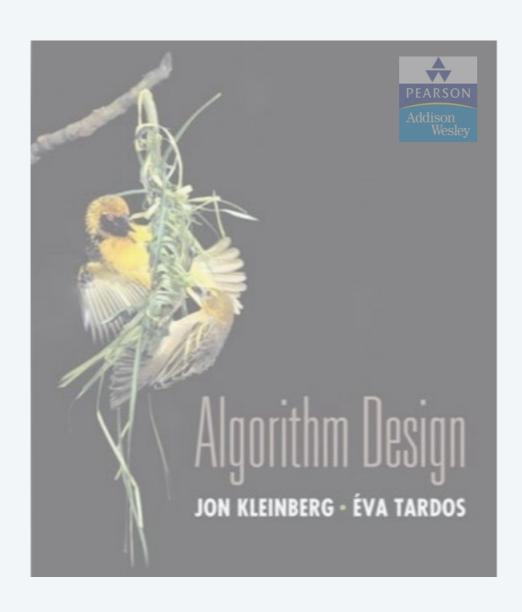


Lecture slides by Kevin Wayne
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<u>http://www.cs.princeton.edu/~wayne/kleinberg-tardos</u>

7. NETWORK FLOW I

- max-flow and min-cut problems
- Ford-Fulkerson algorithm
- max-flow min-cut theorem
- capacity-scaling algorithm
- shortest augmenting paths
- blocking-flow algorithm
- unit-capacity simple networks

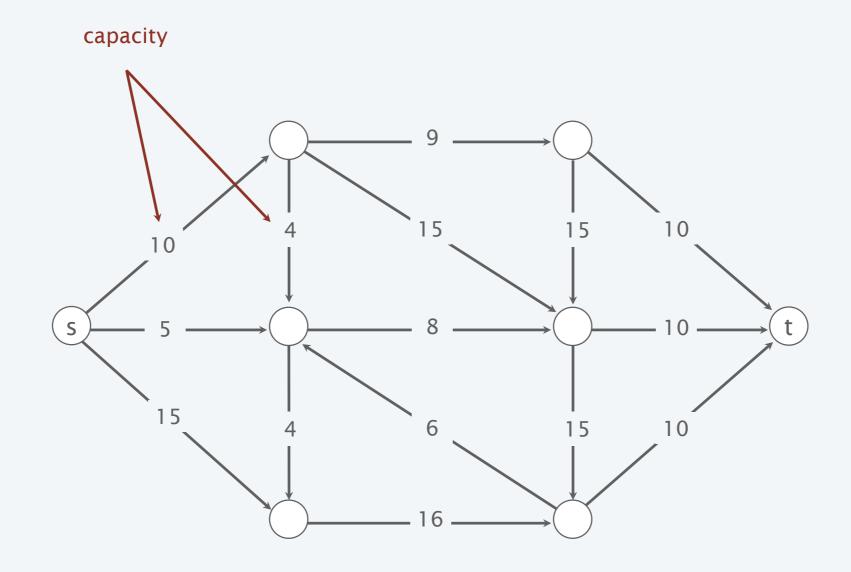


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- Abstraction for material flowing through the edges.
- Digraph G = (V, E) with source $s \in V$ and sink $t \in V$.
- Nonnegative integer capacity c(e) for each $e \in E$.

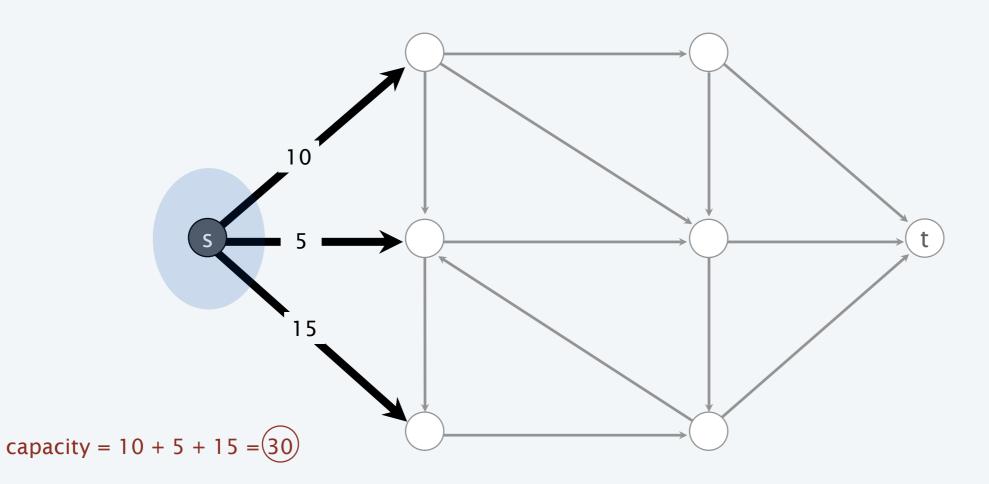
no parallel edges no edge enters s no edge leaves t



Def. A *st*-cut (cut) is a partition (A, B) of the vertices with $s \in A$ and $t \in B$.

Def. Its capacity is the sum of the capacities of the edges from A to B.

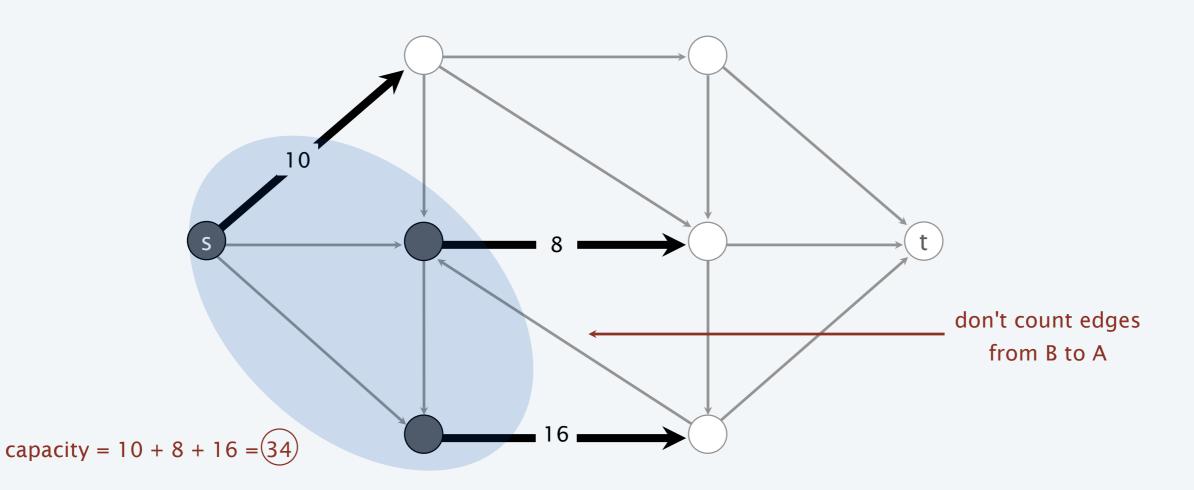
$$cap(A, B) = \sum_{e \text{ out of } A} c(e)$$



Def. A *st*-cut (cut) is a partition (A, B) of the vertices with $s \in A$ and $t \in B$.

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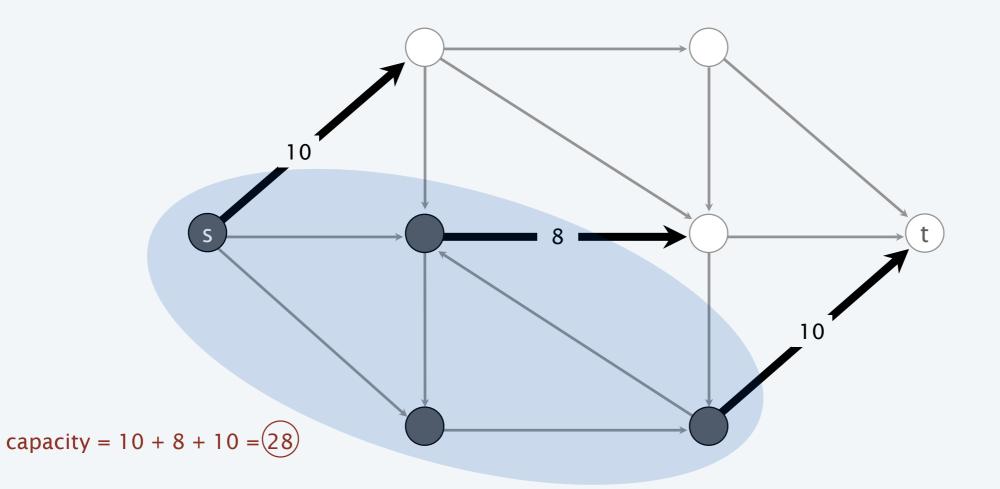


