FUI	NDAMENTAL OF MECHANICAL ENGINEERING AND MECHATRONICS (KME-201T)
	Unit V
	Introduction to Mechatronics and actuation systems
	OBJECTIVE TYPE QUESTIONS
1.	Integration of electronics, control engineering and mechanical engineering is called
	a. Electronics system
	b. Mechanical systems
	c. Mechatronics
	d. Electrical system
2.	Consider the following
	i Mechanical engineering;
	ii Electronic engineering;
	iii Electrical engineering;
	Which of the these are part of mechatronics?
	a. i and ii
	b. i, ii and iii
	c. ii and iii
	d. i and iii
3.	level of mechatronics incorporates I/O devices such as sensors, and actuators that
	integrates electrical signals with mechanical action.
	a. Primary
	b. Secondary
	c. Third
	d. Fourth
4.	level integrates microelectronics into electrically controlled devices
	a. Primary
	b. Secondary
	c. Third
	d. Fourth
5.	level incorporates advanced feedback functions into control strategy thereby enhanced
	quality in terms of sophistication - called "Smart system".
	a. Primary

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- 5. level incorporates advanced feedback functions into control strategy thereby enhancing the

a.	Fourth
6.	level incorporates intelligent control in mechatronic system.
a.	Primary
b.	Secondary
c.	Third
d.	Fourth
7. Applic	eation of mechatronics leads to the products produced are cost effective and of very good
quality	7.
a.	True
b.	False
8. High c	legree of flexibility is observed when mechatronics is incorporated
a.	True
b.	False
9. Due to	mechatronics, machine utilization is lower
a.	True
b.	False
10. Mecha	stronics system has lower initial cost
a.	True
b.	False
11. It requ	ires knowledge of various fields
a.	True
b.	False
12. The ac	ctuators do not produce motion or cause some action.
a.	True
b.	False
13. Actuat	fors
a.	Produce motion
b.	Detects the state of system

d. Gives the feedback

14. Sensors

- a Produce motion
- b. Detects the state of system
- c. Control the system
- d. Gives the feedback

15. Digital devices

- a. Produce motion
- b. Detects the state of system
- c. Control the system
- d. Gives the feedback

16. Graphical display

- a. Produce motion
- b. Detects the state of system
- Control the system
- d. Gives the feedback
- **17.** Which of the following is not the example of mechatronic system?
 - a. Cars
 - b. Simple Bicycle
 - c Bike
 - d Aero nlane
- **18.** Which of the following is not an actuator?
 - a. Solenoid
 - h Motors
 - c. Thermocouple
 - d. Mechanical chain
- **19.** could be describe as an artificial word that combines automotive field and electronics content and it owns many applications in motor vehicles technology.

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- a. Bionics
- h Avionics
- Autotronics

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	d. Robotics
20. In	autotronics, fuel efficiency is increased
	a. True
	b. False
21. A	utotronics decrease the safety of cars
	a. True
	b. False
22	can be defined as the flow of concepts from engineering to biology and vice versa.
	a. Bionics
	b. Avionics
	c. Autotronics
	d. Robotics
23	are the electronic systems used on aircraft, artificial satellites, and spacecrafts.
	a. Bionics
	b. Avionics
	c. Autotronics
	d. Robotics
24. Th	ne transform the energy of the process variable to an output of some other type of
en	nergy which is able to operate some control device.
	a. Sensors
	b. Actuators
	c. Transducers
	d. Feedback
25. A	sensor consists of an element that changes either its state or an analog signal when
is	close to, but often not actually touching, an object.
	a. Proximity
	b. Light
	c. Mass
	d. Thermal
26	sensors involve the use of compressed air, displacement or proximity of an object being
tra	ansformed into a change in air pressure.

