

CS32 Week 7: Hash table & Heap

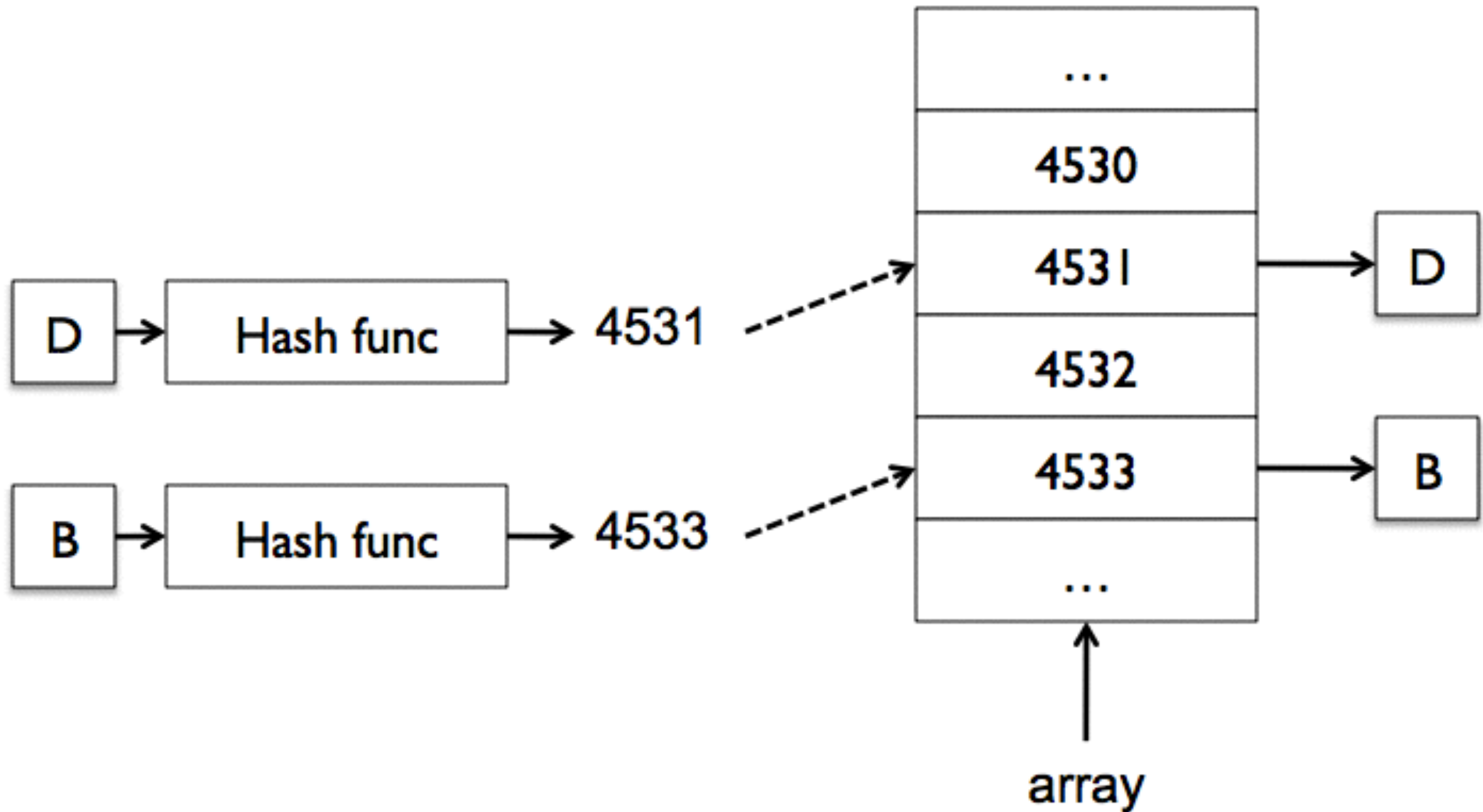
Hash table

- Hash function
 - Take a key and map it to a number
 - “Carey” $\rightarrow H(x) \rightarrow 4531$
- Basic requirement:
 - For same key, produce same value.
- Better hash function:
 - Spreads out the values: two different keys are likely to result in different hash values.
 - Computes each value quickly.

Hash table

- If we have a perfect hash function:
 - $H(x)$ could map the key into an integer range of $[0, 10000]$
 - different key will result in different hash value.
- We could use the hash function to store the data to support fast retrieval.

Hash table



Hash table

- Time complexity:
 - Insert
 - $O(1)$
 - Delete
 - $O(1)$
 - Search
 - Compute the hash value for the key
 - Go to the memory location
 - $O(1)$

