

## 1. Scraper

```
In [ ]: %pip install selenium
%pip install webdriver-manager
```

### 1.1 imports + global variables

```
In [ ]: from selenium import webdriver
from selenium.webdriver.chrome.service import Service as ChromeService
from webdriver_manager.chrome import ChromeDriverManager
from selenium.webdriver.common.by import By
import time
import urllib
import os

football_folder_name = "football_folder"
basketball_folder_name = "basketball_folder"
tennis_folder_name = "tennis_folder"
golf_folder_name = "golf_folder"
volleyball_folder_name = "volleyball_folder"

football_photo_name = "football"
basketball_photo_name = "basketball"
tennisball_photo_name = "tennisball"
golfrail_photo_name = "golfrail"
volleyball_photo_name = "volleyball"
```

### 1.2 download images

```
In [ ]: def download_images(search_term, safe_folder, num_images, safe_word):
    driver = webdriver.Chrome(service=ChromeService(ChromeDriverManager().install()))
    image_successfull = 0

    parent_dir = "C:/Users/Jarne/Documents/schooljaar 2023-2024/ai/task3/datasets"
    path = os.path.join(parent_dir, safe_folder)
    print(path)

    try:
        if not os.path.exists(path):
            print(f"Creating folder: {path}")
            os.makedirs(path)

        search_url = "https://www.google.com/search?q={search_term}&source=imsl&ismisc"
        driver.get(search_url)

        # Wait for the cookie popup and accept cookies
        time.sleep(2)
        driver.find_element(By.XPATH, '//button[aria-label="Reject all"]').click()

        # Scroll down to load more images
        for _ in range(10):
            driver.execute_script("window.scrollTo(0, document.body.scrollHeight);")
            time.sleep(1)

        try:
            driver.find_element(By.XPATH, '//input[@value="Show more results"]').click()
            time.sleep(1)
        except:
            pass

        # Find and download images
        images = driver.find_elements(By.CSS_SELECTOR, 'img[alt="Q&U&P"]')

        while image_successfull < num_images:
            for index, image in enumerate(images[num_images:]):
                src = image.get_attribute('src')
                if src:
                    urllib.request.urlretrieve(src, os.path.join(path, f'({safe_word}){image_successfull}.jpg'))
                    print(f"Downloaded: ({safe_word}){image_successfull}.jpg")
                    image_successfull += 1
                    if image_successfull == num_images:
                        break
            except Exception as e:
                print(f"An error occurred: {e}")
            finally:
                driver.quit()

    def main():
        download_images("soccer ball", football_folder_name, 5000, football_photo_name)
        download_images("basketball ball", basketball_folder_name, 5000, basketball_photo_name)
        download_images("tennis ball", tennis_folder_name, 5000, tennisball_photo_name)
        download_images("golf ball", golf_folder_name, 5000, golfrail_photo_name)
        download_images("volleyball ball", volleyball_folder_name, 5000, volleyball_photo_name)

    if __name__ == '__main__':
        main()
```

## 2. EDA & Data prep

### 2.1 EDA + imports

```
In [ ]: %pip install matplotlib
%pip install numpy
%pip install opencv-python opencv-contrib-python
```

```
In [ ]: import cv2
import numpy as np
import matplotlib.pyplot as plt
import urllib
import random
```

```
In [ ]: def count_images_in_folders(safe_folder):
