

# Solving for optimal weight for almost finite dependent estimator

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## 1 Finite dependence

**Proposition 1** (Characterization of Finite Dependence). *Suppose that there exists a sequence  $\{d_{t+\tau}^*(z)\}_{\tau=0}^\rho$  such that  $(\tilde{\mathbf{f}}_{d_t^*(z),t}(d,z))^\top \prod_{\tau=1}^\rho \mathbf{F}_{d_{t+\tau}^*(z),t+\tau} = \mathbf{0}$  for all  $(d,z) \in \mathcal{D} \times \mathcal{Z}$ , then the model exhibits the  $(\rho+1)$ -period finite dependence with*

$$\tilde{v}_{d_t^*(z),t}(d,z) = \tilde{u}_{d_t^*(z),t}(d,z) + (\tilde{\mathbf{f}}_{d_t^*(z),t}(d,z))^\top \sum_{\tau=1}^\rho \beta^\tau \mathbf{F}_{d_{t+\tau}^*(z),t+\tau} \left( \nabla \bar{\mathbf{e}}^{\mathbf{P}^{t+1}} + \mathbf{u}_{d_{t+\tau}^*(z)} + \mathbf{e}_{d_{t+\tau}^*(z)}^{\mathbf{P}^{t+1}} \right).$$

Arcidiacono and Miller (2016)

When the model exhibits finite dependence, given the initial estimate for  $\{\mathbf{p}_{t+\tau} : \tau = 1, \dots, \rho\}$ , the conditional choice probabilities can be evaluated without solving the Bellman equation.

[Add examples for finite dependence here]

**Lemma 1.** *The model displays finite dependence if and only if  $(\tilde{\mathbf{F}}^T \otimes \tilde{\mathbf{F}}) \text{vec}(\tilde{\mathbf{P}}) = \text{vec}(-\tilde{\mathbf{F}}\mathbf{F}_0)$  has a solution  $\tilde{\mathbf{P}}$ .*

*Proof.* Suppose the model displays finite dependence property, for each  $x^{(i)}$ , we have

$$\left( \mathbf{P}_t(x^{(i)}) - \mathbf{P}'_t(x^{(i)}) \right) \mathbf{F}(x^{(i)}) (\mathbf{P}_{t+1}\mathbf{F}) = \mathbf{0}.$$

Define  $\mathcal{K} = \{\mathbf{D} \in \mathbb{R}^{D+1}, \sum_i \mathbf{D}_i = 0\}$  as the linear space of vectors that sum up to 0. As  $\mathbf{P}_t$  and  $\mathbf{P}'_t$  are arbitrary, we have that

$$\mathbf{D}\mathbf{F}(x^{(i)}) (\mathbf{P}_{t+1}\mathbf{F}) = \mathbf{0}. \quad \forall \mathbf{P} \in \mathcal{S}$$

With  $\mathbf{P}\mathbf{F} \in \mathcal{K}$  as well, we have that  $\text{rank}(\mathbf{P}_{t+1}\mathbf{F}) = 1$ , and  $\dim(\text{null}(\mathbf{P}_{t+1}\mathbf{F})) = |\mathcal{X}| - 1$ . From

the above results, we have that

$$\begin{aligned}\tilde{\mathbf{F}}(\mathbf{P}_{t+1}\mathbf{F}) &= \mathbf{0} \\ \tilde{\mathbf{F}}(\tilde{\mathbf{P}}_{t+1}\tilde{\mathbf{F}} + \mathbf{F}_0) &= \mathbf{0}.\end{aligned}$$

Let  $A \otimes B$  be the Kronecker product of two matrix  $A$  and  $B$  and  $\text{vec}(A)$  be the vectorization of matrix  $A$ . Then by the property of vectorization

$$(\tilde{\mathbf{F}}^T \otimes \tilde{\mathbf{F}}) \text{vec}(\tilde{\mathbf{P}}_{t+1}) = \text{vec}(-\tilde{\mathbf{F}}\mathbf{F}_0).$$

Thus the model displays finite dependence property if and only if above equation has a suitable solution for  $\mathbf{P}_{t+1}$ .  $\square$

To find the optimal weight that minimizes  $(\tilde{\mathbf{F}}^T \otimes \tilde{\mathbf{F}})(\tilde{\mathbf{P}}_{t+1}) + \text{vec}(\tilde{\mathbf{F}}\mathbf{F}_0)$ , we solve the linear equation of  $(\tilde{\mathbf{F}}^T \otimes \tilde{\mathbf{F}}) \text{vec}(\tilde{\mathbf{P}}_{t+1}) = \text{vec}(-\tilde{\mathbf{F}}\mathbf{F}_0)$ .

Note that  $\text{vec}(\tilde{\mathbf{P}})$  has many zeros, then we need to select the non-zero rows that corresponds to the conditional choice probabilities.

A conditional choice probabilities  $\tilde{\mathbf{P}} \in \mathcal{P}$  is

$$\tilde{\mathbf{P}} = \begin{bmatrix} p(1, x^{(1)}) & \dots & p(D, x^{(1)}) & \dots & 0 & \dots & 0 \\ \vdots & \ddots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \dots & p(1, x^{(|\mathcal{X}|)}) & \dots & p(D, x^{(|\mathcal{X}|)}) \end{bmatrix}_{|\mathcal{X}| \times |\mathcal{X}|D}$$

(According to wikipedia), if  $A = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$ , then  $\text{vec}(A) = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}$ . The rows that are non-zero in  $\tilde{\mathbf{P}}$  are  $\{k * |D\mathcal{X}| + m|\mathcal{X}| + k + 1\}$  where  $k = 0, \dots, D, m = 0, \dots, D$ .

Then we can compute the conditional choice probability with OLS using the selected rows. However, this may suffer from the fact that, the parameters are not bounded between 0 and 1.

## References

Arcidiacono, P. and Miller, R. A. (2016). Nonstationary Dynamic Models with Finite Dependence  
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