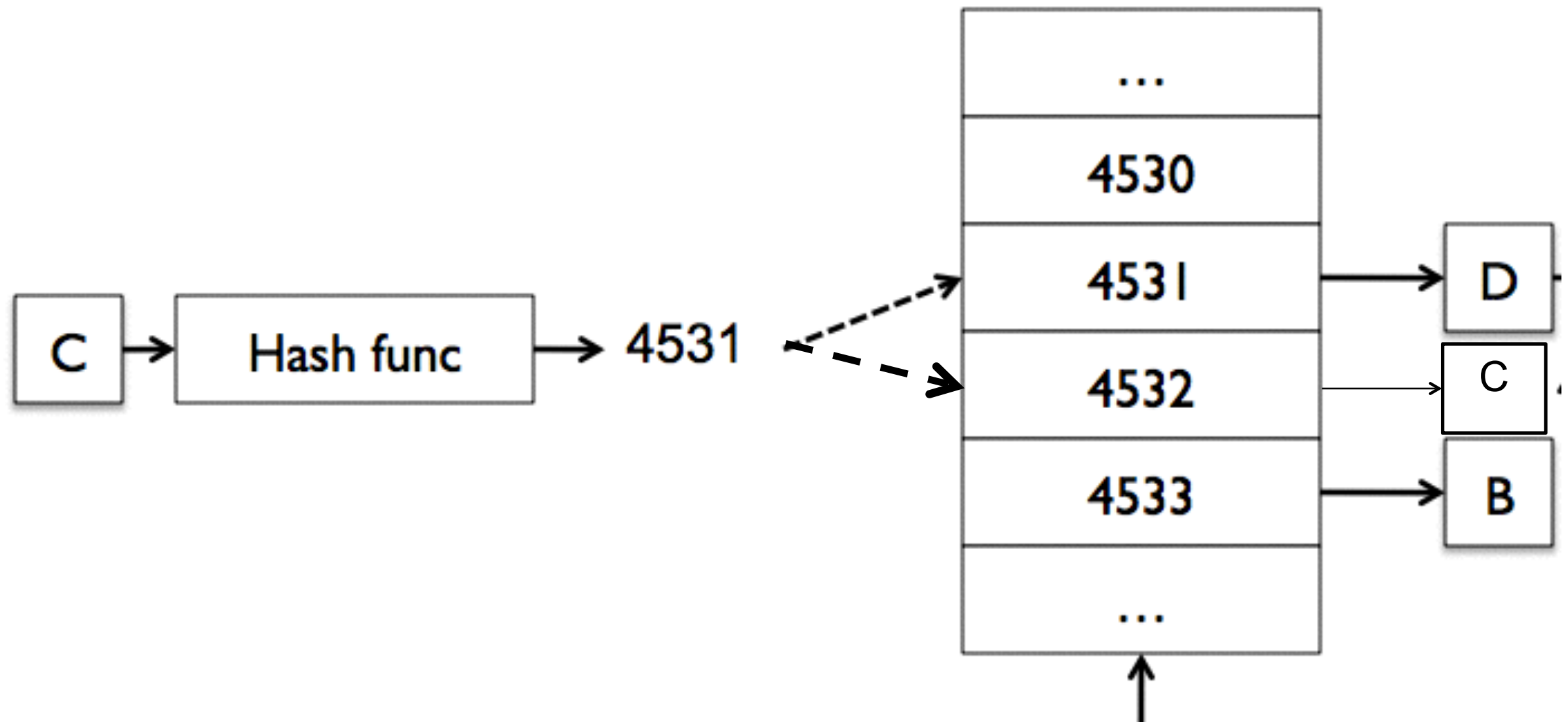
Hash table

- But there is no perfect hash functions
 - There exists the case that two different key would result in the same hash value.
 - “Collision”
 - Typical hash function:
 - mod by a large prime number
 - Design a way to resolve hash function collision
 - Closed: linear probing
 - Open

Hash table

- Close hash table
 - Linear probing
 - Solution: append the value in the next available spot starting from the desired position.

Hash table



Hash table

- Closed hash table (linear probing)
 - Search:
 - Compute the hash value
 - Linear scan starting from the hash value to an empty slot
 - Nearly $O(1)$, depending on the load factor

Hash table

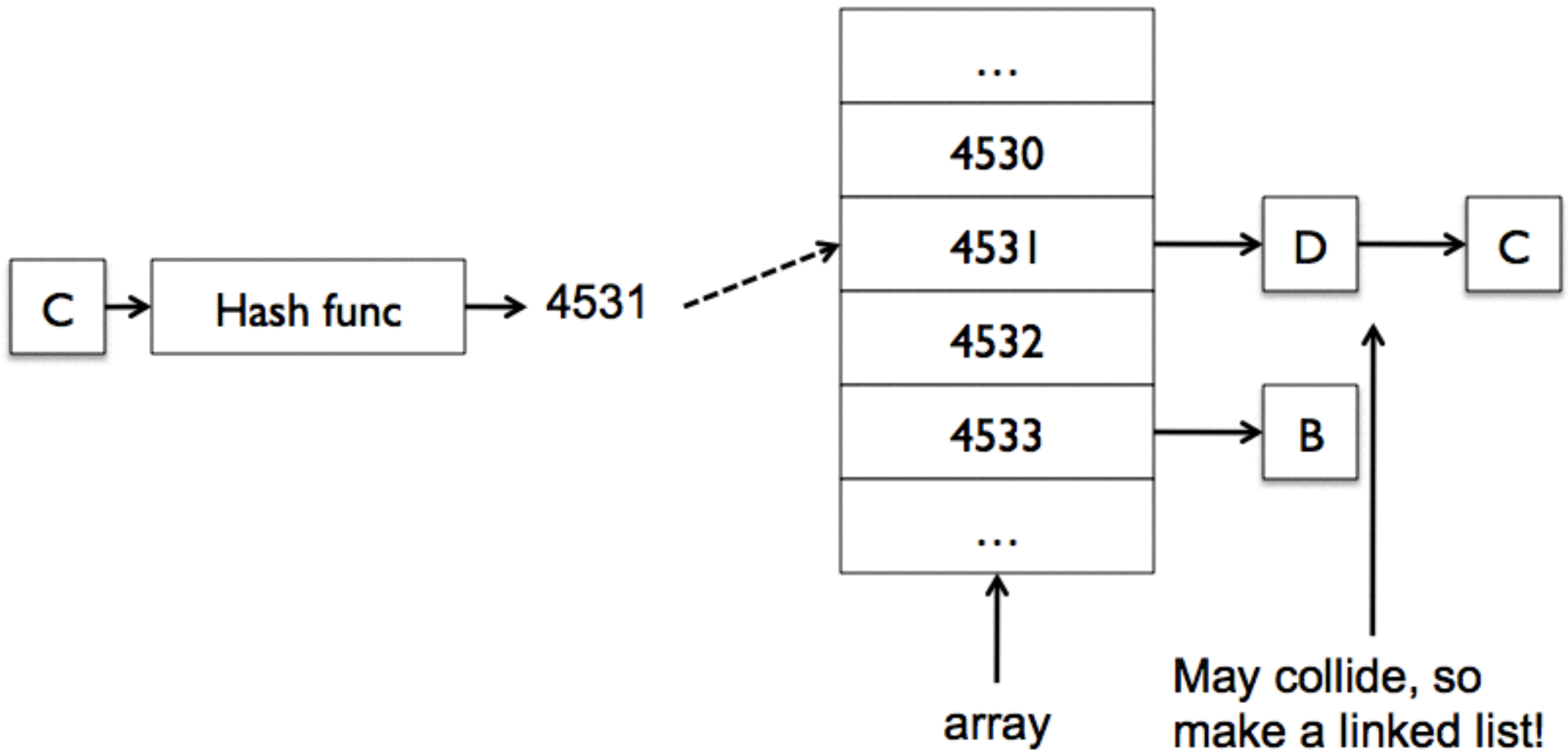
- Closed hash table (linear probing)
 - Problem:
 - Deletion
 - Hard to maintain data integrity for the hash table.