    parent_dir = "C:/Users/Jarne/Documents/schooljaar 2023-2024/ai/task3/datasets"
    path = os.path.join(parent_dir, safe_folder)

    if not os.path.exists(path) or not os.path.isdir(path):
        print(f"Invalid directory: {path}")
        return

    classes = [class_name for class_name in os.listdir(path) if os.path.isfile(os.path.join(path, class_name))]

    print(f"The folder: {safe_folder} has: {len(classes)} images")

    def showRandom2Images(safe_folder, photo_name):
        parent_dir = "C:/Users/Jarne/Documents/schooljaar 2023-2024/ai/task3/datasets"
        path = os.path.join(parent_dir, safe_folder)
        images = []

        for i in range(2):
            rnd = random.randint(0, len([class_name for class_name in os.listdir(path) if os.path.isfile(os.path.join(path, class_name))]))-1
            img_orig = cv2.imread(path + '/' + photo_name + str(rnd) + '.jpg')
            img_rgb = cv2.cvtColor(img_orig, cv2.COLOR_BGR2RGB)
            images.append(img_rgb)

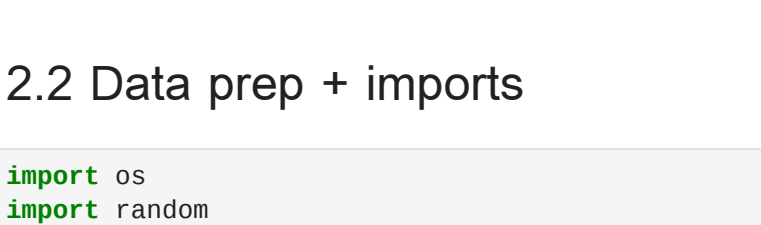
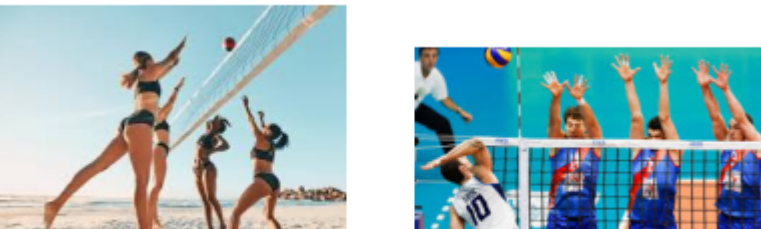
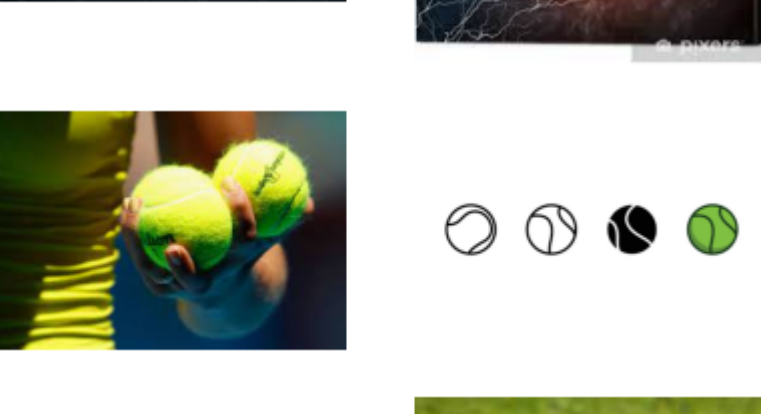
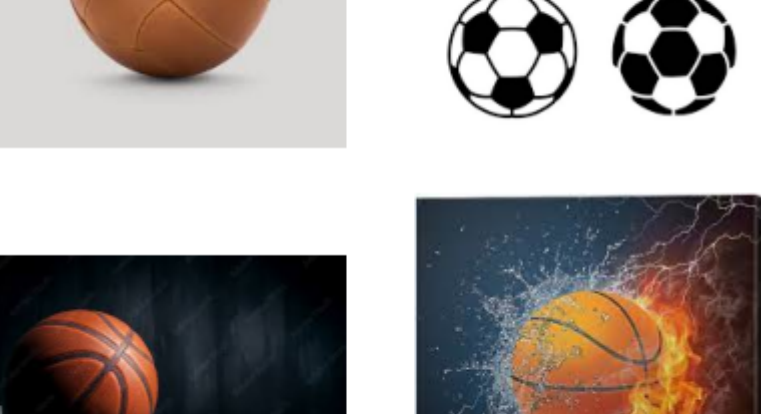
        plt.figure(figsize=(5, 10))
        for i in range(2):
            plt.subplot(1, 2, i+1)
            plt.imshow(images[i])
            plt.axis('off')

    def main():
        count_images_in_folders(football_folder_name)
        count_images_in_folders(basketball_folder_name)
        count_images_in_folders(tennis_folder_name)
        count_images_in_folders(golf_folder_name)
        count_images_in_folders(volleyball_folder_name)

        showRandom2Images(football_folder_name, football_photo_name)
        showRandom2Images(basketball_folder_name, basketball_photo_name)
        showRandom2Images(tennis_folder_name, tennisball_photo_name)
        showRandom2Images(golf_folder_name, golfrail_photo_name)
        showRandom2Images(volleyball_folder_name, volleyball_photo_name)

    if __name__ == '__main__':
        main()

The folder: football_folder has: 5000 images
The folder: basketball_folder has: 5000 images
The folder: tennis_folder has: 5000 images
The folder: golf_folder has: 5000 images
The folder: volleyball_folder has: 5000 images
```



### 2.2 Data prep + imports

```
In [ ]: import os
import random
import shutil
```

```
In [ ]: def split_data(source_folder, training_folder, test_folder, test_percentage=0.1):
    classes = os.listdir(source_folder)

    for class_name in classes:
        class_path = os.path.join(source_folder, class_name)
        images = os.listdir(class_path)

        # Calculate the number of images for the test set
        test_size = int(len(images) * test_percentage)

        # Create destination folders
        train_class_path = os.path.join(training_folder, class_name)
        test_class_path = os.path.join(test_folder, class_name)

        if not os.path.exists(train_class_path):
            os.makedirs(train_class_path)

        if not os.path.exists(test_class_path):
            os.makedirs(test_class_path)

        # Randomly shuffle the list of images
        random.shuffle(images)

        # Move the first 'test_size' images to the test set folder
        for image_name in images[:test_size]:
            source_path = os.path.join(class_path, image_name)
            dest_path = os.path.join(test_class_path, image_name)
            shutil.move(source_path, dest_path)

        # Move the remaining images to the training set folder
