 Resize.png
Rotación de 90 grados aplicada y guardada: PA_12_Resize.png
Rotación de 90 grados aplicada y guardada: PA_5_Resize.png
Rotación de 90 grados aplicada y guardada: PA_8_Resize.png
Rotación de 90 grados aplicada y quardada: PA 7 Resize.png
Rotación de 90 grados aplicada y guardada: PA 1 Resize.png
Rotación de 90 grados aplicada y guardada: PA 4 Resize.png
Rotación de 90 grados aplicada y guardada: PA 16 Resize.png
Rotación de 90 grados aplicada y guardada: PA 17 Resize.png
Rotación de 90 grados aplicada y guardada: PA_18_Resize.png
Rotación de 90 grados aplicada y guardada: PA 27 Resize.png
Rotación de 90 grados aplicada y guardada: PA 23 Resize.png
Rotación de 90 grados aplicada y guardada: PA 35 Resize.png
Rotación de 90 grados aplicada y guardada: PA 19 Resize.png
Rotación de 90 grados aplicada y guardada: PA_20_Resize.png
Rotación de 90 grados aplicada y guardada: PA 32 Resize.png
Rotación de 90 grados aplicada y guardada: PA 25 Resize.png
Rotación de 90 grados aplicada y guardada: PA_36_Resize.png
Rotación de 90 grados aplicada y guardada: PA 28 Resize.png
Rotación de 90 grados aplicada y guardada: PA 31 Resize.png
Rotación de 90 grados aplicada y guardada: PA 24 Resize.png
Rotación de 90 grados aplicada y guardada: PA 21 Resize.png
Rotación de 90 grados aplicada y guardada: PA 29 Resize.png
Rotación de 90 grados aplicada y guardada: PA 34 Resize.png
Rotación de 90 grados de todas las imágenes y JSONs completada.
def load image(image path):
    return cv2.imread(image path)
```

```
def load ison(ison path):
    with open(json path, 'r') as f:
        mask_data = json.load(f)
    return mask data
def rotate image and json 180(image, mask data):
    rotated image = cv2.rotate(image, cv2.ROTATE 180)
    image height, image width = image.shape[:2]
    for shape in mask data['shapes']:
        shape['points'] = [[image width - point[0], image height -
point[1]] for point in shape['points']]
    return rotated image, mask data
def save image and json(rotated image, rotated json, output folder,
original filename):
    image name = os.path.splitext(original filename)[0] + ' 180' +
os.path.splitext(original filename)[1]
    json name = os.path.splitext(original filename)[0] + ' 180.json'
    rotated json['imagePath'] = image name
    cv2.imwrite(os.path.join(output folder, image name),
rotated image)
    with open(os.path.join(output_folder, json name), 'w') as f:
        json.dump(rotated json, f)
def process folder(img folder, json folder, output folder):
    if not os.path.exists(output folder):
        os.makedirs(output folder)
    for filename in os.listdir(img folder):
        if filename.endswith('.png') or filename.endswith('.jpg'):
            img path = os.path.join(img folder, filename)
            json path = os.path.join(json folder,
os.path.splitext(filename)[0] + '.json')
            if os.path.exists(json path):
                image = load image(img path)
                mask data = load json(json path)
```

```
rotated image, rotated ison =
rotate image and json 180(image, mask data)
                save_image_and_json(rotated_image, rotated json,
output folder, filename)
                print(f"Rotación de 180 grados aplicada y guardada:
{filename}")
img folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
json folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
output folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation'
process folder(img folder, json folder, output folder)
print("Rotación de 180 grados de todas las imágenes y JSONs
completada.")
Rotación de 180 grados aplicada y guardada: PA_6_Resize.png
Rotación de 180 grados aplicada y guardada: PA 3 Resize.png
Rotación de 180 grados aplicada y guardada: PA 10 Resize.png
Rotación de 180 grados aplicada y guardada: PA 14 Resize.png
Rotación de 180 grados aplicada y quardada: PA 2 Resize.png
Rotación de 180 grados aplicada y guardada: PA 11 Resize.png
Rotación de 180 grados aplicada y guardada: PA 12 Resize.png
Rotación de 180 grados aplicada y guardada: PA 5 Resize.png
Rotación de 180 grados aplicada y quardada: PA 8 Resize.png
Rotación de 180 grados aplicada y guardada: PA_7_Resize.png
Rotación de 180 grados aplicada y guardada: PA 1 Resize.png
Rotación de 180 grados aplicada y quardada: PA 4 Resize.png
Rotación de 180 grados aplicada y guardada: PA 16 Resize.png
Rotación de 180 grados aplicada y guardada: PA 17 Resize.png
Rotación de 180 grados aplicada y guardada: PA_18_Resize.png
Rotación de 180 grados aplicada y guardada: PA 27 Resize.png
Rotación de 180 grados aplicada y guardada: PA 23 Resize.png
Rotación de 180 grados aplicada y guardada: PA 35 Resize.png
Rotación de 180 grados aplicada y guardada: PA 19 Resize.png
Rotación de 180 grados aplicada y guardada: PA 20 Resize.png
Rotación de 180 grados aplicada y quardada: PA 32 Resize.png
Rotación de 180 grados aplicada y guardada: PA 25 Resize.png
Rotación de 180 grados aplicada y guardada: PA 36 Resize.png
Rotación de 180 grados aplicada y guardada: PA 28 Resize.png
Rotación de 180 grados aplicada y guardada: PA 31 Resize.png
```

