This is Q4 of the assignment

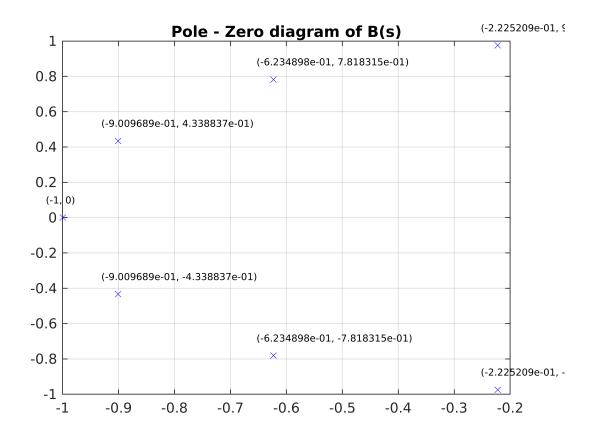
```
[z,p,k] = butter(n,2*pi*f,'low','s');
[num,den] = zp2tf(z,p,k);
```

Part (i) of the assignment

```
len_p = length(p);

for i = 1:len_p
    plot(real(p(i)),imag(p(i)),'bX')
    textString1 = sprintf('(%d, %d)', real(p(i)), imag(p(i)));
    text(real(p(i))-0.03, imag(p(i))+0.1, textString1, 'FontSize', 7);
    hold on
end

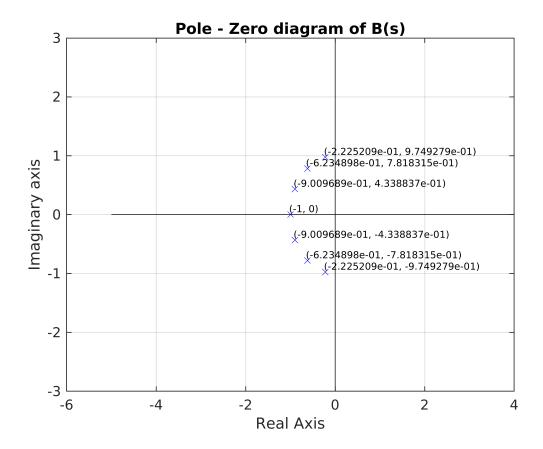
grid on
title('Pole - Zero diagram of B(s)')
```



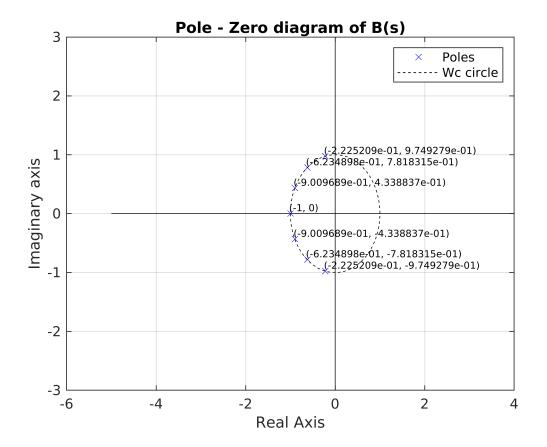
Marking the co-ordinate axis for better view of stability.

```
x_abscissa = [-5 4];
y_abscissa = [0 0];
plot(x_abscissa,y_abscissa,'color', 'black');
xlabel('Real Axis');

x_ord = [0 0];
y_ord = [-3 3];
plot(x_ord,y_ord,'color', 'black');
ylabel('Imaginary axis');
```

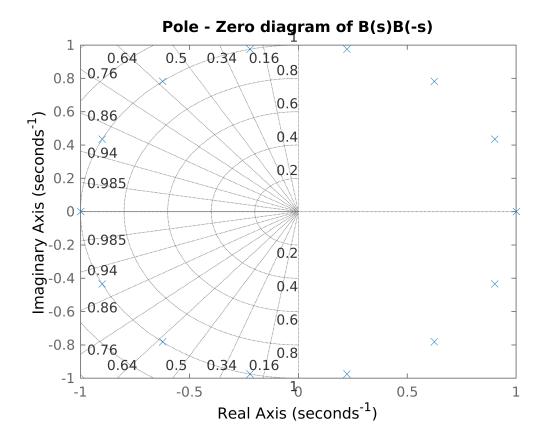


Creating the circles now



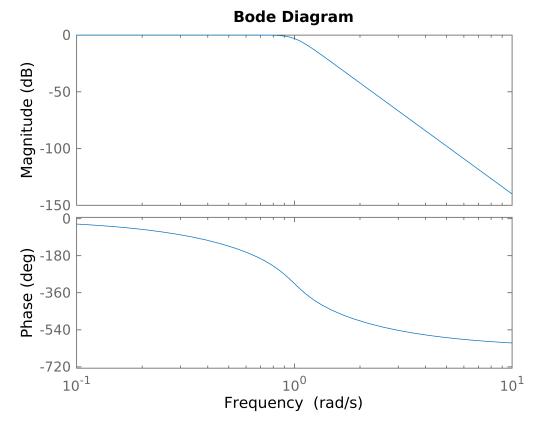
Part (ii) of the question

```
Bs = tf(num,den);
Bs_c = ctranspose(Bs);
x = Bs*Bs_c;
pzmap(x);
grid on
title('Pole - Zero diagram of B(s)B(-s)')
```



Part (iii) of the question

bode(Bs)



display(Bs); % Transfer function

Bs =

s^7 + 4.494 s^6 + 10.1 s^5 + 14.59 s^4 + 14.59 s^3 + 10.1 s^2 + 4.494 s + 1

Continuous-time transfer function.