        for image_name in images[test_size:]:
            source_path = os.path.join(class_path, image_name)
            dest_path = os.path.join(train_class_path, image_name)
            shutil.move(source_path, dest_path)

        # Delete the original class folders
        for class_name in classes:
            class_path = os.path.join(source_folder, class_name)
            shutil.rmtree(class_path)

    def main():
        source_folder = "C:/Users/Jarne/Documents/schooljaar 2023-2024/ai/task3/datasets"
        training_folder = "C:/Users/Jarne/Documents/schooljaar 2023-2024/ai/task3/datasets/training_set"
        test_folder = "C:/Users/Jarne/Documents/schooljaar 2023-2024/ai/task3/datasets/test_set"

        split_data(source_folder, training_folder, test_folder, test_percentage=0.1)

    if __name__ == '__main__':
        main()
```

## 3. CNN network

```
In [ ]: %pip install tensorflow
```

```
In [ ]: import numpy as np
import matplotlib.pyplot as plt
import tensorflow as tf
from tensorflow.keras import keras
from tensorflow.keras import optimizers
from tensorflow.keras import layers
from keras.preprocessing.image import ImageDataGenerator
```

```
In [ ]: NUM_CLASSES = 5
IMG_SIZE = 64
# There is no shuffling option anymore, but there is a translation option
HEIGHT_FACTOR = 0.2
WIDTH_FACTOR = 0.2

# Create a sequential model with a list of layers
model = tf.keras.Sequential([
    # Add a resizing layer to resize the images to a consistent shape
    layers.Resizing(IMG_SIZE, IMG_SIZE),
    # Add a rescaling layer to rescale the pixel values to the [0, 1] range
    layers.Rescaling(1./255),
    # Add some data augmentation layers to apply random transformations during training
    layers.RandomFlip("horizontal"),
    layers.RandomTranslation(HEIGHT_FACTOR, WIDTH_FACTOR),
    layers.RandomZoom(0.2),

    layers.Conv2D(32, (3, 3), input_shape=(64, 64, 3), activation="relu"),
    layers.MaxPooling2D((2, 2)),
    layers.Conv2D(64, (3, 3), activation="relu"),
    layers.MaxPooling2D((2, 2)),
    layers.Conv2D(128, (3, 3), activation="relu"),
    layers.MaxPooling2D((2, 2)),
    layers.Flatten(),
    layers.Dense(128, activation="relu"),
    layers.Dense(NUM_CLASSES, activation="softmax")
])

# Compile and train your model as usual
model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
```

```
In [ ]: from keras.utils import image_dataset_from_directory
# Set the parameters for your data
batch_size = 32
image_size = (64, 64)
validation_split = 0.2
```

```
# Create the training dataset from the 'train' directory
train_ds = image_dataset_from_directory(
    directory='datasets/training_set',
    labels='inferred',
    label_mode='categorical',
    batch_size=batch_size,
    image_size=image_size,
    validation_split=validation_split,
    subset='training',
    seed=123
)
```

```
# Create the validation dataset from the 'train' directory
validation_ds = image_dataset_from_directory(
    directory='datasets/training_set',
    labels='inferred',
    label_mode='categorical',
    batch_size=batch_size,
    image_size=image_size,
    validation_split=validation_split,
    subset='validation',
    seed=123
)
```

```
# Create the testing dataset from the 'test' directory
test_ds = image_dataset_from_directory(
    directory='datasets/test_set',
    labels='inferred',
    label_mode='categorical',
    batch_size=batch_size,
    image_size=image_size
)

Found 22000 files belonging to 5 classes.