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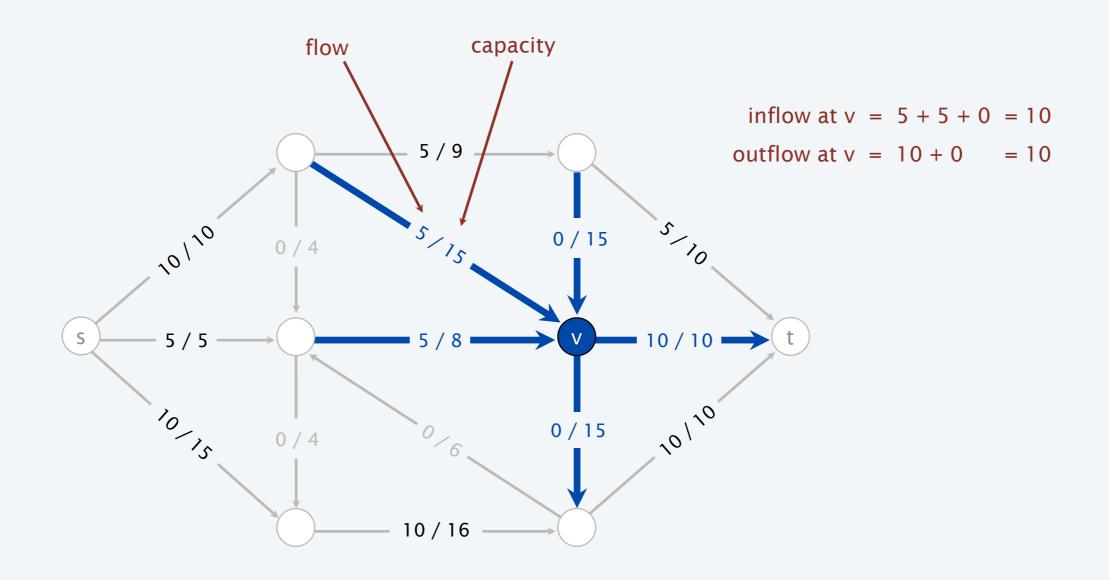
$$cap(A, B) = \sum_{e \text{ out of } A} c(e)$$

Min-cut problem. Find a cut of minimum capacity.



Def. An st-flow (flow) f is a function that satisfies:

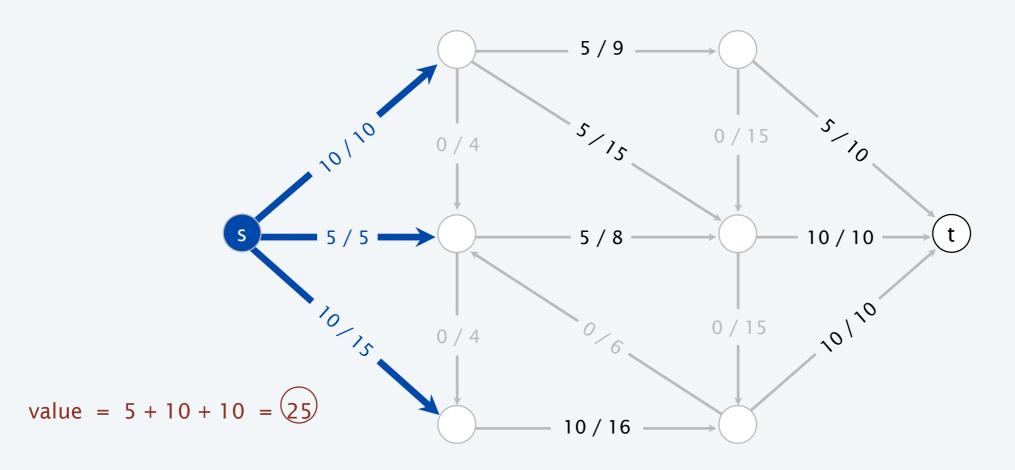
- For each $e \in E$: $0 \le f(e) \le c(e)$ [capacity]
- For each $v \in V \{s, t\}$: $\sum f(e) = \sum f(e)$ [flow conservation] e out of v e in to v



Def. An st-flow (flow) f is a function that satisfies:

- For each $e \in E$: $0 \le f(e) \le c(e)$ [capacity]
- For each $v \in V \{s, t\}$: $\sum f(e) = \sum f(e)$ [flow conservation] e out of ve in to v

Def. The value of a flow f is: $val(f) = \sum f(e)$. e out of s

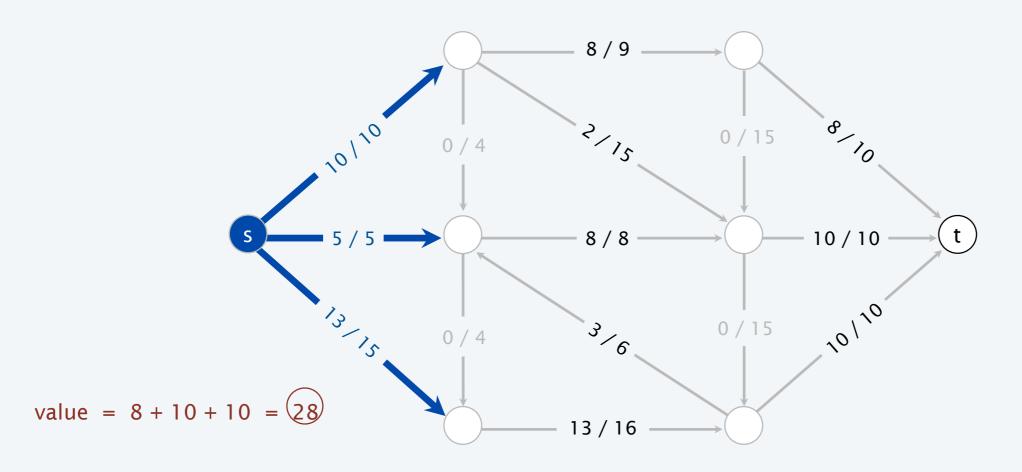


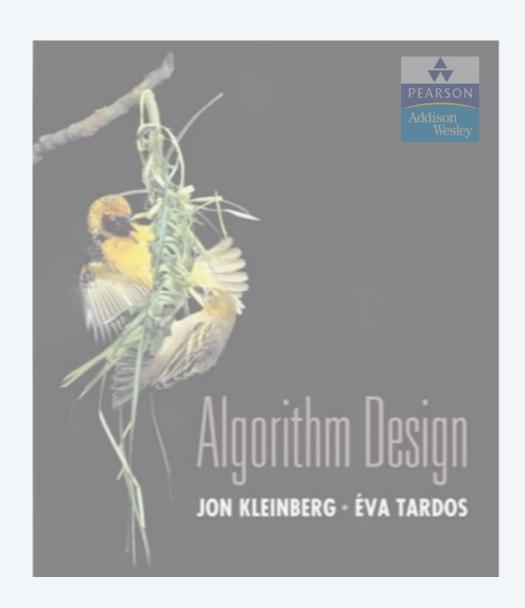
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Def. The value of a flow f is: $val(f) = \sum f(e)$. e out of s

Max-flow problem. Find a flow of maximum value.

