

LOCAL SEARCH

ARTIFICIAL INTELLIGENCE | COMP 131

TODAY ON AI

- Hill climbing
- Simulated annealing
- Genetic algorithms
- Questions?

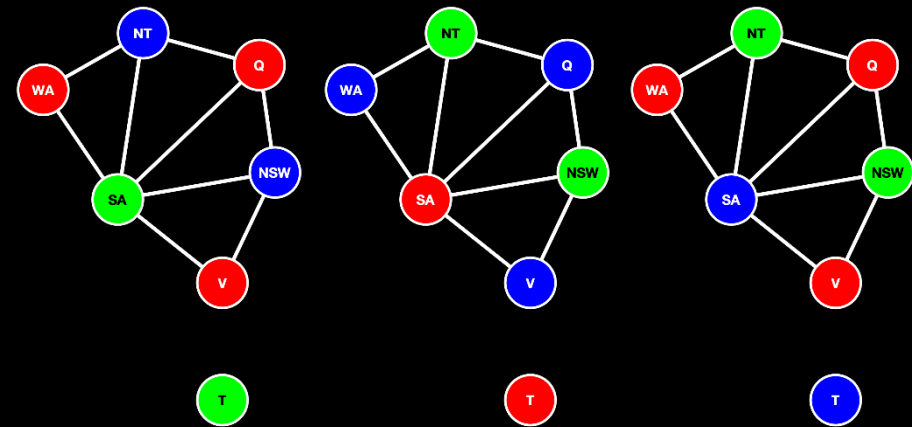
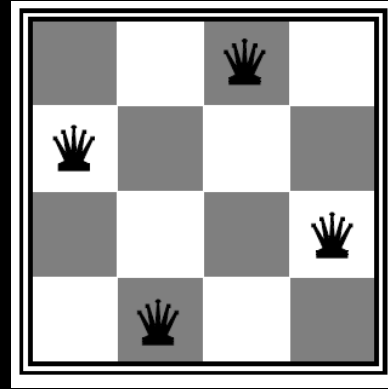
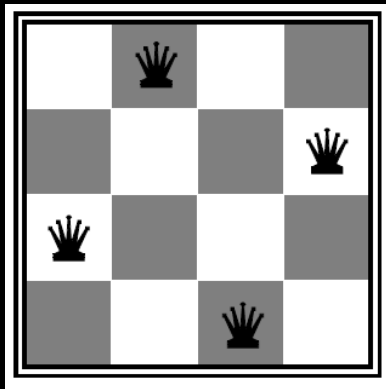
Constraint satisfaction problems (or **CSPs**) belong to a class of problems for which the goal itself is the most important part, not the path used to reach it.

