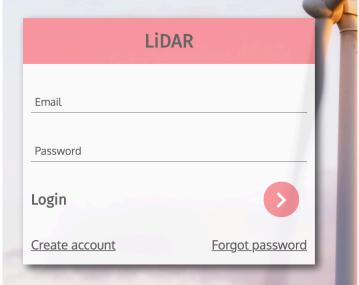
Floating LiDAR User Manual

Setting up your organisation:

Accessing the system:

You will be given a default admin login for the Floating LiDAR Validation System. Connect to https://lidar.icedcoffee.dev, and you will be prompted with a login screen.

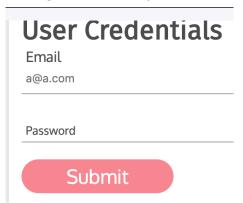


Enter the admin email and password, and press the pink arrow to log in.

To maintain security, it is essential that you change the admin account's email and password immediately. Press the gear icon in the bottom left corner to access the settings menu.

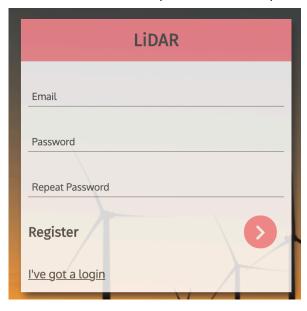


Enter your new email and password in the user credentials section at the top of the settings menu, and press submit.

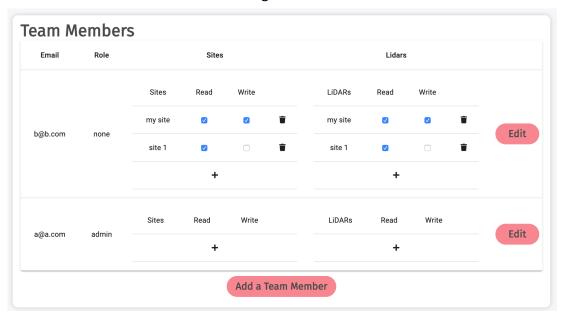


Adding users to the system:

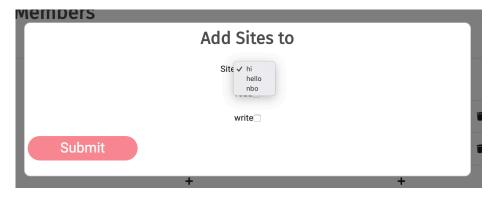
Users first need to create an account. They should navigate to https://lidar.icedcoffee.dev, and press create account. They will be presented with this screen, where they should enter their email and password, and press the pink arrow.



This will take them to the LiDAR dashboard, but they will not be able to see or do anything. You will need to add them to your organisation and give them permissions. Find the team members section of settings.



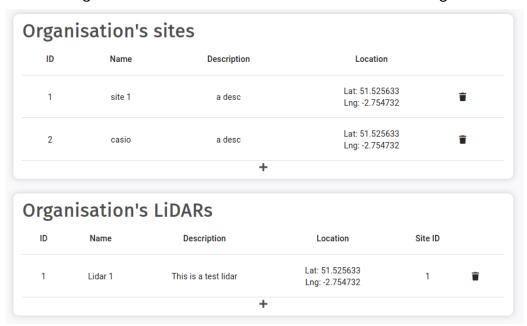
Press 'add a team member', then enter their email and role to add them to your organisation. Once you have added testing sites and LiDAR buoys, you can give users permission to use them by pressing the '+' buttons.



Select the site to give the user access to from the drop-down menu, and press the checkboxes to set their permissions. Giving them read permission allows them to view data and KPIs from the mast and associated buoys. Giving them write permission allows them to edit the data.

Adding devices:

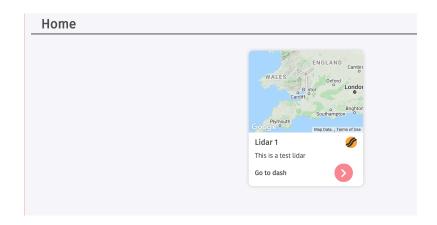
Find the organisation's sites and LiDARs section of the settings menu.



Press the '+' buttons to add mast sites and LiDAR buoys. You will be prompted to enter the serial, optional description and location. For buoys, you will also be given a dropdown menu of mast sites, from which you select the mast for the buoy to be compared against.

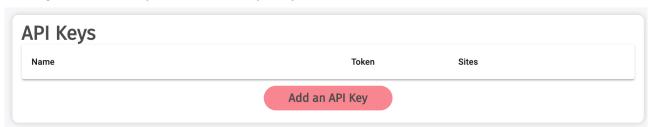
When you press the home button, they should now appear in the overview display.





Configuring device datasources:

Data is sent to the Floating LiDAR validation system directly from the devices. Each device needs an API key to allow it to send data. To make an API key, find API keys in the settings menu, and press 'add an api key'.



You will be prompted to give the key a name, and a drop-down menu will allow you to select a site to generate a key for. The key will have a random API token, which allows devices to send data.

