## Solar Force-Free Magnetic Fields

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1. 
$$\nabla \cdot \vec{B} = 0$$

$$\exists \vec{A} = (A_r, A_\theta, A_\phi) \, s.t. \vec{B} = \nabla \times \vec{A},$$

$$\nabla \times \vec{A} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \vec{e_1} & h_2 \vec{e_2} & h_3 \vec{e_3} \\ \frac{\partial}{\partial u_1} & \frac{\partial}{\partial u_2} & \frac{\partial}{\partial u_3} \\ h_1 A_1 & h_2 A_2 & h_3 A_3 \end{vmatrix}$$

$$= \frac{1}{1 \times r \times r \sin \theta} \begin{vmatrix} 1 \vec{e_r} & r \vec{e_\theta} & r \sin \theta \vec{e_\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} = 0 \\ |A_r & r A_{\theta} & r \sin \theta A_{\phi} | \end{vmatrix}$$

$$= \frac{1}{r^2 \sin \theta} \begin{vmatrix} \frac{\partial}{\partial \theta} & 0 \\ r A_{\theta} & r \sin \theta A_{\phi} \end{vmatrix} \vec{e_r} - \frac{1}{r^2 \sin \theta} \begin{vmatrix} \frac{\partial}{\partial r} & 0 \\ A_r & r \sin \theta A_{\phi} \end{vmatrix} r \vec{e_\theta} + \frac{1}{r^2 \sin \theta} \begin{vmatrix} \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} \\ A_r & r A_{\theta} \end{vmatrix} r \sin \theta \vec{e_\phi}$$

$$= \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( r \sin \theta A_{\phi} \right) \vec{e_r} - \frac{1}{r \sin \theta} \frac{\partial}{\partial r} \left( r \sin \theta A_{\phi} \right) \vec{e_\theta} + \frac{1}{r} \left( \frac{\partial}{\partial r} (r A_{\theta}) - \frac{\partial A_r}{\partial \theta} \right) \vec{e_\phi}$$

$$= \frac{1}{r \sin \theta} \left( \frac{1}{r} \frac{\partial}{\partial \theta} \left( r \sin \theta A_{\phi} \right), -\frac{\partial}{\partial r} \left( r \sin \theta A_{\phi} \right), \sin \theta \left( \frac{\partial}{\partial r} (r A_{\theta}) - \frac{\partial A_r}{\partial \theta} \right) \right)$$

2. 
$$1 \Rightarrow \vec{B} = \frac{1}{r \sin \theta} \left( \underbrace{\frac{1}{r} \frac{\partial}{\partial \theta} \left( r \sin \theta A_{\phi} \right)}_{\widetilde{A}}, -\frac{\partial}{\partial r} \left( r \sin \theta A_{\phi} \right), \underbrace{\sin \theta \left( \frac{\partial}{\partial r} \left( r A_{\theta} \right) - \frac{\partial A_{r}}{\partial \theta} \right)}_{b_{\phi}} \right)$$

