

# HW4-JiawenTong

November 2, 2017

```
In [1]: %matplotlib inline
import numpy as np
from math import *
import matplotlib.pyplot as plt
```

## 0.1 Problem 1

**\*\* Please see proof of Problem 1 (a), (b) on the main writeup report.\*\***

## 0.2 Problem 2

### 0.2.1 (a)

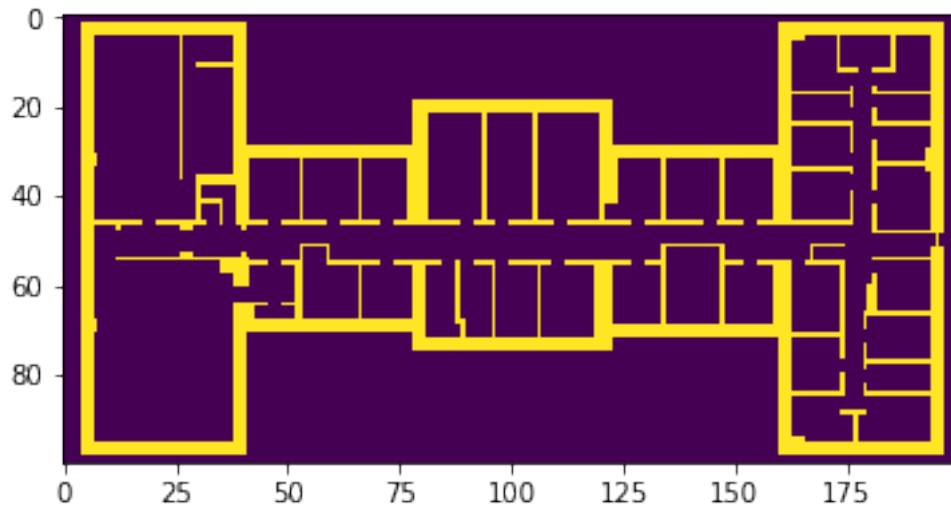
```
In [2]: # Pressure in the region S
def src_f(t):
    p0 = 10
    w = 100*pi
    return p0*sin(w*t)

# Determine if (x=j, y=k) is in S
def is_in_S(j, k):
    if j>=57 and j<=60 and k>=15 and k<=18:
        return True
    else:
        return False

In [3]: # Read in the map of Pierce Hall
M, N = 100, 200
pierce_map = np.zeros((M, N))
lines = open('pierce.txt').readlines()
for i, line in enumerate(lines):
    pierce_map[i, :] = line.replace('\n', '').split(' ')

In [4]: plt.imshow(pierce_map)

Out[4]: <matplotlib.image.AxesImage at 0x110bc8908>
```



```
In [5]: # Computer the big matrix for the pressure field
h = 36.6
c = 3.43e4
dt = h/(2*c)
snaps = 2000
nu = c*c*dt*dt/(h*h)
```

## 0.2.2 Can directly load the pressure field np matrix using

```
large_P = np.load('./pierce/pierce_t2000.npy')
```

It takes ~ 11 mins to run the following cell on my Mac...

```
In [ ]: P = np.zeros((M, N, snaps+1)) # The Pressure Field

# Initial condition t = 0
P[:, :, 0] = 0

# Initial condition t = 1 (t=0 is already satisfied)
for j in range(M):
    for k in range(N):
        if is_in_S(j, k):
            P[j, k, 1] = src_f(dt)

import time
start_time = time.time()

# Iteration <<< Reference: Lecture 15 Code Example Heat.py
for i in range(2, snaps+1):
    for j in range(M):
```

```

for k in range(N):
    if pierce_map[j, k] == 1: # (j, k) is wall, skip
        continue

    if is_in_S(j, k): # (j,k) IN Region S
        P_jk = src_f((i-1)*dt)
        s1 = 2*src_f((i-1)*dt) - src_f((i-2)*dt)
    else: # (j,k) NOT IN Region S
        P_jk = P[j, k, i-1]
        s1 = 2*P[j, k, i-1] - P[j, k, i-2]

    s2 = -4 * P_jk

    orth_neighbors = np.array([(j-1, k), (j+1, k), (j, k-1), (j, k+1)])
    for jn, kn in orth_neighbors:
        if jn<0 or jn>=M or kn<0 or kn>=N: # (jn, kn) is NOT in map, s2 += 0,
            continue
        else:
            if pierce_map[jn, kn] == 1: # Is Wall
                s2 += P_jk
            elif is_in_S(jn, kn): # NOT WALL & In Region S
                s2 += src_f((i-1)*dt)
            else: # NOT WALL & NOT IN Region S
                s2 += P[jn, kn, i-1]

    P[j, k, i] = s1 + nu*s2 # Update P

print("--- Duration = %s seconds ---" % (time.time() - start_time))

np.save('./pierce/pierce_t2000', P)