Sites should send a post request to

lidar.icedcoffee.dev/sites/{mast serial}/sendjson?token={API token}

With {mast serial} replaced with the mast's serial code, and {API token} replaced with the token generated for that site's API key.

The body of the post request should be JSON, formatted in one of two ways:

To send a single sample:

```
"h40": speedAt40m,
        "h60": speedAt60m,
        "h80": speedAt80m,
        "h100": speedAt100m
    },
    "ti": {
        "h30": tiAt30m,
        "h40": tiAt40m,
        "h60": tiAt60m,
        "h80": tiAt80m,
        "h100": tiAt100m
    }
}
To send multiple samples:
{
    "samples": [
        sample0,
        sample1,
        sample2
    1
}
Where each sample is formatted as the same as a single sample.
Buoys should send a post request to
lidar.icedcoffee.dev/lidars/{buoy serial}/sendjson?token={API token}
With {buoy serial} replaced with the buoy's serial code, and {API token} replaced with the
token generated for that site's API key.
The body of the post request should be JSON, formatted in one of two ways:
To send a single sample:
```

```
"timestamp": "2020-05-22T08:45:23Z" //Time sample was taken, ISO 8601
"direction": {
        "h4": directionAt4m,
        "h30": directionAt30m,
        "h40": directionAt40m,
        "h40_ref": referenceDirectionAt40m,
        "h60": directionAt60m,
        "h80": directionAt80m,
        "h100": directionAt100m,
```

{

```
"h120": directionAt120m,
        "h140": directionAt140m,
        "h160": directionAt160m,
        "h180": directionAt180m,
        "h200": directionAt200m
    },
    "speed": {
        "h4": speedAt4m,
        "h30": speedAt30m,
        "h40": speedAt40m,
        "h40 ref": referenceSpeedAt40m,
        "h60": speedAt60m,
        "h80": speedAt80m,
        "h100": speedAt100m,
        "h120": speedAt120m,
        "h140": speedAt140m,
        "h160": speedAt160m,
        "h180": speedAt180m,
        "h200": speedAt200m
    },
    "ti": {
        "h30": tiAt30m,
        "h40": tiAt40m,
        "h40 ref": referenceTiAt40m,
        "h60": tiAt60m,
        "h80": tiAt80m,
        "h100": tiAt100m,
        "h120": tiAt120m,
        "h140": tiAt140m,
        "h160": tiAt160m,
        "h180": tiAt180m,
        "h200": tiAt200m
    }
To send multiple samples:
    "samples": [
        sample0,
```

}

{

```
sample1,
sample2
]
```

Where each sample is formatted as the same as a single sample.

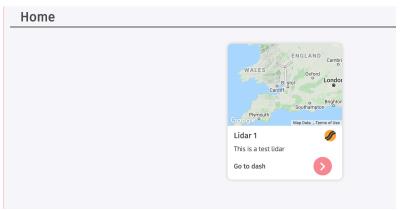
Each device must send its samples in chronological order.

Using the system:

Viewing KPIs:

When you press the home button, an overview of buoys is displayed.





Pressing the pink arrow takes you to the KPI overview, which shows the KPIs recorded for that buoy at different heights, as well as an indicator of whether the KPIs are currently passing.



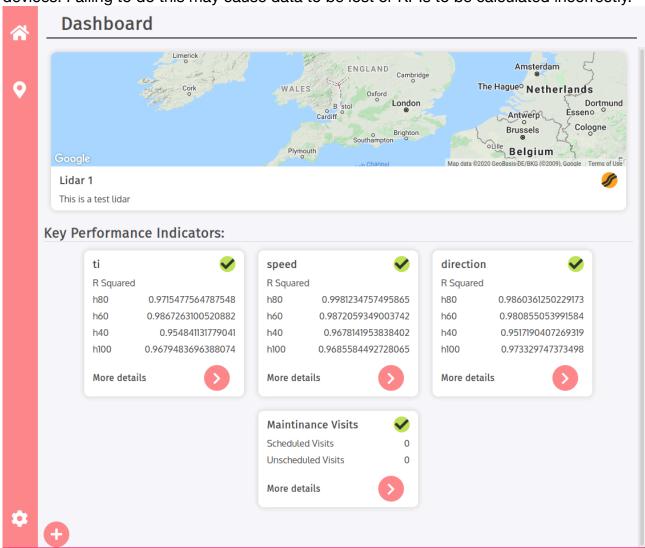
Pressing the pink arrow on a card shows any KPIs that don't fit onto the overview.



rSqr 0.9961544111251849 0.9691182009808708 0.9811009068436437 0.9767458887648214 slope 1.025106595932782 0.9837861015303974 1.0253900679850367 1.0453243957861142

Manually uploading data:

It is also possible to upload data manually, as CSV files. The data should be sent in chronological order, including with respect to any data that may be sent directly from devices. Failing to do this may cause data to be lost or KPIs to be calculated incorrectly.



To upload a csv, press the '+' in the bottom left corner.



An upload data dialog box will appear, allowing you to select a CSV from your computer. See the example CSV's for the correct header format.