```
Rotación de 180 grados aplicada y guardada: PA 24 Resize.png
Rotación de 180 grados aplicada y guardada: PA 21 Resize.png
Rotación de 180 grados aplicada y guardada: PA 29 Resize.png
Rotación de 180 grados aplicada y guardada: PA 34 Resize.png
Rotación de 180 grados de todas las imágenes y JSONs completada.
import os
import cv2
import json
def load image(image path):
    return cv2.imread(image path)
def load ison(ison path):
    with open(json_path, 'r') as f:
        mask data = json.load(f)
    return mask data
def rotate_image_and json 270(image, mask data):
    rotated image = cv2.rotate(image, cv2.ROTATE 90 CLOCKWISE)
    image height, image width = image.shape[:2]
    for shape in mask data['shapes']:
        shape['points'] = [[image height - point[1], point[0]] for
point in shape['points']]
    mask data['imageHeight'], mask data['imageWidth'] = image width,
image height
    return rotated image, mask data
def save image and json(rotated image, rotated json, output folder,
original filename):
    image name = os.path.splitext(original filename)[0] + ' 270' +
os.path.splitext(original filename)[1]
    ison name = os.path.splitext(original filename)[0] + ' 270.json'
    rotated json['imagePath'] = image name
    cv2.imwrite(os.path.join(output folder, image name),
rotated image)
    with open(os.path.join(output folder, json name), 'w') as f:
```

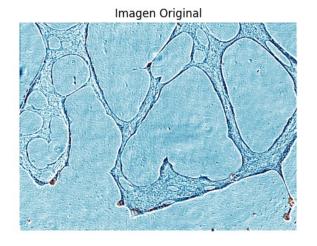
```
ison.dump(rotated ison, f)
def process folder(img folder, json folder, output folder):
    if not os.path.exists(output folder):
        os.makedirs(output folder)
    for filename in os.listdir(img folder):
        if filename.endswith('.png') or filename.endswith('.ipg'):
            img path = os.path.join(img folder, filename)
            json path = os.path.join(json folder,
os.path.splitext(filename)[0] + '.json')
            if os.path.exists(json path):
                image = load_image(img_path)
                mask data = load json(json path)
                rotated image, rotated json =
rotate image and json 270(image, mask data)
                save image and json(rotated image, rotated json,
output folder, filename)
                print(f"Rotación de 270 grados aplicada y guardada:
{filename}")
img_folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
ison folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paulina/IMG RESIZE + JSON RESIZE'
output folder = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation'
process folder(img folder, json folder, output folder)
print("Rotación de 270 grados de todas las imágenes y JSONs
completada.")
Rotación de 270 grados aplicada y guardada: PA 6 Resize.png
Rotación de 270 grados aplicada y guardada: PA_3_Resize.png
Rotación de 270 grados aplicada y guardada: PA 10 Resize.png
Rotación de 270 grados aplicada y guardada: PA 14 Resize.png
Rotación de 270 grados aplicada y guardada: PA_2_Resize.png
Rotación de 270 grados aplicada y guardada: PA 11 Resize.png
Rotación de 270 grados aplicada y guardada: PA 12 Resize.png
Rotación de 270 grados aplicada y guardada: PA_5_Resize.png
Rotación de 270 grados aplicada y guardada: PA 8 Resize.png
```

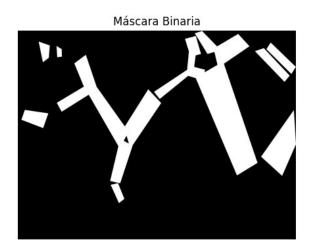
```
Rotación de 270 grados aplicada y guardada: PA 7 Resize.png
Rotación de 270 grados aplicada y quardada: PA 1 Resize.png
Rotación de 270 grados aplicada y guardada: PA 4 Resize.png
Rotación de 270 grados aplicada y quardada: PA 16 Resize.png
Rotación de 270 grados aplicada y quardada: PA 17 Resize.png
Rotación de 270 grados aplicada y guardada: PA 18 Resize.png
Rotación de 270 grados aplicada y quardada: PA 27 Resize.png
Rotación de 270 grados aplicada y quardada: PA 23 Resize.png
Rotación de 270 grados aplicada y guardada: PA 35 Resize.png
Rotación de 270 grados aplicada y quardada: PA 19 Resize.png
Rotación de 270 grados aplicada y guardada: PA 20 Resize.png
Rotación de 270 grados aplicada y guardada: PA 32 Resize.png
Rotación de 270 grados aplicada y guardada: PA 25 Resize.png
Rotación de 270 grados aplicada y quardada: PA 36 Resize.png
Rotación de 270 grados aplicada y guardada: PA 28 Resize.png
Rotación de 270 grados aplicada y guardada: PA 31 Resize.png
Rotación de 270 grados aplicada y guardada: PA 24 Resize.png
Rotación de 270 grados aplicada y guardada: PA_21_Resize.png
Rotación de 270 grados aplicada y quardada: PA 29 Resize.png
Rotación de 270 grados aplicada y guardada: PA 34 Resize.png
Rotación de 270 grados de todas las imágenes y JSONs completada.
```

#Comprobacion