$$\begin{split} \nabla \times \vec{B} &= \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{e_r} & r\vec{e_\theta} & r \sin \theta \vec{e_\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} & 0 \\ \frac{1}{r \sin \theta} \frac{1}{r} \frac{\partial \vec{A}}{\partial \theta} & r \frac{1}{r \sin \theta} \left( -\frac{\partial \vec{A}}{\partial r} \right) & r \sin \theta \frac{1}{r \sin \theta} b_\phi \end{vmatrix} \\ &= \frac{1}{r^2 \sin \theta} \begin{vmatrix} \vec{e_r} & r\vec{e_\theta} & r \sin \theta \vec{e_\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} & 0 \\ \frac{1}{r \sin \theta} \frac{1}{r} \frac{\partial \vec{A}}{\partial \theta} & r \frac{1}{r \sin \theta} \left( -\frac{\partial \vec{A}}{\partial r} \right) & r \sin \theta \frac{1}{r \sin \theta} b_\phi \end{vmatrix} \\ &= \frac{1}{r^2 \sin \theta} \left[ \frac{\partial}{\partial \theta} \left( r \sin \theta \frac{1}{r \sin \theta} b_\phi \right) \vec{e_r} - r \frac{\partial}{\partial r} \left( r \sin \theta \frac{1}{r \sin \theta} b_\phi \right) \vec{e_\theta} + r \sin \theta \left| \frac{\partial}{\partial r} \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} & r \frac{1}{r \sin \theta} \left( -\frac{\partial \vec{A}}{\partial r} \right) \right| \vec{e_\phi} \right] \\ &= \frac{1}{r^2 \sin \theta} \left[ \frac{\partial b_\phi}{\partial \theta} \vec{e_r} - r \frac{\partial b_\phi}{\partial r} \vec{e_\theta} + r \sin \theta \left( \frac{\partial}{\partial r} \left( \frac{1}{\sin \theta} \left( -\frac{\partial \vec{A}}{\partial r} \right) \right) \right) - r \sin \theta \frac{\partial}{\partial \theta} \left( \frac{1}{r \sin \theta} \frac{1}{r \partial \theta} \right) \vec{e_\phi} \right] \\ &= \frac{1}{r^2 \sin \theta} \left[ \frac{\partial b_\phi}{\partial \theta} \vec{e_r} - r \frac{\partial b_\phi}{\partial r} \vec{e_\theta} - \left( r \frac{\partial}{\partial r} \left( \frac{\partial \vec{A}}{\partial r} \right) + \frac{1}{r} \sin \theta \frac{\partial}{\partial \theta} \left( \frac{1}{\sin \theta} \frac{\partial \vec{A}}{\partial \theta} \right) \vec{e_\phi} \right] \\ &= \frac{1}{r \sin \theta} \left[ \frac{1}{r} \frac{\partial b_\phi}{\partial \theta} \vec{e_r} - \frac{\partial b_\phi}{\partial r} \vec{e_\theta} - \left( \frac{\partial}{\partial r} \left( \frac{\partial \vec{A}}{\partial r} \right) + \frac{1}{r^2} \sin \theta \frac{\partial}{\partial \theta} \left( \frac{1}{\sin \theta} \frac{\partial \vec{A}}{\partial \theta} \right) \right) \vec{e_\phi} \right] \end{aligned}$$

(2)

3.  $\nabla \times \vec{B} = \alpha \vec{B}$ 

$$\frac{1}{r}\frac{\partial b_{\phi}}{\partial \theta} = \alpha \frac{1}{r}\frac{\partial}{\partial \theta}\widetilde{A} \tag{3}$$

$$\frac{\partial b_{\phi}}{\partial r} = \alpha \frac{\partial}{\partial r} \widetilde{A} \tag{4}$$

$$-\left(\frac{\partial}{\partial r}\left(\frac{\partial \widetilde{A}}{\partial r}\right) + \frac{1}{r^2}\sin\theta\frac{\partial}{\partial\theta}\left(\frac{1}{\sin\theta}\frac{\partial \widetilde{A}}{\partial\theta}\right)\right) = \alpha \underline{\sin\theta\left(\frac{\partial}{\partial r}\left(rA_{\theta}\right) - \frac{\partial A_r}{\partial\theta}\right)}$$

$$\underbrace{(5)}_{b_{\theta}}$$

4. from (3), (4),

$$\frac{\partial b_{\phi}}{\partial \theta} = \alpha \frac{\partial \widetilde{A}}{\partial \theta}, \frac{\partial b_{\phi}}{\partial r} = \alpha \frac{\partial \widetilde{A}}{\partial r} \Rightarrow \frac{\frac{\partial b_{\phi}}{\partial \theta}}{\frac{\partial \widetilde{A}}{\partial \theta}} = \frac{\frac{\partial b_{\phi}}{\partial r}}{\frac{\partial \widetilde{A}}{\partial r}} \Rightarrow \frac{\partial b_{\phi}}{\partial \theta} \frac{\partial \widetilde{A}}{\partial r} - \frac{\partial b_{\phi}}{\partial r} \frac{\partial \widetilde{A}}{\partial \theta} = 0 = \begin{vmatrix} \frac{\partial b_{\phi}}{\partial r} & \frac{\partial b_{\phi}}{\partial \theta} \\ \frac{\partial \widetilde{A}}{\partial r} & \frac{\partial \widetilde{A}}{\partial \theta} \end{vmatrix} = J\left(b_{\phi}, \widetilde{A}\right)$$
(6)

$$\therefore b_{\phi} = b_{\phi}\left(\widetilde{A}\right)$$

5.