```

In [6]: large\_P = np.load('./pierce/pierce\_t2000.npy')

### 0.2.3 (b)

In [7]: # Provided code for custom plot

```

import sys

# Returns a scaled value of a function in the range 0 to 1, truncating it if necessary
def fscale(v, vmin, vsca):
    vs=(v-vmin)*vsca
    if vs<0: vs=0
    if vs>1: vs=1
    return vs

# Returns a red->white->blue color scheme
def palette1(v):
    v*=2

```

```

    if(v>1):
        v=2-v
        return (v,v,min(1,0.5+3*v))
    else:
        return (min(1,0.5+3*v),v,v)

# Outputs a 2D image from a field using the palette1 color scheme
# fn: the filename to save to
# p: the 2D field to plot
# wa: the matrix describing walls to overlay
# (vmin,vmax): the field range
# ups: the upsampling factor to use (so each field point is convert into an ups by ups)
def plot1(fn,p,wa,vmin,vmax,ups):

    # Check matrix dimensions are the same
    (m,n)=p.shape
    if (m,n)!=wa.shape:
        print("Matrix dimension mismatch")

    # Set up output array and scaling constant
    o=np.zeros((m*ups,n*ups,3))
    vsca=1.0/(vmax-vmin)

    # Assemble the output array
    for i in range(m):
        iu=i*ups
        for j in range(n):
            ju=j*ups
            if wa[i,j]==1:
                o[iu:iu+ups,ju:ju+ups,0]=0
                o[iu:iu+ups,ju:ju+ups,1]=0
                o[iu:iu+ups,ju:ju+ups,2]=0
            else:
                (re,gr,bl)=palette1(fscale(p[i,j],vmin,vsca))
                o[iu:iu+ups,ju:ju+ups,0]=re
                o[iu:iu+ups,ju:ju+ups,1]=gr
                o[iu:iu+ups,ju:ju+ups,2]=bl

    # Save the image
    plt.imsave(fn,o)
    plt.imshow(o)

# Returns a black->red->yellow color scheme (matching Gnuplot's PM3D scheme)
def palette2(v):
    if v>0.5:
        vs=0
    else:
        vs=sin(2*pi*v)

```

```

    return (sqrt(v),v*v*v,vs)

# Outputs a 2D image from a field using the palette2 color scheme
# fn: the filename to save to
# p: the 2D field to plot
# wa: the matrix describing walls to overlay
# (vmin,vmax): the field range
# ups: the upsampling factor to use (so each field point is convert into an ups
#      by ups square)
def plot2(fn,p,wa,vmin,vmax,ups):

    # Check matrix dimensions are the same
    (m,n)=p.shape
    if (m,n)!=wa.shape:
        print("Matrix dimension mismatch")

    # Set up output array and scaling constant
    o=np.zeros((m*ups,n*ups,3))
    vsca=1.0/(vmax-vmin)

    # Assemble the output array
    for i in range(m):
        iu=i*ups
        for j in range(n):
            ju=j*ups
            if wa[i,j]==1:
                o[iu:iu+ups,ju:ju+ups,0]=1
                o[iu:iu+ups,ju:ju+ups,1]=1
                o[iu:iu+ups,ju:ju+ups,2]=1
            else:
                (re,gr,bl)=palette2(fscale(p[i,j],vmin,vsca))
                o[iu:iu+ups,ju:ju+ups,0]=re
                o[iu:iu+ups,ju:ju+ups,1]=gr
                o[iu:iu+ups,ju:ju+ups,2]=bl

    # Save the image
    plt.imsave(fn,o)
    plt.imshow(o)