```
import cv2
import ison
import numpy as np
import matplotlib.pyplot as plt
import os
def load image(image path):
    image = cv2.imread(image path)
    return image
def create mask from json(json path, image shape):
    with open(json path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image shape[0], image shape[1]), dtype=np.uint8)
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
    return mask
```

```
def display image and mask(image, mask):
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR BGR2RGB))
    plt.title("Imagen Original")
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.imshow(mask, cmap='gray')
    plt.title("Máscara Binaria")
    plt.axis('off')
    plt.show()
image_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/IMG NOR + JSON/H_10.png'
json_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/IMG NOR + JSON/H 10.json'
image = load image(image path)
mask = create mask from json(json path, image.shape)
display image and mask(image, mask)
```

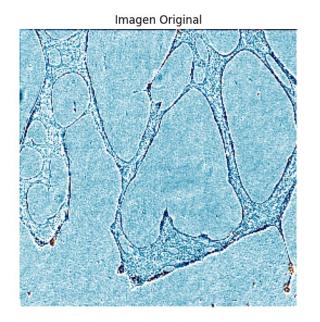




```
import cv2
import json
import numpy as np
import matplotlib.pyplot as plt
```

```
import os
def load image(image path):
    image = cv2.imread(image path)
    return image
def create_mask_from_json(json_path, image_shape):
    with open(json path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image shape[0], image shape[1]), dtype=np.uint8)
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
    return mask
def display image and mask(image, mask):
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR BGR2RGB))
    plt.title("Imagen Original")
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.imshow(mask, cmap='gray')
    plt.title("Máscara Binaria")
    plt.axis('off')
    plt.show()
image path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/IMG RESIZE + JSON
RESIZE/H 10 Resize.png'
json path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/IMG RESIZE + JSON
RESIZE/H 10 Resize.json'
image = load image(image path)
mask = create mask from json(json path, image.shape)
```

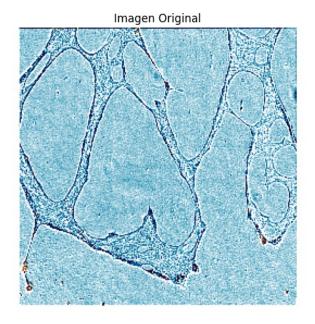
display_image_and_mask(image, mask)





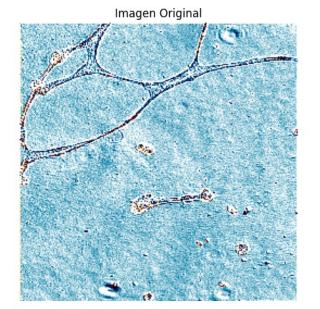
```
import cv2
import json
import numpy as np
import matplotlib.pyplot as plt
import os
def load_image(image_path):
    image = cv2.imread(image path)
    return image
def create_mask_from_json(json_path, image_shape):
    with open(json path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image_shape[0], image_shape[1]), dtype=np.uint8)
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
    return mask
def display image and mask(image, mask):
```

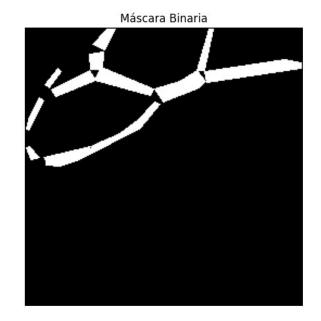
```
plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR BGR2RGB))
    plt.title("Imagen Original")
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.imshow(mask, cmap='gray')
    plt.title("Máscara Binaria")
    plt.axis('off')
    plt.show()
image path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation/H 10 Resize flip.png'
json_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation/H 10 Resize flip.json'
image = load image(image path)
mask = create mask from json(json path, image.shape)
display_image_and_mask(image, mask)
```





```
def load image(image path):
    image = cv2.imread(image path)
    return image
def create mask from json(json path, image shape):
    with open(json path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image shape[0], image shape[1]), dtype=np.uint8)
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
    return mask
def display_image_and_mask(image, mask):
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR BGR2RGB))
    plt.title("Imagen Original")
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.imshow(mask, cmap='gray')
    plt.title("Máscara Binaria")
    plt.axis('off')
    plt.show()
image_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paola/Data_Augmentation/90/P_40_Resize_90.png'
json path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paola/Data Augmentation/90/P 40 Resize 90.json'
image = load image(image path)
mask = create mask from json(json path, image.shape)
display image and mask(image, mask)
```





```
import cv2
import json
import numpy as np
import matplotlib.pyplot as plt
import os
def load image(image path):
    image = cv2.imread(image_path)
    return image
def create mask from json(json path, image shape):
   with open(json_path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image shape[0], image shape[1]), dtype=np.uint8)
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
    return mask
def display_image_and_mask(image, mask):
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR BGR2RGB))
    plt.title("Imagen Original")
```

```
plt.axis('off')

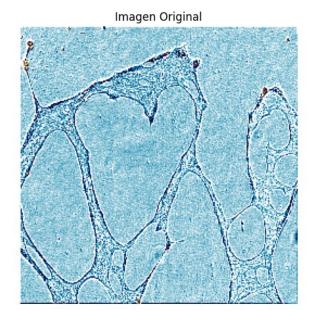
plt.subplot(1, 2, 2)
plt.imshow(mask, cmap='gray')
plt.title("Máscara Binaria")
plt.axis('off')