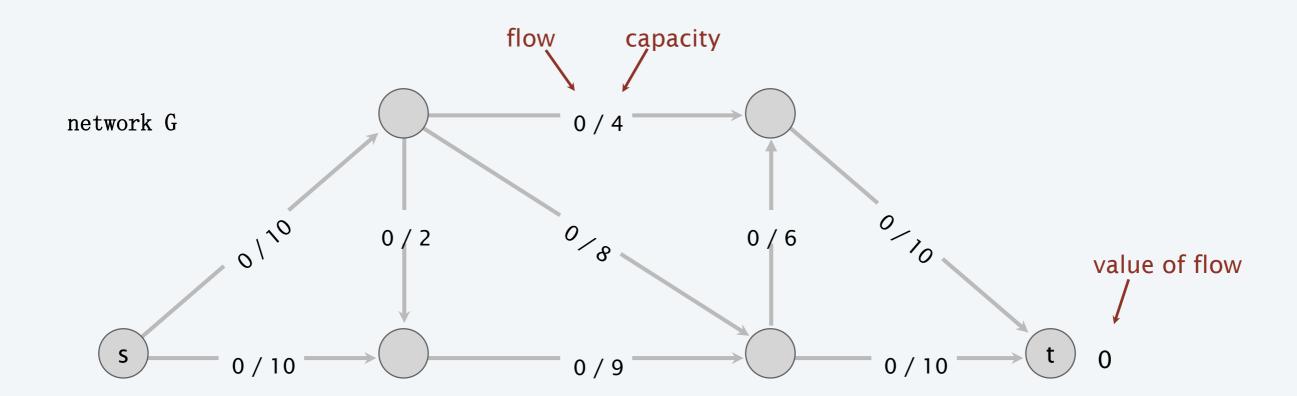




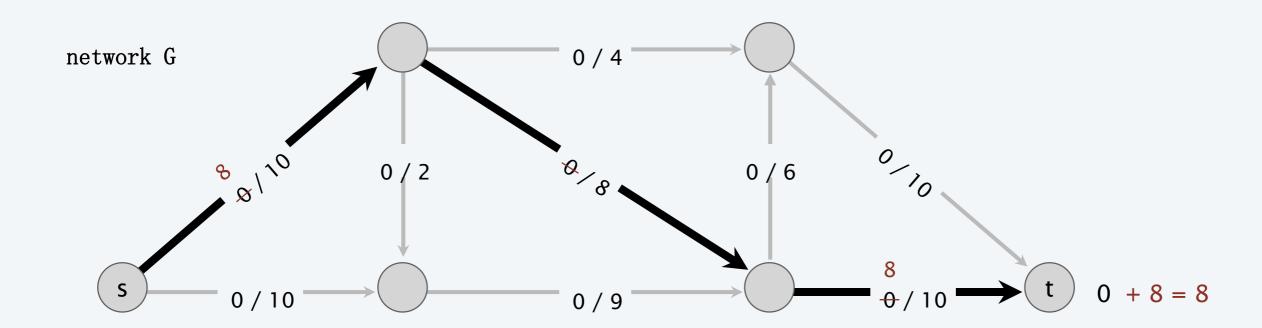
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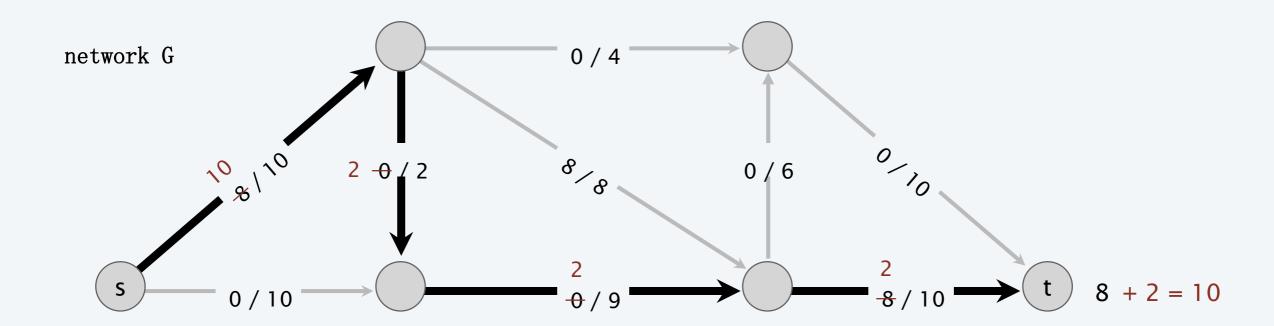
- Start with f(e) = 0 for all edge $e \in E$.
- Find an $s \sim t$ path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.



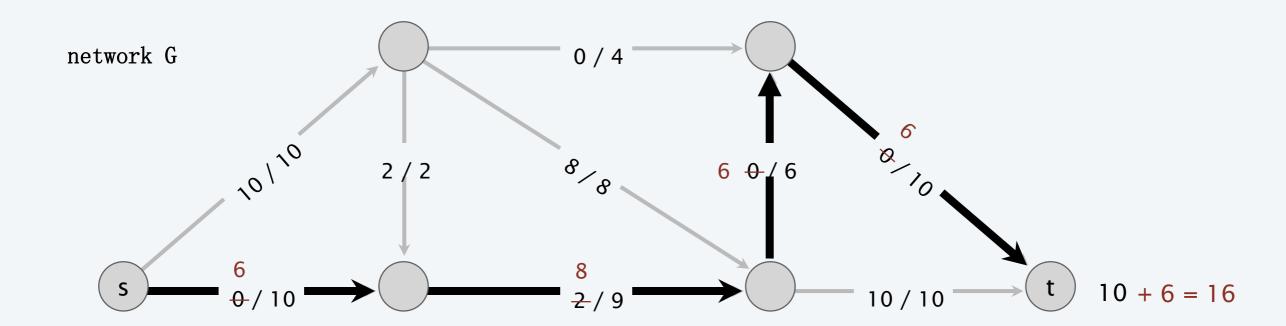
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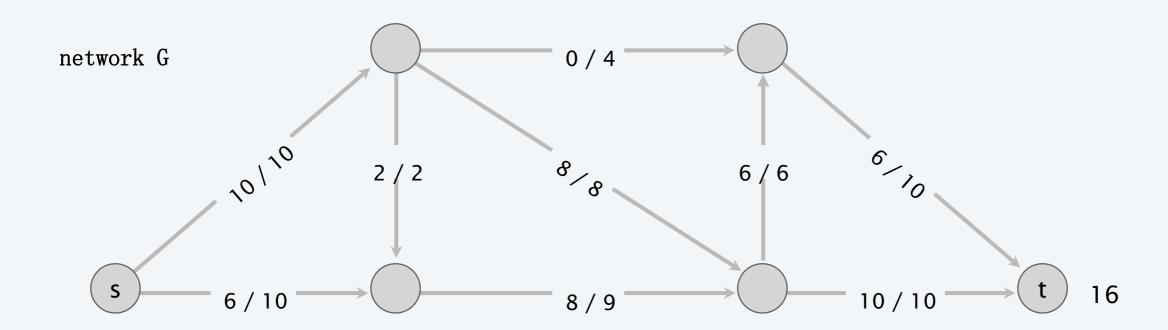


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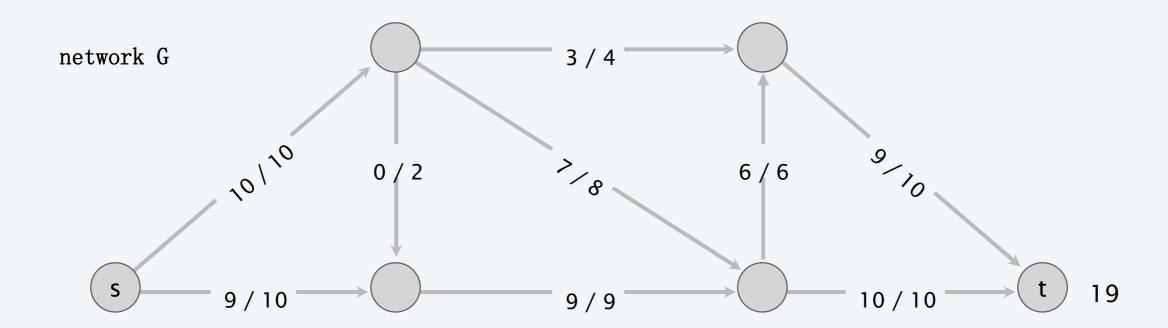
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- Augment flow along path P.
- Repeat until you get stuck.

ending flow value = 16



- Start with f(e) = 0 for all edge $e \in E$.
- Find an $s \sim t$ path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.

but max-flow value = 19



Original edge: $e = (u, v) \in E$.

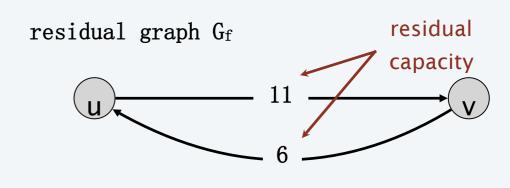
- Flow f(e).
- Capacity c(e).

Residual edge.

- "Undo" flow sent.
- e = (u, v) and $e^R = (v, u)$.
- Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$

original graph G u 6 / 17 v flow capacity



Residual graph: $G_f = (V, E_f)$.

- Residual edges with positive residual capacity.
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}.$

• Key property: f' is a flow in G_f iff f+f' is a flow in G.

where flow on a reverse edge negates flow on a forward edge Def. An augmenting path is a simple $s \sim t$ path P in the residual graph G_f .

Def. The bottleneck capacity of an augmenting P is the minimum residual capacity of any edge in P.

Key property. Let f be a flow and let P be an augmenting path in G_f . Then f' is a flow and $val(f') = val(f) + bottleneck(G_f, P)$.

AUGMENT (f, c, P)

 $b \leftarrow \text{bottleneck capacity of path } P.$

Foreach edge $e \in P$

IF
$$(e \in E) f(e) \leftarrow f(e) + b$$
.

ELSE
$$f(e^R) \leftarrow f(e^R) - b$$
.