EXAMPLES

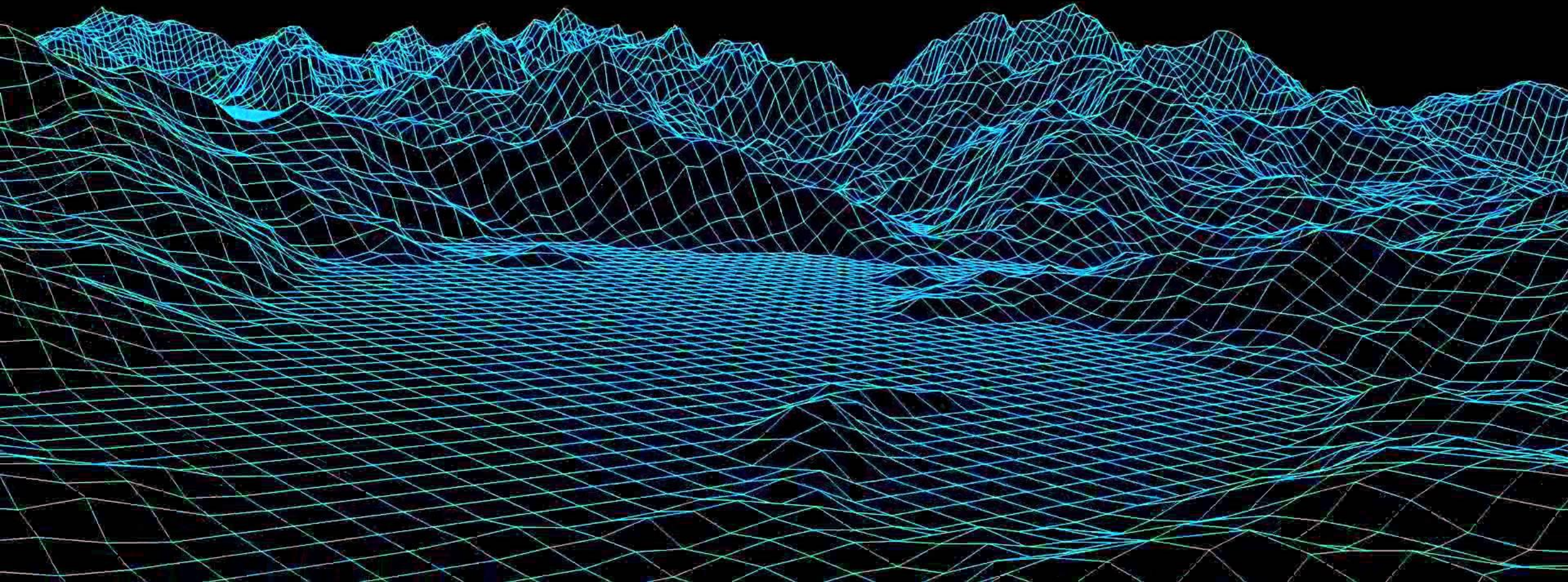
- Map coloring!
- Sudokus
- Crossword puzzles
- Job scheduling
- Cryptarithmic puzzles
- N-Queens problems
- Hardware configuration
- Assignment problems
- Transportation scheduling
- Fault diagnosis
- More...

Local search algorithms aim to solve some Constraint Satisfaction Problems more efficiently. Specifically, they are tailored to find a solution to problems whose **search space is very big** or **infinite** without returning the actual path to the solution

They can **always** provide an answer to the problem, even if it is both not definitive nor correct.



Local search algorithms work best when a function that measure the **fitness** of the solution can be defined and the **fitness landscape** is continuous.



- This class of algorithms operate on **single current nodes** that represent the complete state of the search
- The **current state** is the only thing that matter
- The state is evaluated with an **objective function**
- They **generally tend to move** through neighborhoods