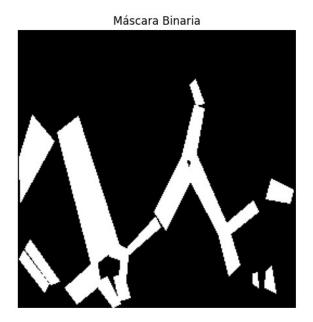
plt.show()

image_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-SOLUCION/IMG MIOTUBOS/Herbert/Data_Augmentation/H_10_Resize_180.png'
json_path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-SOLUCION/IMG MIOTUBOS/Herbert/Data_Augmentation/H_10_Resize_180.json'
image = load_image(image_path)

mask = create_mask_from_json(json_path, image.shape)

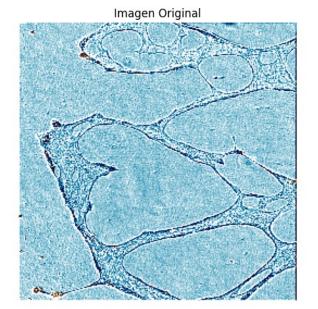
display_image_and_mask(image, mask)
```





```
def load_image(image_path):
   image = cv2.imread(image_path)
   return image
```

```
def create mask from json(json path, image shape):
    with open(json path, 'r') as f:
        data = json.load(f)
    mask = np.zeros((image shape[0], image shape[1]), dtype=np.uint8)
    for shape in data['shapes']:
        points = np.array(shape['points'], dtype=np.int32)
        cv2.fillPoly(mask, [points], 255)
    return mask
def display image and mask(image, mask):
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(cv2.cvtColor(image, cv2.COLOR_BGR2RGB))
    plt.title("Imagen Original")
    plt.axis('off')
    plt.subplot(1, 2, 2)
    plt.imshow(mask, cmap='gray')
    plt.title("Máscara Binaria")
    plt.axis('off')
    plt.show()
image path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation/H 10 Resize 270.png'
ison path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Herbert/Data Augmentation/H 10 Resize 270.json'
image = load image(image path)
mask = create_mask_from_json(json_path, image.shape)
display image and mask(image, mask)
```





Entrenamiento de CNN

```
import os
import cv2
import json
import numpy as np
from sklearn.model_selection import train_test_split
def load_data(dataset_path):
    images = []
    masks = []
    for json_file in os.listdir(dataset_path):
        if json file.endswith('.json'):
            json_path = os.path.join(dataset_path, json_file)
            with open(json_path) as f:
                data = json.load(f)
                image_name = data['imagePath']
                mask_data = data['shapes']
            img path = os.path.join(dataset path, image name)
            image = cv2.imread(img path, cv2.IMREAD GRAYSCALE)
            image = image / 255.0
            images.append(image)
            mask = np.zeros(image.shape, dtype=np.float32)
```

```
for shape in mask data:
                if shape['label'] == 'miotubo':
                    points = np.array(shape['points'], dtype=np.int32)
                    cv2.fillPoly(mask, [points], 1)
            masks.append(mask)
    images = np.array(images).astype(np.float32)
    masks = np.array(masks).astype(np.float32)
    images = np.expand dims(images, axis=-1)
    masks = np.expand dims(masks, axis=-1)
    print(f"Imágenes cargadas: {images shape}, Máscaras cargadas:
{masks.shape}")
    return images, masks
dataset path = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG MIOTUBOS/Paola/reeeeeee'
X, y = load data(dataset path)
X train, X val, y train, y val = train test split(X, y, test size=0.2,
random state=42)
Imágenes cargadas: (40, 256, 256, 1), Máscaras cargadas: (40, 256,
256, 1)
from sklearn.model selection import train test split
X_train, X_val, y_train, y_val = train_test_split(X, y, test_size=0.2,
random state=42)
print(f"Dimensiones del conjunto de entrenamiento: {X train.shape},
{y train.shape}")
print(f"Dimensiones del conjunto de validación: {X val.shape},
{y val.shape}")
Dimensiones del conjunto de entrenamiento: (32, 256, 256, 1), (32,
256, 256, 1)
Dimensiones del conjunto de validación: (8, 256, 256, 1), (8, 256,
256, 1)
from tensorflow.keras import layers, models
def build unet(input shape):
    inputs = layers.Input(shape=input shape)
```