RETURN f.

Ford-Fulkerson augmenting path algorithm.

- Start with f(e) = 0 for all edge $e \in E$.
- Find an augmenting path P in the residual graph G_f .
- Augment flow along path P.
- Repeat until you get stuck.

```
FORD-FULKERSON (G, s, t, c)

FOREACH edge e \in E : f(e) \leftarrow 0.

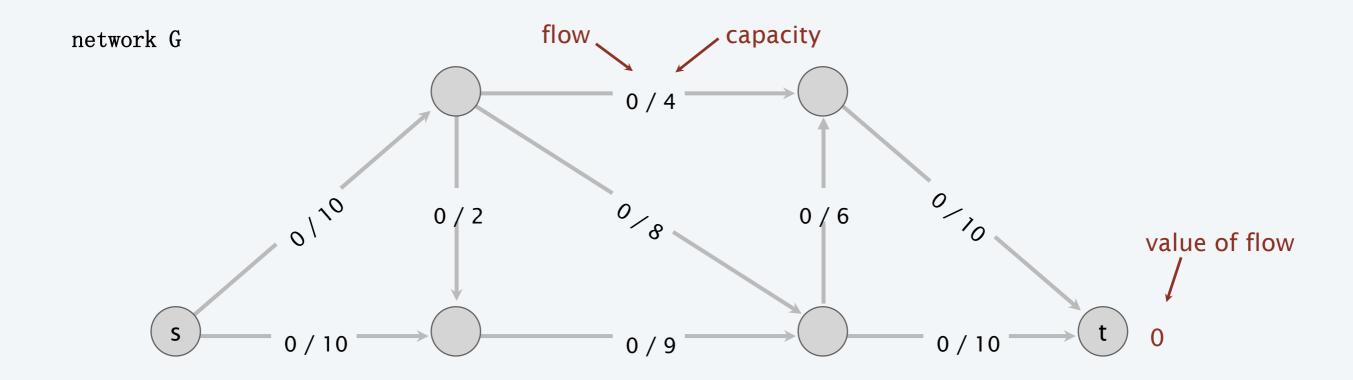
G_f \leftarrow residual graph.

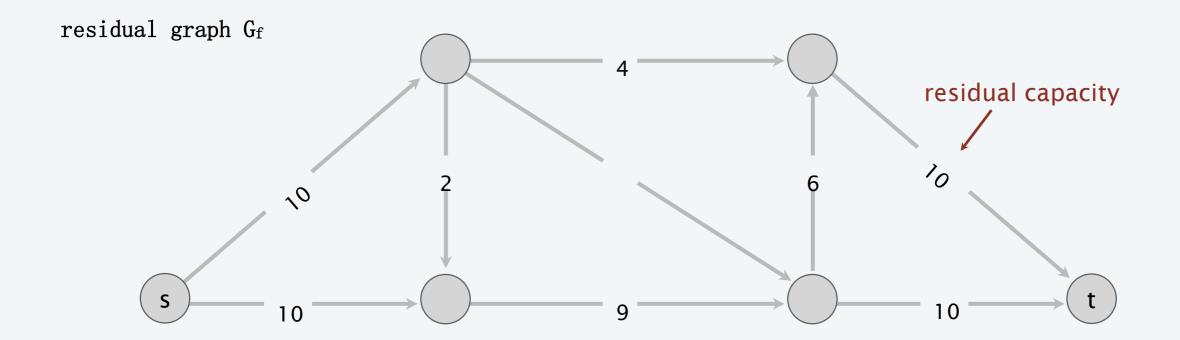
WHILE (there exists an augmenting path P in G_f)

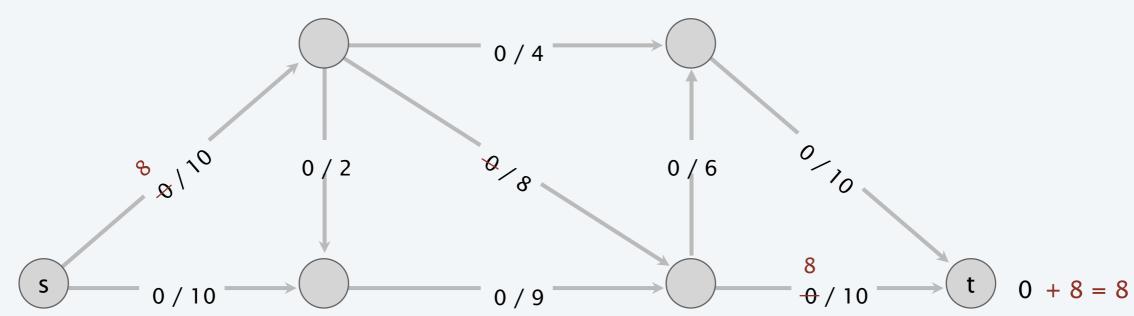
f \leftarrow AUGMENT (f, c, P).

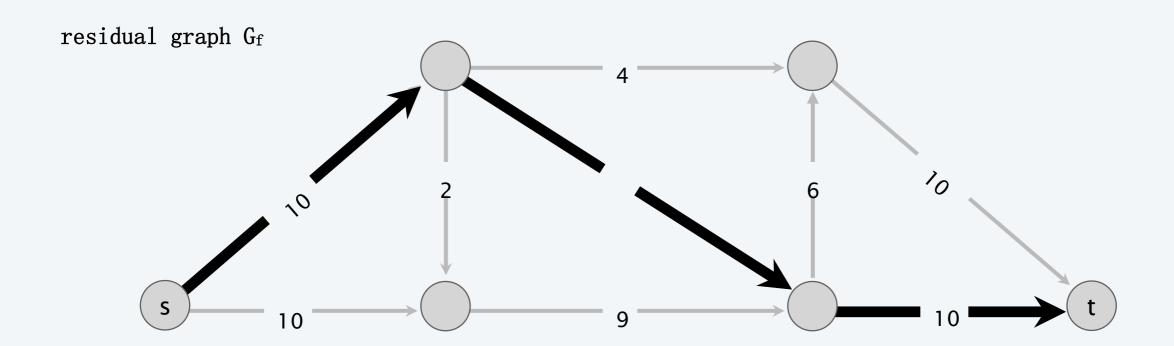
Update G_f.

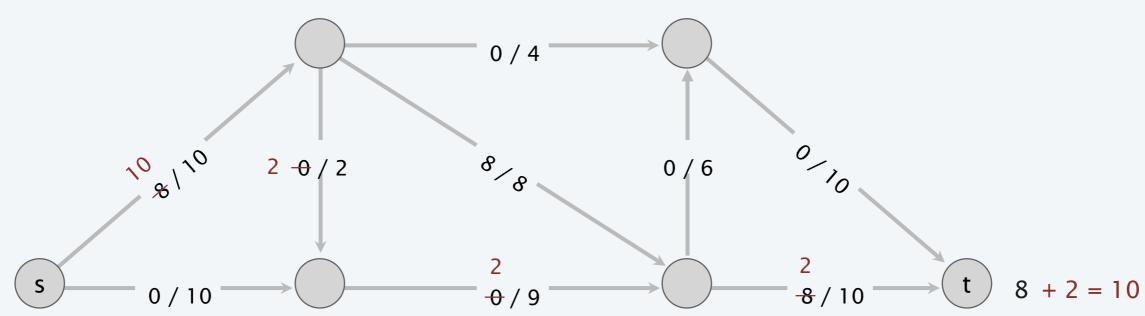
RETURN f.
```