GOOD

Generally much faster for large or infinite state space. More memory efficient

BAD

Incomplete and suboptimal. Not systematic search

Hill climbing algorithms

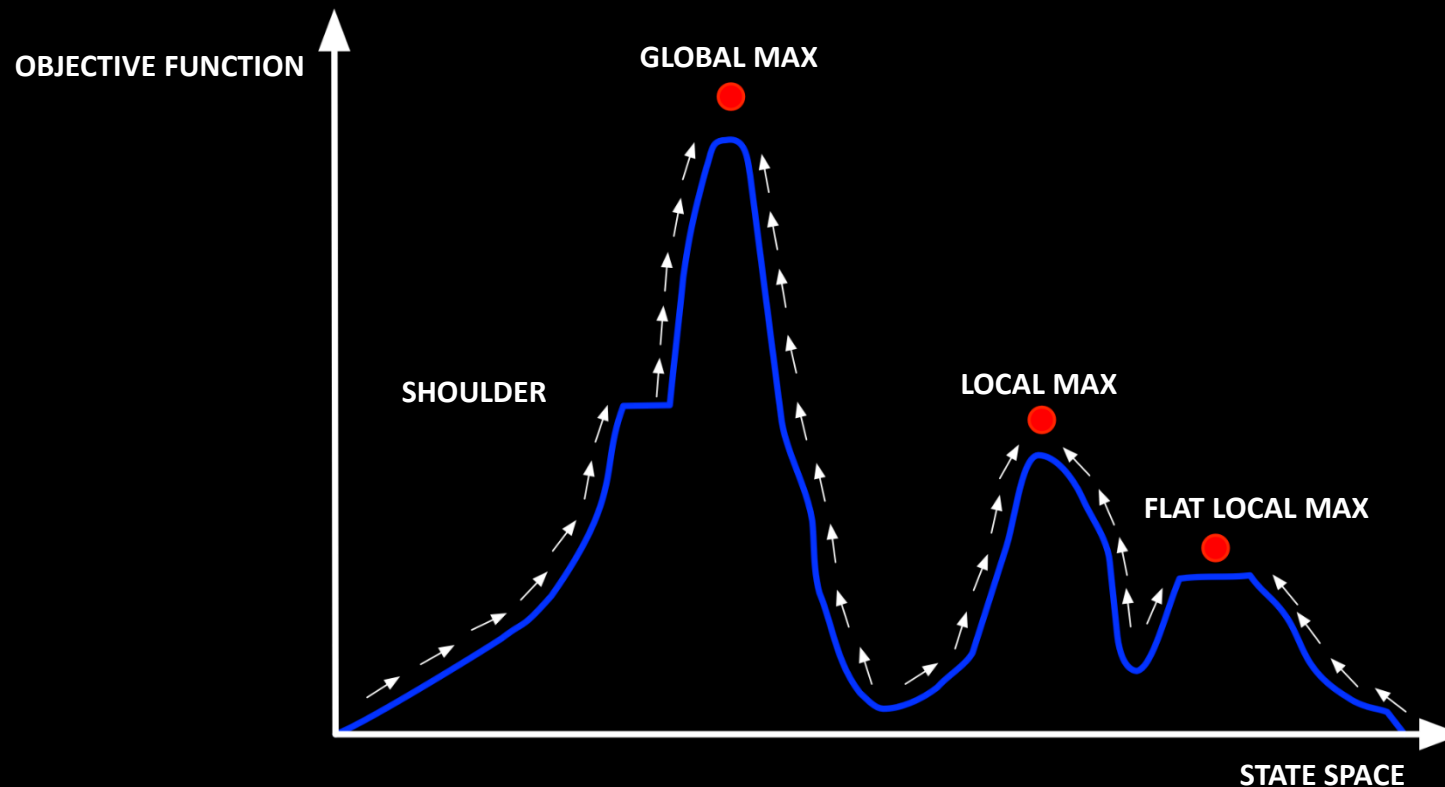
Hill climbing algorithm is the **most basic local search** technique. It is **greedy** in nature. At each step, the current node is **replaced** by the best neighbor.

```
1 function Hill-climbing(PROBLEM) return SOLUTION, or FAILURE
2
3 current = Make-node(PROBLEM initial state)
4
5 loop do
6     neighbor = a highest-valued successor of current
7     if neighbor.value ≤ current value then
8         return current state
9     current = neighbor
```