$$\begin{vmatrix} \frac{\partial b_{\phi}}{\partial r} & \frac{\partial b_{\phi}}{\partial \theta} \\ \frac{\partial A}{\partial r} & \frac{\partial A}{\partial \theta} \end{vmatrix} = 0 \Rightarrow \nabla b_{\phi} \times \nabla \widetilde{A} = 0, \nabla b_{\phi} = \begin{bmatrix} \frac{\partial b_{\phi}}{\partial r} \\ \frac{1}{r} \frac{\partial b_{\phi}}{\partial \theta} \\ \frac{1}{r \sin \theta} \frac{\partial b_{\phi}}{\partial \phi} \end{bmatrix} = \begin{bmatrix} \frac{\partial b_{\phi}}{\partial \overline{A}} \frac{\partial \overline{A}}{\partial r} \\ \frac{1}{r \sin \theta} \frac{\partial b_{\phi}}{\partial \overline{A}} \frac{\partial \overline{A}}{\partial \theta} \\ \frac{1}{r \sin \theta} \frac{\partial b_{\phi}}{\partial \overline{A}} \frac{\partial \overline{A}}{\partial \theta} \end{bmatrix} = \frac{db_{\phi}}{d\overline{A}} \nabla \widetilde{A}.$$
(7)

$$\alpha \frac{\partial \widetilde{A}}{\partial r} = \frac{\partial b_{\phi}}{\partial r} = \frac{\partial b_{\phi}}{\partial \widetilde{A}} \frac{\partial \widetilde{A}}{\partial r} = \frac{db_{\phi}}{d\widetilde{A}} \frac{\partial \widetilde{A}}{\partial r} \Rightarrow \alpha = \frac{db_{\phi}}{d\widetilde{A}}$$
(8)

6. from (5)

$$-\frac{\partial^2 \widetilde{A}}{\partial r^2} - \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left( \frac{1}{\sin \theta} \frac{\partial \widetilde{A}}{\partial \theta} \right) = \alpha b_{\phi} \tag{9}$$

where  $\alpha = \frac{db_{\phi}}{d\overline{A}}$ , so

$$-\frac{\partial^{2}\widetilde{A}}{\partial r^{2}} - \frac{\sin\theta}{r^{2}} \frac{\partial}{\partial \theta} \left( \frac{1}{\sin\theta} \frac{\partial \widetilde{A}}{\partial \theta} \right) = b_{\phi} \frac{db_{\phi}}{d\widetilde{A}} = \frac{d}{d\widetilde{A}} \left( \frac{1}{2} b_{\phi}^{2} \right) \Rightarrow \frac{\partial^{2}\widetilde{A}}{\partial r^{2}} + \frac{\sin\theta}{r^{2}} \frac{\partial}{\partial \theta} \left( \frac{1}{\sin\theta} \frac{\partial \widetilde{A}}{\partial \theta} \right) + \frac{d}{d\widetilde{A}} \left( \frac{1}{2} b_{\phi}^{2} \right) = 0$$

$$(10)$$

Let  $\widetilde{A} = \widetilde{A}(r, \theta) = F(\cos \theta) r^{-n}, b_{\phi} = a\widetilde{A}^{1 + \frac{1}{n}},$ 

$$\frac{\partial^2 \widetilde{A}}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left( \frac{1}{\sin \theta} \frac{\partial \widetilde{A}}{\partial \theta} \right) + \frac{d}{d\widetilde{A}} \left( \frac{1}{2} b_{\phi}^2 \right) = 0 \tag{11}$$

where  $\widetilde{A} = \widetilde{A}(r, \theta) = F(\cos \theta) r^{-n}$ ,  $b_{\phi} = a\widetilde{A}^{1+n^{-1}}$ .

Then

$$\frac{\partial^{2}}{\partial r^{2}} \left( F \left( \cos \theta \right) r^{-n} \right) + \frac{\sin \theta}{r^{2}} \frac{\partial}{\partial \theta} \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( F \left( \cos \theta \right) r^{-n} \right) \right] + \frac{d}{d\widetilde{A}} \left[ \frac{1}{2} \left( a\widetilde{A}^{1+n^{-1}} \right)^{2} \right] = 0 \tag{12}$$

Now, firstly

$$\frac{\partial^2}{\partial r^2} \left( F(\cos \theta) \, r^{-n} \right) = \frac{\partial}{\partial r} \left[ \frac{\partial}{\partial r} \left( F(\cos \theta) \, r^{-n} \right) \right] = F(\cos \theta) \, n(n+1) r^{-(n+2)} \tag{13}$$