```
conv1 = layers.Conv2D(64, (3, 3), activation='relu',
padding='same')(inputs)
    conv1 = layers.Conv2D(64, (3, 3), activation='relu',
padding='same')(conv1)
    pool1 = layers.MaxPooling2D(pool size=(2, 2))(conv1)
    conv2 = layers.Conv2D(128, (3, 3), activation='relu',
padding='same')(pool1)
    conv2 = layers.Conv2D(128, (3, 3), activation='relu',
padding='same')(conv2)
    pool2 = layers.MaxPooling2D(pool size=(2, 2))(conv2)
    conv3 = layers.Conv2D(256, (3, 3), activation='relu',
padding='same')(pool2)
    conv3 = layers.Conv2D(256, (3, 3), activation='relu',
padding='same')(conv3)
    pool3 = layers.MaxPooling2D(pool size=(2, 2))(conv3)
    conv4 = layers.Conv2D(512, (3, 3), activation='relu',
padding='same')(pool3)
    conv4 = layers.Conv2D(512, (3, 3), activation='relu',
padding='same')(conv4)
    pool4 = layers.MaxPooling2D(pool size=(2, 2))(conv4)
    conv5 = layers.Conv2D(1024, (3, 3), activation='relu',
padding='same')(pool4)
    conv5 = layers.Conv2D(1024, (3, 3), activation='relu',
padding='same')(conv5)
    up6 = layers.UpSampling2D(size=(2, 2))(conv5)
    conv6 = layers.Conv2D(512, (3, 3), activation='relu',
padding='same')(up6)
    conv6 = layers.Conv2D(512, (3, 3), activation='relu',
padding='same')(conv6)
    concat6 = layers.concatenate([conv4, conv6], axis=3)
    conv6 = layers.Conv2D(512, (3, 3), activation='relu',
padding='same')(concat6)
    conv6 = layers.Conv2D(512, (3, 3), activation='relu',
padding='same')(conv6)
    up7 = layers.UpSampling2D(size=(2, 2))(conv6)
    conv7 = layers.Conv2D(256, (3, 3), activation='relu',
padding='same')(up7)
    conv7 = layers.Conv2D(256, (3, 3), activation='relu',
padding='same')(conv7)
    concat7 = layers.concatenate([conv3, conv7], axis=3)
    conv7 = layers.Conv2D(256, (3, 3), activation='relu',
```

```
padding='same')(concat7)
    conv7 = layers.Conv2D(256, (3, 3), activation='relu',
padding='same')(conv7)
    up8 = layers.UpSampling2D(size=(2, 2))(conv7)
    conv8 = layers.Conv2D(128, (3, 3), activation='relu',
padding='same')(up8)
    conv8 = layers.Conv2D(128, (3, 3), activation='relu',
padding='same')(conv8)
    concat8 = layers.concatenate([conv2, conv8], axis=3)
    conv8 = layers.Conv2D(128, (3, 3), activation='relu',
padding='same')(concat8)
    conv8 = layers.Conv2D(128, (3, 3), activation='relu',
padding='same')(conv8)
    up9 = layers.UpSampling2D(size=(2, 2))(conv8)
    conv9 = layers.Conv2D(64, (3, 3), activation='relu',
padding='same')(up9)
    conv9 = layers.Conv2D(64, (3, 3), activation='relu',
padding='same')(conv9)
    concat9 = layers.concatenate([conv1, conv9], axis=3)
    conv9 = layers.Conv2D(64, (3, 3), activation='relu',
padding='same')(concat9)
    conv9 = layers.Conv2D(64, (3, 3), activation='relu',
padding='same')(conv9)
    outputs = layers.Conv2D(1, (1, 1), activation='sigmoid')(conv9)
    model = models.Model(inputs=[inputs], outputs=[outputs])
    model.compile(optimizer='adam', loss='binary crossentropy',
metrics=['accuracy'])
    return model
input shape = X train.shape[1:]
model = build unet(input shape)
model.summary()
Model: "functional 5"
  Layer (type)
                            Output Shape
                                                               Param #
  Connected to
```

(None, 256, 256, 64)	640
(None, 256, 256, 64)	36,928
(None, 128, 128, 64)	0
(None, 128, 128, 128)	73,856
(None, 128, 128, 128)	147,584
(None, 64, 64, 128) 	Θ
(None, 64, 64, 256)	295,168
(None, 64, 64, 256)	590,080
(None, 32, 32, 256)	Θ
	(None, 256, 256, 64) (None, 128, 128, 64) (None, 128, 128, 128) (None, 64, 64, 128) (None, 64, 64, 256) (None, 64, 64, 256) (None, 64, 64, 256)

conv2d_141 (Conv2D) max_pooling2d_22[0][0]	(None, 32, 32, 512)	1,180,160
conv2d_142 (Conv2D) conv2d_141[0][0]	(None, 32, 32, 512)	2,359,808
max_pooling2d_23 conv2d_142[0][0] (MaxPooling2D)	(None, 16, 16, 512)	0
conv2d_143 (Conv2D) max_pooling2d_23[0][0]	(None, 16, 16, 1024)	4,719,616
conv2d_144 (Conv2D) conv2d_143[0][0]	(None, 16, 16, 1024)	9,438,208
up_sampling2d_20 conv2d_144[0][0] (UpSampling2D)	(None, 32, 32, 1024)	Θ
conv2d_145 (Conv2D) up_sampling2d_20[0][0]	(None, 32, 32, 512)	4,719,104
conv2d_146 (Conv2D) conv2d_145[0][0]	(None, 32, 32, 512)	2,359,808
concatenate_20 conv2d_142[0][0], (Concatenate) conv2d_146[0][0]	(None, 32, 32, 1024)	0
conv2d_147 (Conv2D) concatenate_20[0][0]	(None, 32, 32, 512)	4,719,104
conv2d_148 (Conv2D) conv2d_147[0][0]	(None, 32, 32, 512)	2,359,808

up_sampling2d_21 conv2d_148[0][0] (UpSampling2D)	(None, 64, 64, 512) 	0
conv2d_149 (Conv2D) up_sampling2d_21[0][0]	(None, 64, 64, 256)	1,179,904
conv2d_150 (Conv2D) conv2d_149[0][0]	(None, 64, 64, 256)	590,080
concatenate_21 conv2d_140[0][0], (Concatenate) conv2d_150[0][0]	(None, 64, 64, 512) 	0
conv2d_151 (Conv2D) concatenate_21[0][0]	(None, 64, 64, 256)	1,179,904
conv2d_152 (Conv2D) conv2d_151[0][0]	(None, 64, 64, 256)	590,080
up_sampling2d_22 conv2d_152[0][0] (UpSampling2D)	(None, 128, 128, 256) 	0
conv2d_153 (Conv2D) up_sampling2d_22[0][0]	(None, 128, 128, 128)	295,040
conv2d_154 (Conv2D) conv2d_153[0][0]	(None, 128, 128, 128)	147,584
concatenate_22 conv2d_138[0][0], (Concatenate) conv2d_154[0][0]	(None, 128, 128, 256) 	0

conv2d_155 (Conv2D) concatenate_22[0][0]	(None, 128, 128, 128)	295,040
conv2d_156 (Conv2D) conv2d_155[0][0]	(None, 128, 128, 128)	147,584
up_sampling2d_23 conv2d_156[0][0] (UpSampling2D)	(None, 256, 256, 128)	0
conv2d_157 (Conv2D) up_sampling2d_23[0][0]	(None, 256, 256, 64)	73,792
conv2d_158 (Conv2D) conv2d_157[0][0]	(None, 256, 256, 64)	36,928
concatenate_23 conv2d_136[0][0], (Concatenate) conv2d_158[0][0]	(None, 256, 256, 128)	Θ
conv2d_159 (Conv2D) concatenate_23[0][0]	(None, 256, 256, 64)	73,792
conv2d_160 (Conv2D) conv2d_159[0][0]	(None, 256, 256, 64)	36,928
conv2d_161 (Conv2D) conv2d_160[0][0]	(None, 256, 256, 1)	65

Total params: 37,646,593 (143.61 MB)

Trainable params: 37,646,593 (143.61 MB)

Non-trainable params: 0 (0.00 B)

batch_size=8,