Hash table

- Open hash table
 - Use Linkedlist for each hash value (bucket)
 - Maintain the linkedlist for collision
 - Insert: append a new node
 - Delete: delete a node from the linked list

Hash table

- Open hash table



Hash table

- Open hash table
 - Search:
 - Find the corresponding bucket
 - Traverse the linkedlist to find the item

Hash table

- Complexity analysis
 - Desired performance:
 - Insertion, deletion, search: $O(1)$
 - Collision ruins the wish
 - Insertion, deletion and search would take longer
 - But approximately $O(1)$
 - Based on the load factor and how frequent a collision from the hash function happens.
 - Generally open hash table performs better than closed hash table using linear probing.

Hash table

- Compared with Binary Search Tree

	Hash table	Binary Search Tree
Speed	$O(1)$	$O(\log n)$
Max size	Closed: by array size Open: unlimited	unlimited
Space efficiency	Waste a lot of memory	Only memory needed
Ordering	No ordering (random)	sorted

Hash table

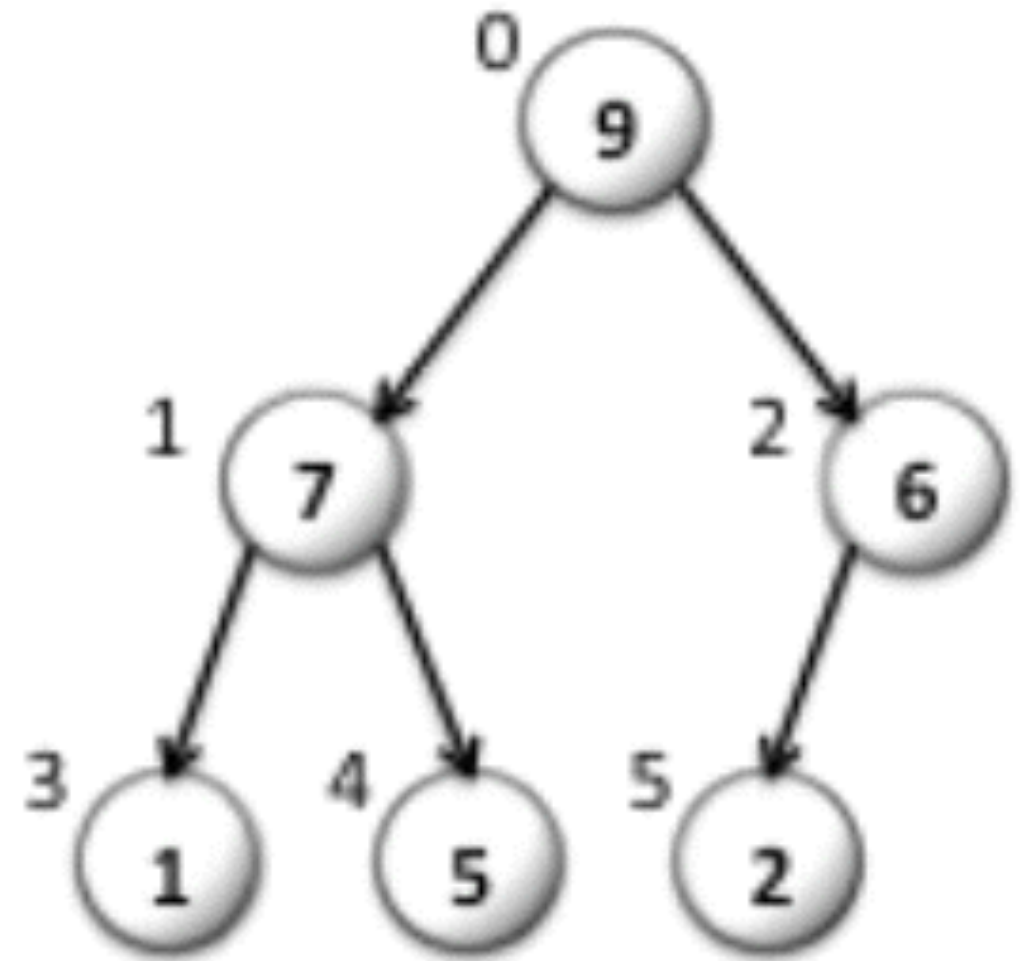
- To keep a better performance, keep a low load factor.
 - ❑ A waste of memory.
 - ❑ Tradeoffs between space and speed.