Using 18000 files for training.
Found 22000 files belonging to 5 classes.
Using 4000 files for validation.
Found 2000 files belonging to 5 classes.
```

## 4. Training model

```
In [ ]: steps_per_epoch = len(train_ds)
history = model.fit(train_ds,
                    validation_data=validation_ds,
                    steps_per_epoch=
                        steps_per_epoch,
                    epochs=100,
                    verbose=1, # Set to 1 to see training progress
                        callbacks=[
                            # Add early stopping to prevent overfitting
                            tf.keras.callbacks.EarlyStopping(monitor='val_loss', patience=10, restore_best_weights=True),

                            # Add learning rate scheduling
                            tf.keras.callbacks.ReduceLROnPlateau(monitor='val_loss', factor=0.2, patience=5, min_lr=1e-7),

                            # Add model checkpoint to save the best weights during training
                            tf.keras.callbacks.ModelCheckpoint(filepath='best_model.h5', monitor='val_loss', save_best_only=True)
                        ]
                    )
```

```
Epoch 1/100
500/500 [=====] - 21s 37ms/step - loss: 1.8141 - accuracy: 0.6887 - val_loss: 0.7945 - val_accuracy: 0.7616 - lr: 0.0010
Epoch 2/100
500/500 [=====] - ETA: 1:02 - loss: 0.8696 - accuracy: 0.8575
C:/Users/Jarne/AppData/Local/Programs/Python/Python310/Lib/site-packages/keras/src/callback/training.py:3103: UserWarning: You are saving your model as an HDF5 file via `model.save()`. This file format is considered legacy. We recommend using instead the native Keras format, e.g., `model.save('my_model.keras')`.
```

```
WARNING:tensorflow:
500/500 [=====] - 20s 38ms/step - loss: 0.6469 - accuracy: 0.6887 - val_loss: 0.6991 - val_accuracy: 0.7476 - lr: 0.0010
Epoch 3/100
500/500 [=====] - 21s 37ms/step - loss: 0.7223 - accuracy: 0.7327 - val_loss: 0.6534 - val_accuracy: 0.7582 - lr: 0.0010
Epoch 4/100
500/500 [=====] - 22s 38ms/step - loss: 0.6276 - accuracy: 0.7677 - val_loss: 0.5875 - val_accuracy: 0.8249 - lr: 0.0010
Epoch 5/100
500/500 [=====] - 22s 38ms/step - loss: 0.5589 - accuracy: 0.7954 - val_loss: 0.4553 - val_accuracy: 0.8324 - lr: 0.0010
Epoch 6/100
500/500 [=====] - 21s 38ms/step - loss: 0.4882 - accuracy: 0.8231 - val_loss: 0.4246 - val_accuracy: 0.8484 - lr: 0.0010
Epoch 7/100
500/500 [=====] - 21s 37ms/step - loss: 0.4458 - accuracy: 0.8373 - val_loss: 0.3626 - val_accuracy: 0.8662 - lr: 0.0010
Epoch 8/100
500/500 [=====] - 21s 37ms/step - loss: 0.4015 - accuracy: 0.8523 - val_loss: 0.3189 - val_accuracy: 0.8891 - lr: 0.0010
Epoch 9/100
500/500 [=====] - 22s 38ms/step - loss: 0.3675 - accuracy: 0.8713 - val_loss: 0.2685 - val_accuracy: 0.9131 - lr: 0.0010
Epoch 10/100
500/500 [=====] - 21s 38ms/step - loss: 0.3439 - accuracy: 0.8771 - val_loss: 0.354 - val_accuracy: 0.8993 - lr: 0.0010