```

```

In [8]: P_last = large_P[:, :, -1]
        p_min = np.min(P_last)
        p_max = np.max(P_last)
        print('The magitude of the P in the last iteration is {} ~ {}'.format(p_min, p_max))

```

The magitude of the P in the last iteration is -43.34730364254081 ~ 41.53652109925552

```

In [9]: ts = [0.015, 0.105, 0.505, 1.005]

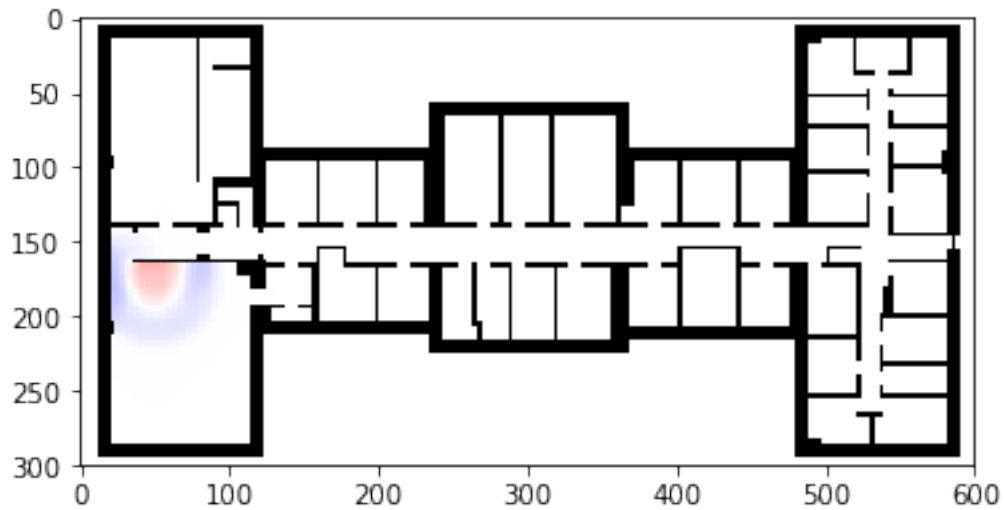
```

```

# Load in the wall matrix
wall = np.loadtxt("pierce.txt",dtype=np.int8)

# Plot t = 0.015
plot1("./pierce/t0.png", large_P[:, :, int(ts[0]/dt)], wall, -45, 45, 3)

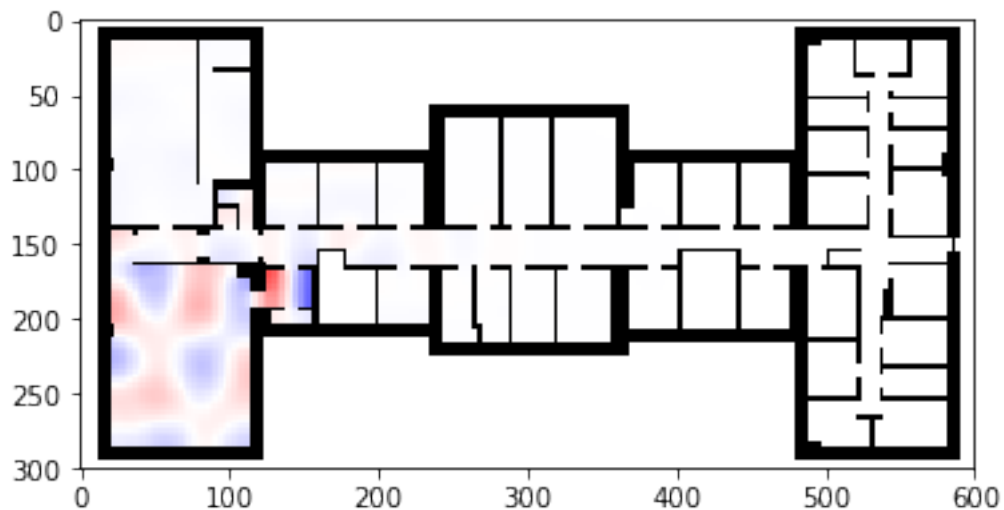
```



```

In [10]: # Plot t = 0.105
plot1("./pierce/t1.png", large_P[:, :, int(ts[1]/dt)], wall, -45, 45, 3)

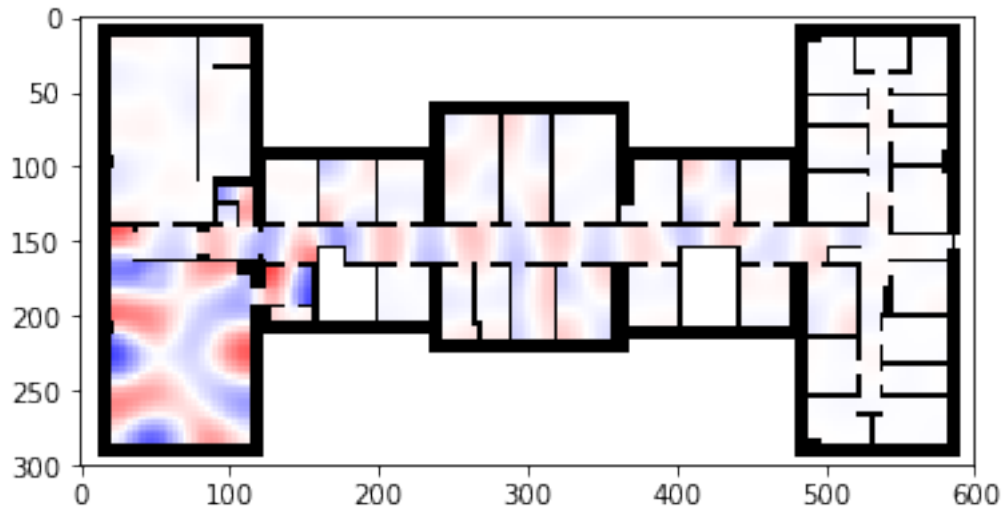
```