Heap

- ADT having easy access to largest or smallest item in your data
 - ❑ Maxheap & minheap
 - ❑ Can be used to implement priority queue
 - ❑ $O(1)$ for getting the largest/smallest item
 - ❑ $O(\log n)$ for inserting an item
 - ❑ $O(\log n)$ for removing largest/smallest item
- ❑ What if we use BST?

Heap

- Heap is a complete binary tree
- Each node's value is larger than or equals to it's children's.
 - Maxheap
 - Every subtree is a maxheap too.



Heap

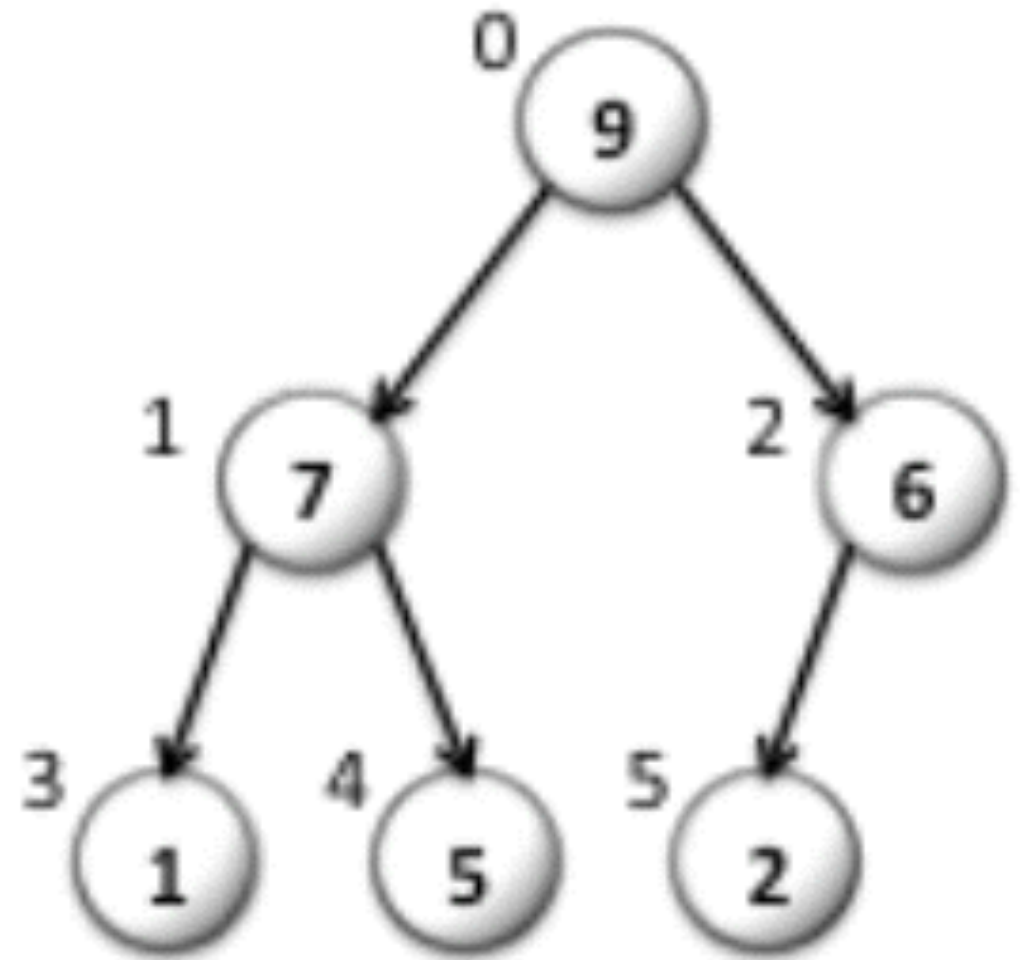
- Complete Binary Tree
 - L level
 - For first L-1 Levels, tree is full
 - For level L, nodes are on the left
- If N nodes, what's the level of the tree?
 - Guaranteed $\log_2(N)$

Heap

- To maintain largest item on the top
 - How to insert an item
 - How to remove the largest item