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a.	Light
b.	Mass
c.	Pneumatic
d.	Thermal
27. Photod	liodes are
a.	Mass sensors
b.	Light sensors
c.	Pneumatic sensors
d.	None of these
28. Photor	esistor works on principle that When the light is incident, the covalent bond breaks and many
free el	ectrons and holes are formed. Thus current is generated.
a.	True
b.	False
29	sensors measure the mass of the fluid or particles flowing through a part.
a.	Light
b.	Mass
c.	Pneumatic
d.	Thermal
30. Tempe	erature sensors may be contact or non-contact types
a.	True
b.	False
31	works on the principle of any change in resistivity, area or length will lead to change in
resista	nce.
a.	Capacitive transducer
b.	Resistive transducer
c.	Inductive transducer
d.	Mechanical transducer
32. Kinem	atic chain haslinks.
a.	1
b.	2
c.	3

d.	4		
33. Kinem	33. Kinematic chain istransducer.		
a.	Electronic		
b.	Mechanical		
c.	Pneumatic		
d.	Hydraulic		
34. Gears	are hydraulic transducers		
a.	True		
b.	False		
35. Gears	may be parallel or helical teeth		
a.	True		
b.	False		
36. The sh	hape of the teeth is such that rotation can occur in only one direction in		
a.	Gears		
b.	Chain		
c.	Ratchet and pawl		
d.	Belt		
37. Slip ca	an not be prevented in chain drives		
a.	True		
b.	False		
38. Hydra	ulic actuators works on		
a.	Bernoulli's principle		
b.	Pascal's law		
c.	Ohm's law		
d.	None of these		
39. Direct	ional control valses provides flow path.		
a.	True		
b.	False		
40. A rota	ry actuator is an actuator that produces a rotary motion or torque.		
a.	True		

41. An is an energy storage device: a device which accepts energy, stores energy, and			
releases energy as needed.			
a. Intensifier			
b. Transducer			
c. Accumulator			
d. Accelerator			
42. A device which increases the power of a signal in a hydraulic servomechanism or			
other system through the use of fixed and variable orifices is called			
a. Intensifier			
b. Transducer			
c. Accumulator			
d. Accelerator			
43 systems use air as the medium which is abundantly available and can be exhausted			
into the atmosphere after completion of the assigned task.			
a. Electronic			
b. Mechanical			
c. Pneumatic			
d. Hydraulic			
44. Sequencing circuits automatically move actuators in a predetermined sequence.			
a. True			
b. False			
45. Safety valve is a pressure control valve			
a. True			
b. False			
46. A servo motor is a typical example of			
a) Electronics system			
b) Mechanical system			
c) Computer system			
d) Mechatronics system			

	b) Sensors
	c) Actuators
	d) Digital controls
18.	A Mechatronics system contains feedback.
	a) True
	b) False
9.	In the level of integration of Mechatronics system, an example of the first level is
	a) Fluid valves
	b) Automatic machine tools
	c) Industrial robots
	d) Microprocessors
50.	A thermocouple is a transducer.
	a) True
	b) False
1.	Which type of gear is used to convert rotary into translatory motion?
	a) Spur gear
	b) Rack and pinion
	c) Helical gear
	d) Internal gear
52.	What are transducers?
	a) They convert power from one form to another
	b) They convert work from one form to another
	c) They convert work to power
	d) They convert energy from one form to another
53.	What type of energy conversion does a piezoelectric transducer perform?
	a) It converts mechanical energy to sound energy
	b) It converts sound energy to mechanical energy
	c) It converts mechanical energy to electrical energy

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	b) Electric Field
	c) Magnetic field
	d) Temperature
5	5. Transformer is a type of transducer.
	a) True
	b) False
5	6. The resistance of a thermistor is directly proportional to its temperature.
	a) True
	b) False
5	7. Active transducers do not require power source for operation.
	a) True
	b) False
5	8. Which among the following transducer is an example of active transducer?
	a) LDR (Light dependant sensor)
	b) Strain gauge
	c) Hall effect sensor
	d) Photovoltaic cell
5	9. What is the principle of operation of Potentiometric position sensor?
	a) Resistive Effect
	b) Hall Effect
	c) Mutual Inductance
	d) Eddy current effect
6	0. Which type of materials can be detected by Eddy current position sensor?
	a) Conducting materials
	b) Insulating materials
	c) Semi-Insulating Materials
	d) Amorphous Materials
6	1. Proximity sensor is a type of position sensor.
	a) contact
	b) non-contact

