

Convex Optimization Project Midterm Report

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Our group is interested in the second problem, which is about optimal transport. Since many tough problems in various fields (e.g. medical imaging, biological feature identification, and some new-introduced neural networks) may be reformulated into optimal transport problems, it is crucial to find an efficient and reliable method to solve this problem. Our research will focus on finding such solutions.

1 Description to the Problem

In order to find a solution to this problem, we first formulate the original problem into the following linear programming form:

$$\begin{aligned} & \text{minimize} && \sum_{i=1}^m \sum_{j=1}^n c_{ij} \pi_{ij} \\ & \text{subject to} && \sum_{j=1}^n \pi_{ij} = \mu_i \quad \forall i = 1, \dots, m \\ & && \sum_{i=1}^m \pi_{ij} = \nu_j \quad \forall j = 1, \dots, n \\ & && \pi_{ij} \geq 0 \end{aligned} \tag{1}$$

where c_{ij} denote the distance between i and j , and π_{ij} are variables to solve.

2 Works We Have Done

We have solved the previous linear programming problem in interior method and simplex method by calling MOSEK directly.

In our numerical experiments, we used two random generated images μ and ν (with size $m \times n$, i.e., the indices of μ and ν are elements in $\{0, 1, \dots, m\} \times \{0, 1, \dots, n\}$) as experimental subjects, and assumed $m = n$. The entries in μ and ν are randomly sampled from $[0, 1)$ uniformly, and then μ and ν are renormalized to a sum of 10000 respectively. We used Euclidean distance $c_{ij} = \sqrt{(i_1 - j_1)^2 + (i_2 - j_2)^2}$ to represent the distance between two pixels $i = (i_1, i_2)$ and $j = (j_1, j_2)$. We then applied interior point methods and simplex methods in MOSEK to solve the optimal transport problem described in (1). Three sizes (16×16 , 32×32 and 64×64) are tested. Results of running time are included in Table 1.

Table 1 Running Time (s) on Each Method

Size	Simplex Method	Interior Point Method
16×16	0.15	0.36
32×32	3.99	12.84
64×64	134.36	349.04

3 Further Research

In the further research of this topic, we will first do more numerical experiments on different experimental subjects, such as test objects given in DOTmark. We will also implement some other methods to solve this problem, and in the meantime we will analyze the properties of these methods. Besides, we are going to read the paper *DOTmark —A Benchmark for Discrete Optimal Transport and Multiscale Strategies for Computing Optimal Transport*, and we will compare methods in these papers with existing methods and find out advantages and disadvantages of them. If time permits, we will try some way to improve these methods.

Since optimal transport problems are formulated in a special way, it may be possible to find some specific methods for such problems, where efficiency may be much better than solving linear programming problems directly. This is another way for our future research.