

## 2024 International Conference on Artificial Intelligence in Information and Communication (ICAIC) | 979-8-3503-4434-9/24/\$31.00 ©2024 IEEE | DOI: 10.1109/ICAIC60209.2024.104633342

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Hierarchical beam search, in which initial beam steering is performed with a wide beamwidth and a narrow beamwidth is searched based on the results, has been considered a scheme to reduce the beam search time. [16], [17]. However, as the number of UEs increases, the UE placement becomes uniform, so sufficient reduction cannot be achieved. A scheme to estimate beams from UE positions has also been considered [18], [19]. At the time of initial connection, it is necessary to transmit position information for each UE, which increases the control overhead.

Massive Multiple-Input Multiple-Output (Massive MIMO), in which the base station (BS) has a huge number of antennas, has been considered as one of the technologies to realize high-speed and high-capacity wireless communications [5], [6]. Massive MIMO can provide the beamforming gain to the

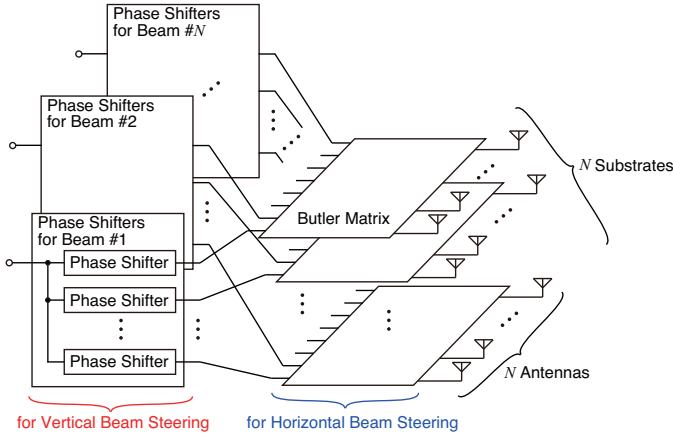


Fig. 1. Block diagram of proposed beam search scheme.

This letter proposes a novel beam search scheme using fast beam steering to reduce the overhead required for beam sweeping. A phase shifter capable of fast switching in the order of nanoseconds has been proposed [20]. This letter assumes a phased array antenna with fast beam switching using this phase shifter. The proposed scheme performs beam steering only at high speed within a single SSB. The proposed beam search scheme can reduce the beam search period by searching multiple beams in a single SSB instead of searching for one beam in one SSB as in the conventional scheme. In the case of a two-dimensional array antenna with  $N \times N$ , the beam search time can be reduced to  $1/N$  by fast beam steering in one dimension. Computer simulation results evaluate the characteristics of the proposed scheme.

## II. PROPOSED BEAM SEARCH SCHEME WITH FAST BEAM STEERING

First, let us describe the configuration used in the beam search scheme with fast beam steering. The proposed configuration of  $N \times N$  array antennas is shown in Fig. 1. The  $N \times N$  array antenna consists of a one-dimensional patch array antenna, a Butler matrix, and a variable phase shifter. The patch array antenna and the butler matrix are mounted on the same substrate, stacking  $N$  substrates. These substrates are connected to a variable phase shifter set with  $N$  variable phase shifters. A phase shifter is used, which can switch phases discretely and rapidly within a single symbol [20]. The input signals of the beams corresponding to each horizontal direction are split into  $N$  branches, and each is input to a variable phase shifter. The outputs of the variable phase shifters are input to the same port of the Butler matrix on each substrate. This allows the horizontal beam to be formed according to the input port of the Butler matrix and the vertical beam to be formed by the variable phase shifter.