```
epochs=50)
model.save('/content/sample data/1ModeloFinal.h5')
Epoch 1/50
           ______ 14s 995ms/step - accuracy: 0.5236 - loss:
4/4 -----
0.8737 - val accuracy: 0.9546 - val loss: 0.5302
Epoch 2/50
             ______ 3s 702ms/step - accuracy: 0.9217 - loss:
4/4 -----
0.5454 - val accuracy: 0.9546 - val loss: 0.4690
Epoch 3/50
               ______ 5s 661ms/step - accuracy: 0.9234 - loss:
0.4442 - val accuracy: 0.9546 - val loss: 0.1963
Epoch 4/50
                ---- 3s 662ms/step - accuracy: 0.9273 - loss:
0.2897 - val accuracy: 0.9546 - val loss: 0.1936
Epoch 5/50
           ______ 5s 662ms/step - accuracy: 0.9248 - loss:
4/4 —
0.2686 - val accuracy: 0.9546 - val_loss: 0.1954
0.2715 - val accuracy: 0.9546 - val loss: 0.1889
0.2662 - val accuracy: 0.9546 - val loss: 0.1899
0.2719 - val accuracy: 0.9546 - val loss: 0.1942
Epoch 9/50
                5s 706ms/step - accuracy: 0.9255 - loss:
4/4 ----
0.2628 - val accuracy: 0.9546 - val loss: 0.1868
Epoch 10/50
                _____ 5s 671ms/step - accuracy: 0.9273 - loss:
4/4 -
0.2555 - val accuracy: 0.9546 - val loss: 0.1873
Epoch 11/50

5s 672ms/step - accuracy: 0.9271 - loss:
0.2538 - val accuracy: 0.9546 - val loss: 0.1871
Epoch 12/50

5s 669ms/step - accuracy: 0.9278 - loss:
0.2495 - val accuracy: 0.9546 - val loss: 0.1802
Epoch 13/50

4/4 — 5s 667ms/step - accuracy: 0.9206 - loss:
0.2711 - val_accuracy: 0.9546 - val_loss: 0.2072
Epoch 14/50
             ______ 5s 661ms/step - accuracy: 0.9227 - loss:
0.2611 - val accuracy: 0.9546 - val loss: 0.1726
Epoch 15/50
              3s 662ms/step - accuracy: 0.9228 - loss:
4/4 -----
0.2577 - val accuracy: 0.9546 - val_loss: 0.1734
```

```
Epoch 16/50
          ______ 5s 700ms/step - accuracy: 0.9248 - loss:
4/4 —
0.2457 - val accuracy: 0.9545 - val loss: 0.1733
Epoch 17/50

5s 657ms/step - accuracy: 0.9245 - loss:
0.2416 - val accuracy: 0.9538 - val_loss: 0.1688
Epoch 18/50
             ______ 3s 660ms/step - accuracy: 0.9143 - loss:
4/4 -----
0.2552 - val accuracy: 0.9546 - val loss: 0.1660
Epoch 19/50
              ______ 3s 661ms/step - accuracy: 0.9228 - loss:
4/4 -----
0.2550 - val_accuracy: 0.9536 - val_loss: 0.1734
Epoch 20/50
                ----- 3s 703ms/step - accuracy: 0.9221 - loss:
4/4 ——
0.2332 - val accuracy: 0.9538 - val loss: 0.1604
Epoch 21/50
              ______ 5s 656ms/step - accuracy: 0.9157 - loss:
4/4 —
0.2625 - val_accuracy: 0.9533 - val_loss: 0.1640
Epoch 22/50