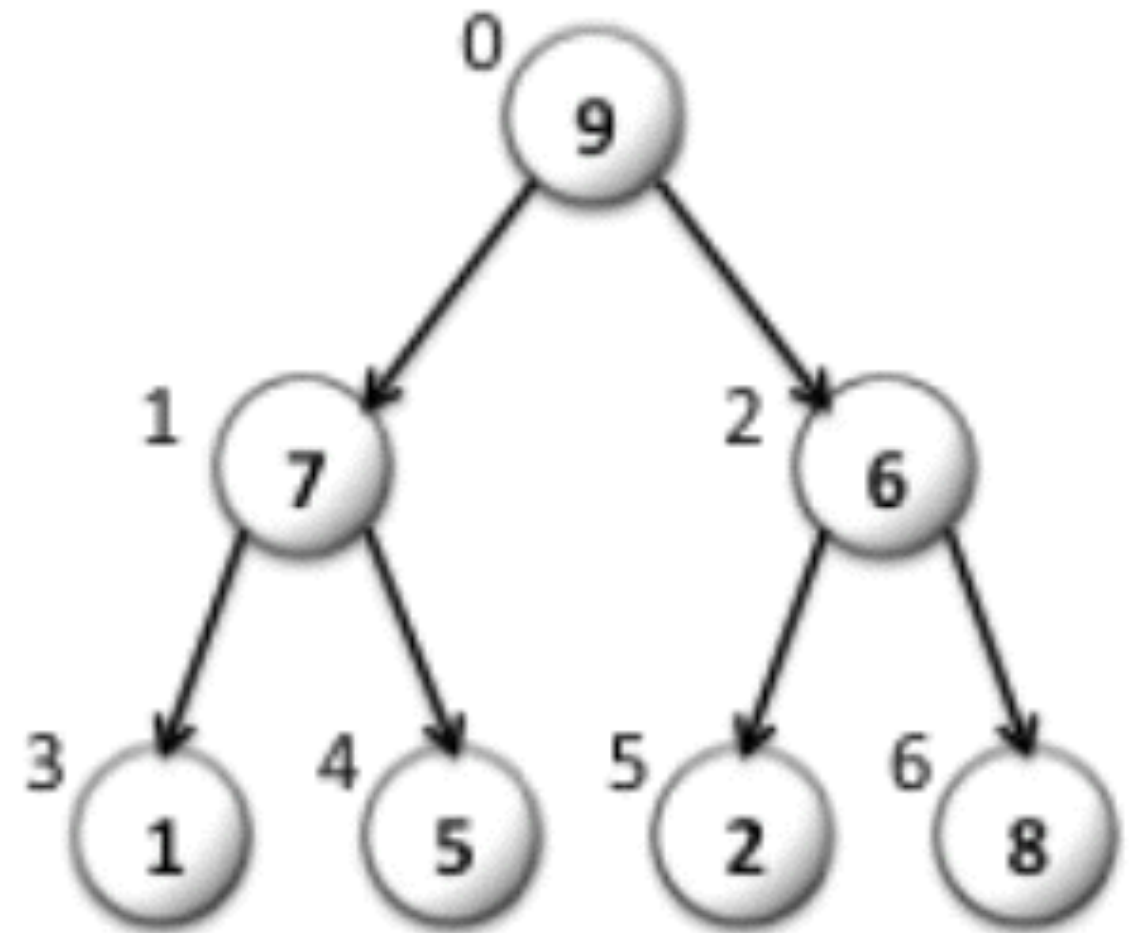
Heap

- Insert an item into maxheap
 - Insert 8
 - Append the next node
 - Bubble up to make it still a maxheap