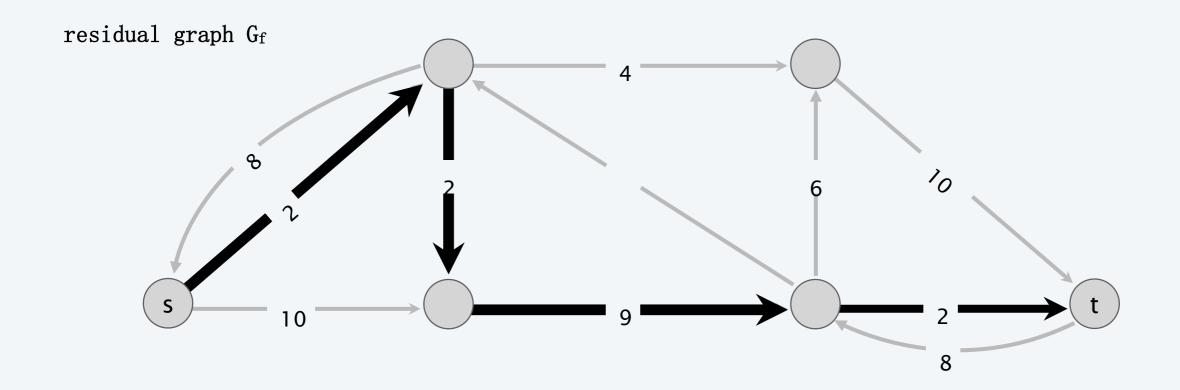


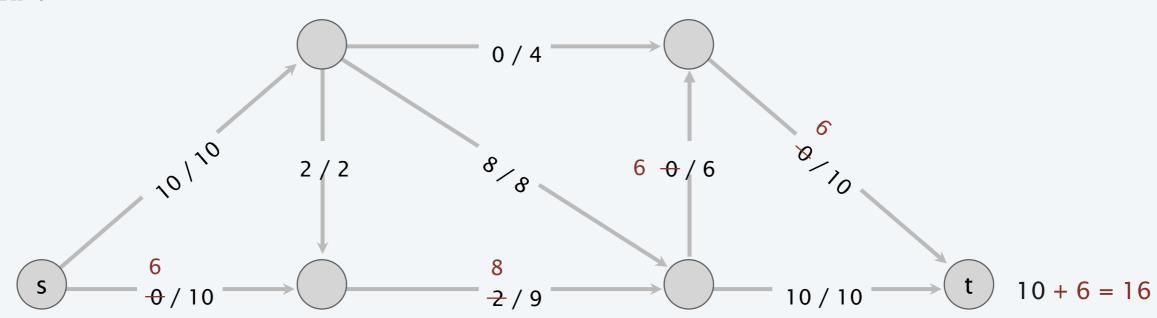


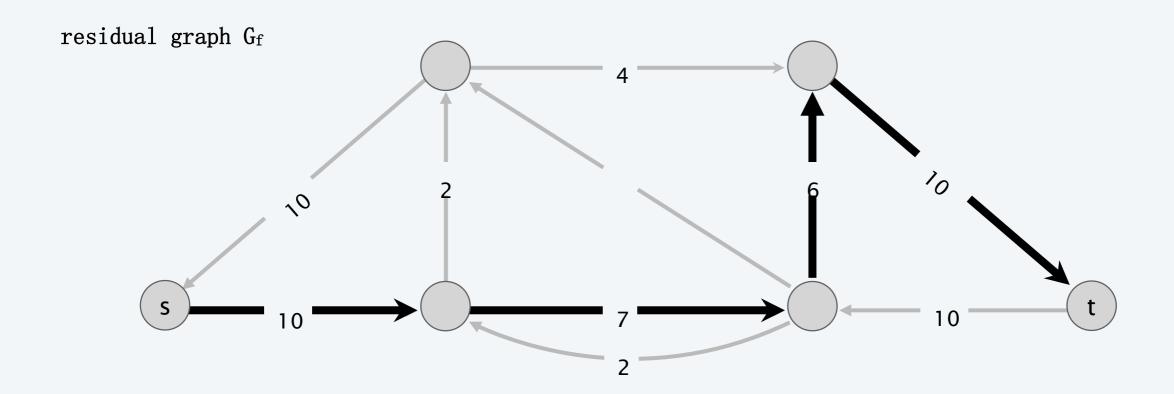


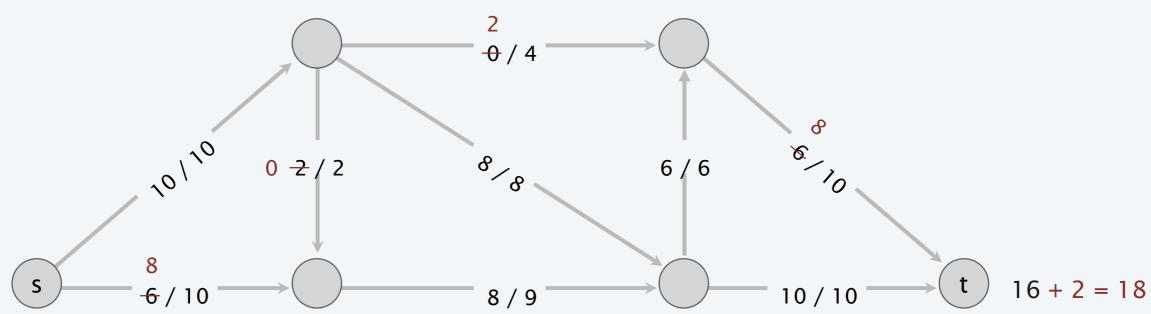


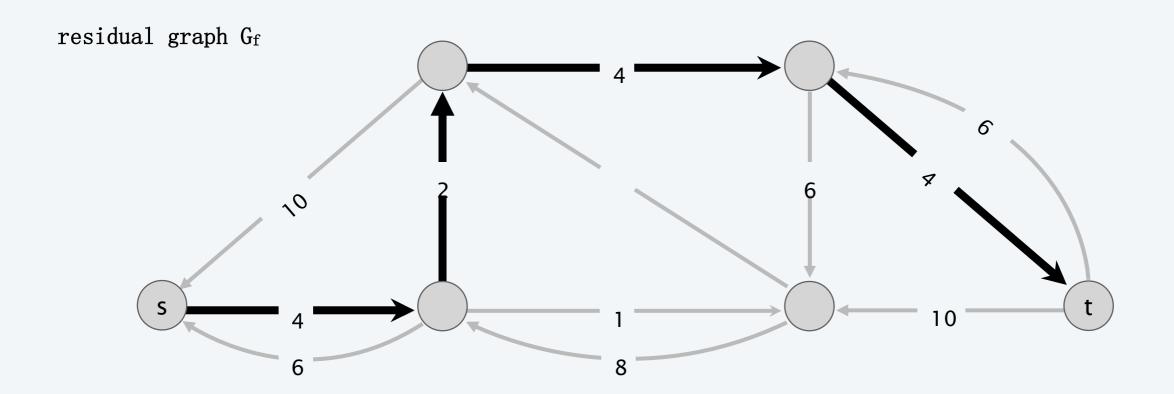


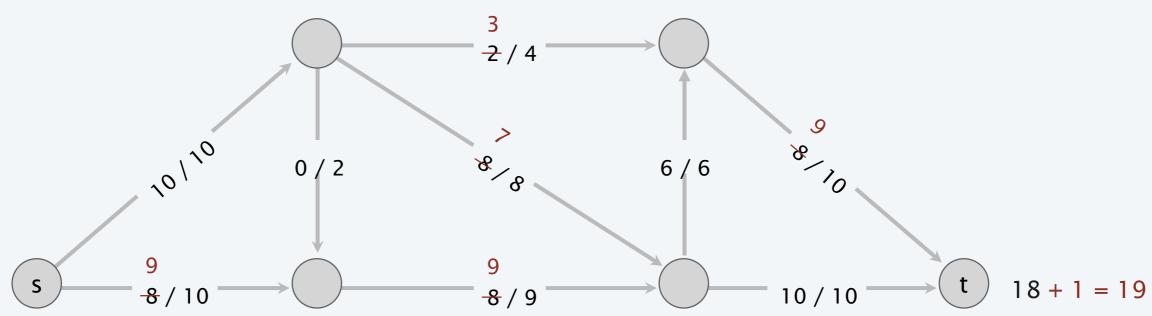


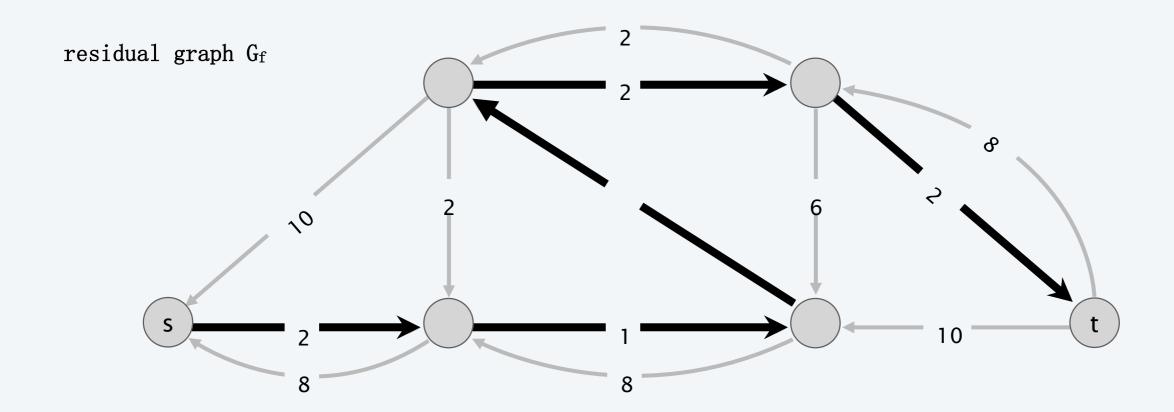