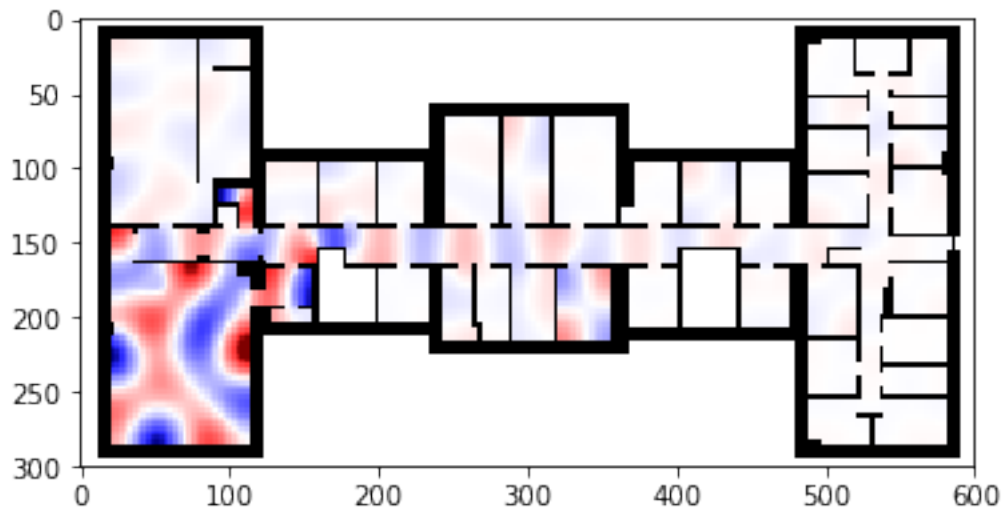
```

In [11]: # Plot t = 0.505
plot1("./pierce/t2.png", large_P[:, :, int(ts[2]/dt)], wall, -45, 45, 3)

```



```
In [12]: # Plot  $t = 1.005$ 
plot1("./pierce/t3.png", large_P[:, :, int(ts[3]/dt)], wall, -45, 45, 3)
```



0.2.4 (c)

```
In [13]: P_C_t = large_P[35, 73, :]
P_G_t = large_P[61, 109, :]
P_M_t = large_P[91, 188, :]
t_C, t_G, t_M = -1, -1, -1
```

```

n_time_step = large_P.shape[-1]
for n in range(n_time_step):
    if t_C != -1 and t_G != -1 and t_M != -1:
        break
    if abs(P_C_t[n]) > 1e-3 and t_C == -1:
        t_C = n * dt
    if abs(P_G_t[n]) > 1e-3 and t_G == -1:
        t_G = n * dt
    if abs(P_M_t[n]) > 1e-3 and t_M == -1:
        t_M = n * dt

print('Time (sec) when the three people first hear the sound\n')
print('C: {} \nG: {} \nM: {}'.format(t_C, t_G, t_M))