Epoch 11/100
500/500 [=====] - 21s 38ms/step - loss: 0.3339 - accuracy: 0.8867 - val_loss: 0.3834 - val_accuracy: 0.9028 - lr: 0.0010
Epoch 12/100
500/500 [=====] - 22s 38ms/step - loss: 0.3833 - accuracy: 0.8905 - val_loss: 0.2286 - val_accuracy: 0.9269 - lr: 0.0010
Epoch 13/100
500/500 [=====] - 22s 38ms/step - loss: 0.3001 - accuracy: 0.8949 - val_loss: 0.2163 - val_accuracy: 0.9267 - lr: 0.0010
Epoch 14/100
500/500 [=====] - 21s 38ms/step - loss: 0.2693 - accuracy: 0.9048 - val_loss: 0.1941 - val_accuracy: 0.9469 - lr: 0.0010
Epoch 15/100
500/500 [=====] - 22s 38ms/step - loss: 0.1824 - accuracy: 0.9180 - val_loss: 0.2452 - val_accuracy: 0.9182 - lr: 0.0008-04
Epoch 16/100
500/500 [=====] - 22s 38ms/step - loss: 0.2515 - accuracy: 0.9180 - val_loss: 0.2452 - val_accuracy: 0.9182 - lr: 0.0008-04
Epoch 17/100
500/500 [=====] - 22s 38ms/step - loss: 0.2422 - accuracy: 0.9137 - val_loss: 0.1952 - val_accuracy: 0.9244 - lr: 0.0010
Epoch 18/100
500/500 [=====] - 22s 38ms/step - loss: 0.2375 - accuracy: 0.9148 - val_loss: 0.1441 - val_accuracy: 0.9528 - lr: 0.0010
Epoch 19/100
500/500 [=====] - 21s 38ms/step - loss: 0.2249 - accuracy: 0.9208 - val_loss: 0.1269 - val_accuracy: 0.9511 - lr: 0.0010
Epoch 20/100
500/500 [=====] - 21s 37ms/step - loss: 0.2087 - accuracy: 0.9278 - val_loss: 0.1354 - val_accuracy: 0.9247 - lr: 0.0010
Epoch 21/100
500/500 [=====] - 24s 42ms/step - loss: 0.1886 - accuracy: 0.9285 - val_loss: 0.1387 - val_accuracy: 0.9584 - lr: 0.0010
Epoch 22/100
500/500 [=====] - 22s 38ms/step - loss: 0.2008 - accuracy: 0.9296 - val_loss: 0.1841 - val_accuracy: 0.9371 - lr: 0.0010
Epoch 23/100
500/500 [=====] - 21s 37ms/step - loss: 0.1819 - accuracy: 0.9338 - val_loss: 0.1951 - val_accuracy: 0.9388 - lr: 0.0010
Epoch 24/100
500/500 [=====] - 21s 37ms/step - loss: 0.1273 - accuracy: 0.9367 - val_loss: 0.1588 - val_accuracy: 0.9436 - lr: 0.0010
Epoch 25/100
500/500 [=====] - 22s 38ms/step - loss: 0.1293 - accuracy: 0.9557 - val_loss: 0.1151 - val_accuracy: 0.9648 - lr: 2.000e-04
Epoch 26/100
500/500 [=====] - 21s 37ms/step - loss: 0.1189 - accuracy: 0.9584 - val_loss: 0.1816 - val_accuracy: 0.9573 - lr: 2.000e-04
Epoch 27/100
500/500 [=====] - 21s 37ms/step - loss: 0.1895 - accuracy: 0.9538 - val_loss: 0.8989 - val_accuracy: 0.9671 - lr: 2.000e-04
Epoch 28/100
500/500 [=====] - 21s 37ms/step - loss: 0.1824 - accuracy: 0.9642 - val_loss: 0.1816 - val_accuracy: 0.9678 - lr: 2.000e-04
Epoch 29/100
500/500 [=====] - 22s 38ms/step - loss: 0.8992 - accuracy: 0.9672 - val_loss: 0.1339 - val_accuracy: 0.9569 - lr: 2.000e-04
Epoch 30/100
500/500 [=====] - 22s 38ms/step - loss: 0.1843 - accuracy: 0.9644 - val_loss: 0.1311 - val_accuracy: 0.9648 - lr: 2.000e-04
Epoch 31/100
500/500 [=====] - 21s 38ms/step - loss: 0.8965 - accuracy: 0.9658 - val_loss: 0.1859 - val_accuracy: 0.9716 - lr: 2.000e-04