Next, let us describe the beam search procedure. Fig. 2 shows the configuration of the SSB for  $N \times N$  beams and examples of horizontal and vertical beam steering configurations. This example shows for  $N = 8$ . There are  $N$  SSBs corresponding to  $N$  types of horizontal beams, each

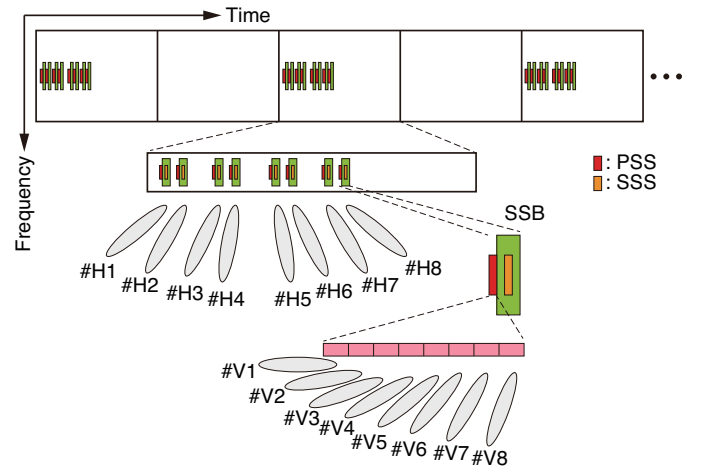


Fig. 2. SSB placement and beam steering.

transmitting at a different time. The SSBs are assumed to be those specified in [15]. Each SSB transmits using a different horizontal beam. The same synchronization signal is transmitted repeatedly with  $N$  SSBs as one period. The UE assumes that the correspondence between SSBs and horizontal beams is known. The horizontal beam is searched for by measuring the Reference Signal Received Power (RSRP) using the secondary synchronization signal (SSS) in the SSB as before, and the horizontal beam with the largest RSRP is selected. A high-speed phase shifter searches for the vertical beam within a single SSB. Vertical beam steering is performed in  $N$  steps within one symbol time of the primary synchronization signal (PSS) in the SSB. Specifically, the PSS is divided into  $N$  segments, and each is transmitted using a different vertical beam. The UE uses the PSS to detect the cell ID and symbol start timing. After timing synchronization, the PSS is divided into  $N$  segments in the time domain, the point with the maximum power is detected, and the corresponding vertical beam is selected. Perform the same vertical beam steering for each SSB and perform the same vertical beam detection for all SSBs. From the detection results of  $N$  SSBs, the beam with the highest number of selections is selected as the vertical beam. Although beam steering in the PSS degrades time synchronization accuracy, the accuracy can be maintained by using the demodulation reference signal (DMRS) in the SSBs for channel demodulation. As described above,  $N^2$  vertical and horizontal beam searches can be performed in  $N$  SSB segments, thus reducing the search time to  $1/N$ .

## III. COMPUTER SIMULATIONS

### A. Simulation Conditions

The computer simulation results evaluate the feasibility of the proposed scheme. Table I lists the simulation parameters. The center frequency was set to 4.5 GHz, and the signal bandwidth to 100 MHz. A 64-element ( $8 \times 8$ ) two-dimensional patch array antenna was used, and eight types of horizontal beams ( $33^\circ$ ,  $53^\circ$ ,  $69^\circ$ ,  $83^\circ$ ,  $97^\circ$ ,  $111^\circ$ ,  $127^\circ$ ,  $147^\circ$ ). The

TABLE I  
SIMULATION CONDITIONS

Center frequency	4.5 GHz
Bandwidth	100 MHz
SSB settings	Case B [15]
No. of SSB	8
No. of Tx antennas	64 ( $8 \times 8$ )
No. of Rx antennas	1
Transmission power	25 dBm
Feeder loss	3 dB
Tx antenna gain	6 dBi/Antenna
Rx antenna gain	0 dBi
Horizontal beam direction ( $^\circ$ )	33, 53, 69, 83, 97, 111, 127, 147
Vertical beam direction ( $^\circ$ )	90, 100, 110, 120, 130, 140, 150, 160
Noise power	-174 dBm/Hz
Noise figure	9 dB
Antenna height of BS	40 m
Antenna height of UE	1.5 m

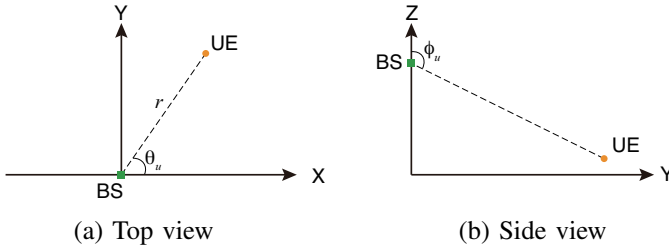


Fig. 3. UE placement.