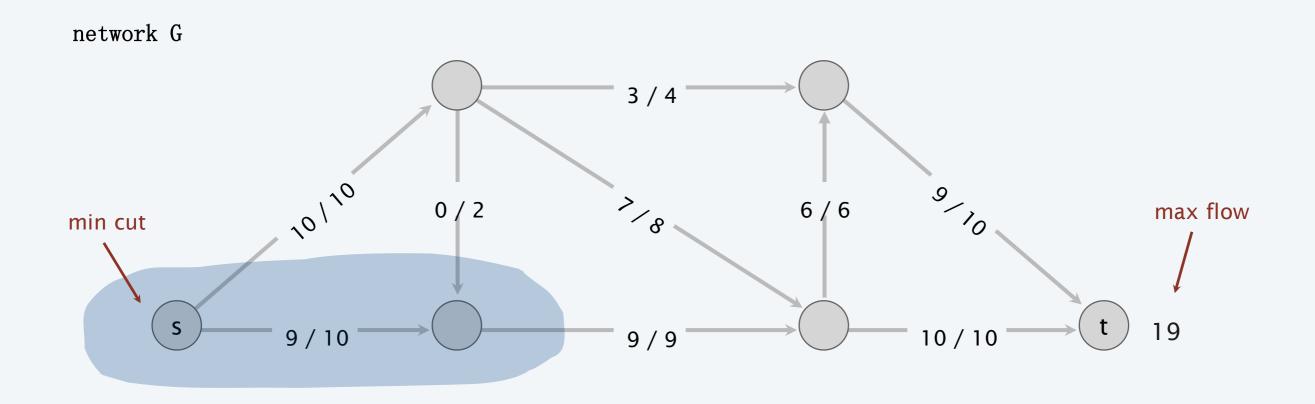


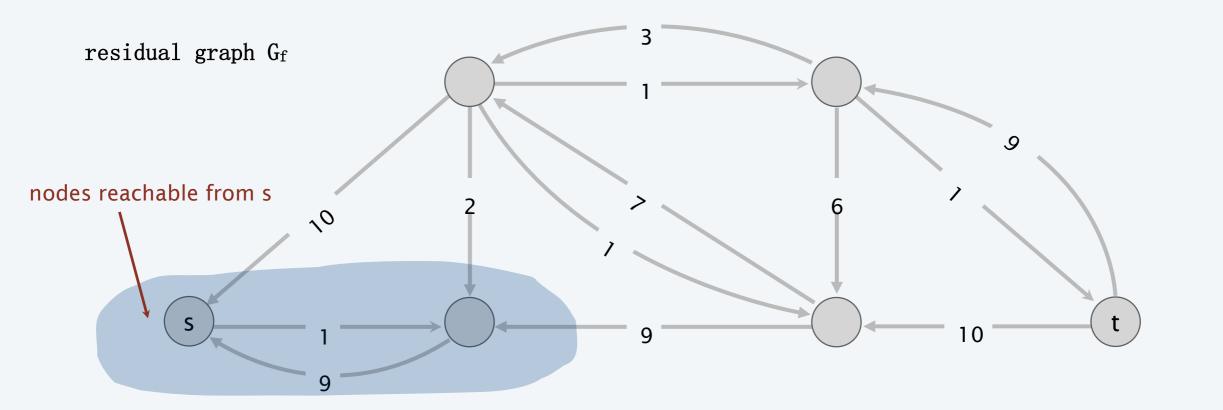


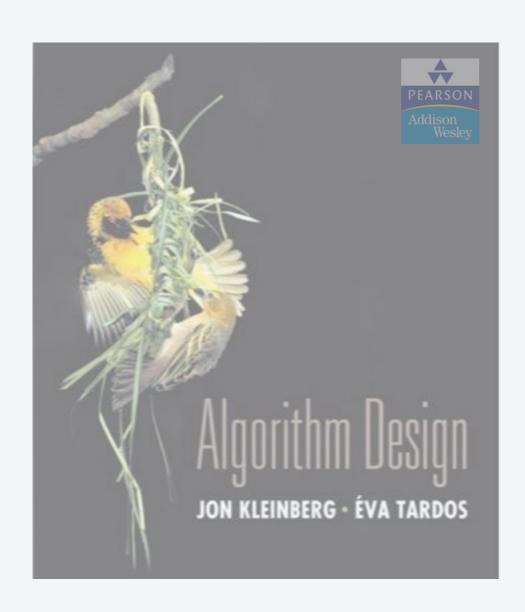










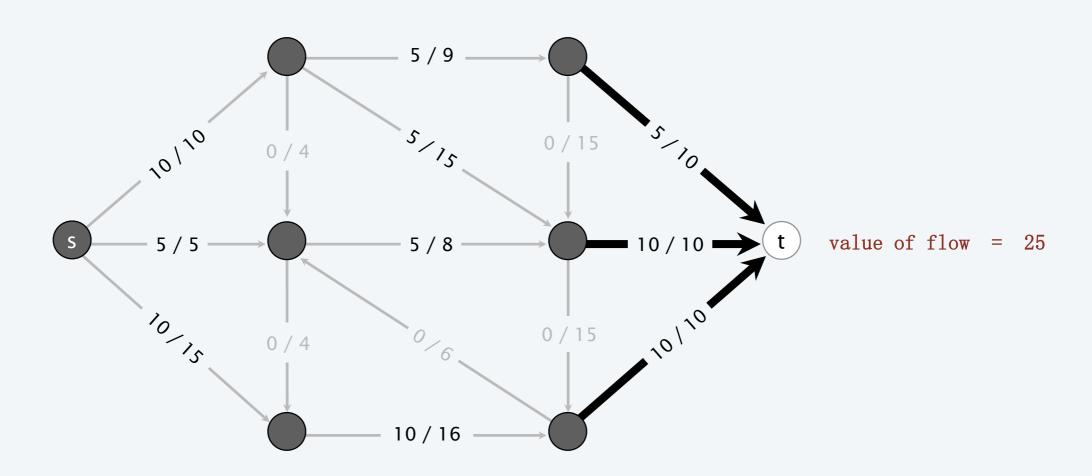


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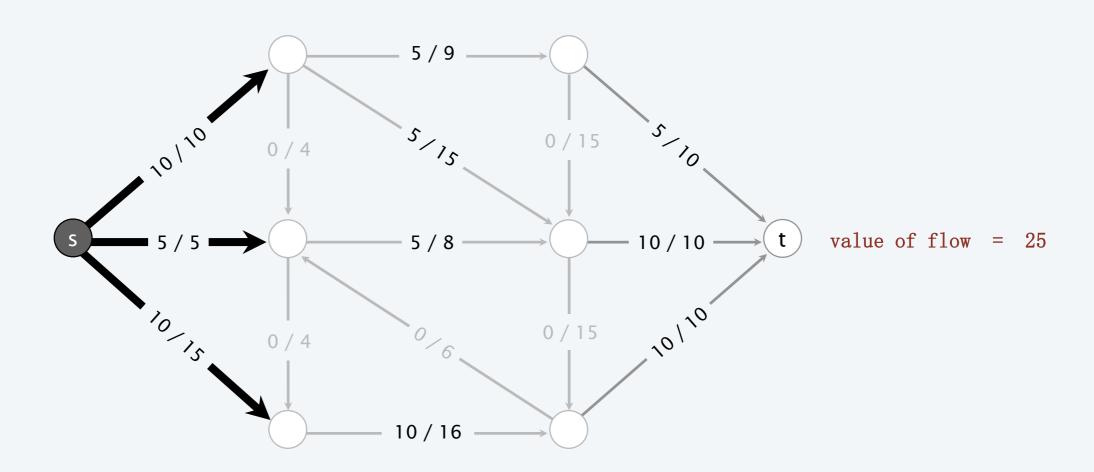
$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$$

