

**EE 105 Feedback Control Systems**  
**Department of Electrical and Computer Engineering**  
**Tufts University Fall 2018**  
**Homework #7**

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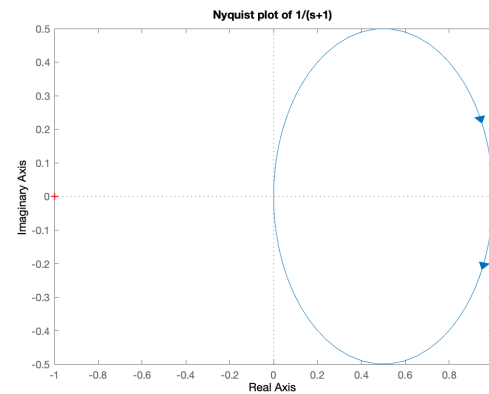
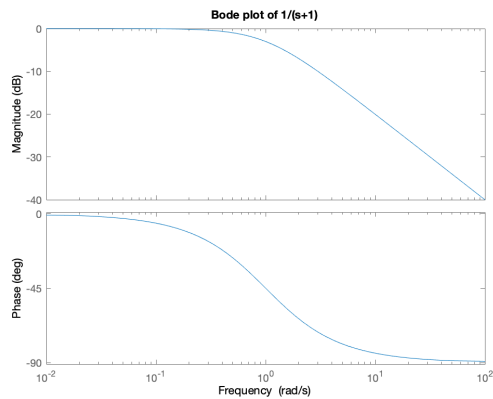
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## 1 Problem 1

### 1.1 Part A

The transfer function is:

$$L(s) = \frac{1}{s+1}$$

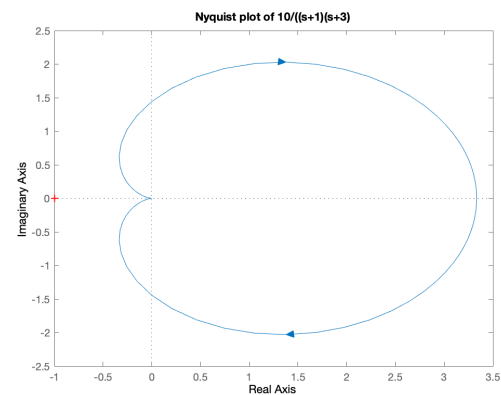
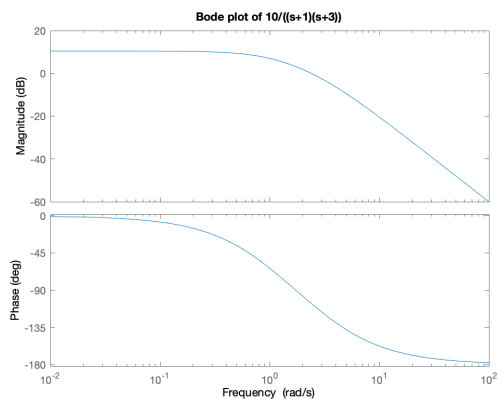


It's stable even if crank  $K$  up to infinity.

### 1.2 Part B

The transfer function is:

$$L(s) = \frac{10}{(s+1)(s+3)}$$

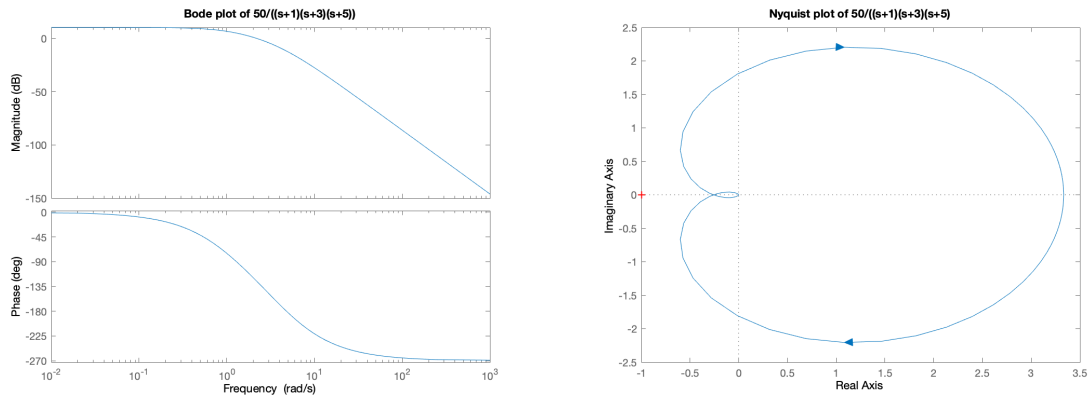


It's stable even if crank  $K$  up to infinity.

### 1.3 Part C

The transfer function is:

$$L(s) = \frac{50}{(s+1)(s+3)(s+5)}$$

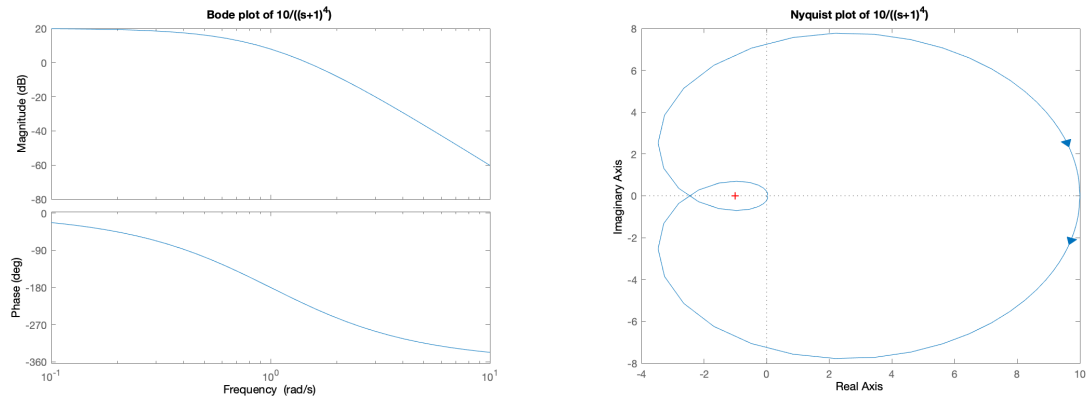


It's stable. But if give an additional gain of 4, the system will be unstable.