secondly,

$$\frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( F(\cos \theta) r^{-n} \right) \right] \\
= \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left[ r^{-n} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( F(\cos \theta) \right) \right] \\
= r^{-(n+2)} \sin \theta \frac{\partial}{\partial \theta} \left[ \frac{1}{\sin \theta} \left( \frac{dF(\cos \theta)}{d \cos \theta} \right) \frac{d \cos \theta}{d \theta} \right] \\
= r^{-(n+2)} \sin \theta \frac{\partial}{\partial \theta} \left[ -\frac{1}{\sin \theta} \sin \theta \frac{dF(\cos \theta)}{d \cos \theta} \right] \\
= -r^{-(n+2)} \sin \theta \frac{\partial}{\partial \theta} \left[ \frac{dF(\cos \theta)}{d \cos \theta} \right] \\
= -r^{-(n+2)} \sin \theta \frac{d}{d \theta} \left[ \frac{dF(\cos \theta)}{d \cos \theta} \right] \\
= -r^{-(n+2)} \sin \theta \frac{d}{d \theta} \left[ \frac{dF(\cos \theta)}{d \cos \theta} \right] \\
= -r^{-(n+2)} \sin \theta \frac{d}{d \theta} \left[ \frac{dF(\cos \theta)}{d \cos \theta} \right]$$
by using  $d\theta = -\frac{1}{\sin \theta} d \cos \theta$ 

$$= \sin^2(\theta) r^{-(n+2)} \frac{d}{d \cos \theta} \left[ \frac{dF(\cos \theta)}{d \cos \theta} \right] \\
= \sin^2(\theta) r^{-(n+2)} \frac{d^2(F(\cos \theta))}{d(\cos \theta)}$$

thirdly,

$$\frac{d}{d\widetilde{A}} \left[ \frac{1}{2} \left( a\widetilde{A}^{1+n^{-1}} \right)^{2} \right] 
= \frac{d}{d\widetilde{A}} \left[ \frac{1}{2} a^{2} \widetilde{A}^{2+2n^{-1}} \right] 
= \frac{1}{2} a^{2} \left( 2 + 2n^{-1} \right) \widetilde{A}^{1+2n^{-1}} 
= a^{2} \left( 1 + n^{-1} \right) \widetilde{A}^{1+2n^{-1}} 
= a^{2} \left( 1 + n^{-1} \right) \left[ F \left( \cos \theta \right) r^{-n} \right]^{1+2n^{-1}} 
= a^{2} \left( 1 + n^{-1} \right) F^{1+2n^{-1}} \left( \cos \theta \right) r^{-(n+2)}$$
(15)

therefore,

$$\frac{\partial^{2}}{\partial r^{2}} \left( F(\cos\theta) \, r^{-n} \right) + \frac{\sin\theta}{r^{2}} \frac{\partial}{\partial \theta} \left[ \frac{1}{\sin\theta} \frac{\partial}{\partial \theta} \left( F(\cos\theta) \, r^{-n} \right) \right] + \frac{d}{d\widetilde{A}} \left[ \frac{1}{2} \left( a\widetilde{A}^{1+n^{-1}} \right)^{2} \right] \\
= F(\cos\theta) \, n(n+1) r^{-(n+2)} + \sin^{2}(\theta) \, r^{-(n+2)} \frac{d^{2}(F(\cos\theta))}{d(\cos\theta)} + a^{2} \left( 1 + n^{-1} \right) F^{1+2n^{-1}}(\cos\theta) \, r^{-(n+2)} \\
= r^{-(n+2)} \left[ F(\cos\theta) \, n(n+1) r^{-(n+2)} + \sin^{2}(\theta) \, \frac{d^{2}(F(\cos\theta))}{d(\cos\theta)} + a^{2} \left( 1 + n^{-1} \right) F^{1+2n^{-1}}(\cos\theta) \right] \\
= 0 \tag{16}$$

One can get that

$$F(\cos\theta) n(n+1)r^{-(n+2)} + \sin^2(\theta) \frac{d^2(F(\cos\theta))}{d(\cos\theta)} + a^2(1+n^{-1})F^{1+2n^{-1}}(\cos\theta) = 0$$
 (17)

Finally,

$$\left(1-\mu^2\right)\frac{d^2F}{d\mu} + n(n+1)F + a^2\left(1+n^{-1}\right)F^{1+2n^{-1}} = \left(1-\mu^2\right)\frac{d^2F}{d\mu} + n(n+1)F + a^2\left(1+\frac{1}{n}\right)F^{1+\frac{2}{n}} = 0 \quad (18)$$

$$\vec{B} = \frac{1}{r\sin\theta} \left( \frac{1}{r} \frac{\partial \widetilde{A}}{\partial \theta}, -\frac{\partial \widetilde{A}}{\partial r}, b_{\phi} \left( \widetilde{A} \right) \right)$$
(19)

where  $\widetilde{A} = \frac{F(\cos \theta)}{r}$ ,  $b_{\phi} = a \frac{F^2(\cos \theta)}{r^2}$ ,  $\cos \theta = \mu$ .