net flow across cut = 5 + 10 + 10 = 25

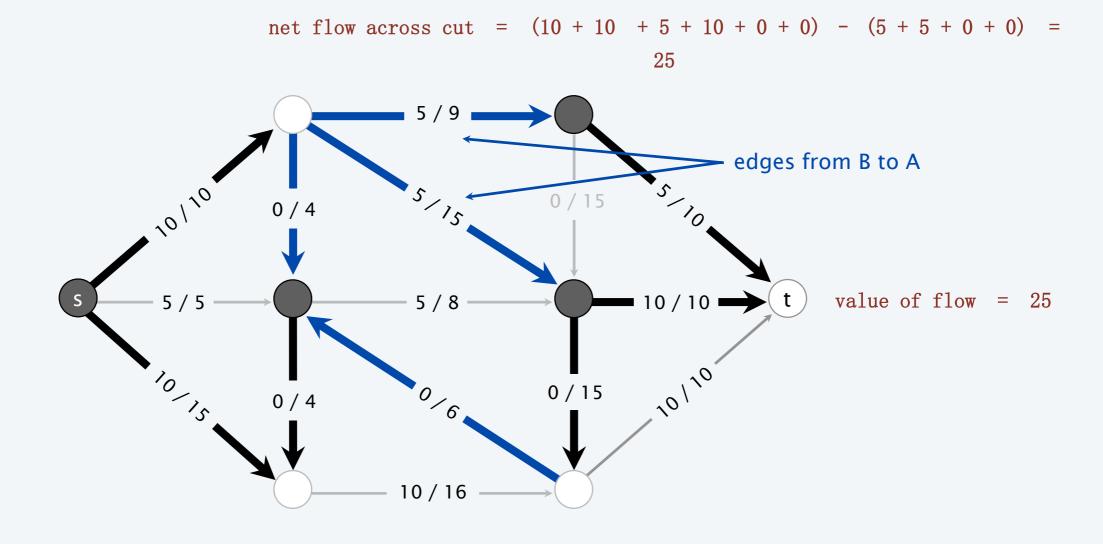


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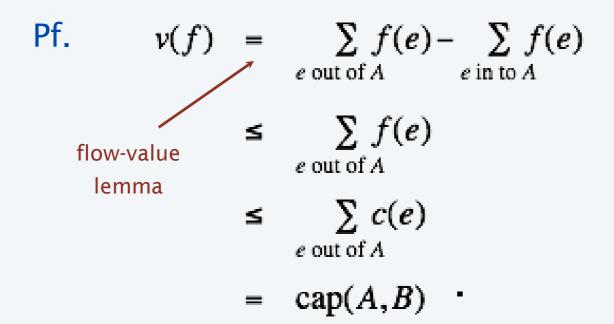


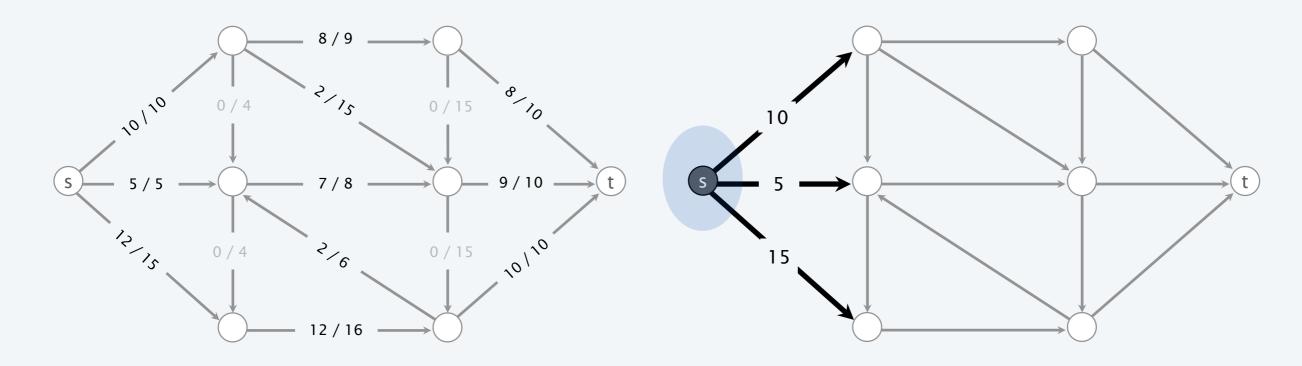
$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$$

Pf.
$$v(f) = \sum_{e \text{ out of } s} f(e)$$
by flow conservation, all terms
$$= \sum_{v \in A} \left(\sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right)$$

$$= \sum_{v \in A} f(e) - \sum_{e \text{ in to } v} f(e).$$

Weak duality. Let f be any flow and (A, B) be any cut. Then, $v(f) \le cap(A, B)$.





Augmenting path theorem. A flow f is a max-flow iff no augmenting paths. Max-flow min-cut theorem. Value of the max-flow = capacity of min-cut.

- Pf. The following three conditions are equivalent for any flow f:
 - i. There exists a cut (A, B) such that cap(A, B) = val(f).
- ii. f is a max-flow.
- iii. There is no augmenting path with respect to f.

$$[i \Rightarrow ii]$$

- Suppose that (A, B) is a cut such that cap(A, B) = val(f).
- Then, for any flow f', $val(f') \le cap(A, B) = val(f)$.
- Thus, f is a max-flow. \uparrow weak duality by assumption

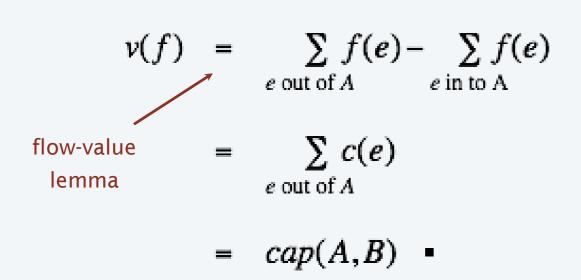
Augmenting path theorem. A flow f is a max-flow iff no augmenting paths. Max-flow min-cut theorem. Value of the max-flow = capacity of min-cut.

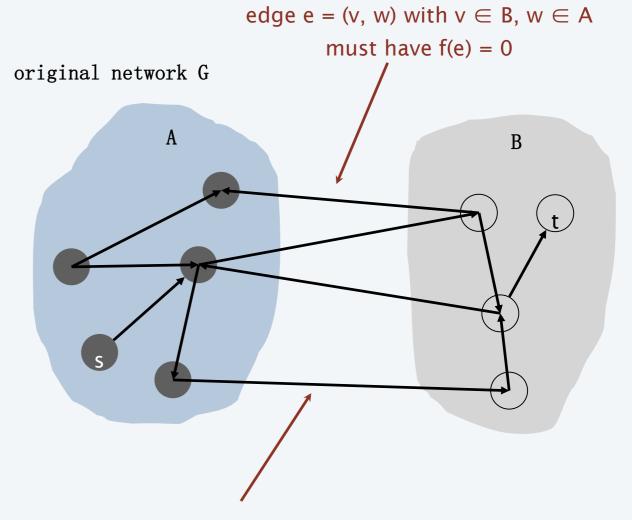
- Pf. The following three conditions are equivalent for any flow f:
 - i. There exists a cut (A, B) such that cap(A, B) = val(f).
- ii. f is a max-flow.
- iii. There is no augmenting path with respect to f.
- [ii \Rightarrow iii] We prove contrapositive: \sim iii \Rightarrow \sim ii.
 - Suppose that there is an augmenting path with respect to f.
 - Can improve flow f by sending flow along this path.
 - Thus, f is not a max-flow.

Max-flow min-cut theorem

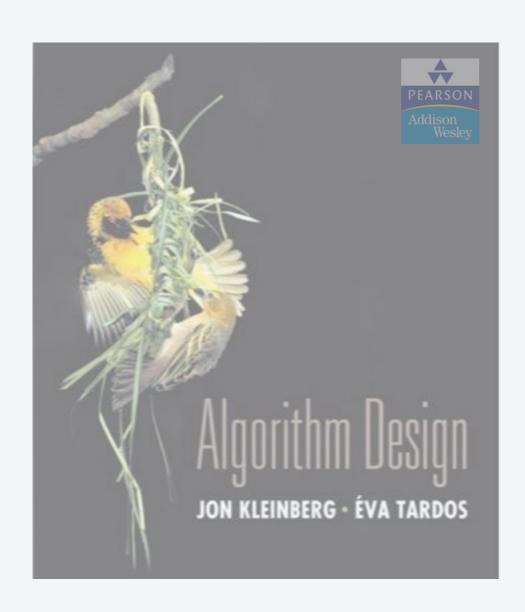
$[iii \Rightarrow i]$

- Let f be a flow with no augmenting paths.
- Let A be set of nodes reachable from s in residual graph G_f .
- By definition of cut $A, s \in A$.
- By definition of flow f, $t \notin A$.





edge e = (v, w) with $v \in A$, $w \in B$ must have f(e) = c(e)



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Assumption. Capacities are integers between 1 and *C*.

Integrality invariant. Throughout the algorithm, the flow values f(e) and the residual capacities $c_f(e)$ are integers.

Theorem. The algorithm terminates in at most $val(f^*) \le nC$ iterations. Pf. Each augmentation increases the value by at least 1. •

Corollary. The running time of Ford-Fulkerson is O(m n C). Corollary. If C = 1, the running time of Ford-Fulkerson is O(m n).

Integrality theorem. Then exists a max-flow f^* for which every flow value $f^*(e)$ is an integer.