GOOD Very simple to implement

BAD It can easily get stuck in local maxima, ridges and plateau

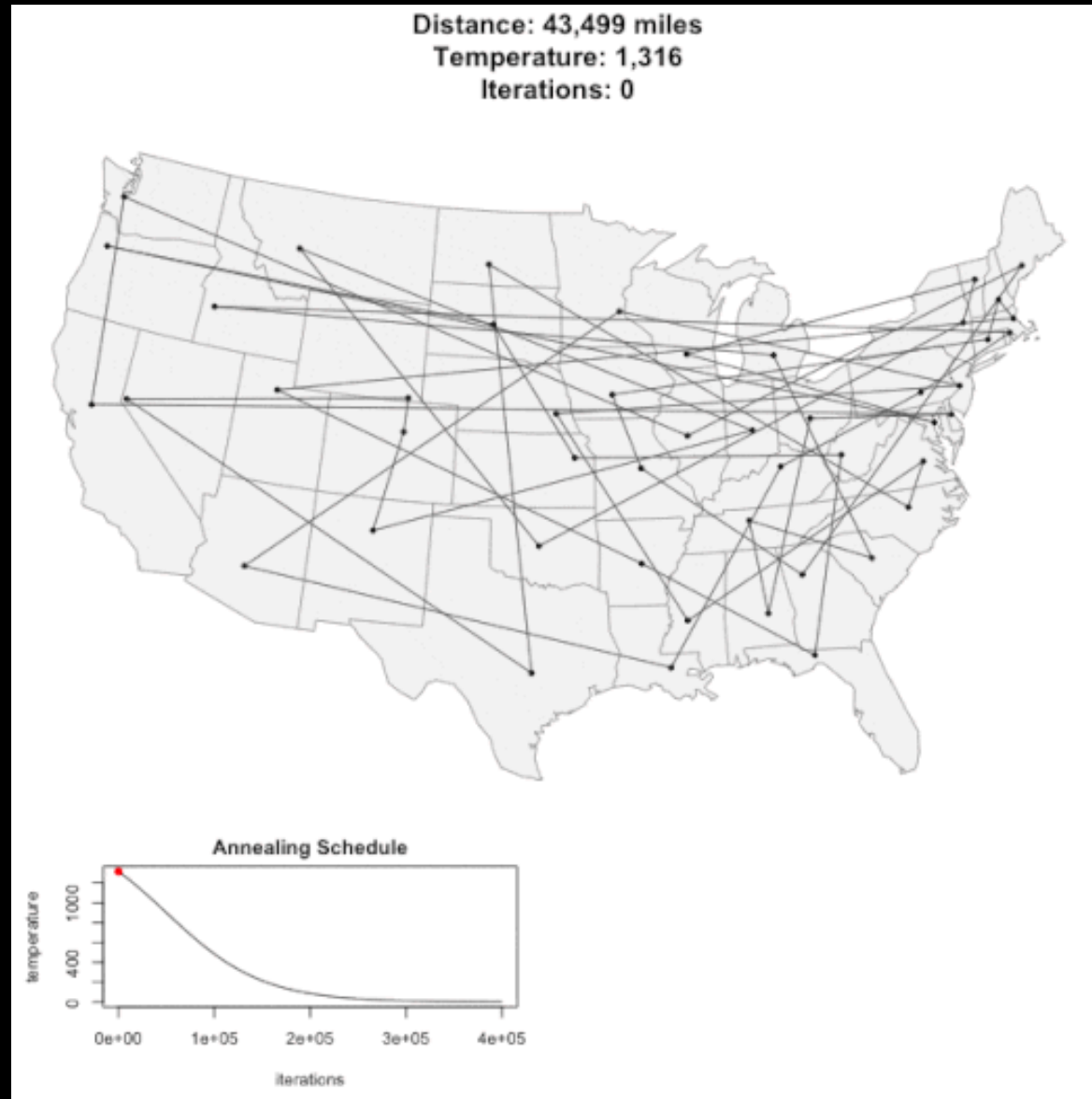
- **Randomly choose** to initialize several times
- Implement hill climbing for **each initialization** and find the optimal
- If each hill climbing search has a **probability p of success**, then the expected number of restarts required is $1/p$.



Simulated annealing

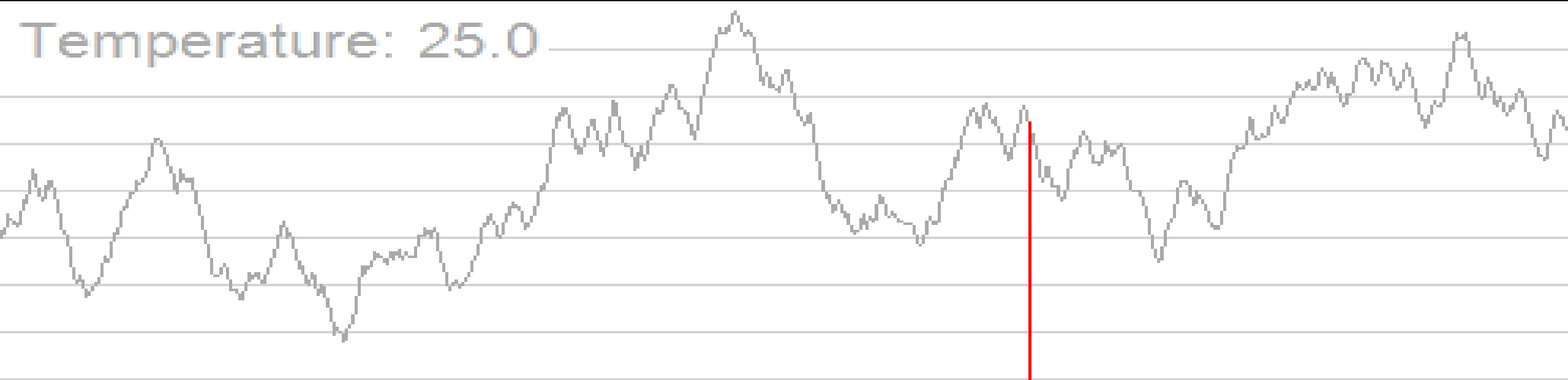
Simulated annealing is a class of algorithms that is inspired by statistical physics:

- **Annealing** is used in metal forging and glass making to aid the formation of crystal structures in the material
- The process **slowly reduces the temperature** the material to allow initial more random arrangements of atoms. At **lower temperatures** the crystallin structure is more stable



The **Traveling Salesman Problem** is a mathematical problem, formulated by W. R. Hamilton in the 1800s, in which one has to find which is the **shortest route** which passes through each of a set of points once and only once.