SSB setup is based on Case B of [15], where eight SSBs correspond to eight different horizontal beams, and the SSBs are transmitted at other times. Vertically, eight types of beams are formed every  $10^\circ$  from  $90^\circ$  to  $160^\circ$  using variable phase shifters. The PSS is divided into eight beams in the time domain, and the vertical beams are switched for transmission. For SSB other than PSS, beams of  $90^\circ$  were used. The BS antenna height was set to 40 m, and the UE antenna height to 1.5 m. Polarization of antennas was not considered. The simulation was assumed to be an additive white Gaussian noise (AWGN) channel for line-of-sight communication.

### B. Cell ID Detection Performance

First, the cell ID detection characteristics when the proposed method is used are evaluated. Fig. 3 shows the placement of BS and UE. When the BS is placed at the origin, the UE is separated from  $r$  in the horizontal plane, and the direction is

TABLE II  
CELL ID DETECTION RATE

$r$	$\theta_u$	Beam index for horizontal beam steering							
		1	2	3	4	5	6	7	8
100	$76^\circ$	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
200	$76^\circ$	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
300	$76^\circ$	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
400	$76^\circ$	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	$83^\circ$	1.00	0.99	0.11	1.00	0.01	1.00	0.00	1.00
200	$83^\circ$	1.00	0.54	1.00	1.00	0.92	0.04	0.79	1.00
300	$83^\circ$	1.00	0.48	1.00	1.00	0.85	0.99	1.00	1.00
400	$83^\circ$	1.00	0.99	1.00	1.00	1.00	1.00	1.00	1.00

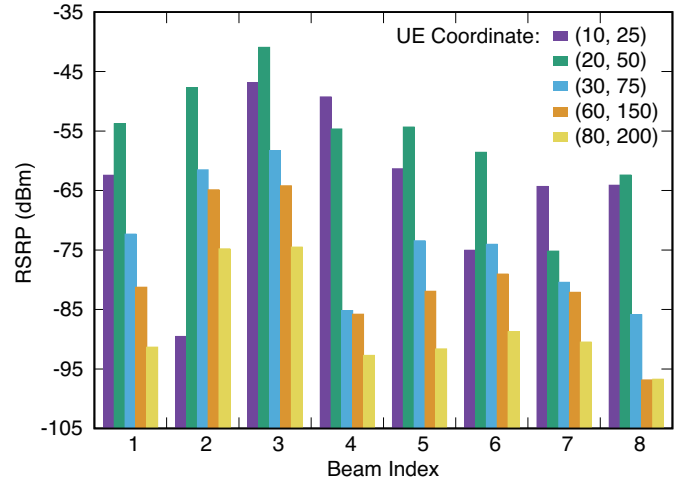


Fig. 4. RSRP characteristics for every horizontal beams.

$\theta_u$  from the X-axis. The distances between BS and UE are  $r = 100, 200, 300, 400$  m. The directions are set to  $\theta_u = 76^\circ$ , which is the mid direction of beams 3 and 4 in the horizontal plane, and  $\theta_u = 83^\circ$ , which is the front direction of beam 4. The number of candidate cell IDs is set to five, and cell IDs are detected. The evaluation is based on the correct detection rate of cell IDs when each SSB is received.