Finally,

$$B_r = \frac{1}{r\sin\theta} \left[ \frac{1}{r} \frac{\partial}{\partial\theta} \left( \frac{F(\cos\theta)}{r} \right) \right] = \frac{1}{r\sin\theta} \frac{1}{r^2} \frac{\partial F}{\partial\cos\theta} \frac{\partial\cos\theta}{\partial\theta} = -\frac{1}{r\sin\theta} \frac{\sin\theta}{r^2} \frac{\partial F}{\partial\cos\theta} = \frac{1}{r^3} \frac{\partial F}{\partial\cos\theta} = \frac{1}{r^3$$

$$B_{\theta} - \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial r} \left( \frac{F(\cos \theta)}{r} \right) \right] = \frac{1}{r \sin \theta} \frac{F}{r^2} = \frac{1}{r^3 \sin \theta} F = \frac{1}{r^3} \frac{1}{(1 - \cos^2 \theta)^{\frac{1}{2}}} F = \frac{1}{r^3} \frac{1}{(1 - \mu^2)^{\frac{1}{2}}} F, 0 \le \theta < \pi, -1 \le \mu < 1$$
(21)

$$B_{\phi} = a \frac{1}{r \sin \theta} \frac{F^2(\cos \theta)}{r^2} = a \frac{1}{r^3 \sin \theta} F^2 = a \frac{1}{r^3 (1 - \mu^2)^{\frac{1}{2}}} F^2$$
 (22)

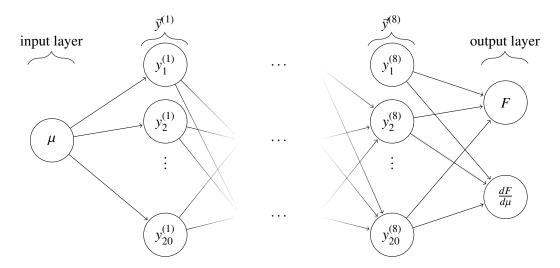


Fig. 1: Our Module

1. 
$$i = 1$$

$$\vec{y}^{(1)} = f\left(W^{(1)}x + b^{(1)}\right) \in \mathbb{R}^{20 \times 1}$$
(23)

where  $x \in \mathbb{R}^{1 \times 1}$ ,  $W^{(1)} \in \mathbb{R}^{20 \times 1}$ ,  $b^{(1)} \in \mathbb{R}^{20 \times 1}$ ,  $f = tanh(\cdot)$ .

## 2. $2 \le i \le 8$

$$\vec{x}^{(i+1)} = \vec{y}^{(i)}, \quad 1 \le i \in \mathbb{Z} \le 8 \tag{24}$$

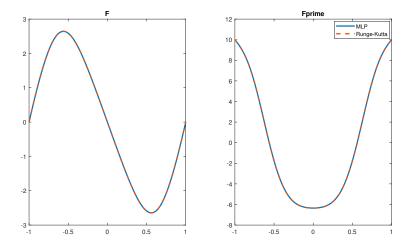
$$\vec{y}^{(i)} = f(W^{(i)}x^{(i)} + \vec{b}^{(i)}) = x^{(i+1)} \in \mathbb{R}^{20 \times 1}, \quad 1 \le i \in \mathbb{Z} \le 8$$
 (25)

where  $\vec{x}^{(i)} = \in \mathbb{R}^{20 \times 1}$ ,  $W^{(i)} \in \mathbb{R}^{20 \times 20}$ ,  $\vec{b}^{(i)} \in \mathbb{R}^{20 \times 1}$ .

3. i = 9

$$\vec{y}^{(9)} = f\left(W^{(9)}\vec{x}^{(9)} + \vec{b}^{(9)}\right) = \begin{bmatrix} F \\ F' \end{bmatrix} \in \mathbb{R}^{2 \times 1}$$
 (26)

where  $\vec{x}^{(9)} = \in \mathbb{R}^{20 \times 1}, W^{(9)} \in \mathbb{R}^{2 \times 20}, \vec{b}^{(9)} \in \mathbb{R}^{2 \times 1}$ 



**Fig.** 2: Numerical solution to (18) when n = 1.

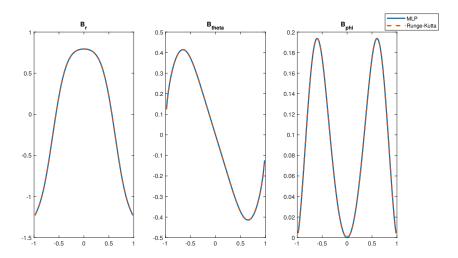


Fig. 3: Numerical solution to (19).

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