```

Time (sec) when the three people first hear the sound

C: 0.07362682215743441

G: 0.1088396501457726

M: 0.2310174927113703

## 0.2.5 (d)

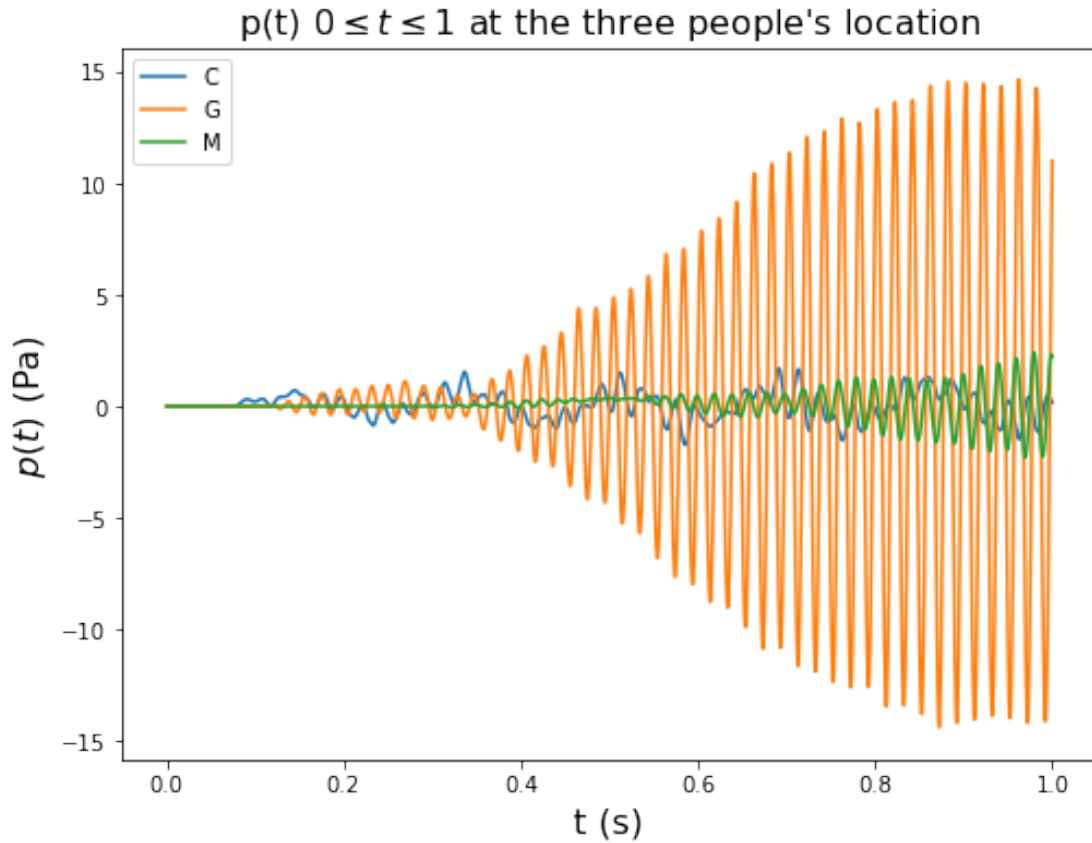
```

In [14]: # Plot  $p(t)$  at the three people's location for  $0 \leq t \leq 1$ 
fig, ax = plt.subplots(1, 1, figsize=(8, 6))
t_steps = int(1/dt) + 1
t_lin = np.linspace(0, 1, t_steps)
ax.plot(t_lin, P_C_t[:t_steps], label='C')
ax.plot(t_lin, P_G_t[:t_steps], label='G')
ax.plot(t_lin, P_M_t[:t_steps], label='M')
ax.set_xlabel('t (s)', fontsize=16)
ax.set_ylabel('$p(t)$ (Pa)', fontsize=16)
ax.set_title('p(t)  $0 \leq t \leq 1$  at the three people\'s location', fontsize=16)
ax.legend()