### 1.4 Part D

The transfer function is:

$$L(s) = \frac{10}{(s+1)^4}$$

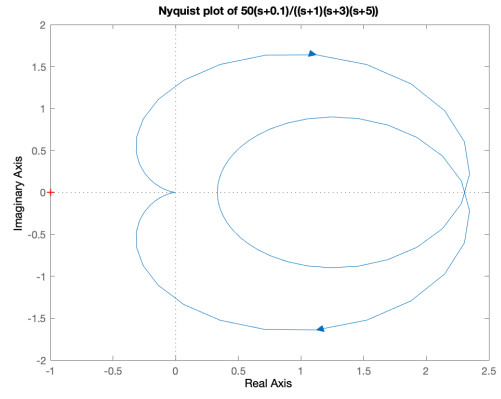
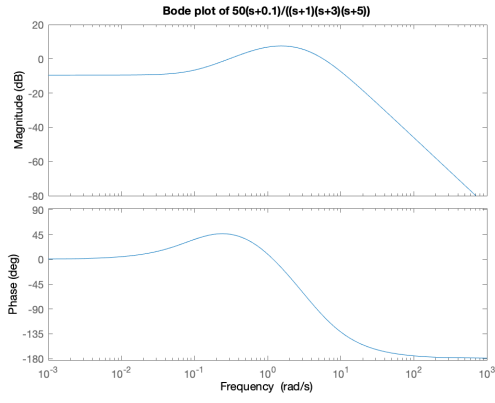


It's unstable. But if give an additional gain of 0.41, the system will be stable.

### 1.5 Part E

The transfer function is:

$$L(s) = \frac{50(s+0.1)}{(s+1)(s+3)(s+5)}$$

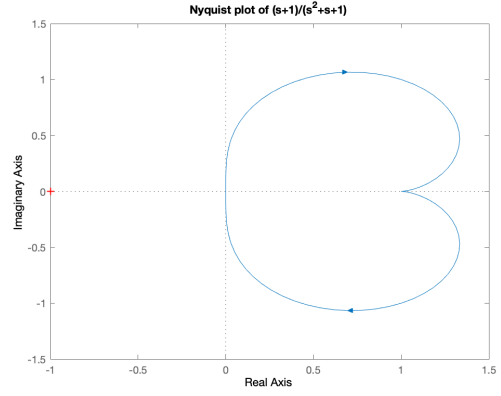
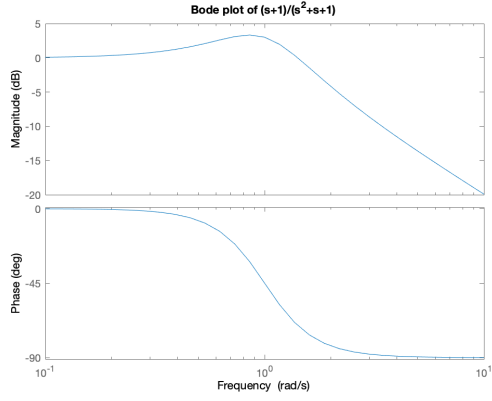


It's stable even if crank  $K$  up to infinity.

## 1.6 Part F

The transfer function is:

$$L(s) = \frac{s+1}{s^2+s+1}$$

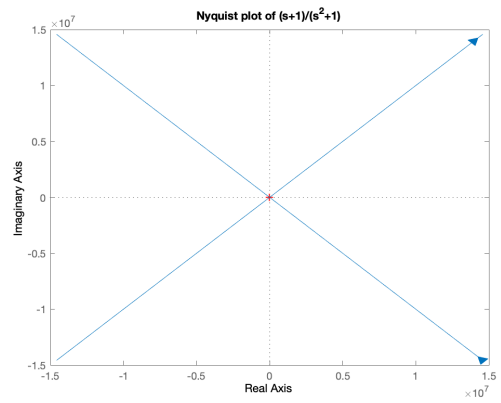
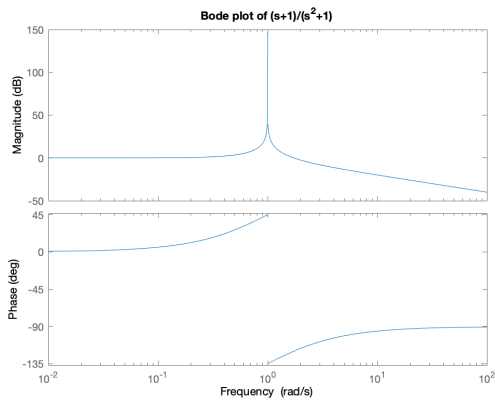


It's stable even if crank  $K$  up to infinity.

## 1.7 Part F

The transfer function is:

$$L(s) = \frac{s+1}{s^2+1}$$



It's stable while in close loop even if crank  $K$  up to infinity.