5s 658ms/step - accuracy: 0.9258 - loss:
0.2287 - val accuracy: 0.9540 - val loss: 0.1614
0.2414 - val accuracy: 0.9522 - val_loss: 0.1603
0.2401 - val accuracy: 0.9521 - val_loss: 0.1605
Epoch 25/50
               _____ 5s 701ms/step - accuracy: 0.9271 - loss:
0.2263 - val accuracy: 0.9546 - val loss: 0.1667
Epoch 26/50
               _____ 3s 663ms/step - accuracy: 0.9202 - loss:
0.2455 - val accuracy: 0.9517 - val loss: 0.1617
Epoch 27/50

5s 661ms/step - accuracy: 0.9214 - loss:
0.2364 - val accuracy: 0.9530 - val_loss: 0.1590
Epoch 28/50

5s 664ms/step - accuracy: 0.9234 - loss:
0.2336 - val accuracy: 0.9514 - val loss: 0.1661
Epoch 29/50

4/4 — 5s 662ms/step - accuracy: 0.9248 - loss:
0.2295 - val accuracy: 0.9537 - val loss: 0.1582
0.2382 - val accuracy: 0.9536 - val_loss: 0.1650
Epoch 31/50
              ______ 3s 705ms/step - accuracy: 0.9240 - loss:
0.2221 - val accuracy: 0.9546 - val loss: 0.1952
Epoch 32/50
```

```
______ 5s 700ms/step - accuracy: 0.9230 - loss:
0.2749 - val accuracy: 0.9539 - val loss: 0.1624
Epoch 33/50
                  _____ 5s 661ms/step - accuracy: 0.9206 - loss:
4/4 —
0.2343 - val accuracy: 0.9546 - val loss: 0.1533
Epoch 34/50
              ______ 3s 707ms/step - accuracy: 0.9280 - loss:
4/4 -
0.2200 - val accuracy: 0.9523 - val loss: 0.1610
Epoch 35/50

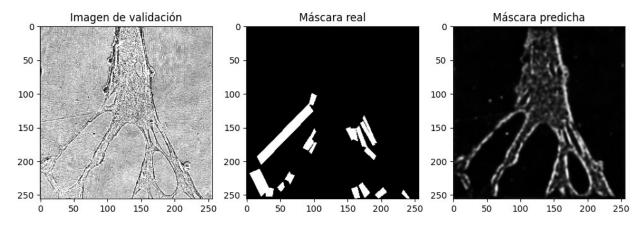
4/4 — 5s 661ms/step - accuracy: 0.9272 - loss:
0.2308 - val accuracy: 0.9543 - val loss: 0.1581
Epoch 36/50
               ______ 5s 697ms/step - accuracy: 0.9226 - loss:
4/4 ———
0.2358 - val accuracy: 0.9542 - val loss: 0.1562
Epoch 37/50
                ______ 5s 660ms/step - accuracy: 0.9243 - loss:
4/4 ———
0.2326 - val_accuracy: 0.9545 - val_loss: 0.1551
Epoch 38/50
                  ---- 5s 697ms/step - accuracy: 0.9254 - loss:
0.2220 - val accuracy: 0.9546 - val loss: 0.1532
Epoch 39/50
                 _____ 3s 661ms/step - accuracy: 0.9267 - loss:
4/4 —
0.2143 - val accuracy: 0.9543 - val loss: 0.1529
Epoch 40/50

3s 704ms/step - accuracy: 0.9222 - loss:
0.2243 - val_accuracy: 0.9546 - val loss: 0.1500
Epoch 41/50

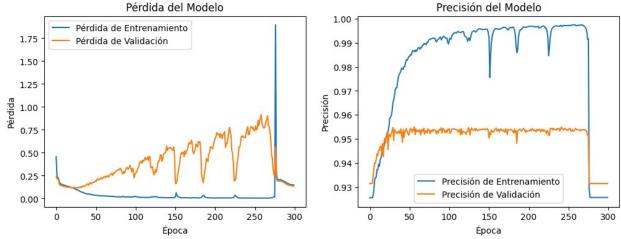
3s 702ms/step - accuracy: 0.9251 - loss:
0.2179 - val accuracy: 0.9543 - val_loss: 0.1520
Epoch 42/50
               _______ 5s 659ms/step - accuracy: 0.9286 - loss:
4/4 -----
0.2093 - val accuracy: 0.9546 - val_loss: 0.1455
Epoch 43/50
                ______ 5s 702ms/step - accuracy: 0.9282 - loss:
0.2075 - val accuracy: 0.9547 - val loss: 0.1570
Epoch 44/50
                  _____ 5s 658ms/step - accuracy: 0.9273 - loss:
0.2054 - val accuracy: 0.9546 - val loss: 0.1562
Epoch 45/50
4/4 -
                ______ 3s 659ms/step - accuracy: 0.9174 - loss:
0.2326 - val accuracy: 0.9532 - val_loss: 0.1396
Epoch 46/50