```

Out[14]: <matplotlib.legend.Legend at 0x126bfcdd8>





### 0.3 Problem 3

#### 0.3.1 (b)

```
In [15]: n = 101
         h = 2/(n-1)
         b = 1/(h*h)

         def get_F(U): # F(U)
             F = np.zeros((n-2,))
             F[0] = (U[1]-2*U[0])*b - exp(U[0])
             F[n-3] = (-2*U[n-3]+U[n-4])*b - exp(U[n-3])
             for i in range(1, n-3):
                 F[i] = (U[i+1] - 2*U[i] + U[i-1])*b - exp(U[i])
             return F

         def get_J(U): # Jacobian of F(U)
             A = np.zeros((n-2, n-2))
             A[0:n-3, 1:n-2] = b*np.eye(n-3)
             B = np.zeros((n-2, n-2))
```

```

B[1:n-2, 0:n-3] = b*np.eye(n-3)
J = np.add(-2*b*np.eye(n-2), A, B)

for i in range(n-2):
    J[i,i] += -exp(U[i])
return J

# Newton Roots Finding:  $F(U) = 0$ 
U0 = np.zeros((n-2,))
F = get_F(U0)
J = get_J(U0)
delta_U = np.linalg.solve(J, -1*F)
U = U0
relative_step = 100
while relative_step > 1e-10:
    U = np.add(delta_U, U)
    F = get_F(U)
    J = get_J(U)
    delta_U = np.linalg.solve(J, -1*F)
    relative_step = np.linalg.norm(delta_U)/np.linalg.norm(U)

In [16]: # Pad the approximate solution U with U0 & Un-1
U_all = np.zeros((n,))
U_all[0] = 0
U_all[-1] = 0
U_all[1:-1] = np.copy(U)

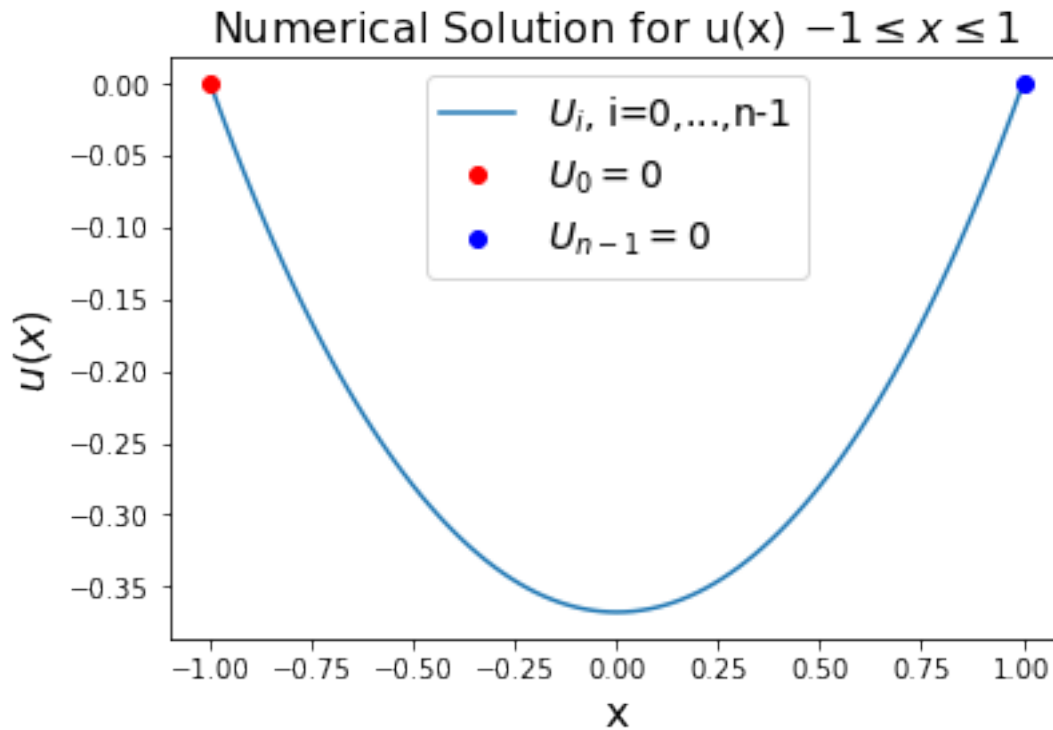
# Plot U
plt.plot(np.linspace(-1, 1, n), U_all, '-', label='$U_i$, i=0,...,n-1')

plt.plot(-1, 0, 'ro', label='$U_0 = 0$')
plt.plot(1, 0, 'bo', label='$U_{n-1} = 0$')

plt.legend(fontsize=14)
plt.title('Numerical Solution for  $u(x)$   $-1 \leq x \leq 1$ ', fontsize=16)
plt.xlabel('x', fontsize=16)
plt.ylabel('$u(x)$', fontsize=16)

Out[16]: <matplotlib.text.Text at 0x126e92320>