- The basic idea follows the **annealing physical metaphor**: select random successors with decreasing probability, also known as **temperature**.
- A gradient ΔE is calculated:
 - If $\Delta E > 0$ the new state is **accepted immediately** as an improvement
 - If $\Delta E < 0$ the new state is **accepted only with a probability** that depends on ΔE and T
- If T decreases slowly enough, the algorithm will converge



```
1 function Simulated-annealing(PROBLEM,SCHEDULE) return SOLUTION, or FAILURE
2 current = Make-node(PROBLEM initial state)
3 loop do
4   T = SCHEDULE(t)
5   if T = 0 then
6     return current state
7   next = a randomly selected successor of current
8   ΔE = next value - current value
9   if ΔE > 0 then
10    current = next
11  else
12    current = next only with probability  $e^{\frac{\Delta E}{T}}$ 
```


Genetic algorithm

Genetic algorithms are a randomized heuristic search strategy:

- They use a **natural selection metaphor** to find the best solution to a problem
- The selection process is applied to a population that is composed of **candidate solutions**
- The purpose is to **evolve a population** from which strong and diverse candidates can emerge via mutation and crossover, also known as mating

- An hypothesis is described by a **chromosome**
- Few successor functions are needed (also known as **fringe functions**):
 - Mutation
 - crossover
- A **fitness function** is used to implement a natural selection process
- A **solution test** is required if different from the fitness function
- Some general parameters guide the evolution of the population:
 - **Population size**
 - **Generation limit**

1. Start with a random population
2. Apply a **fitness function** to recognize the fittest individuals
3. Keep N hypotheses at each step that have a high value of a fitness function
4. Possibly **cull** the less fit individuals and remove them
5. Apply one or more **successor operations** to generate a new population
6. Apply the solution test to the best candidate
7. Start over

A **successor operation** changes the current state of the search into something new:

- A **Mutation** fringe operation: given a candidate, return a slightly different candidate
- A **Crossover** fringe operation: given two candidates, produce one that has elements of each

We don't always generate a successor for each individual. Rather, we generate a successor **population** based on the individuals in the current population, weighted by fitness.

A new population can be generated by:

- Given a population P , generate P' by performing crossover $|P|$ times, each time selecting candidates with probability **proportional to their fitness**
- Get P'' by mutating each individual in P'
- Return P''

The previous approach doesn't explicitly allow individuals to survive more than one generation.

Crossover is **not necessary**, though it can be helpful in escaping local maxima. Mutation is **fundamental**.

GOOD

- Faster and with lower memory requirements
- It can explore a very large search space
- Easy to design