5s 701ms/step - accuracy: 0.9265 - loss:
0.1948 - val accuracy: 0.9456 - val loss: 0.1382
Epoch 47/50
                ______ 5s 659ms/step - accuracy: 0.9270 - loss:
4/4 ----
0.1953 - val accuracy: 0.9544 - val loss: 0.1467
Epoch 48/50
4/4 -
                  _____ 5s 698ms/step - accuracy: 0.9224 - loss:
```

```
0.2257 - val accuracy: 0.9547 - val loss: 0.1604
Epoch 49/50
                  _____ 5s 659ms/step - accuracy: 0.9235 - loss:
4/4 —
0.2392 - val accuracy: 0.9547 - val loss: 0.1483
Epoch 50/50
                    --- 5s 658ms/step - accuracy: 0.9236 - loss:
4/4 -
0.2038 - val accuracy: 0.9546 - val loss: 0.1386
WARNING:absl:You are saving your model as an HDF5 file via
`model.save()` or `keras.saving.save model(model)`. This file format
is considered legacy. We recommend using instead the native Keras
format, e.g. `model.save('my_model.keras')` or
`keras.saving.save model(model, 'my model.keras')`.
import matplotlib.pyplot as plt
predictions = model.predict(X val)
n = 6
plt.figure(figsize=(12, 6))
plt.subplot(1, 3, 1)
plt.title("Imagen de validación")
plt.imshow(X val[n].squeeze(), cmap='gray')
plt.subplot(1, 3, 2)
plt.title("Máscara real")
plt.imshow(y val[n].squeeze(), cmap='gray')
plt.subplot(1, 3, 3)
plt.title("Máscara predicha")
plt.imshow(predictions[n].squeeze(), cmap='gray')
plt.show()
1/1 -
                        0s 29ms/step
```



```
import matplotlib.pyplot as plt
plt.figure(figsize=(12, 4))
plt.subplot(1, 2, 1)
plt.plot(history.history['loss'], label='Pérdida de Entrenamiento')
plt.plot(history.history['val loss'], label='Pérdida de Validación')
plt.title('Pérdida del Modelo')
plt.xlabel('Época')
plt.ylabel('Pérdida')
plt.legend()
plt.subplot(1, 2, 2)
plt.plot(history.history['accuracy'], label='Precisión de
Entrenamiento')
plt.plot(history.history['val_accuracy'], label='Precisión de
Validación')
plt.title('Precisión del Modelo')
plt.xlabel('Época')
plt.ylabel('Precisión')
plt.legend()
plt.show()
```



```
model = load model('/content/sample data/SeundoModeloFinal.h5')
image dir = '/content/drive/MyDrive/7mo Semestre /RETO-MIOTUBOS-
SOLUCION/IMG-VIDEO/Plate1 derived A3 04 05 Phi8Color INCOMPLETE'
save dir = '/content/video3 rojo'
os.makedirs(save dir, exist ok=True)
input height = 256
input width = 256
for image name in os.listdir(image dir):
    if image_name.endswith(('.png', '.jpg', '.jpeg')):
        image path = os.path.join(image dir, image name)
        original image = cv2.imread(image path, cv2.IMREAD GRAYSCALE)
        resized_image = cv2.resize(original_image, (input_width,
input height))
        input image = resized image / 255.0
        input image = np.expand dims(input image, axis=-1)
        input image = np.expand dims(input image, axis=0)
        predicted mask = model.predict(input image)[0]
        predicted mask = (predicted mask.squeeze() *
255).astype('uint8')
          binary mask = cv2.threshold(predicted mask, 127, 255,
cv2.THRESH BINARY)
```

```
binary mask resized = cv2.resize(binary mask,
(original image.shape[1], original image.shape[0]))
        colored image = cv2.cvtColor(original image,
cv2.COLOR GRAY2BGR)
        colored mask = np.zeros like(colored image)
        colored_mask[:, :, 2] = binary_mask_resized
        highlighted image = cv2.addWeighted(colored image, 0.7,
colored mask, 0.3, 0)
        output path colored = os.path.join(save dir,
f"imagen con mascara roja {image name}")
        cv2.imwrite(output_path_colored, highlighted image)
        print(f"Imagen {image name} procesada y guardada en
{output path colored}")
WARNING:absl:Compiled the loaded model, but the compiled metrics have
yet to be built. `model.compile metrics` will be empty until you train
or evaluate the model.
                _____ 1s 913ms/step
Imagen 18.png procesada y guardada en
/content/video3 rojo/imagen con mascara roja 18.png
                    0s 29ms/step
1/1 -
Imagen 19.png procesada y guardada en
/content/video3_rojo/imagen_con_mascara_roja_19.png
                     _____0s_26ms/step
Imagen 20.png procesada y guardada en
/content/video3 rojo/imagen con mascara roja 20.png
                       - 0s 19ms/step
Imagen 21.png procesada y guardada en
/content/video3_rojo/imagen_con_mascara_roja_21.png
                       - 0s 19ms/step
Imagen 23.png procesada y guardada en
/content/video3_rojo/imagen_con_mascara_roja_23.png
                    0s 25ms/step
1/1 -
Imagen 22.png procesada y guardada en
/content/video3 rojo/imagen con mascara roja 22.png
1/1 -
                     0s 21ms/step
Imagen 24.png procesada y guardada en
/content/video3 rojo/imagen con mascara roja 24.png
```