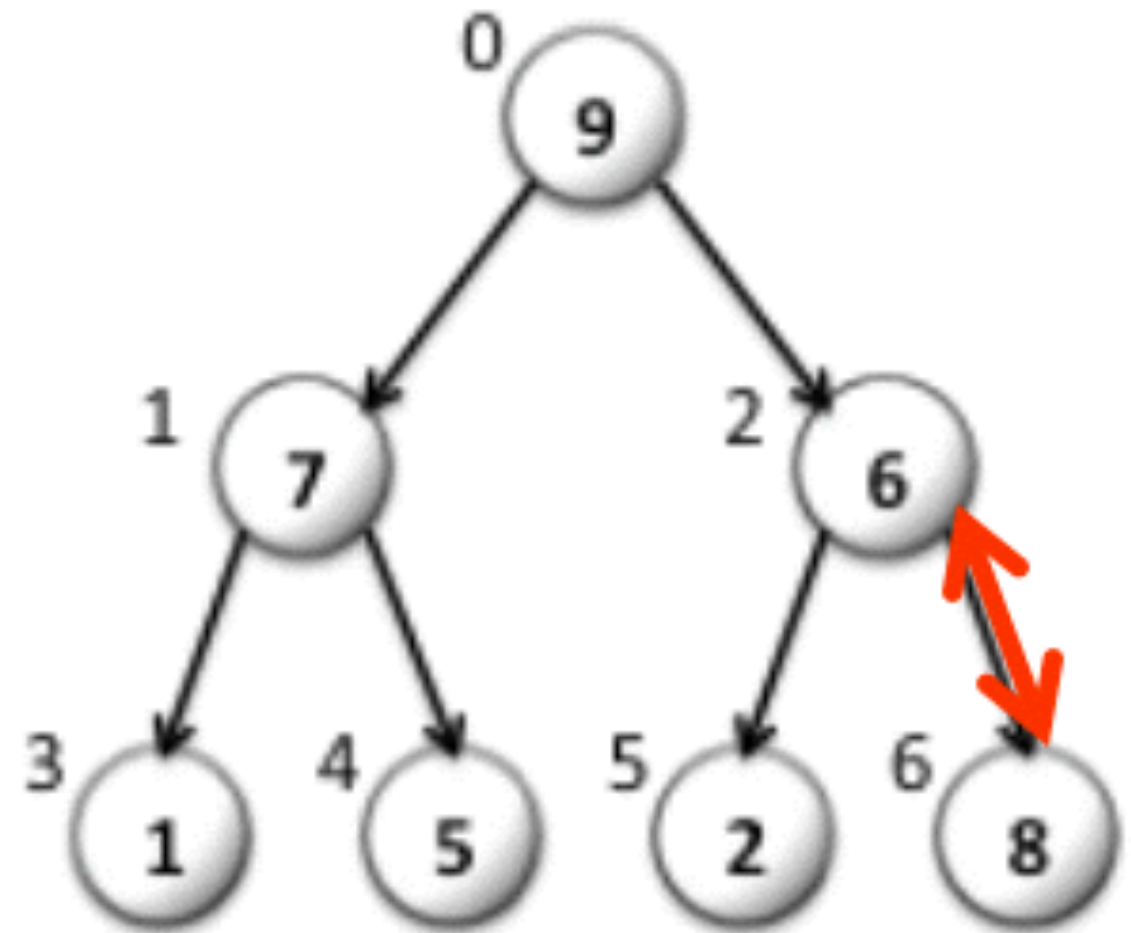
Heap

- Insert an item into maxheap
 - Insert 8
 - Append the next node
 - Bubble up to make it still a maxheap
 - Is it larger than parent?
 - Swap if yes.



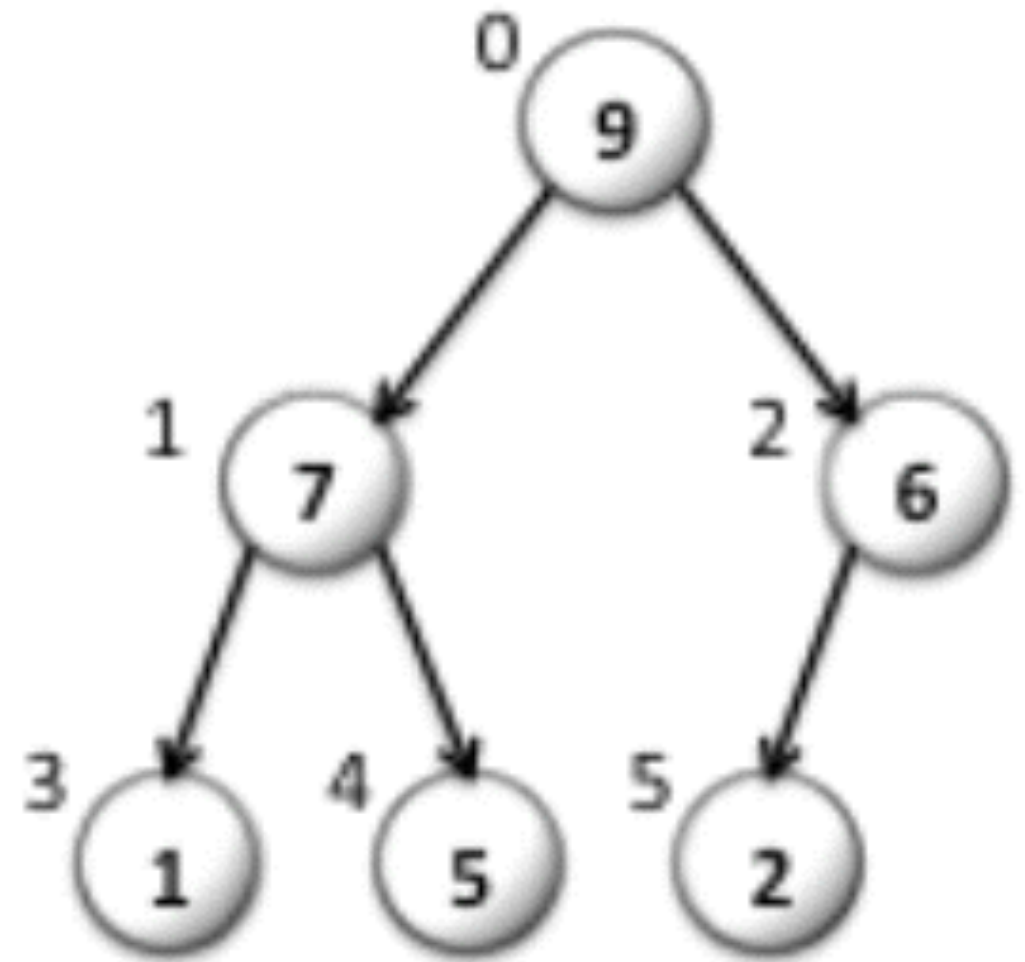
Heap

- Insert an item into maxheap
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 - Complexity?
 - $O(\log n)$