BAD

- Randomized – not optimal or even complete
- Can get stuck on local maxima, though mutation can help mitigate this
- It can be hard to design a chromosome

```

1  function GENETIC-ALGORITHM(population, FITNESS-FN) return an individual
2      repeat
3          new population ← empty set
4          for i = 1 to SIZE(population) do
5              x ← RANDOM-SELECTION(population, FITNESS-FN)
6              y ← RANDOM-SELECTION(population, FITNESS-FN)
7              child ← REPRODUCE(x, y)
8              if (small random probability) then child ← MUTATE(child)
9              add child to new population
10             population ← new population
11         until some individual is fit enough, or enough time has elapsed
12         return the best individual in population, according to FITNESS-FN
13
14 function REPRODUCE(x, y) return an individual
15     n ← LENGTH(x)
16     c ← random number from 1 to n
17     return APPEND SUBSTRING(x, 1, c), SUBSTRING(y, c + 1, n)

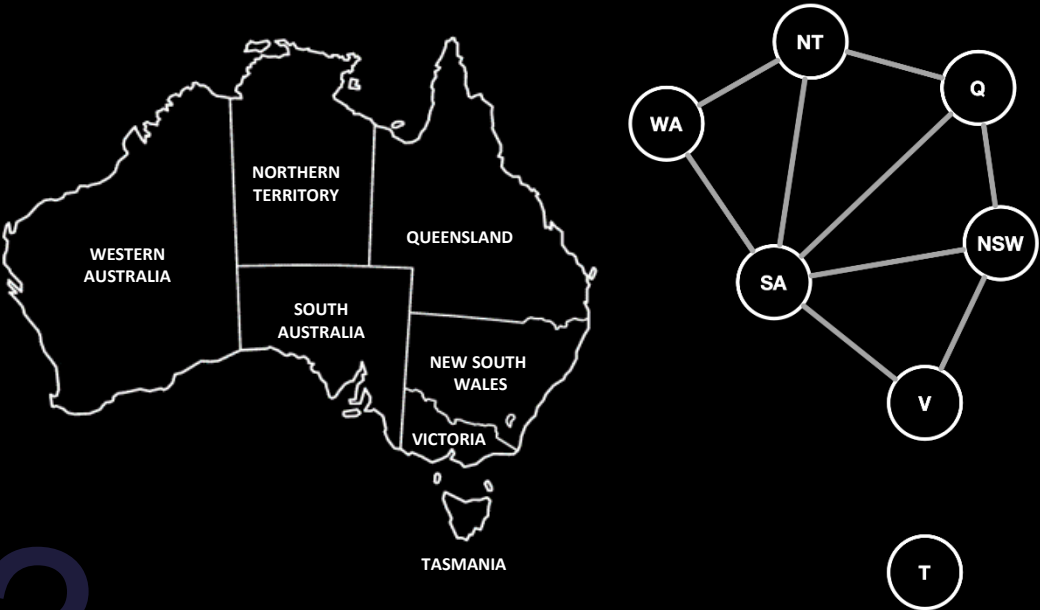
```

■ **STATES**
Color the Australia map so that neighboring regions do not match

■ **CHROMOSOME**

WA	NT	Q	NSW	V	SA	T
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■ **FITNESS FUNCTION**
Number of pairs of regions that do not violate the constraint (max value 10)



#	INDIVIDUAL	FITNES FUNCTION	NORMALIZED FITNES FUNCTION
1	R G R B R B B	9	14%
2	R R R G G B B	7	11%
3	G G R B B R R	7	11%
4	R G B B R B G	7	11%
5	G G R R R B B	7	11%
6	G B G B R B B	8	13%
7	B G B G R R R	9	15%
8	G B B G B R B	9	14%
		63	100%

POPULATION

1	R	G	R	B	R	B	B
2	R	R	R	G	G	B	B
3	G	G	R	B	B	R	R
4	R	G	B	B	R	B	G
5	G	G	R	R	R	B	B
6	G	B	G	B	R	B	B
7	B	G	B	G	R	R	R
8	G	B	B	G	B	R	B

SELECTION

9 14%

7 11%

7 11%

7 11%

7 11%

8 13%

9 15%

9 14%

7	B	G	B	G	R	R	R
8	G	B	B	G	B	R	B
1	R	G	R	B	R	B	B
6	G	B	G	B	R	B	B

2	R	R	R	G	G	B	B
3	G	G	R	B	B	R	R
4	R	G	B	B	R	B	G
5	G	G	R	R	R	B	B

If **culling** is applied, the least fit individuals are eliminated

CROSS-OVER

1	B	G	B	G	B	R	B
2	G	B	B	G	R	R	R
3	R	G	G	B	R	B	B
4	G	B	R	B	R	B	B
5	G	G	B	G	R	R	R
8	B	B	G	B	R	B	B
7	G	B	G	B	R	B	B
6	R	G	R	G	B	R	B

MUTATION

1	B	G	B	G	B	R	B
2	G	B	R	G	R	R	R
3	R	G	G	B	R	B	B
4	G	B	R	B	R	B	B
5	G	G	B	G	G	R	R
8	B	B	G	B	R	B	B
7	G	B	G	B	R	B	B
6	R	G	R	B	B	R	B

Chapters 4.1 – 4.6

Chapter 5

QUESTIONS ?

ARTIFICIAL INTELLIGENCE COMP 131

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