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С) eddy current
d) resistive
62. \(\)	Which type of material can be sensed by inductive proximity sensor?
a) Wooden type
b) Metallic type
С) Plastic type
d) Glass type
63. <i>A</i>	A proximity sensor requires physical contact.
a) True
b) False
64.]	In which type of system does power transmission takes place through compressed air?
a) Fluid power system
b) Hydraulic system
c) Pneumatic system
d) Stepper motors
65. ⁻	The compressed air is delivered to the pneumatic system through the air compressor.
a) True
b) False
66. V	What is the function of the air dryer?
a) Removes dirt
b) Removes moisture
С) Controls the rate of flow
d) Controls the pressure
67. V	Which part of the Pneumatic system stores the compressed air?
a) Air dryer
b) Air compressor
c) Air receiver tank
d) Air lubricator
68. '	What is the function of the flow control valve?
a) Controls the direction of flow of air
b) The moisture is separated and removed

	e) it converts the incontained energy to hydraune energy
	d) It controls the rate of flow of compressed air
69.	The direction control valve controls
	a) direction of flow
	b) rate of flow
	c) moisture
	d) force and motion
70.	What is the function of a pressure control valve?
	a) To control the force generated by actuators
	b) To perform two operations in sequence
	c) To control the direction of flow
	d) To avoid the development of excess of pressure
71.	The function of the pressure relief valve is
	a) to open when the inlet pressure is more
	b) to control the force generated by actuators
	c) to control different parameters of the fluid
	d) to control the direction of flow
72.	. What is the function of the air compressor?
	a) Decreases the pressure of air
	b) Increases the pressure of air
	c) Removes dust particles
	d) Adds lubricating oil
73.	What is the use of Intake air filters?
	a) To reduce the temperature of the air
	b) Used as storage and smoothened
	c) To prevent dust from entering the compressor
	d) To remove the traces of moisture
74.	In which type of system does power transmission takes place through compressed air?
	a) Fluid power system
	b) Hydraulic system

(c) Pneumatic system
(d) Stepper motors
75.]	Hydraulic systems are slower in operation.
ä	a) True
1	b) False
76.	What is the purpose of pawl, when it is used against a ratchet which is attached to a shaft?
ä	a) It allows unidirectional motion of shaft
1	b) It allows bidirectional motion of shaft
(e) It does not allow motion of shaft
(d) It is used to create additional friction force for the shaft
77.	The movement of the ratchet can be locked by pawl if it moves in opposite direction.
ä	a) True
1	b) False
78. `	Which among the following operations does not use belt drives?
ä	a) Mining
1	b) Logging
(e) Road construction
(d) Bicycles
79. `	Which among the following is an advantage of using belt drives over chain drives?
ä	a) Efficiency
1	b) Noise
(c) Cost
	d) Durability

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82. Which type of coil is a solenoid?		
a) Electromagnetic		
b) Electrical		
c) Mechanical		
d) Chemical		
83. High degree of flexibility is observed when mechatronics is incorporated		
a. True		
b. False		
84. Due to mechatronics, machine utilization is lower		

- 90. There is incorporation of intelligent, self-correcting sensory and feedback systems in
 - a. Mechanical system
 - b. Electronics system
 - Mechatronics system
 - d. Electrical system
- **91.** Degree of flexibility has increased in mechatronics system.
 - a. True
 - b. False
- 92. It is cheap to incorporate mechatronics approach to an existing/old system.

- a. True
- b. False
- **93.** LEDs and LCDs are
 - a. Display devices
 - b. Sensors
 - Actuators
 - d. Signals
- **94.** In aircrafts, flight control is example of mechatronics
 - a. True
 - b. False
- **95.** Washing machine is a
 - a. Mechatronics system
 - b. Electronics system
 - c. Mechanical system
 - d None of these
- **96.** Autotronics = X + Electronics. What is X denoting?
 - a. Biology
 - h Aviation
 - Mechanical
 - d. Automobile

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