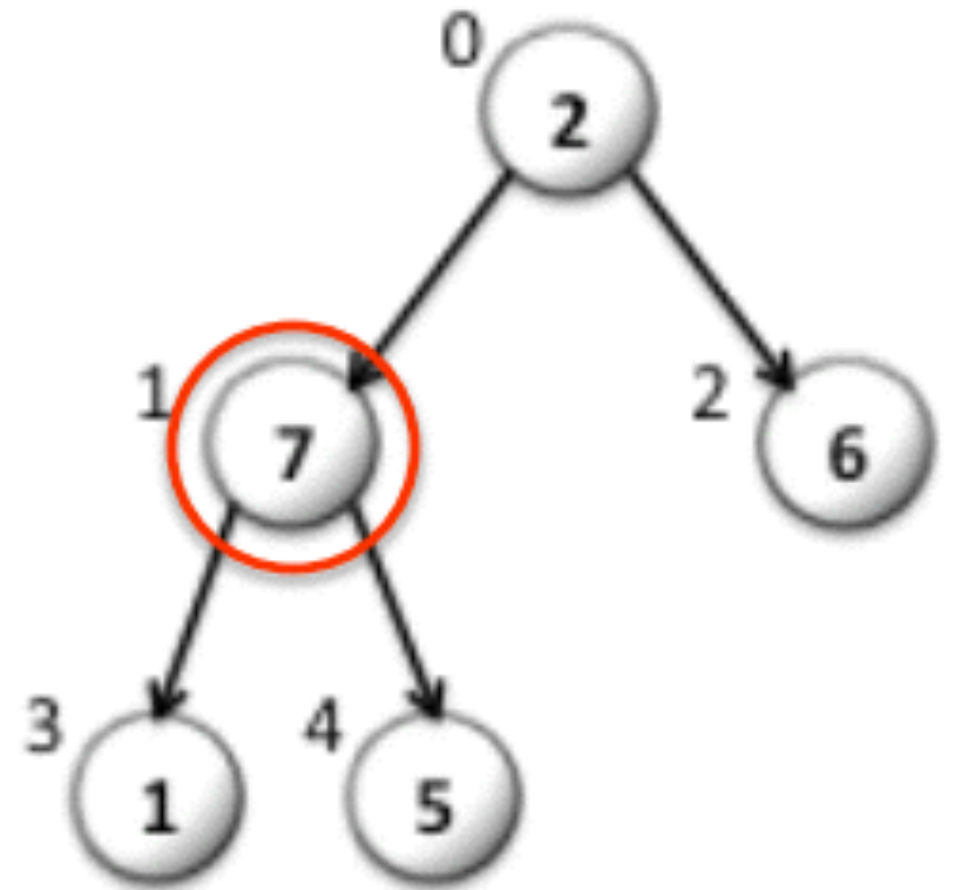
Heap

- Extract largest item from maxheap
 - Need to re-organize the tree to maintain largest one on top.
 - Find the last node, place the value to top node
 - Delete last node then
 - Bubble down, re-organize
 - Compare two children
 - Swap with larger one



