

- 1) Noise Continued - Chapter 1 of DHS
  - 2) ML vs MAP vs Bayesian approaches - Chapter 3 of DHS
  - 3) Discriminative vs Generative methods - Chapter from Tom Mitchell's book
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$x_1, x_2, x_3, \dots, x_n$   
 $y_1, y_2, y_3, \dots, y_n$

$y = f(x)$  ✓  
 $x = g(y)$

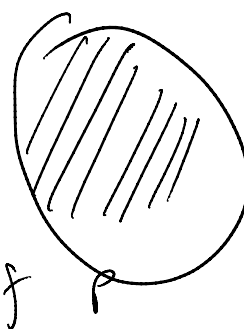
$p(x, y)$

①  $E_{\text{train}}$

② PARAMETERS

③  $x, \hat{x}$

④  $y, \hat{y}$



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$X, Y, x, y$

$$N = 100, n = 45, y = 1$$

$$P(y = +1 | N, n)$$

$$P(y = -1 | N, n)$$

$$P(y = +1 | N, n) > \frac{P(y = +1 | N, n)}{1 - P(y = +1 | N, n)}$$

$$P(y = +1 | N, n) > \frac{1}{2}$$

$$P(y = +1 | N, n) = \theta$$

$$\text{ARGMAX}_{\theta} P(n, N | \theta)$$

$\theta$

$$\textcircled{1} P(n, N | \theta) = \binom{N}{n} \theta^n (1-\theta)^{N-n}$$

$$\text{ARGMAX}_{\theta} \binom{N}{n} \theta^n (1-\theta)^{N-n}$$

$$\theta_{ML} = \frac{n}{N} = \frac{45}{100}$$

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MAP

$$\textcircled{1} ML = \underset{\theta}{\text{ARGMAX}} \frac{P(D|\theta)}{P(n, N|\theta)}$$

$$\textcircled{2} MAP \equiv \underset{\theta}{\text{ARGMAX}} \frac{P(\theta|D)}{P(\theta|n, N)} \quad ||$$

$$P(\theta|n, N) = \frac{P(n, N|\theta) P(\theta)}{P(n, N)}$$

$$\Rightarrow \underset{\theta}{\text{ARGMAX}} P(\theta|n, N) = \underset{\theta}{\text{ARGMAX}} P(n, N|\theta) P(\theta)$$

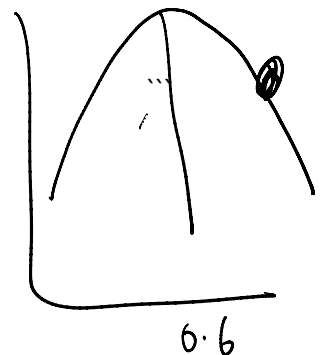
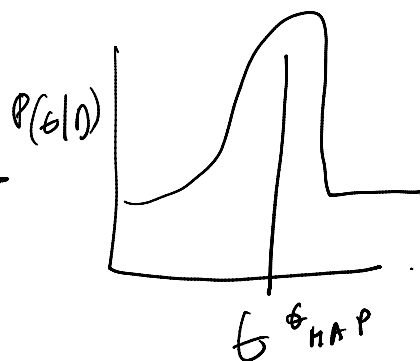
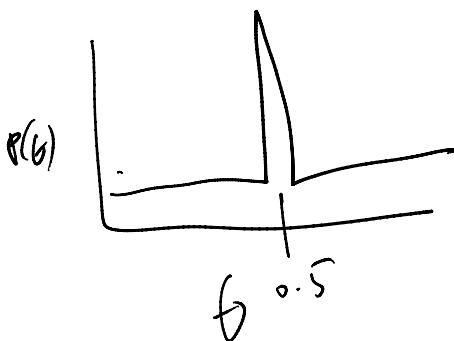
$$P(n, N|\theta) = \binom{N}{n} \theta^n (1-\theta)^{N-n}$$

$$P(\theta|a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \theta^{a-1} (1-\theta)^{b-1}$$

$$\underset{\theta}{\text{ARGMAX}} \theta^{n+a-1} (1-\theta)^{N-n+b-1} \quad ||$$

$$\theta_{MAP} = \frac{n+a-1}{N+a+b-2} > \frac{1}{2}$$

$$\theta_{ML} = \frac{n}{N} > \frac{1}{2}$$



$$\theta^{0.5}$$

$$\theta^{n+1}$$

$$\theta^b$$

$$p(y=+1 | n, \theta) = \int_{\sigma} p(y=+1, \theta | n, \theta) d\theta \quad \checkmark$$

$$= \int_{\sigma} p(y=+1 | \theta, n, \theta) p(\theta | n, \theta) d\theta \quad \checkmark$$

$$\int_{\sigma} p(y=+1 | \theta) p(\theta | n, \theta) d\theta \quad \checkmark$$

$$\int_{\sigma} \theta \beta(\theta | n+a, n-n+b) d\theta$$

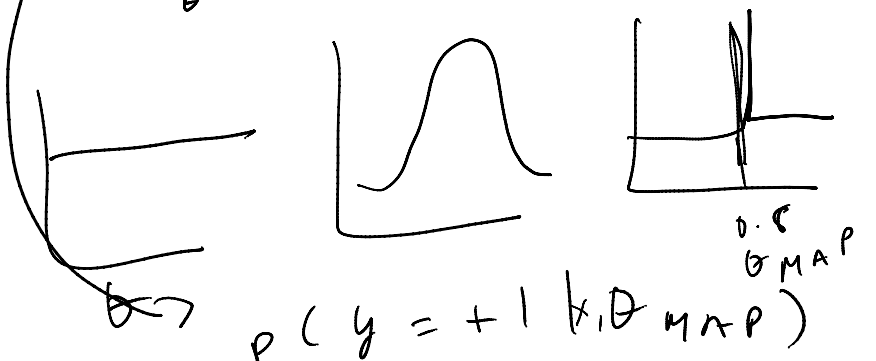
$$= \frac{n+a}{n+a+b}$$

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$$p(y=+1 | x, X, Y)$$

$$= \int_{\theta} p(y=+1, \theta | x, X, Y) d\theta$$

$$= \int_{\theta} P(y=+1 | \theta, x, y) P(\theta | x, y) d\theta$$

$$= \int_{\theta} P(y=+1 | \theta, x) P(\theta | x, y) d\theta$$


$\rightarrow P(y=+1 | x, \theta_{MAP})$

$$\theta_{MAP} = \underset{\theta}{\text{ARGMAX}} P(\theta | x, y)$$

$$\stackrel{\text{ML ASSUMPTION}}{=} \frac{P(x, y | \theta) P(\theta)}{P(x, y | \theta)}$$

$$P(y | x) = \frac{P(x | y) P(y)}{P(x)}$$

$$\underset{y}{\text{ARGMAX}} P(y | x) \stackrel{?}{=} \underset{y}{\text{ARGMAX}} P(x | y) P(y)$$

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DISC
GEN

SVM