Epoch 32/100
500/500 [=====] - 22s 38ms/step - loss: 0.8928 - accuracy: 0.9673 - val_loss: 0.1859 - val_accuracy: 0.9691 - lr: 2.000e-04
Epoch 33/100
500/500 [=====] - 22s 38ms/step - loss: 0.8829 - accuracy: 0.9706 - val_loss: 0.8814 - val_accuracy: 0.9718 - lr: 4.000e-05
Epoch 34/100
500/500 [=====] - 22s 38ms/step - loss: 0.8839 - accuracy: 0.9734 - val_loss: 0.8932 - val_accuracy: 0.9689 - lr: 4.000e-05
Epoch 35/100
500/500 [=====] - 21s 37ms/step - loss: 0.8763 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 36/100
500/500 [=====] - 21s 37ms/step - loss: 0.8763 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 37/100
500/500 [=====] - 21s 37ms/step - loss: 0.8763 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 38/100
500/500 [=====] - 22s 38ms/step - loss: 0.8763 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 39/100
500/500 [=====] - 21s 37ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 40/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 41/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 42/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 43/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 44/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 45/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 46/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 47/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 48/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 49/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
Epoch 50/100
500/500 [=====] - 21s 36ms/step - loss: 0.8759 - accuracy: 0.9734 - val_loss: 0.8868 - val_accuracy: 0.9789 - lr: 4.000e-05
```

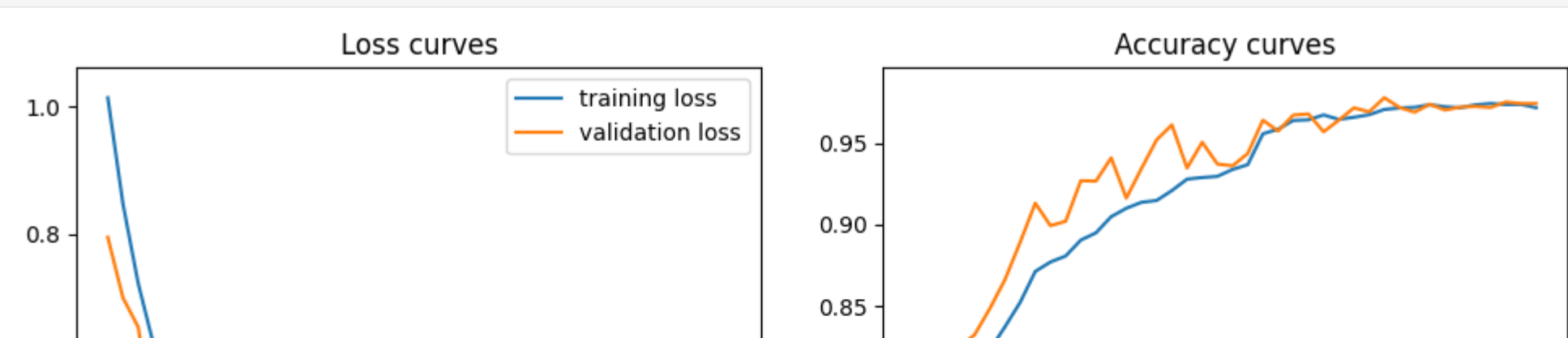
```
In [ ]: # Create a figure and a grid of subplots with a single call
fig, (ax1, ax2) = plt.subplots(2, 2, figsize=(10, 5))

# Plot the loss curves on the first subplot
ax1.plot(history.history['loss'], label='training loss')
ax1.plot(history.history['val_loss'], label='validation loss')
ax1.set_title('Loss curves')
ax1.set_xlabel('Epoch')
ax1.set_ylabel('Loss')
ax1.legend()

# Plot the accuracy curves on the second subplot
ax2.plot(history.history['accuracy'], label='training accuracy')
ax2.plot(history.history['val_accuracy'], label='validation accuracy')
ax2.set_title('Accuracy curves')
ax2.set_xlabel('Epoch')
ax2.set_ylabel('Accuracy')
ax2.legend()

# Adjust the spacing between subplots
fig.tight_layout()

# Show the figure
plt.show()
```



```
In [ ]: model.save('saved_model/model')
INFO:tensorflow:Assets written to: saved_model/assets
INFO:tensorflow:Assets written to: saved_model/assets
```

### 4.1 Checking our model

```
In [ ]: test_loss, test_acc = model.evaluate(test_ds)
print('Test accuracy (model_only):', test_acc)
79/79 [=====] - 1s 46ms/step - loss: 0.8978 - accuracy: 8.9756
Test accuracy (model_only): 8.97560004196167
```