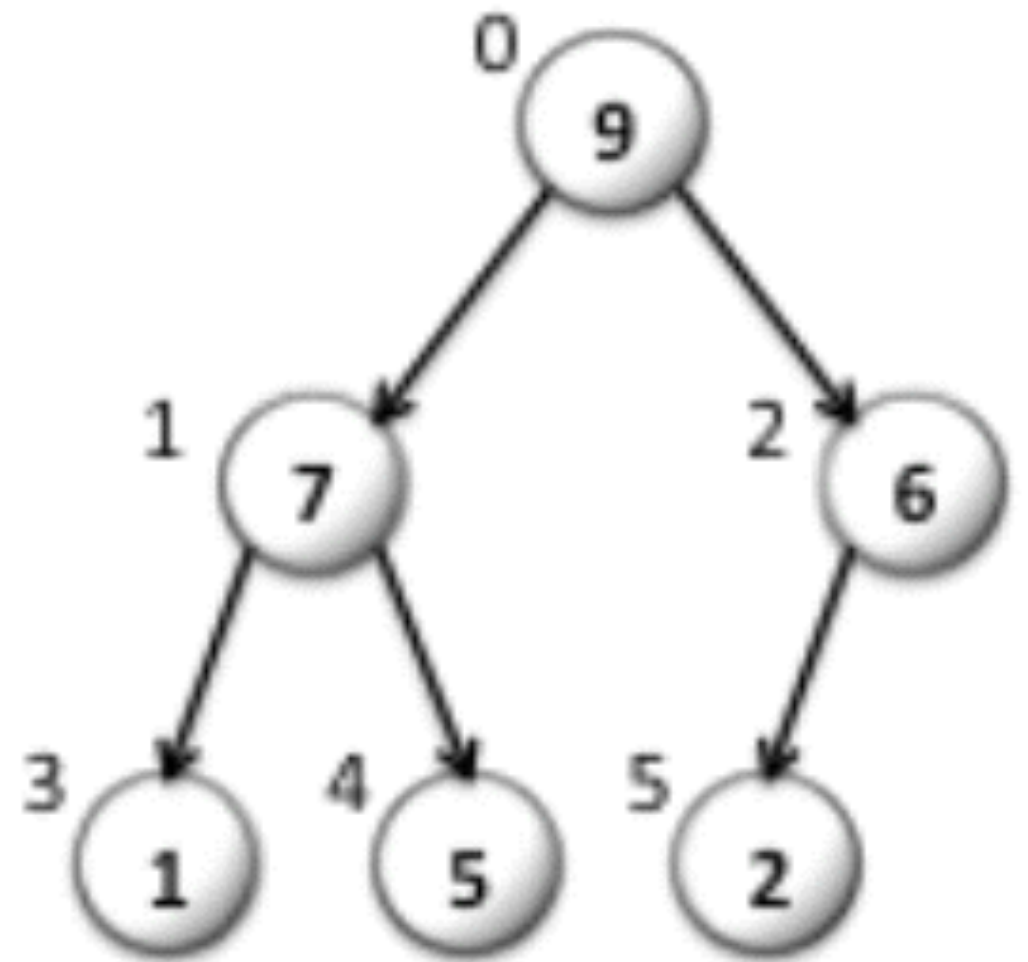
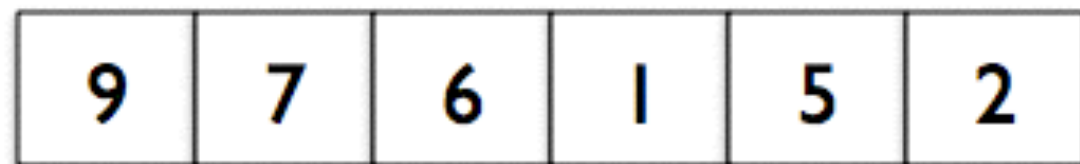
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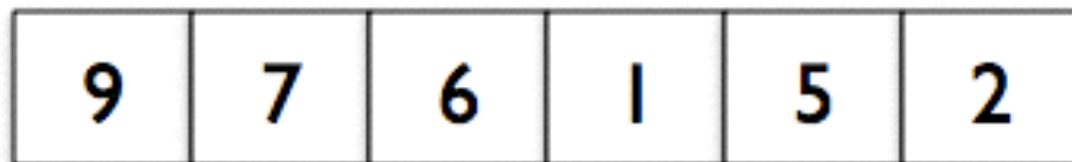
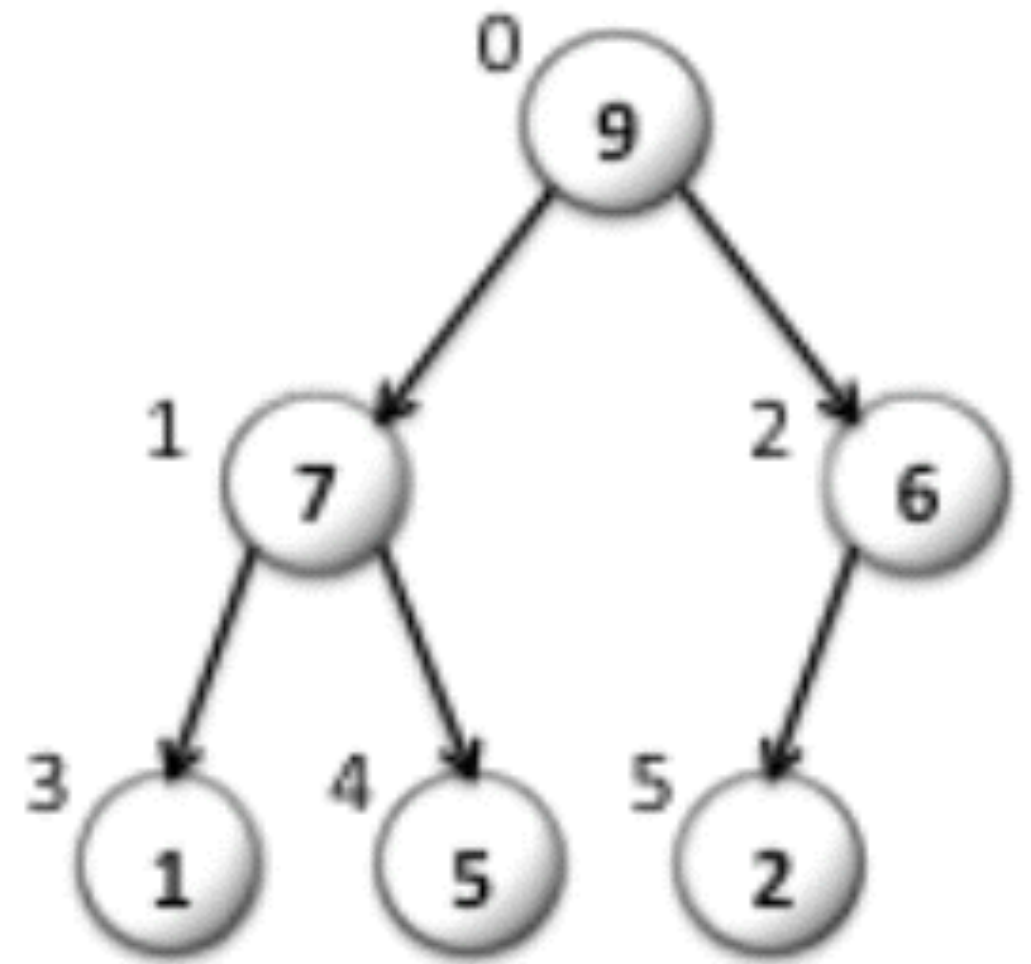
Heap

- Heap implementation
 - Using an array
 - Store data in level-ordering order



Heap

- Array Implementation
 - Last node
 - Last position
 - Given a node at position i
 - Parent position?
 - $(i - 1) / 2$
 - Given a node at position i
 - Children position?
 - $2*i + 1, 2*i + 2$



Heapsort

- Use heap to sort
 - Insert items in a maxheap
 - Extract largest item from maxheap one by one to get the data sorted
- 2, 6, 3, 1, 5, 4, 7, 8
- Show how the heap looks like after each step
 - Insert into a maxheap
 - Extract max from the heap

Heapsort

- In-place heap sort
 - You could build the maxheap in your array, without using another array.
 - Heapification
 - General idea: build maxheap from bottom, swap items if necessary.
 - 2, 6, 3, 1, 5, 4, 7, 8
 - Extracting max is same as before

Heapsort

- Complexity
 - Heapification: $O(n)$
 - Extracting max:
 - N times
 - Each time $O(\log n)$ for maintaining maxheap
 - $O(n \log n)$
 - Total: $O(n \log n)$
- Advantage:
 - Guaranteed $O(n \log n)$
 - In-place sorting