Pf. Since algorithm terminates, theorem follows from invariant.

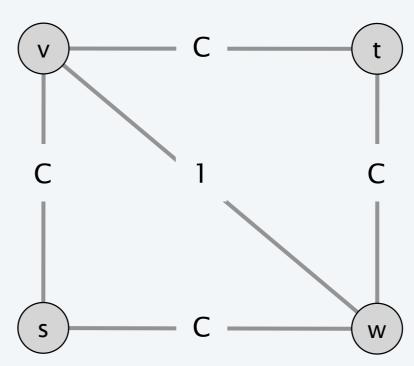
Q. Is generic Ford-Fulkerson algorithm poly-time in input size?

m, n, and log C

- A. No. If max capacity is C, then algorithm can take $\geq C$ iterations.
 - $s \rightarrow v \rightarrow w \rightarrow t$
 - $s \rightarrow w \rightarrow v \rightarrow t$
 - $s \rightarrow v \rightarrow w \rightarrow t$
 - \bullet $s \rightarrow w \rightarrow v \rightarrow t$
 - •
 - $s \rightarrow v \rightarrow w \rightarrow t$
 - $s \rightarrow w \rightarrow v \rightarrow t$

each augmenting path sends only 1 unit of flow

(# augmenting paths = 2C)



Use care when selecting augmenting paths.

- Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- If capacities are irrational, algorithm not guaranteed to terminate!

Goal. Choose augmenting paths so that:

- Can find augmenting paths efficiently.
- Few iterations.

Choosing good augmenting paths

Choose augmenting paths with:

- Max bottleneck capacity.
- Sufficiently large bottleneck capacity.
- Fewest number of edges.

Theoretical Improvements in Algorithmic Efficiency for Network Flow Problems

JACK EDMONDS

University of Waterloo, Waterloo, Ontario, Canada

AND

RICHARD M. KARP

University of California, Berkeley, California

ABSTRACT. This paper presents new algorithms for the maximum flow problem, the Hitcheoek transportation problem, and the general minimum-cost flow problem. Upper bounds on the numbers of steps in these algorithms are derived, and are shown to compare favorably with upper bounds on the numbers of steps required by earlier algorithms.

Edmonds-Karp 1972 (USA)

Dokl. Akad. Nauk SSSR Tom 194 (1970), No. 4 Soviet Math. Dokl. Vol. 11 (1970), No.5

ALGORITHM FOR SOLUTION OF A PROBLEM OF MAXIMUM FLOW IN A NETWORK WITH POWER ESTIMATION

UDC 518.5

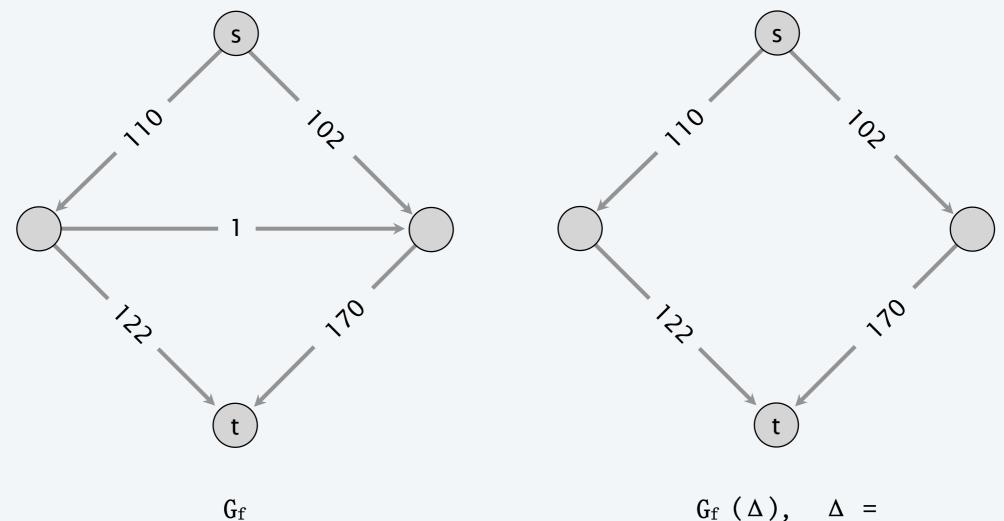
E. A. DINIC

Different variants of the formulation of the problem of maximal stationary flow in a network and its many applications are given in [1]. There also is given an algorithm solving the problem in the case where the initial data are integers (or, what is equivalent, commensurable). In the general case this algorithm requires preliminary rounding off of the initial data, i.e. only an approximate solution of the problem is possible. In this connection the rapidity of convergence of the algorithm is inversely proportional to the relative precision.

Dinic 1970 (Soviet Union)

Intuition. Choose augmenting path with highest bottleneck capacity: it increases flow by max possible amount in given iteration.

- Don't worry about finding exact highest bottleneck path.
- Maintain scaling parameter Δ .
- Let $G_f(\Delta)$ be the subgraph of the residual graph consisting only of arcs with capacity $\geq \Delta$.



 $G_f(\Delta)$,

```
CAPACITY-SCALING(G, s, t, c)
FOREACH edge e \in E : f(e) \leftarrow 0.
\Delta \leftarrow largest power of 2 \leq C.
WHILE (\Delta \geq 1)
   G_f(\Delta) \leftarrow \Delta-residual graph.
    WHILE (there exists an augmenting path P in G_f(\Delta))
       f \leftarrow \text{AUGMENT}(f, c, P).
       Update G_f(\Delta).
   \Delta \leftarrow \Delta / 2.
RETURN f.
```

Capacity-scaling algorithm: proof of correctness

Assumption. All edge capacities are integers between 1 and *C*.

Integrality invariant. All flow and residual capacity values are integral.

Theorem. If capacity-scaling algorithm terminates, then f is a max-flow. Pf.

- By integrality invariant, when $\Delta = 1 \Rightarrow G_f(\Delta) = G_f$.
- Upon termination of $\Delta = 1$ phase, there are no augmenting paths. •

Lemma 1. The outer while loop repeats $1 + \log_2 C$ times. Pf. Initially $C/2 < \Delta \le C$; Δ decreases by a factor of 2 in each iteration.

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then, the value of the max-flow $\leq val(f) + m \Delta$. \longleftarrow proof on next slide

Lemma 3. There are at most 2m augmentations per scaling phase. Pf.

- Let f be the flow at the end of the previous scaling phase.
- LEMMA 2 $\Rightarrow val(f^*) \leq val(f) + 2 m \Delta$.
- Each augmentation in a Δ -phase increases val(f) by at least Δ . •

Theorem. The scaling max-flow algorithm finds a max flow in $O(m \log C)$ augmentations. An augmentation need O(m), including setup of graph and finding a path. It can be implemented to run in $O(m^2 \log C)$ time.

Pf. Follows from LEMMA 1 and LEMMA 3. •

Capacity-scaling algorithm: analysis of running time

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then, the value of the max-flow $\leq val(f) + m \Delta$. Pf.

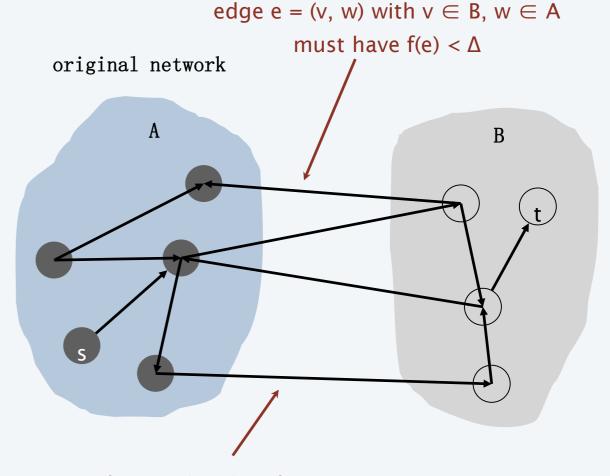
- We show there exists a cut (A, B) such that $cap(A, B) \leq val(f) + m \Delta$.
- Choose *A* to be the set of nodes reachable from *s* in $G_f(\Delta)$.
- By definition of cut $A, s \in A$.
- By definition of flow $f, t \notin A$.

$$val(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$

$$\geq \sum_{e \text{ out of } A} (c(e) - \Delta) - \sum_{e \text{ in to } A} \Delta$$

$$= \sum_{e \text{ out of } A} c(e) - \sum_{e \text{ out of } A} \Delta - \sum_{e \text{ in to } A} \Delta$$

$$\geq cap(A, B) - m\Delta \quad \blacksquare$$



edge e = (v, w) with $v \in A$, $w \in B$ must have $f(e) > c(e) - \Delta$