```

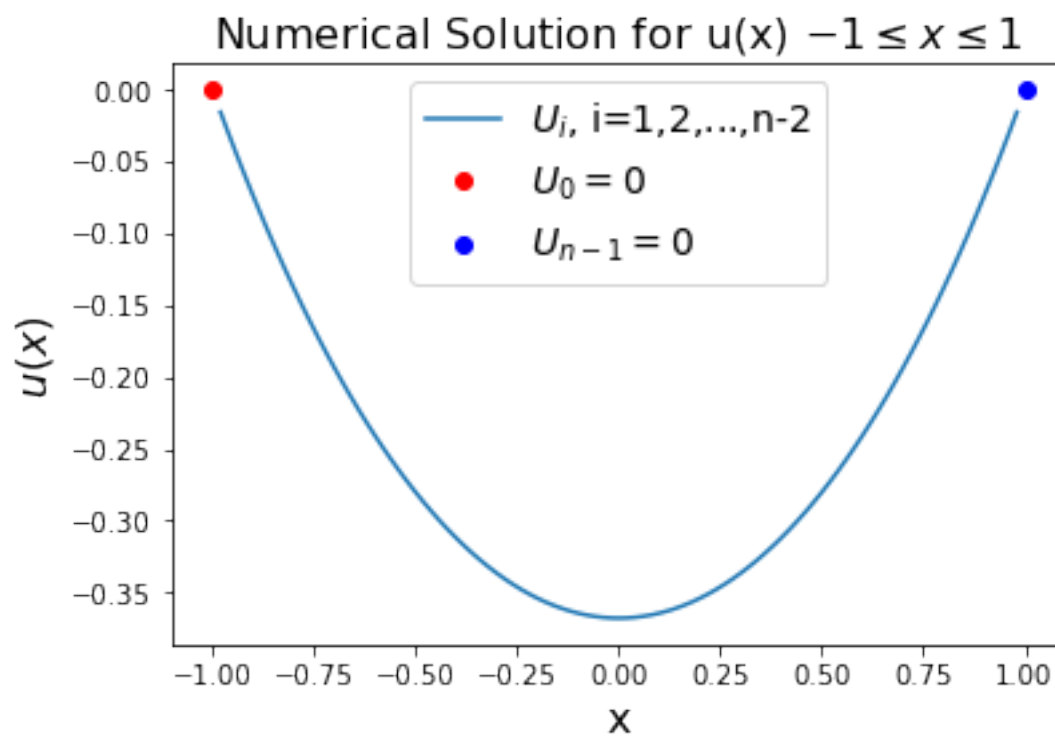


```
In [17]: # Plot the approximate solution U
plt.plot(np.linspace(-1, 1, n)[1:-1], U, '-', label='$U_i$, i=1,2,...,n-2')

# Pad with U0 & Un-1
plt.plot(-1, 0, 'ro', label='$U_0 = 0$')
plt.plot(1, 0, 'bo', label='$U_{n-1} = 0$')

plt.legend(fontsize=14)
plt.title('Numerical Solution for u(x)  $-1 \leq x \leq 1$ ', fontsize=16)
plt.xlabel('x', fontsize=16)
plt.ylabel('$u(x)$', fontsize=16)
```

Out[17]: <matplotlib.text.Text at 0x125e7ffd0>



```
In [18]: print('Approximation to u(0) is {}, index={}'.format(U[int(1/h-1)], int(1/h-1)))
```

```
Approximation to u(0) is -0.36804818818603935, index=49
```

```
In [ ]:
```