Table II lists the correct detection rate of cell IDs using the proposed method. In  $\theta_u = 76^\circ$ , the cell IDs are successfully detected in all beams, although the received power fluctuates within a symbol due to fast beam steering in the PSS. The  $76^\circ$  direction is in the main beam for beams 3 and 4 and in the side lobes for beams other than 3 and 4. This is because the Signal-to-Noise Power ratio (SNR) can be ensured. On the other hand, in the case of  $\theta_u = 83^\circ$  with beam 4 direction, the cell ID detection rate is degraded except for beams 1, 4, and 8. The  $83^\circ$  direction is null except for beam 4 and degrades the SNR. Lower SNR increases the probability of timing detection errors and degrades the detection performance. However, cell IDs are successfully detected in beams 1 and 8. This is because the beams are more angled than the frontal direction ( $33^\circ$  and  $147^\circ$ ), and thus nulls are not formed sufficiently. The horizontal and vertical beams were detected correctly in the present results. The simulation results show that cell IDs cannot be detected correctly for beams with insufficient SNR, but the correct cell IDs can be detected by selecting cell IDs for beams with a certain amount of received power.

### C. Beam Detection Performance

Next, the beam detection characteristics are evaluated. In this simulation, time synchronization is assumed to be perfect. The UEs were placed horizontally in the  $69^\circ$  direction (beam 3) at four locations (in meters):  $(x, y) = (10, 25), (20, 50), (30, 75), (60, 150), (80, 200)$ . Let us evaluate the horizontal beam detection performance. Fig. 4 shows the RSRPs for each horizontal beam at each location. It can be seen that the RSRP of beam 3 is the largest at any position

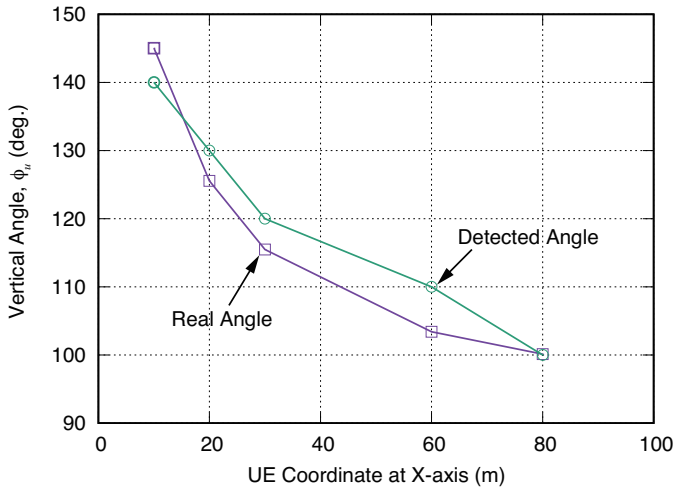


Fig. 5. Detected vertical angle using proposed scheme.

of the UE, indicating that the horizontal beam can be detected correctly. The difference from the adjacent beam 2 is smaller at the position where the UE is  $x \geq 60$  m. Let us show the characteristics of vertical beam detection. The vertical beam search results are shown in Fig. 5. For comparison, the actual vertical angle  $\theta_u$  calculated from the UE position is also shown. As the distance between the BS and the UE increases,  $\theta_u$  becomes smaller. The results show that the searched beam angle follows the position of the UE. The maximum error is  $7^\circ$ , but since the angular resolution in the vertical direction is  $10^\circ$ , this is not a problem for the vertical beam steering used in this study.

#### IV. CONCLUSIONS

To reduce the beam search time in Massive MIMO, which increases as the number of candidate beams increases, a beam search scheme using fast beam steering is proposed. The proposed beam search scheme performs fast beam steering using a fast phase shifter in a single SSB and reduces the number of signals required for beam search by using the SSB to search for beams. Computer simulations show that the proposed beam search method can select horizontal and vertical beams corresponding to the position of the UE while reducing the number of SSBs relative to the number of beams.

#### ACKNOWLEDGMENT

This work was supported in part by the National Institute of Information and Communications Technology ("Research and development on high-speed beam steering technology toward Beyond 5G" adopted number 06001) and JSPS KAKENHI Grant Number JP23K16874 and 22K04101.

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