

YIJUN YUAN

(+49)15122079050 ◊ yijun.yuan@uni-wuerzburg.de

<https://jarrome.github.io>

EDUCATION

Julius Maximilian University of Würzburg, Germany

October 2021 - Present

Ph.D, advised by Prof. **Andreas Nüchter**

ShanghaiTech University, China

September 2018 - June 2021

MSC., advised by Prof. **Sören Schwertfeger**

Outstanding Graduation. GPA: 3.5/4.0

ShanghaiTech University, China

September 2014 - June 2018

BE., Computer Science and Technology.

GPA: 3.69/4.0

EXPERIENCE

ETH Zürich, Switzerland

January 2024 - March 2024

*PhD research visiting, in Prof. **Marc Pollefeys**'s group*

Julius Maximilian University of Würzburg, Germany

October 2019 - December 2019

*Research visiting, advised by Prof. **Andreas Nüchter**, sponsored by DAAD scholarship*

RESEARCH

1. **Yuan, Y.**, & Nuechter, A. (2024). Uni-Fusion: Universal Continuous Mapping. IEEE Transactions on Robotics (**T-RO**).
2. **Yuan, Y.**, & Nchter, A. (2023). Online Learning of Neural Surface Light Fields Alongside Real-Time Incremental 3D Reconstruction. IEEE Robotics and Automation Letters (RAL).
3. **Yuan, Y.**, & Nchter, A. (2022), An Algorithm for the SE(3)-Transformation on Neural Implicit Maps for Remapping Functions, IEEE Robotics and Automation Letters (RAL).
4. **Yuan, Y.**, & Nchter, A. (2022), Indirect Point Cloud Registration: Aligning Distance Fields using a Pseudo Third Point Set, IEEE Robotics and Automation Letters (RAL).
5. Hou, J., **Yuan, Y.**, He, Z. & Schwertfeger, S. (2021). Matching Maps based on the Area Graph. Intelligent Service Robotics (JIST).
6. **Yuan, Y.**, Borrmann, D., Hou, J., Ma, Y., Nchter, A., & Schwertfeger, S. (2021). Self-supervised Point Set Local Descriptors for Point Cloud Registration. Sensors.
7. **Yuan, Y.**, Xu, Q., and Schwertfeger, S. (2020). Configuration-space Flipper Planning on 3D Terrain. In 2020 IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR).
8. Long, X., Xu, Q., **Yuan, Y.**, He, Z., and Schwertfeger, S. (2020). Improved Visual-Inertial Localization for Low-cost Rescue Robots. 21st World Congress of the International Federation of Automatic Control (IFAC-WC).
9. Hou, J., **Yuan, Y.**, and Schwertfeger, S. (2019). Area Graph: Generation of Topological Maps using the Voronoi Diagram. In 2019 19th International Conference on Advanced Robotics (ICAR).
10. **Yuan, Y.**, Wang, L., and Schwertfeger, S. (2019). Configuration-space flipper planning for rescue robots. In 2019 IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR).
11. **Yuan, Y.**, and Schwertfeger, S. (2019). Incrementally Building Topology Graphs via Distance Maps. In 2019 IEEE International Conference on Real-time Computing and Robotics (RCAR).
12. **Yuan, Y.**, Kuang, H., and Schwertfeger, S. (2018). Fast Gaussian Process Occupancy Maps. In 2018 15th International Conference on Control, Automation, Robotics and Vision (ICARCV).

AWARDS

Outstanding Graduation

June 2021

- ShanghaiTech University, China

DAAD-Short Term Scholarship

August 2019

- German Academic Exchange Service

NO.4 in total score, Best on HPCG and Tensorflow

June 2018

- ISC-HPC 2018 high performance competition, Frankfurt, Germany.